

CSCE 585: Machine Learning Systems

Lecture 7: Understanding and Explaining the Root Causes of (Performance) Faults in (ML) Systems with Causal AI

Fall 2024 Course Website: https://pooyanjamshidi.github.io/mls/

Pooyan Jamshidi





Reconciling Accuracy, Cost, and Latency of Inference Serving Systems



Pooyan Jamshidi University of South Carolina

https://pooyanjamshidi.github.io/





Problem:

Multi-Objective Optimization with Known Constraints under Uncertainty

$$\max \quad \alpha \cdot AA - (\beta \cdot RC + \gamma \cdot LC)$$

subject to
$$\lambda \leq \sum_{m \in M} th_m(n_m),$$
$$\lambda_m \leq th_m(n_m)$$
$$p_m(n_m) \leq L, \forall m \in M,$$
$$RC \leq B,$$

Solutions:

Different Assumptions

InfAdapter [2023]: Autoscaling for ML Inference

IPA [2024]: Autoscaling for ML Inference Pipeline

Sponge [2024]: Autoscaling for ML Inference Pipeline Dynamic SLO

What is Causal AI?



Let's start with a (fiction) story

- Zeus is a patient waiting for a heart transplant. On 1 January, he received a new heart. Five days later, he died.
- Imagine that we can somehow know, that had Zeus not received a heart transplant on 1 January then he would have been alive five days later.
 - All others things in his life being unchanged.
- Now, what do you think was the cause of Zeus's death?!
- Most people would agree that the transplant caused Zeus' death.
- The intervention had a causal effect.

Let's start with a (fiction) story

- Hera, received a heart transplant on 1 January. Five days later she was alive.
- Again, imagine we can somehow know that had Hera not received the heart on 1 January then she would still have been alive five days later.
 - All others things in his life being unchanged.
- The transplant did not have a causal effect on Hera's five day survival.

Let's collect some data!

ID	А	Ŷ	
Rheia	0	0	
Kronos	0	1	
Demeter	0	0	
Hades	0	0	
Hestia	1	0	
Poseidon	1	0	
Hera	1	0	
Zeus	1	1	
Artemis	0	1	
Apollo Circe	0	1	
	0	0	
Ares	1	1	
Athene	1	1	
Eros	1	1	
Aphrodite	1	1	
Prometheus]	1	
Selene]	1	
Hermes	1	0	
Eos	1	0	
Helios	1	0	

Exposure variable A (1: exposed, 0: unexposed); Outcome variable Y (1: death, 0: survival)

ID	$Y_{\alpha=0}$	$Y_{\alpha=1}$	
Rheia	0	1	
Kronos	1	0	
Demeter	0	0	
Hades	0	0	
Hestia	0	0	
Poseidon	1	0	
Hera	0	0	
Zeus	0	1	
Artemis	1	1	
Apollo Circe	1	0	
Circe	0	1	
Ares	1	1	
Athene	1	1	
Eros	0	1	
Aphrodite Prometheus	0	1	
Prometheus	0	1	
Selene	1	1	
Hermes	1	0	
Eos	1	0	
Helios	1	0	



Individual Causal Effect

ID	Α	Y	$Y_{\alpha=0}$	$Y_{\alpha=1}$	
Rheia	0	0	0	?	
Kronos	0	1	1	?	
Demeter	0	0	0	?	
Hades	0	0	0	?	
Hestia	1	0	?	0	
Poseidon	1			0	
Hera	1		?	0	
Zeus	1			1	
Artemis	0			?	
Apollo	0			?	
Circe	0 1	0/6)		?	
Ares	1		?	1	
Athene	1	$\geq 1/$?	1	
Eros	1	ן א	J ?	1	
Aphrodite	1	\sim	?	1	
Prometheus	1	1	?	1	
Selene	1	1	?	1	
Hermes	1	0	?	0	
Eos	1	0	?	0	
Helios	1	0	?	0	

contrast of the values of counterfactual outcomes, but only one of those values is observed.

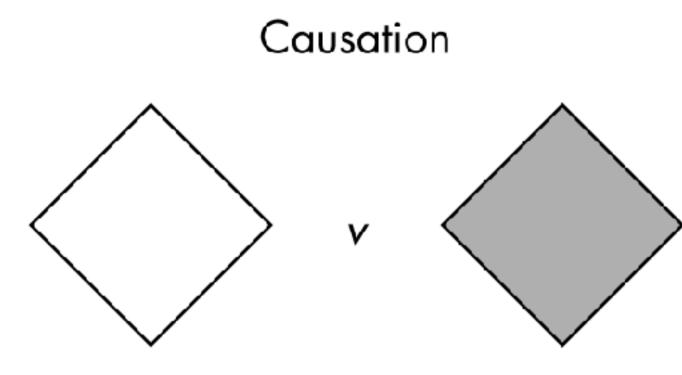
Population Causal Effects

- Pr[Ya = 1]: proportion of subjects that would have developed the outcome Y had all subjects in the population of interest received exposure value a.
- The exposure has a causal effect in the population if $Pr[Ya=1=1] \neq Pr[Ya=0=1]$.
- Unlike individual causal effects, population causal effects can sometimes be computed—or, more rigorously, consistently estimated.

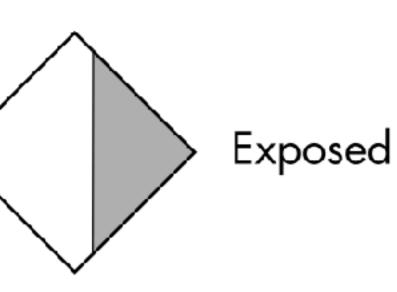
$$Pr[Y_{a=1} = 1] - Pr[Y_{a=0} = 1] \neq 0$$

Association is not Causation!

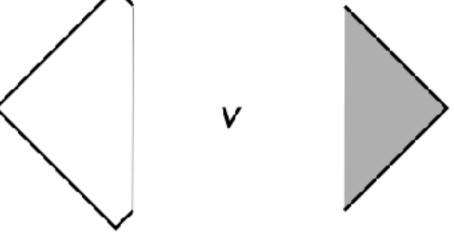




Observed population







Computing Causal Effects via Randomization

Unlike association measures, effect measures cannot be directly computed because of missing data. However, effect measures can be computed/estimated in randomized experiments!

- Suppose we have a (near-infinite) population and that we flip a coin for each subject in such
- each group, Pr[Y = 1|A = 1] and Pr[Y = 1|A = 0].
- subjects in group 2 receive placebo, or vice versa.
- 1|A = 0].)
- Formally, we say that both groups are **exchangeable**.

population. We assign the subject to group 1 if the coin turns tails, and to group 2 if it turns heads.

• Next we administer the treatment or exposure of interest (A = 1) to subjects in group 1 and placebo (A = 0) to those in group 2. Five days later, at the end of the study, we compute the mortality risks in

• When subjects are randomly assigned to groups 1 and 2, the proportion of deaths among the exposed, Pr[Y = 1|A = 1], will be the same whether subjects in group 1 receive the exposure and

• Because group membership is randomised, both groups are "comparable": which particular group got the exposure is irrelevant for the value of Pr[Y = 1|A = 1]. (The same reasoning applies to Pr[Y = 1|A = 1].

Let's do some math! $Pr[Y = 1 | A = 1] = Pr[Y = 1 | A = 0] = Pr[Y_a = 1]$ $Pr[Y_a = 1 | A = a] = Pr[Y = 1 | A = a]$ SUPERIAPPY- $Pr[Y = 1 | A = a] = Pr[Y_a = 1]$

In ideal randomized experiments, Association is Causation!





But not in non-randomized observational studies **Still remember this?**

Pr[Y = 1 | A = 1] = 7/13

Pr[Y = 1 | A = 0] = 3/7

CONTINUING PROFESSIONAL EDUCATION

M A Hernán

A definition of causal effect for epidemiological research

J Epidemiol Community Health 2004;58:265-271. doi: 10.1136/jech.2002.006361

Limitations!

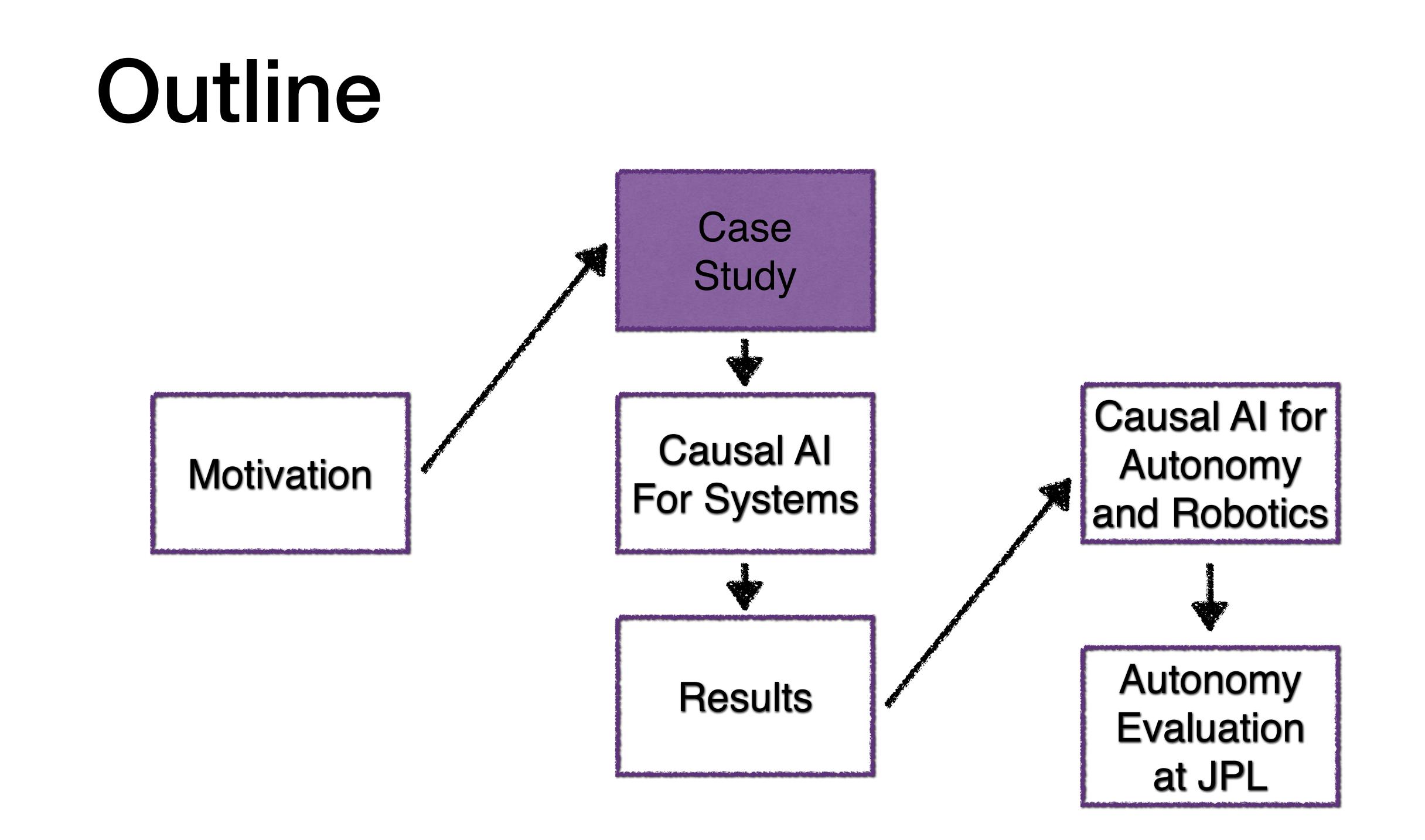
- well defined.
- Loss to follow up
- Non-compliance
- Unblinding \bullet

• We have so far assumed that the counterfactual outcomes Y_a exist and are

Now, let's look at some applications of Causal AI in Computer Systems





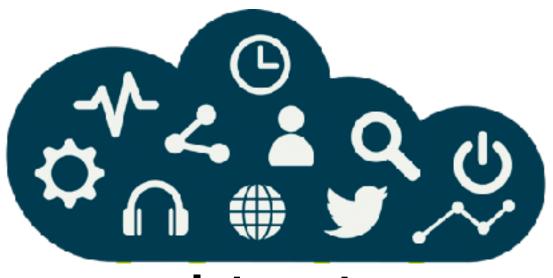




Case Study 1 SocialSensor

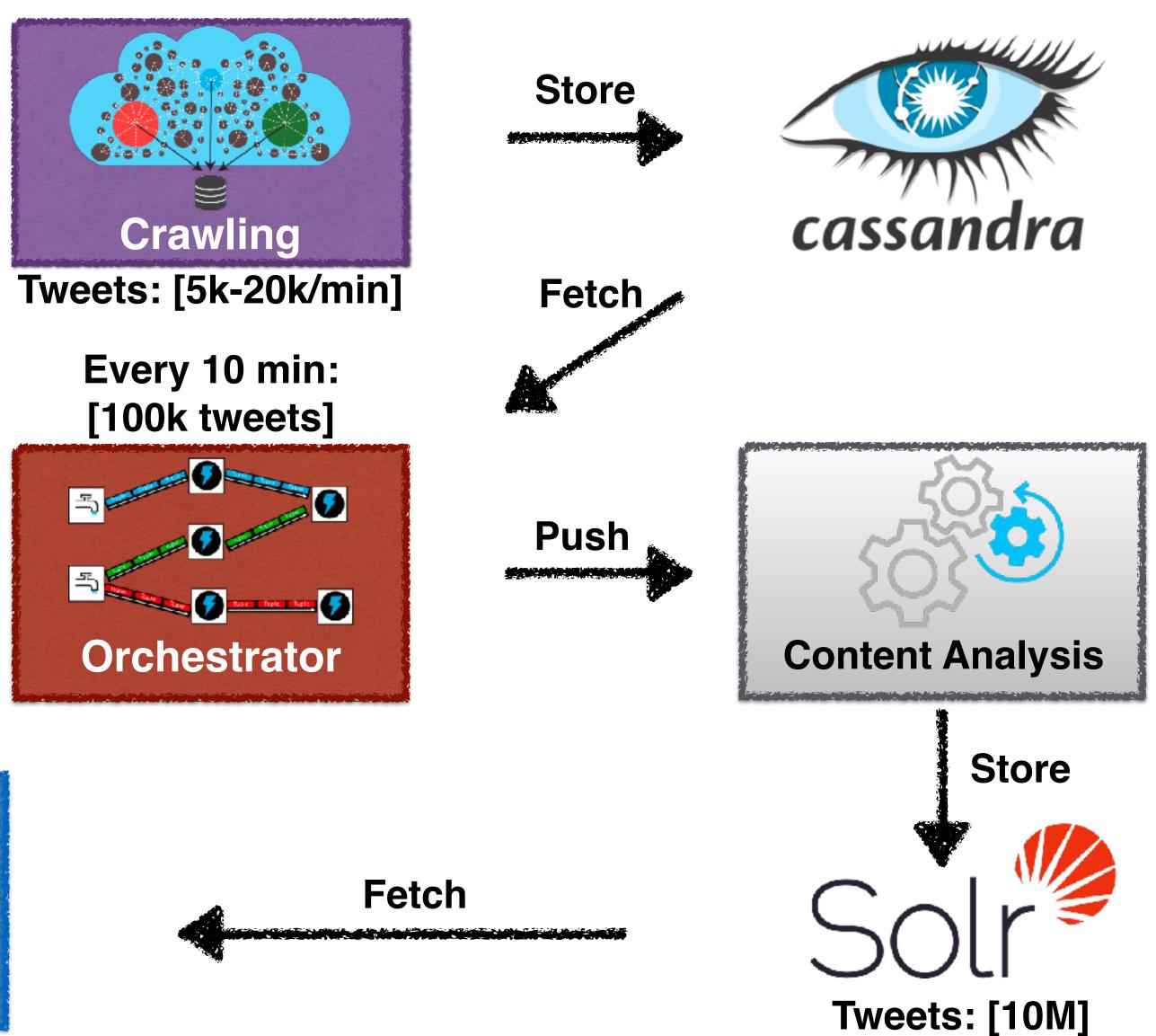


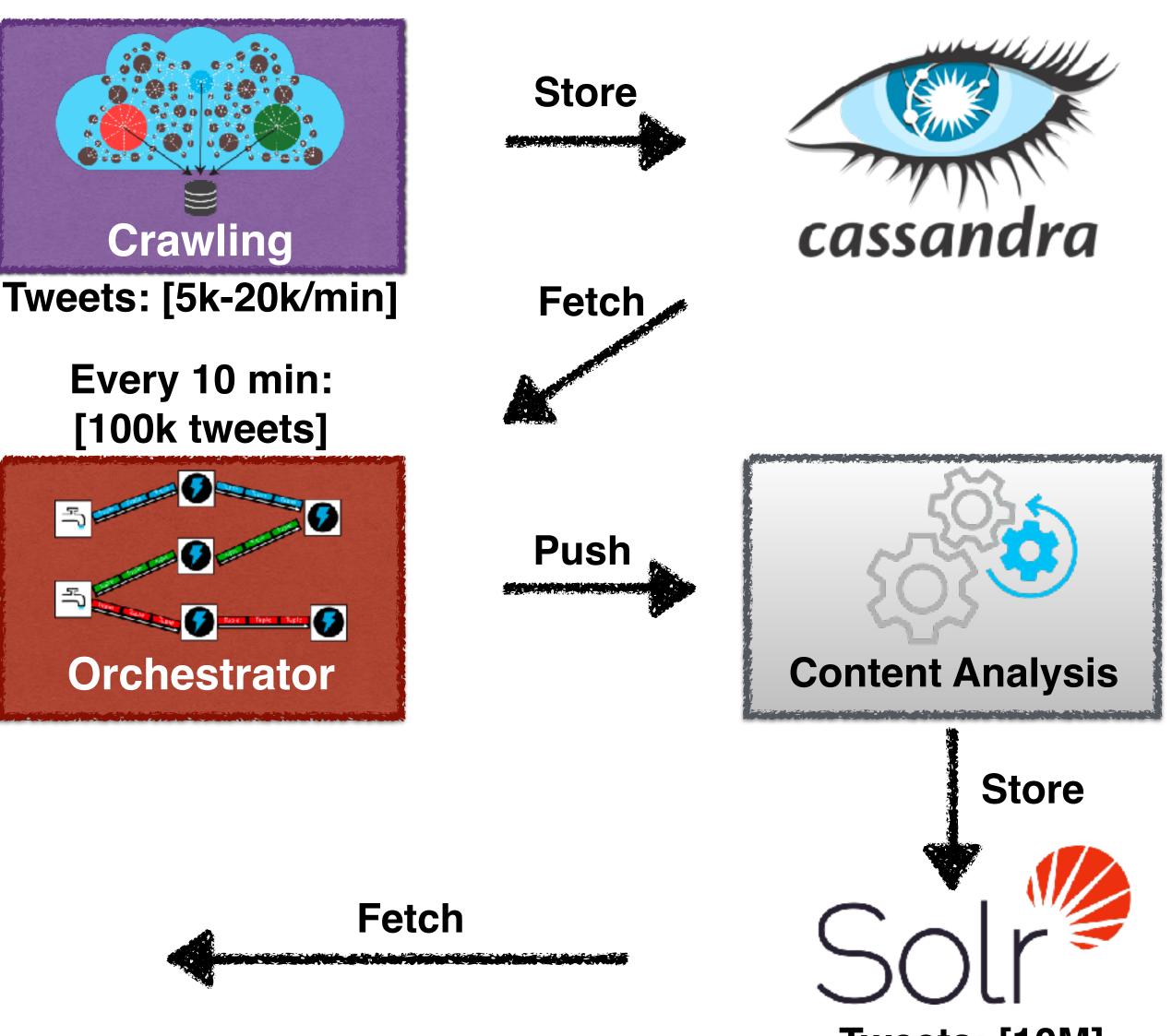
SocialSensor



Internet

Crawled items









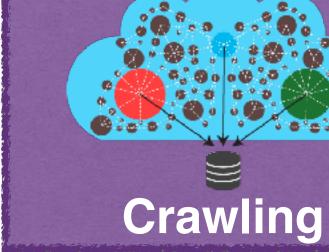
18

Challenges



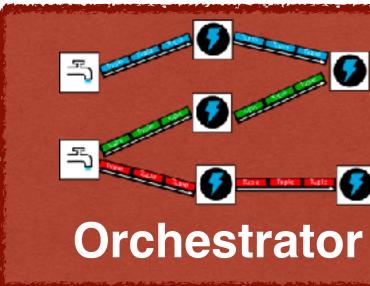
Crawled items

10X



Tweets: [5k-20k/min]

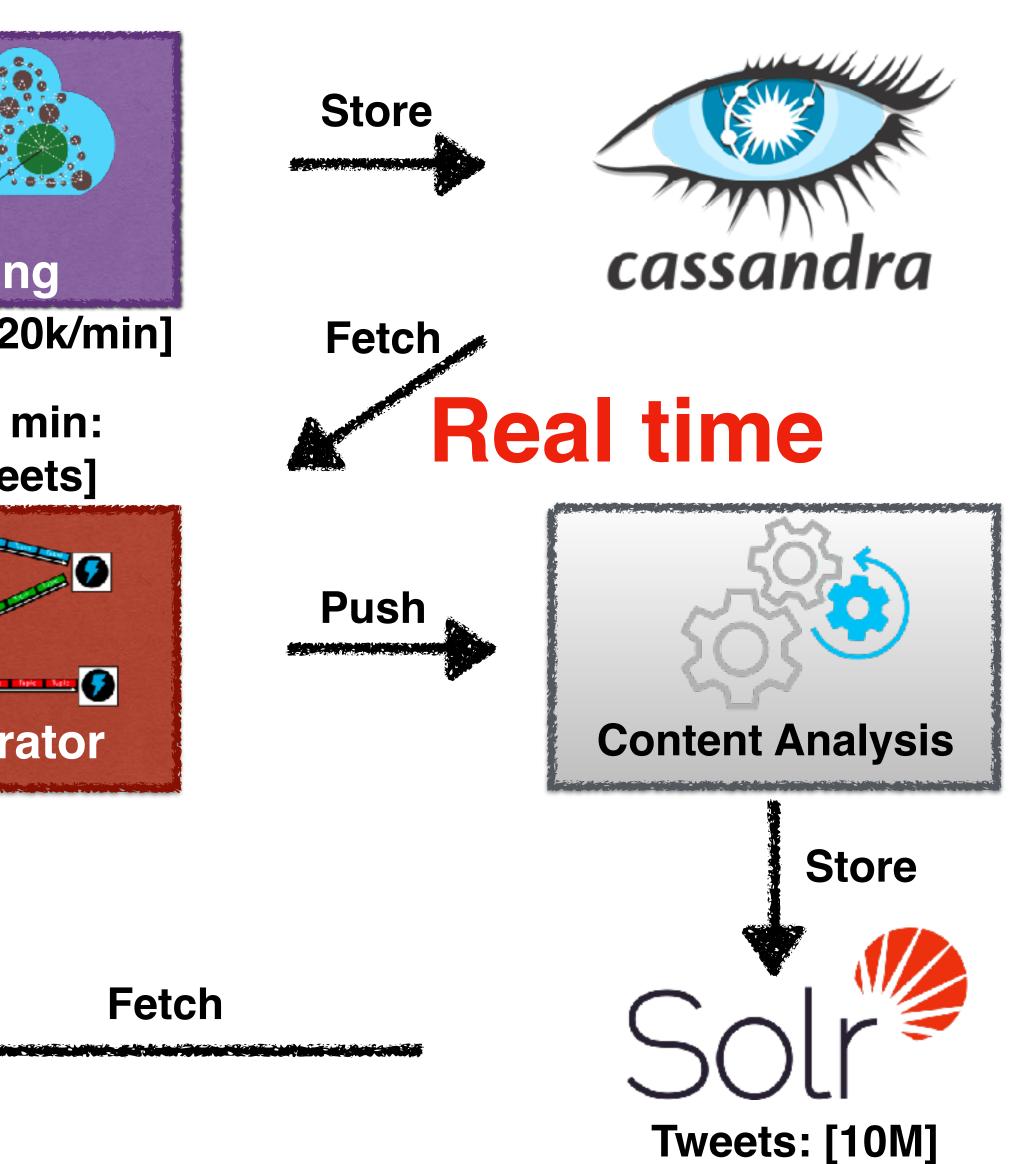
Every 10 min: [100k tweets]











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using more resources?

How can we gain a better performance without



Let's try out different system configurations!

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Opportunity: Data processing engines in the pipeline were all configurable





STORM

> 100



 2^{300}



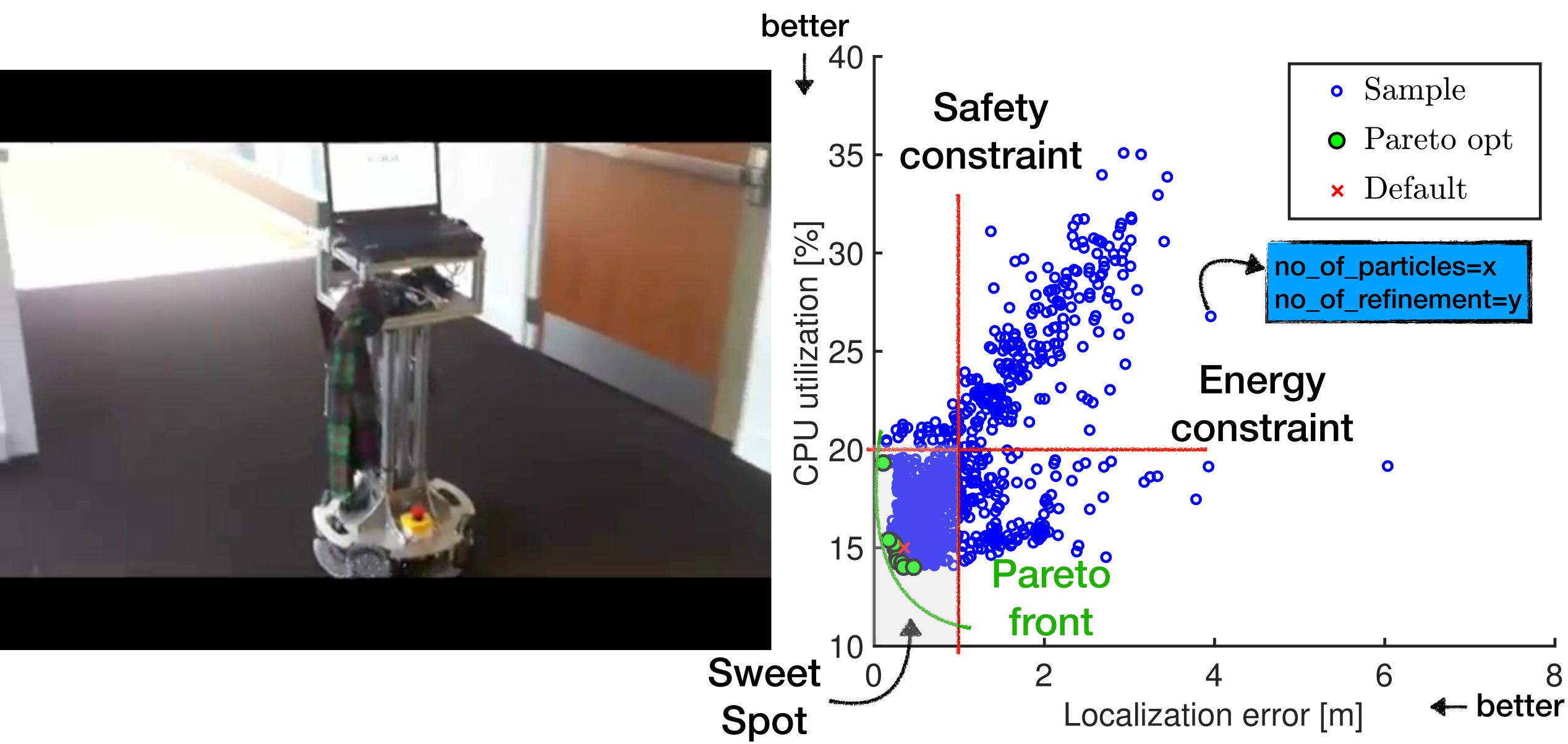
More configurations than estimated atoms in the universe

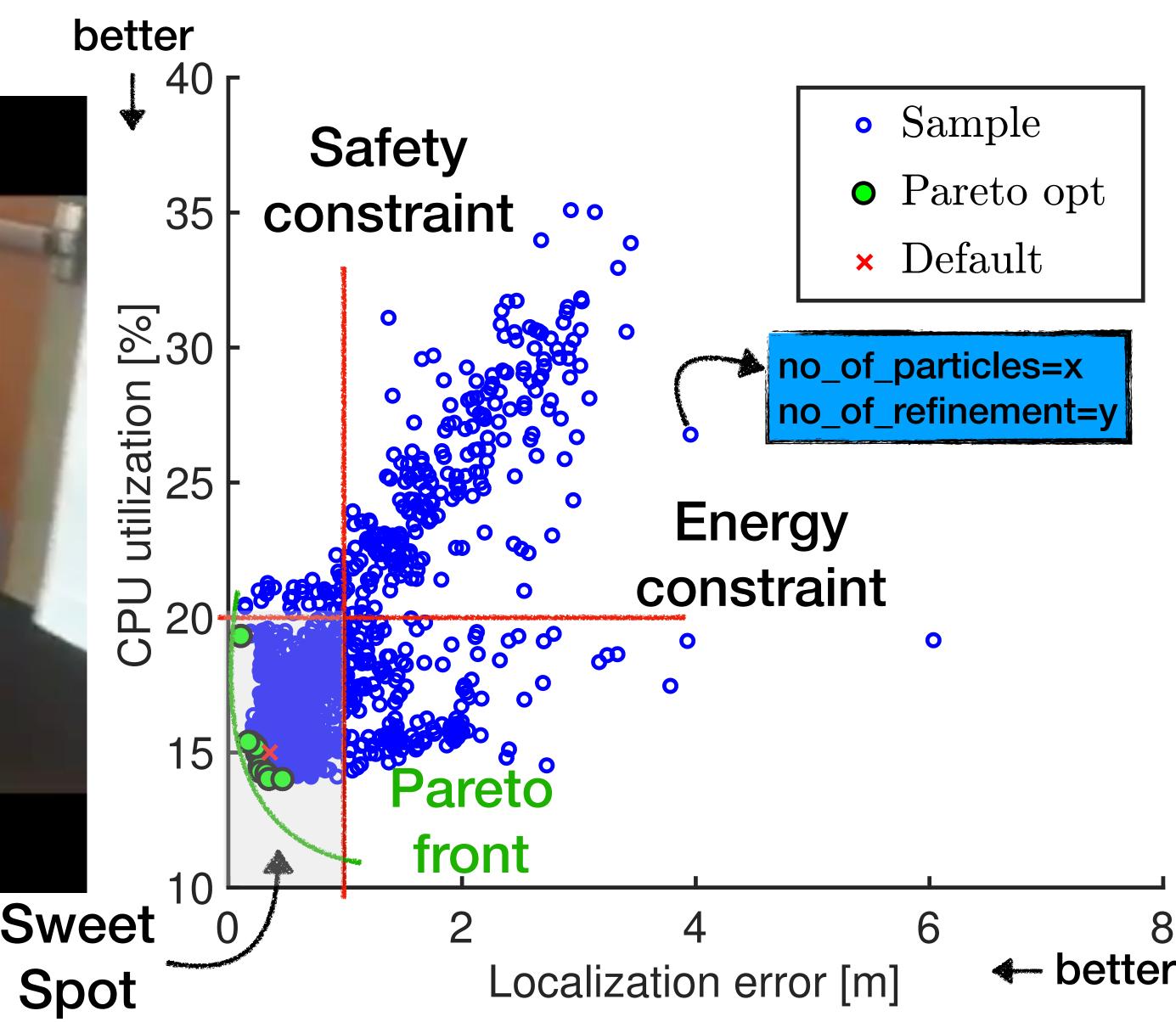


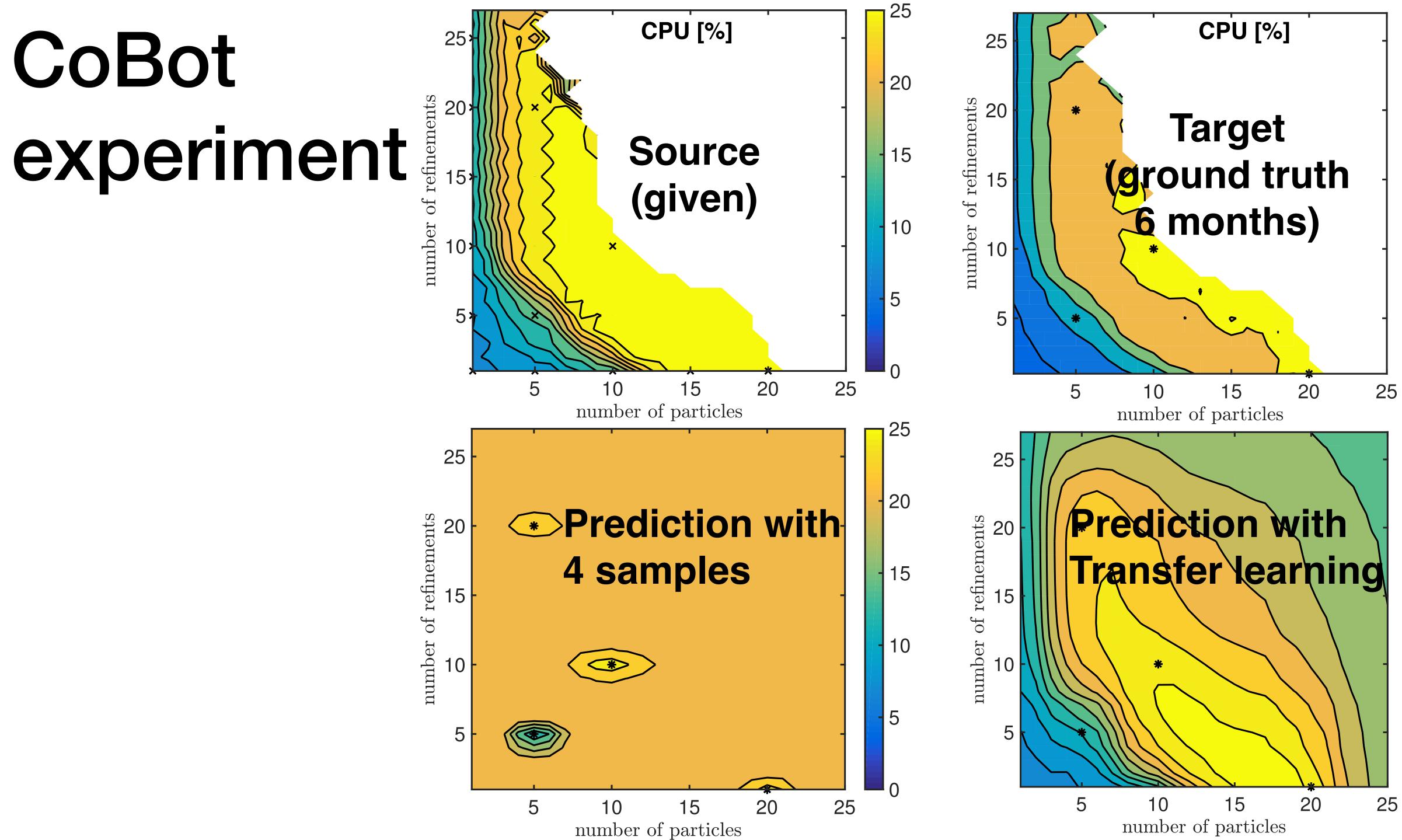
Case Study 2 Robotics



CoBot experiment: DARPA BRASS































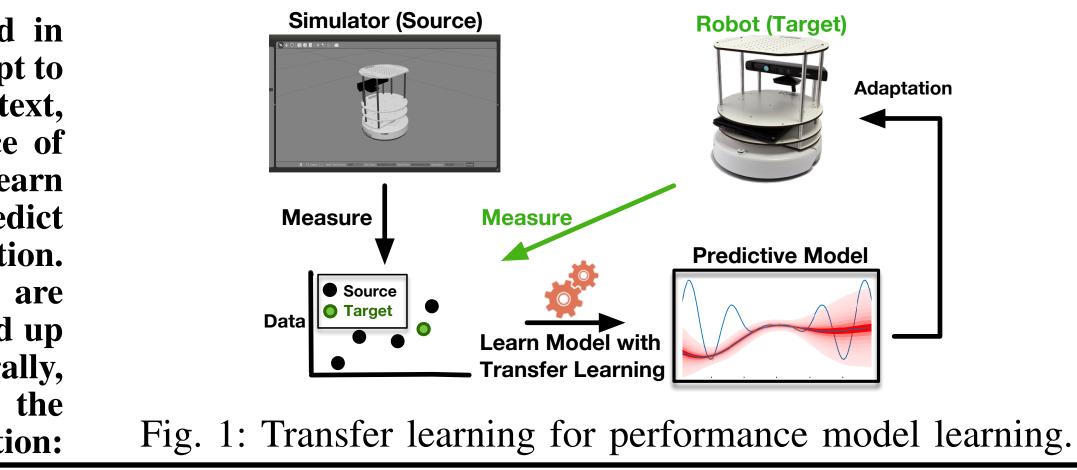


Details: [SEAMS '17]

Transfer Learning for Improving Model Predictions in Highly Configurable Software

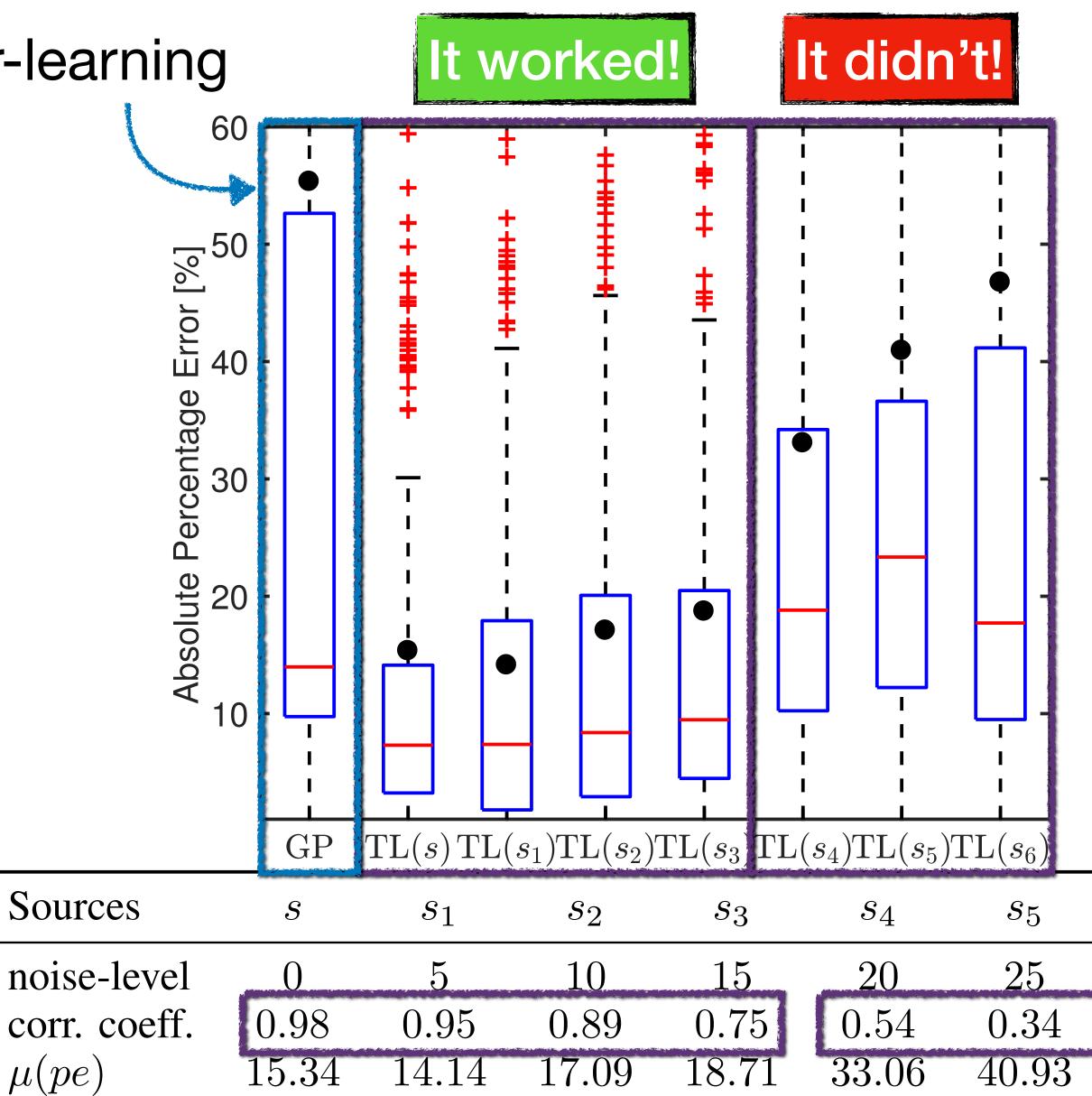
Pooyan Jamshidi, Miguel Velez, Christian KästnerNorbert SiegmundCarnegie Mellon University, USABauhaus-University Weimar, Germany{pjamshid,mvelezce,kaestner}@cs.cmu.edunorbert.siegmund@uni-weimar.de

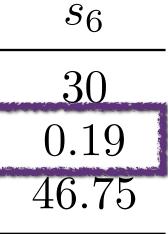
Abstract—Modern software systems are built to be used in dynamic environments using configuration capabilities to adapt to changes and external uncertainties. In a self-adaptation context, we are often interested in reasoning about the performance of the systems under different configurations. Usually, we learn a black-box model based on real measurements to predict the performance of the system given a specific configuration. However, as modern systems become more complex, there are many configuration parameters that may interact and we end up learning an exponentially large configuration space. Naturally, this does not scale when relying on real measurements in the actual changing environment. We propose a different solution: Prasad Kawthekar Stanford University, USA pkawthek@stanford.edu

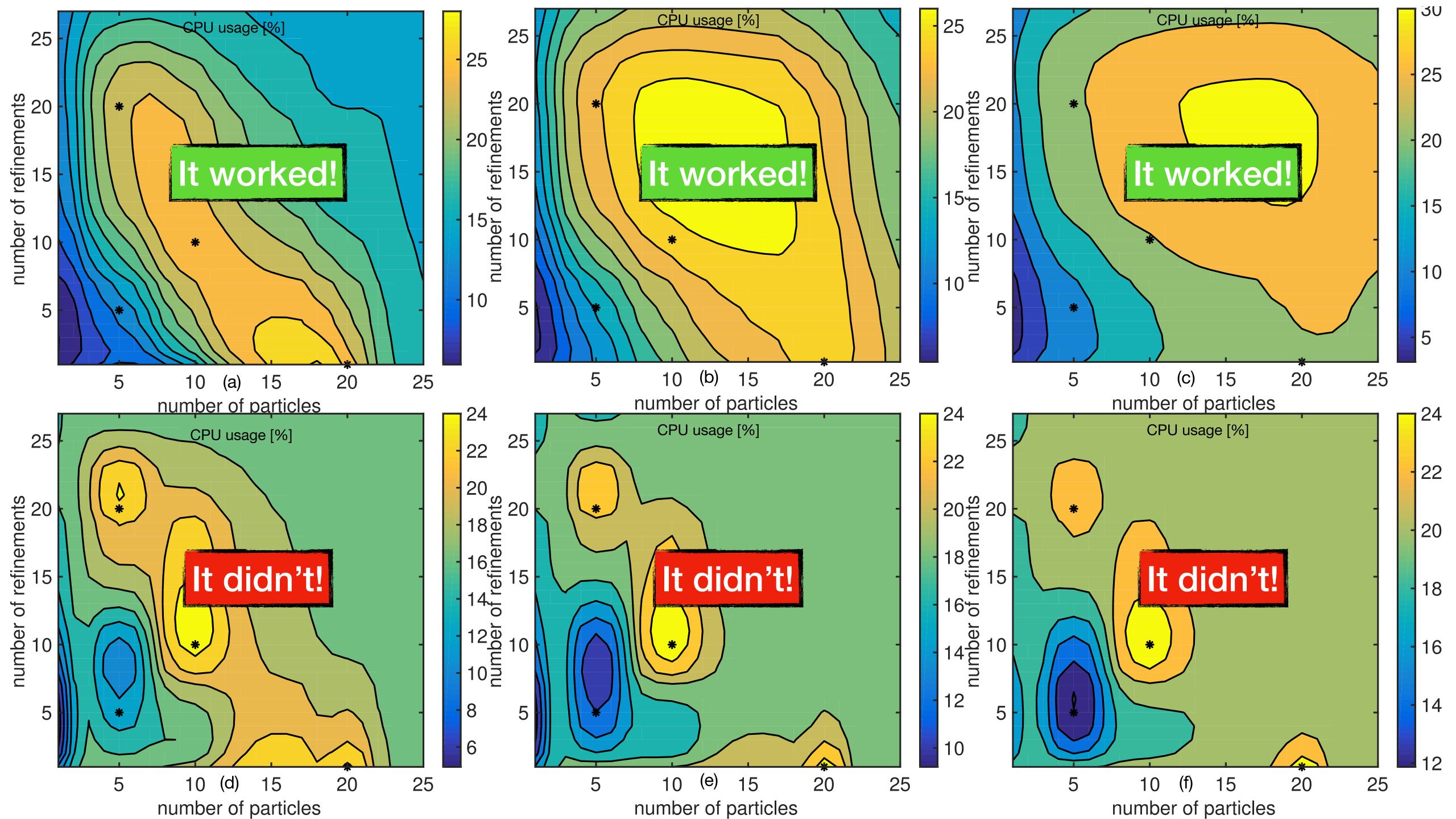


Looking further: When transfer learning goes wrong Non-transfer-learning

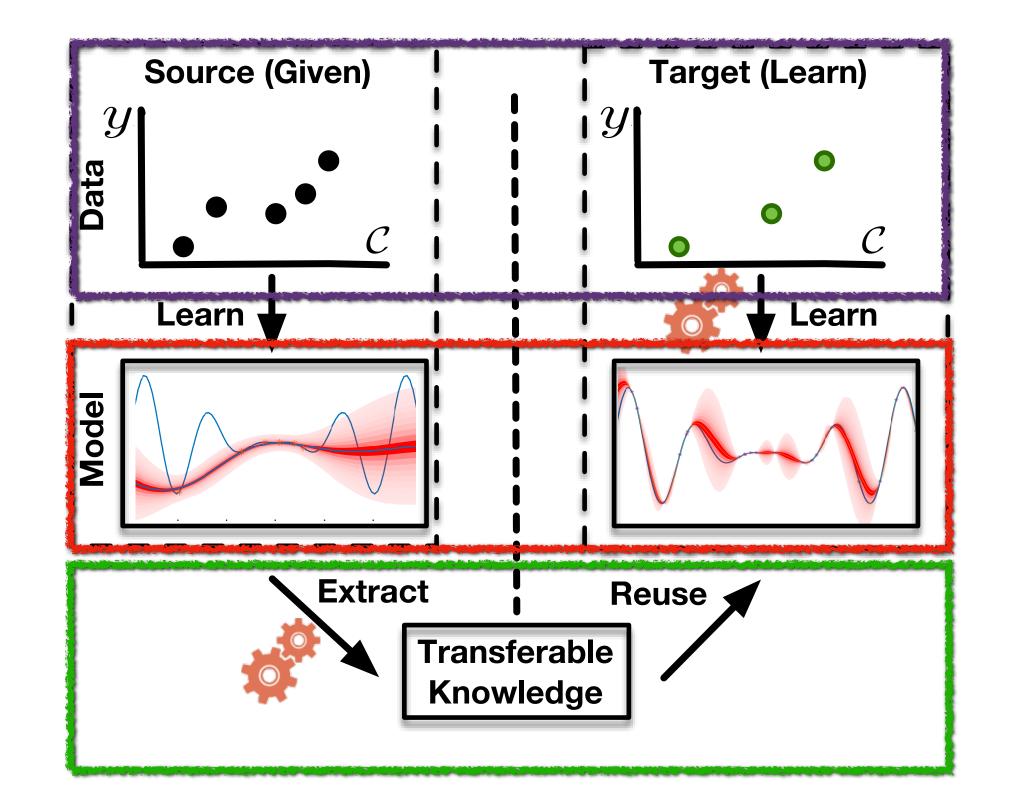
Insight: Predictions become more accurate when the source is more related to the target.







Key question: Can we develop a theory to explain when transfer learning works?



Q1: How source and target are "related"?

Q2: What characteristics are preserved?

Q3: What are the actionable insights?

Transfer Learning for Performance Modeling of Configurable Systems: An Exploratory Analysis

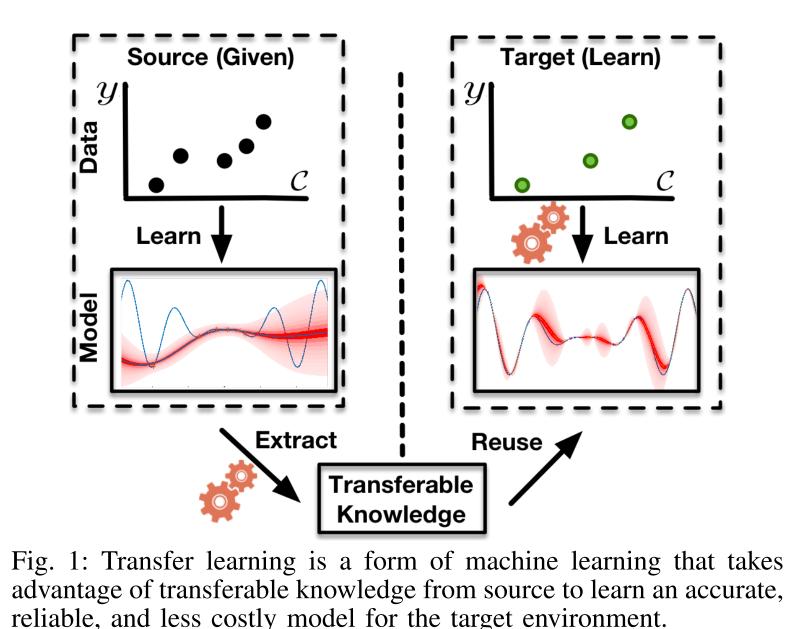
Pooyan Jamshidi Carnegie Mellon University, USA

Norbert Siegmund Bauhaus-University Weimar, Germany

Abstract—Modern software systems provide many configuration options which significantly influence their non-functional properties. To understand and predict the effect of configuration options, several sampling and learning strategies have been proposed, albeit often with significant cost to cover the highly dimensional configuration space. Recently, transfer learning has been applied to reduce the effort of constructing performance models by transferring knowledge about performance behavior across environments. While this line of research is promising to learn more accurate models at a lower cost, it is unclear why and when transfer learning works for performance modeling. To shed light on when it is beneficial to apply transfer learning, we conducted an empirical study on four popular software systems, varying software configurations and environmental conditions, such as hardware, workload, and software versions, to identify the key knowledge pieces that can be exploited for transfer learning. Our results show that in small environmental changes (e.g., homogeneous workload change), by applying a linear transformation to the performance model, we can understand the performance behavior of the target environment, while for severe environmental changes (e.g., drastic workload change) we

Details: [ASE '17]

Miguel Velez, Christian Kästner Akshay Patel, Yuvraj Agarwal Carnegie Mellon University, USA



Details: [AAAI Spring Symposium '19]

Transfer Learning for Performance Modeling of Configurable Systems: A Causal Analysis

Mohammad Ali Javidian, Pooyan Jamshidi, Marco Valtorta

Department of Computer Science and Engineering University of South Carolina, Columbia, SC, USA

Abstract

Modern systems (e.g., deep neural networks, big data analytics, and compilers) are highly configurable, which means they expose different performance behavior under different configurations. The fundamental challenge is that one cannot simply measure all configurations due to the sheer size of the configuration space. Transfer learning has been used to reduce the measurement efforts by transferring knowledge about performance behavior of systems across environments. Previously, research has shown that statistical models are indeed transferable across environments. In this work, we investigate identifiability and transportability of causal effects and statistical relations in highly-configurable systems. Our causal analysis agrees with previous exploratory analysis (Jamshidi et al. 2017) and confirms that the causal effects of configuration options be carried over across environments with high

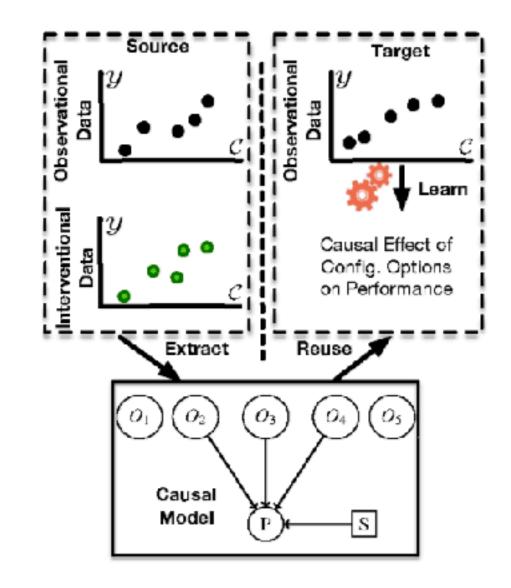


Figure 1: Exploiting causal inference for performance analysis.

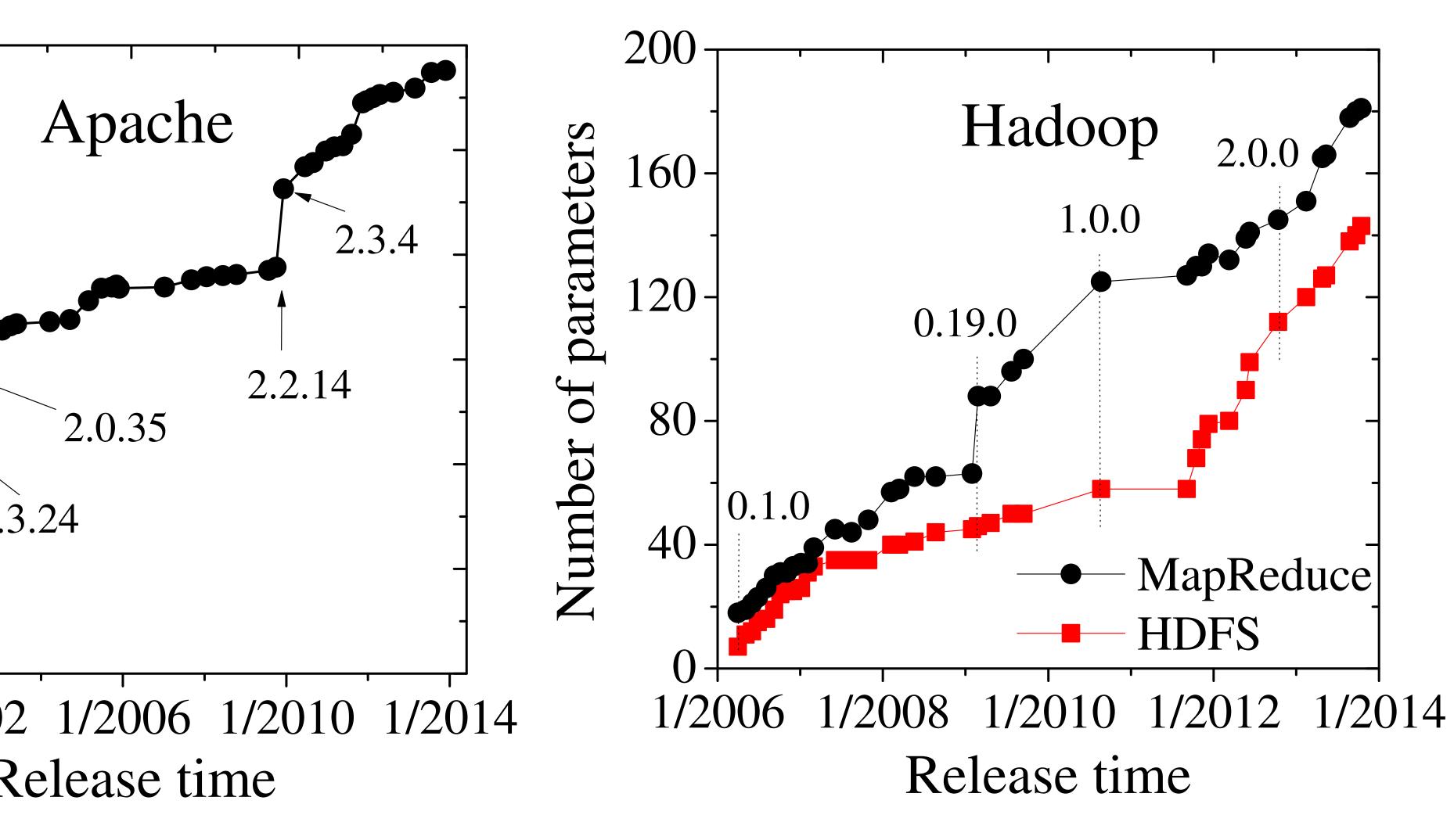


```
102
103
      drpc.port: 3772
104
     drpc.worker.threads: 64
    drpc.max buffer size: 1048576
105
     drpc.queue.size: 128
106
     drpc.invocations.port: 3773
107
     drpc.invocations.threads: 64
108
     drpc.request.timeout.secs: 600
109
     drpc.childopts: "-Xmx768m"
110
     drpc.http.port: 3774
111
     drpc.https.port: -1
112
     drpc.https.keystore.password:
113
     drpc.https.keystore.type: "JKS"
114
115
     drpc.authorizer.acl.filename: "drpc-auth-acl.yaml"
116
      drpc.authorizer.acl.strict: false
117
118
      transactional.zookeeper.root: "/transactional"
119
      transactional.zookeeper.servers: null
120
      transactional.zookeeper.port: null
121
122
123
     ## blobstore configs
     supervisor.blobstore.class: "org.apache.storm.blobstore.NimbusBlobStore"
124
125 supervisor.blobstore.download.thread.count: 5
     supervisor.blobstore.download.max_retries: 3
126
     supervisor.localizer.cache.target.size.mb: 10240
127
     supervisor.localizer.cleanup.interval.ms: 600000
128
129
```

drpc.http.creds.plugin: org.apache.storm.security.auth.DefaultHttpCredentialsPlugi



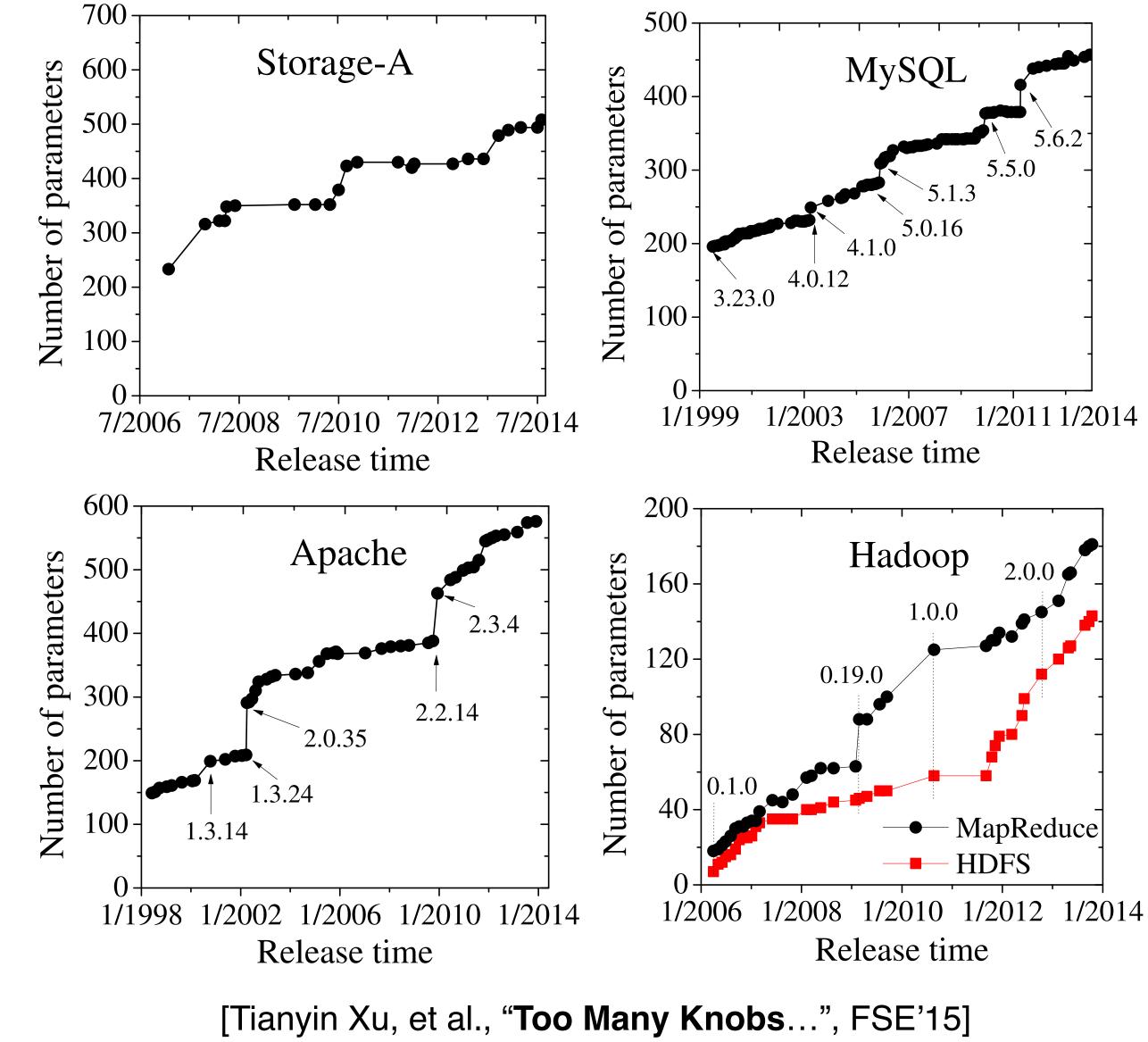
Empirical observations confirm that systems are 8 7/2010 7/2012 7/2014 1/1999 1/2003 1/2007 1/2011 1/2014 Release time Release time



[Tianyin Xu, et al., "Too Many Knobs...", FSE'15]



Empirical observations confirm that systems are becoming increasingly configurable

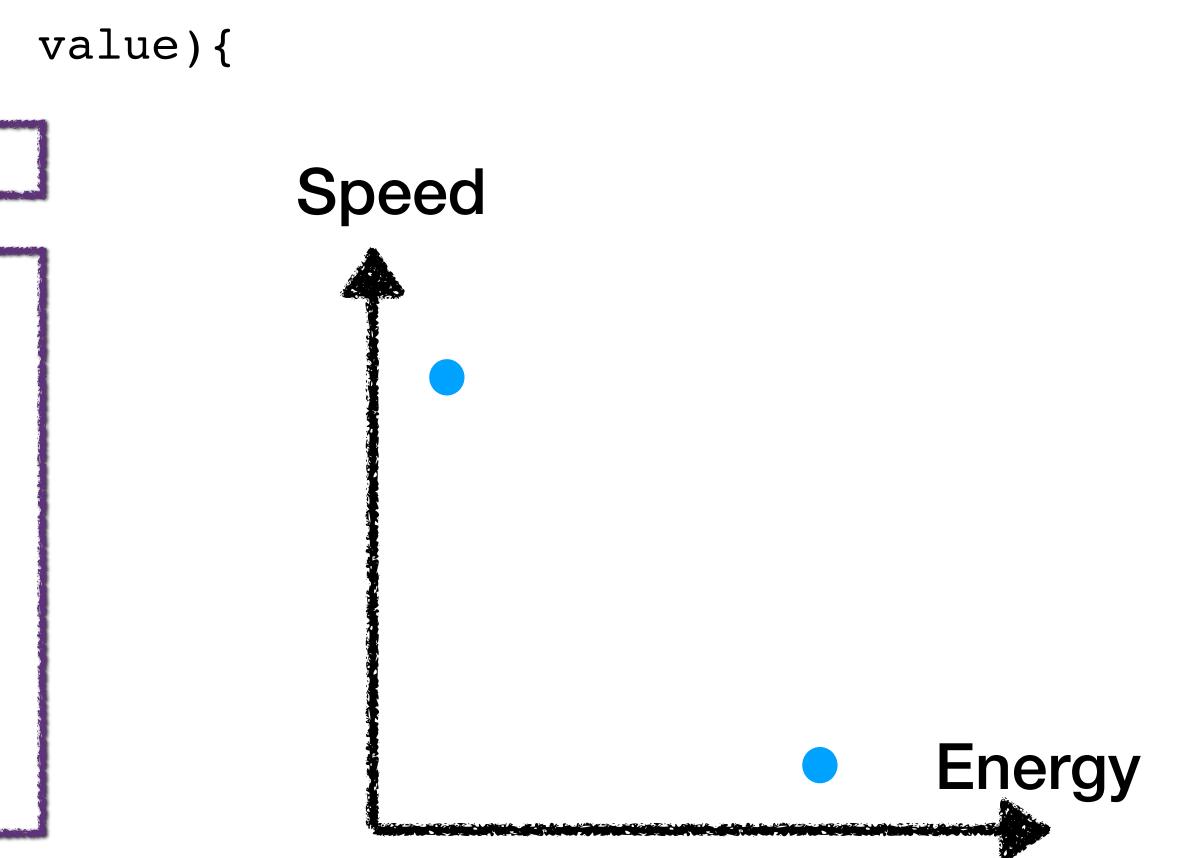




Configurations determine the performance behavior

```
void Parrot setenv(. . . name, . . . value){
#ifdef PARROT HAS SETENV
 my_setenv(name, value, 1);
#else
  int name len=strlen(name);
  int val_len=strlen(value);
  char* envs=glob env;
  if(envs==NULL){
    return;
  strcpy(envs,name);
  strcpy(envs+name_len,"=");
  strcpy(envs+name_len + 1,value);
  putenv(envs);
```

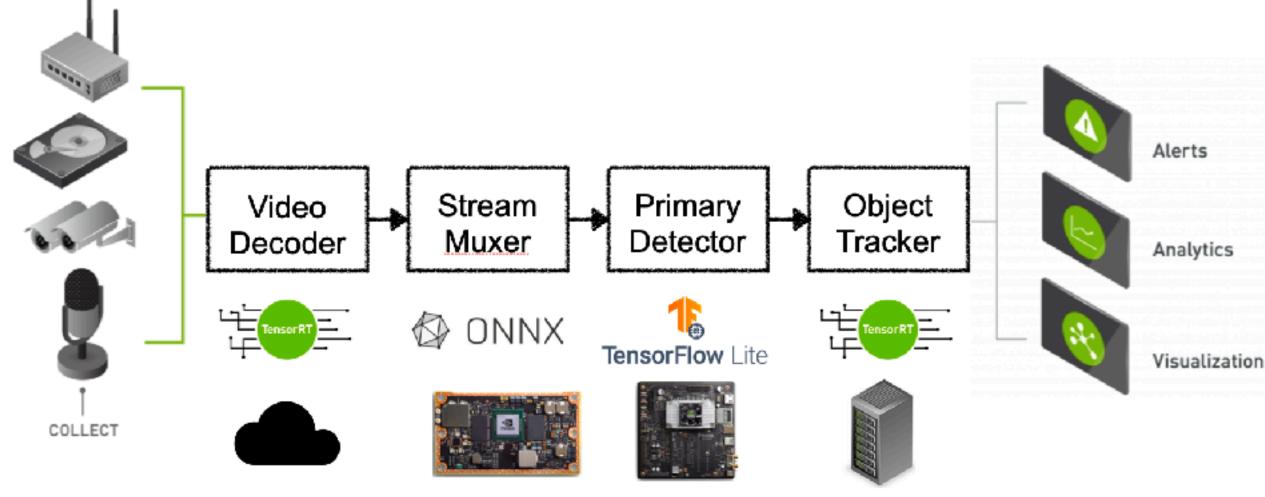
#endif



Challenges of configurations

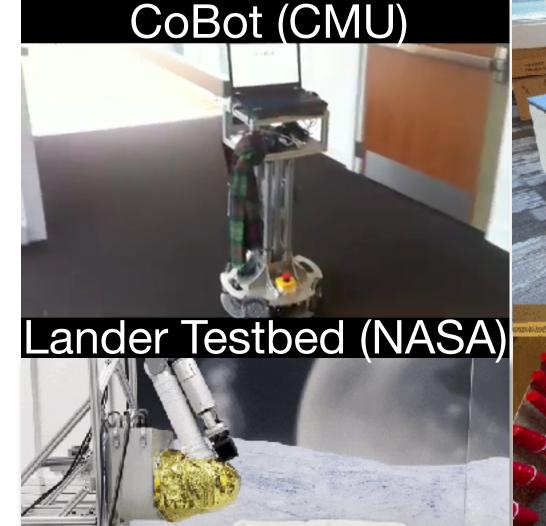
- Difficulties in knowing which parameters should be set
- Setting the parameters to obtain the intended behavior
- Reasoning about multiple objectives (energy, speed)

The variability space (design space) of (composed) systems is exponentially increasing

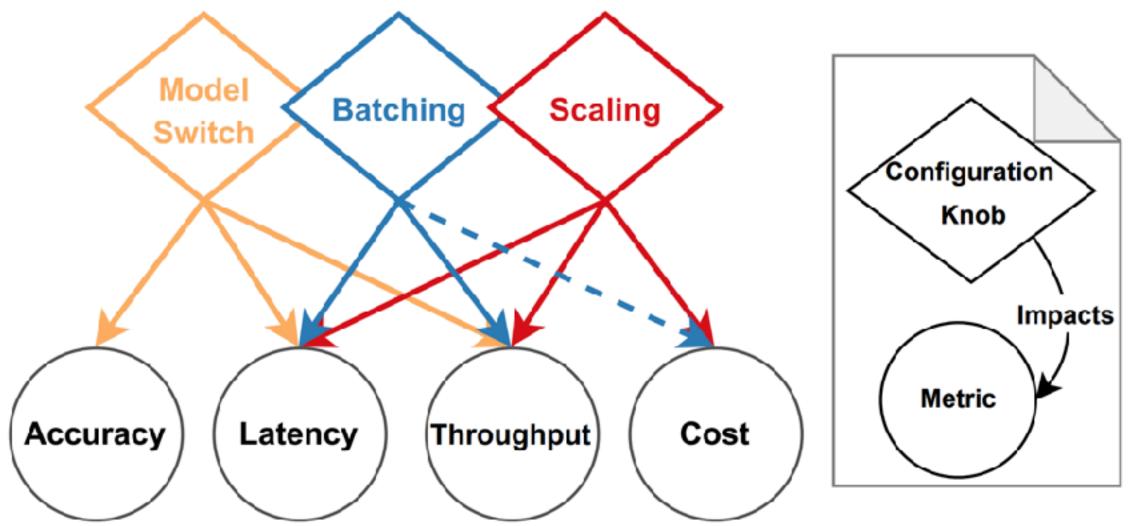


Systems operate in uncertain environments with imperfect and incomplete knowledge Husky UGV (UofSC)

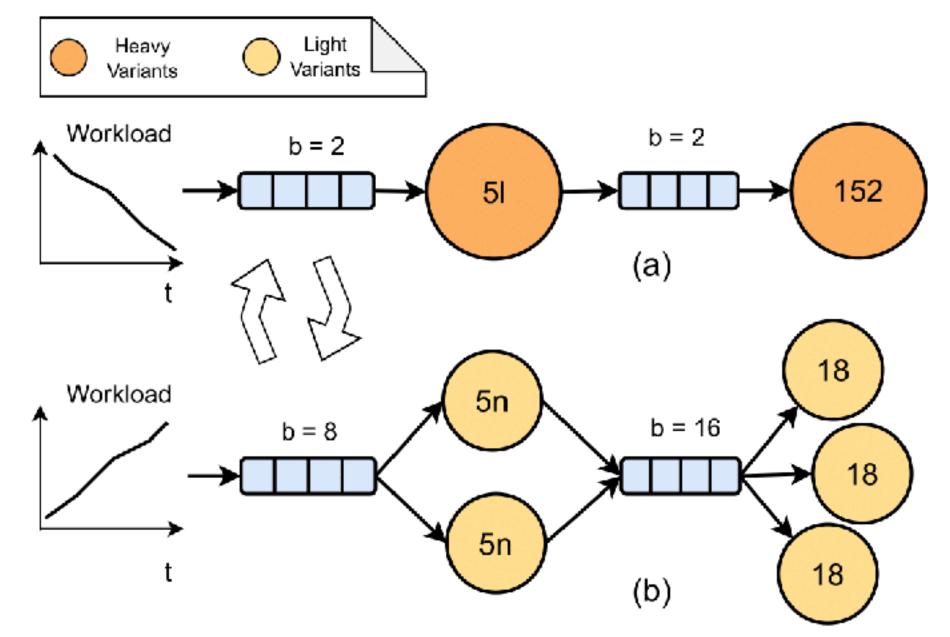
Turtlebot 3 (UofSC)



Performance goals are competing and users have preferences over these goals



Goal: Enabling users to find the right quality tradeoff





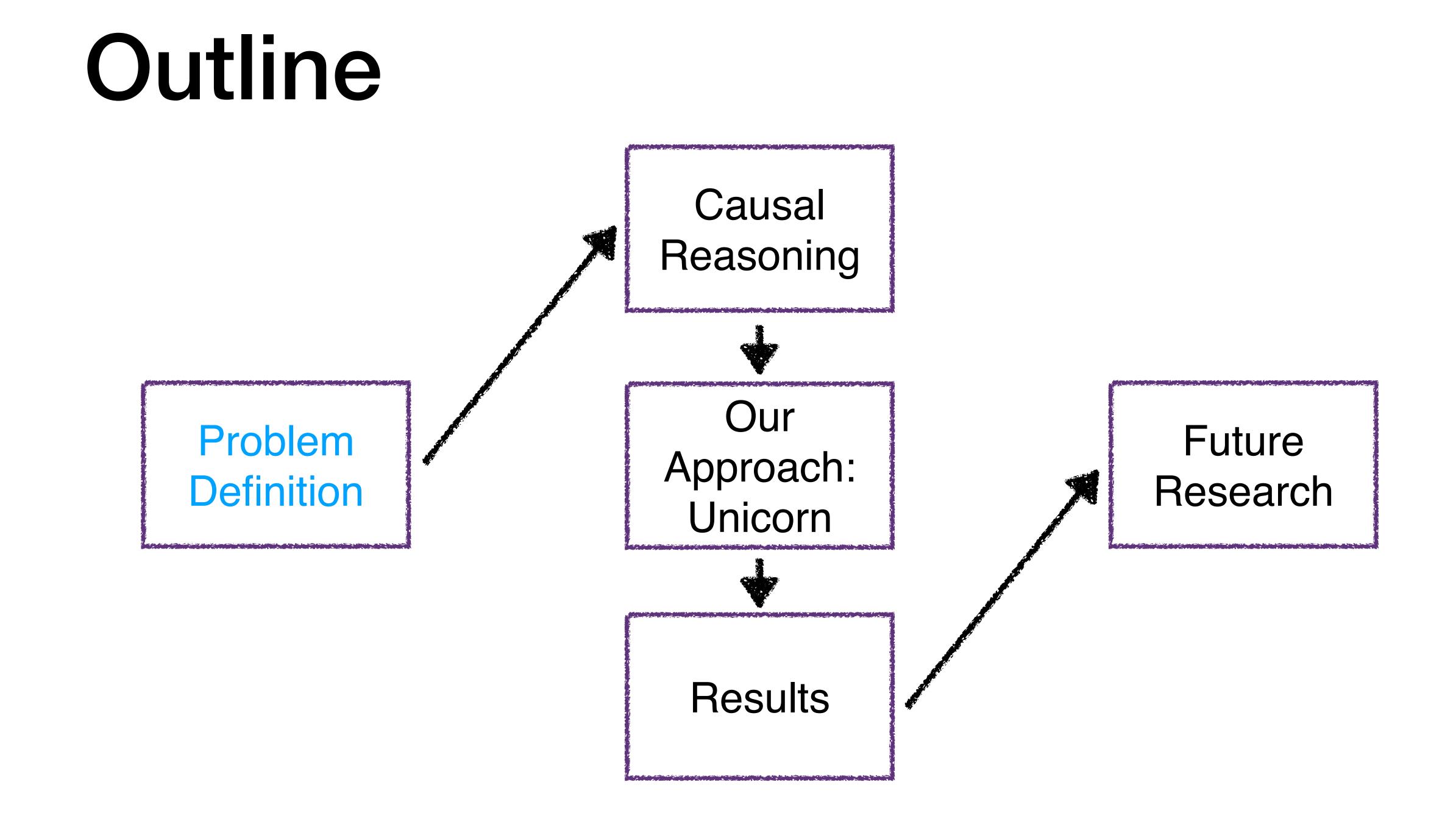


The goal of our research is...

Understanding the performance behavior of real-world highly-configurable systems that scale well...

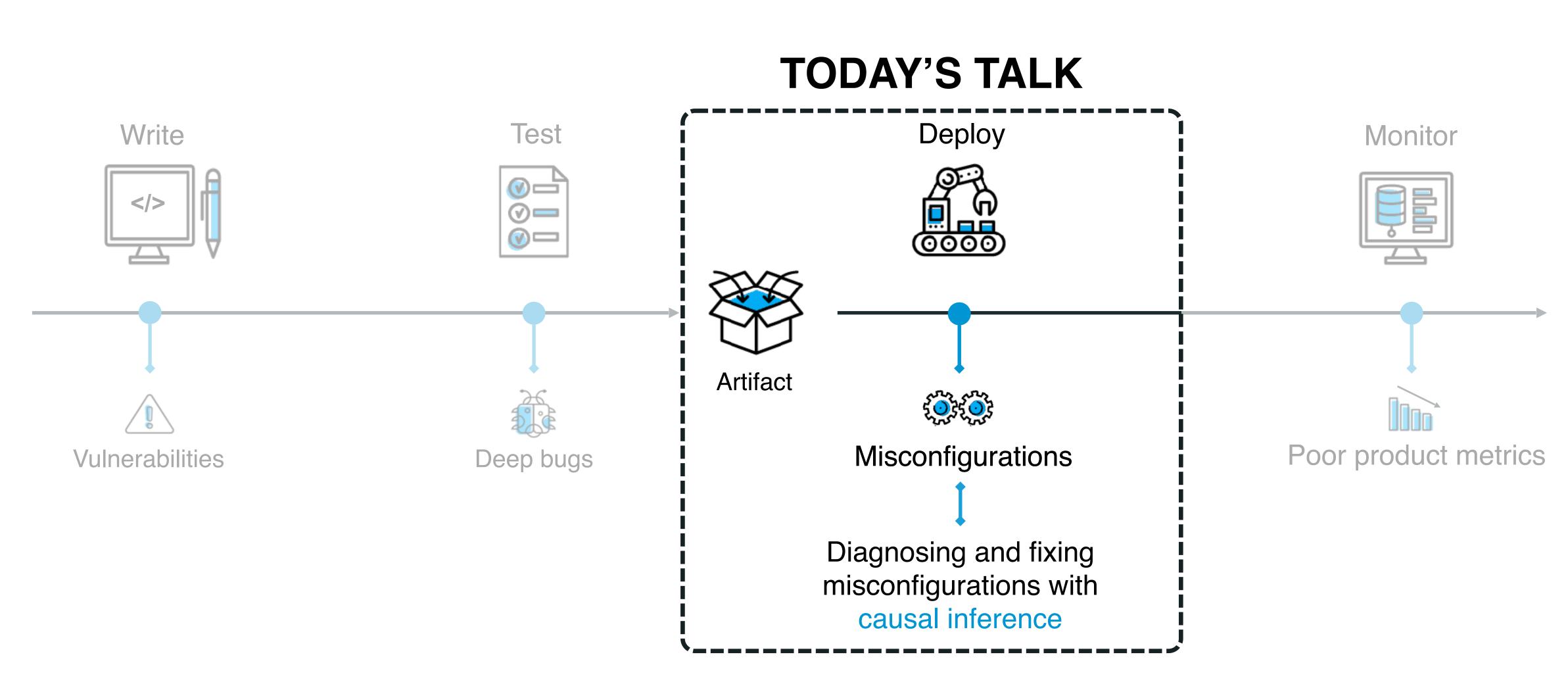
... and enabling developers/users to reason about qualities (performance, energy) and to make tradeoffs?







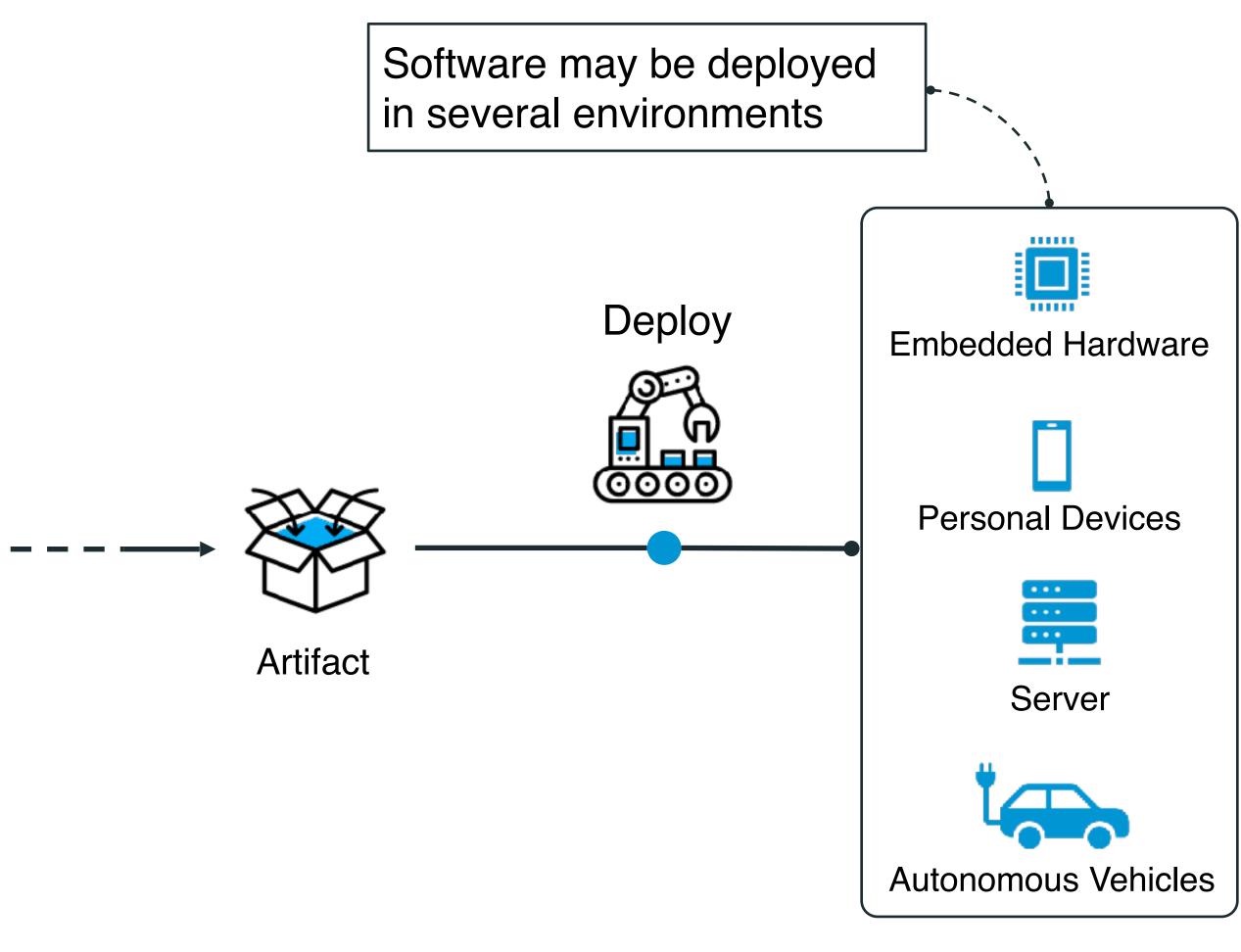
A Typical Software Lifecycle







Today's Talk



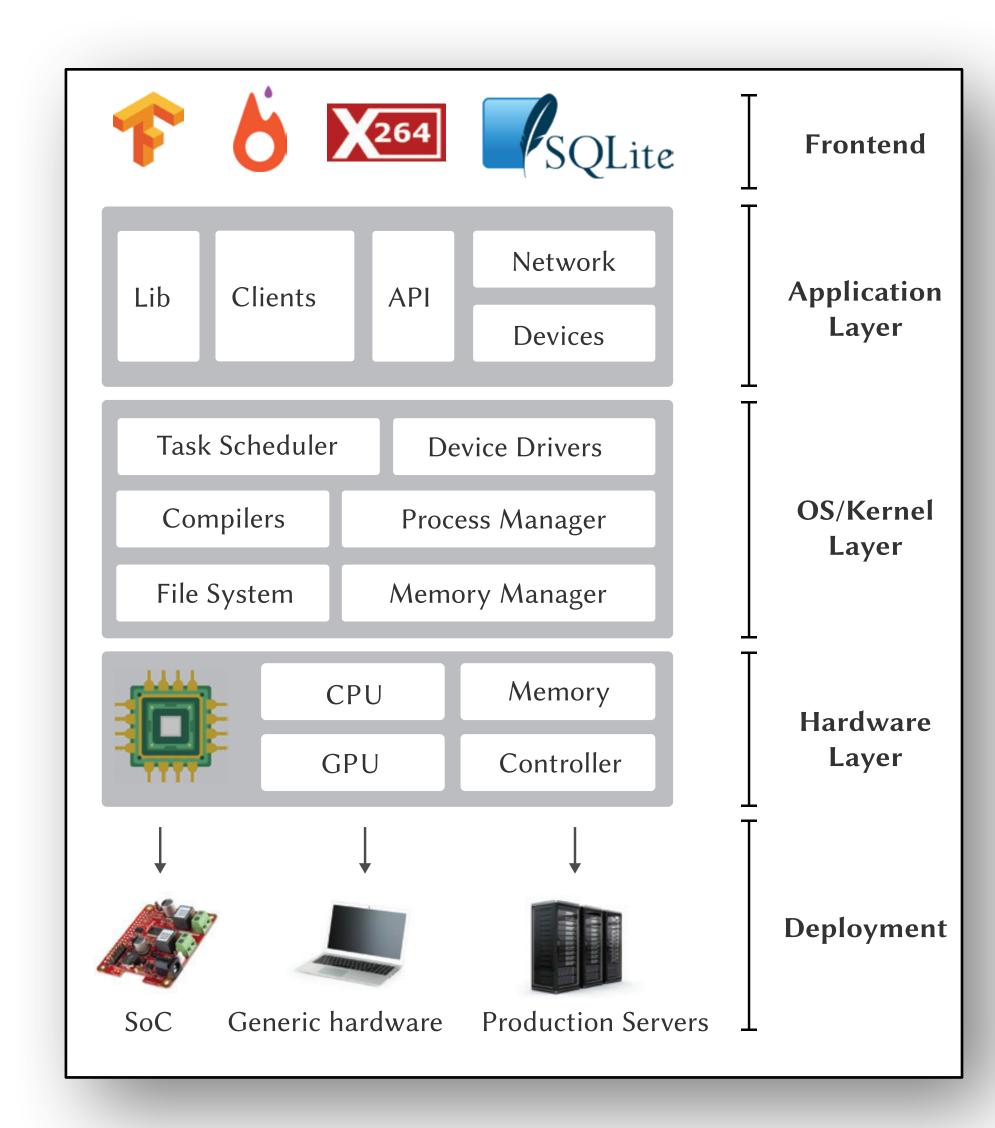
Deployment Environments

Challenge

- Each deployment environment \triangleright must be configured correctly
- This is challenging and prone to \triangleright misconfigurations



Today's Talk



Problem

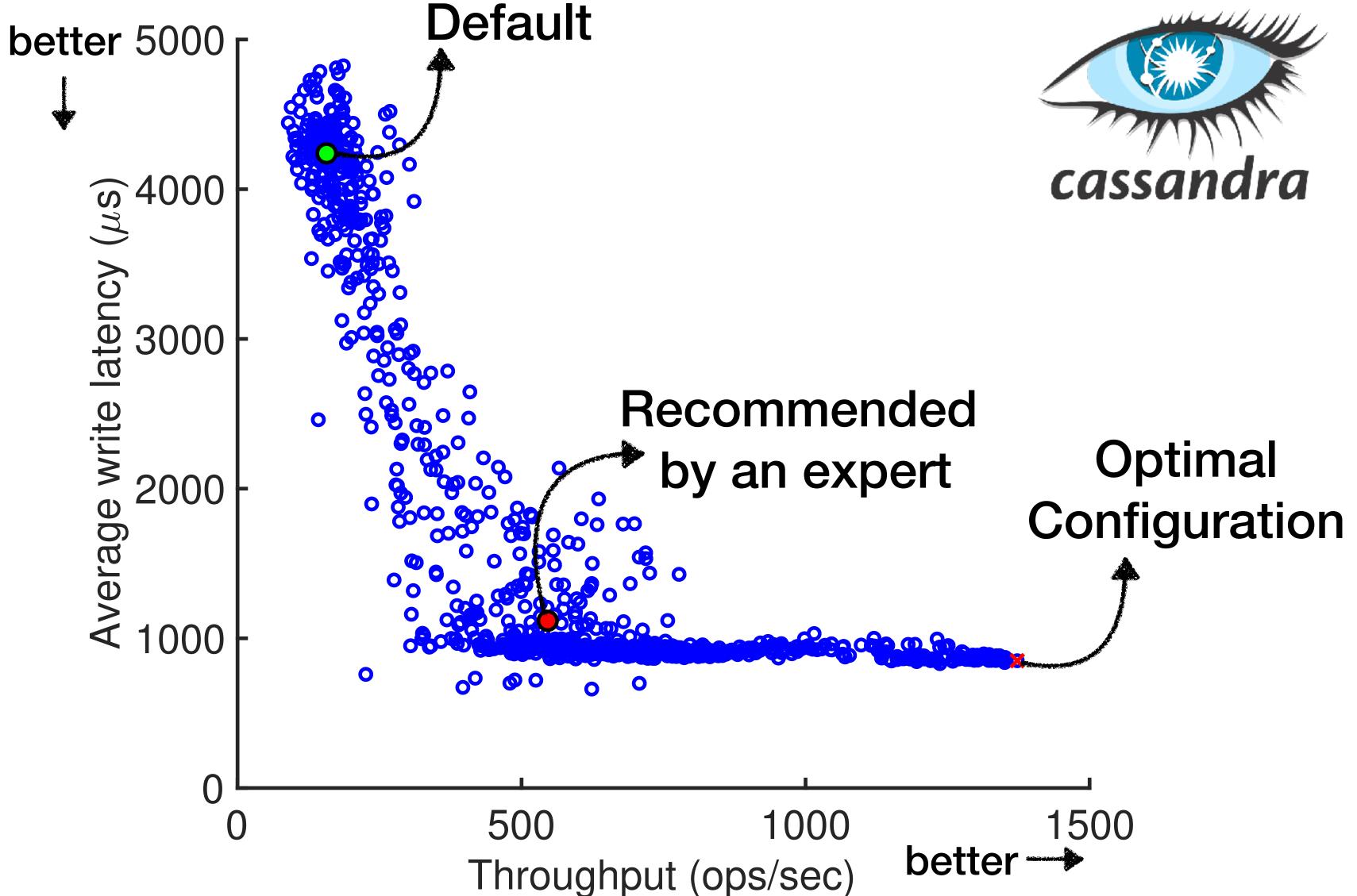
- Each deployment environment must be configured correctly
- This is challenging and prone to misconfigurations

Why?

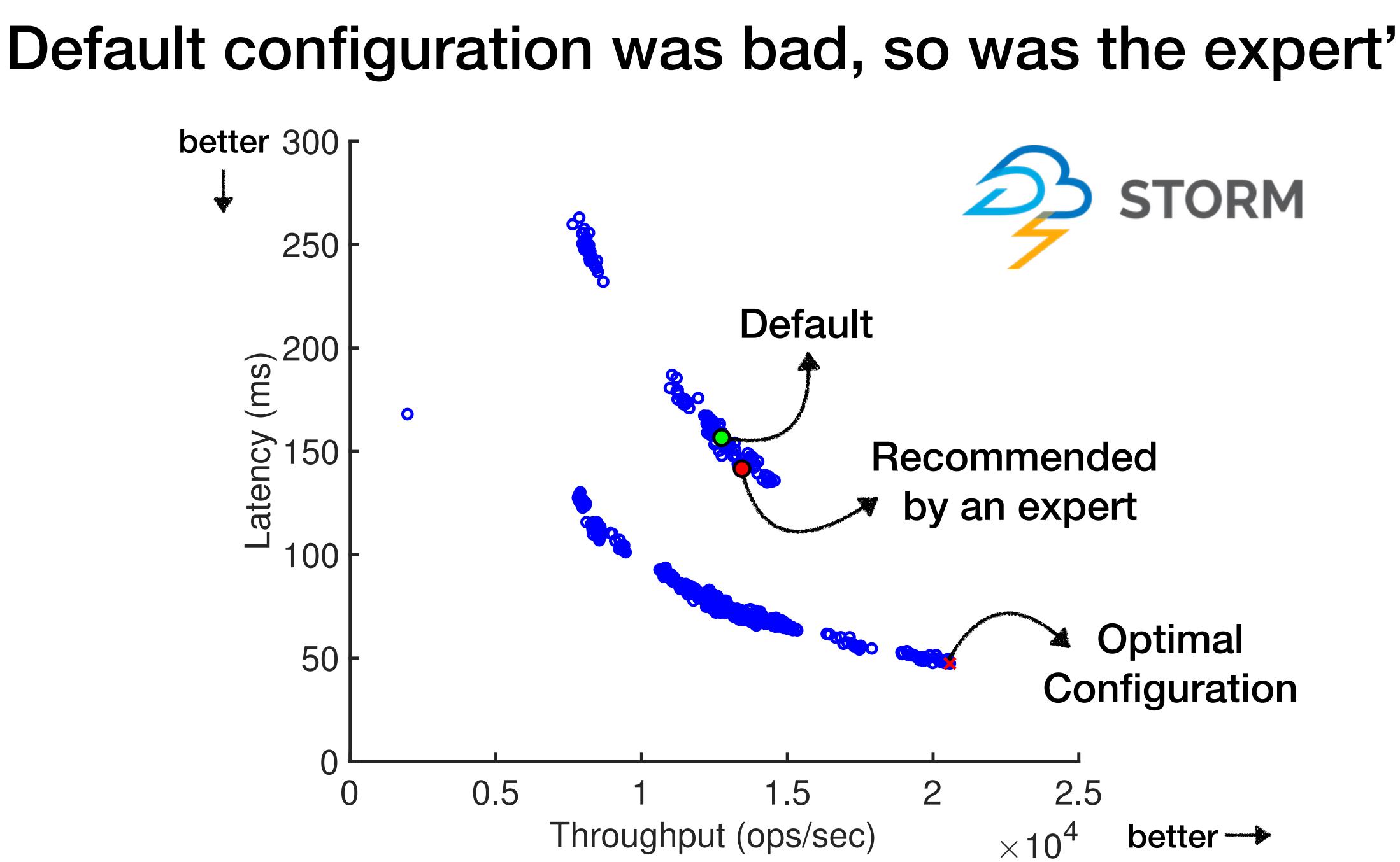
- The configuration options lie across the software stack
- There are several non-trivial interactions with one another
- The configuration space is combinatorially large with 100's of configuration options



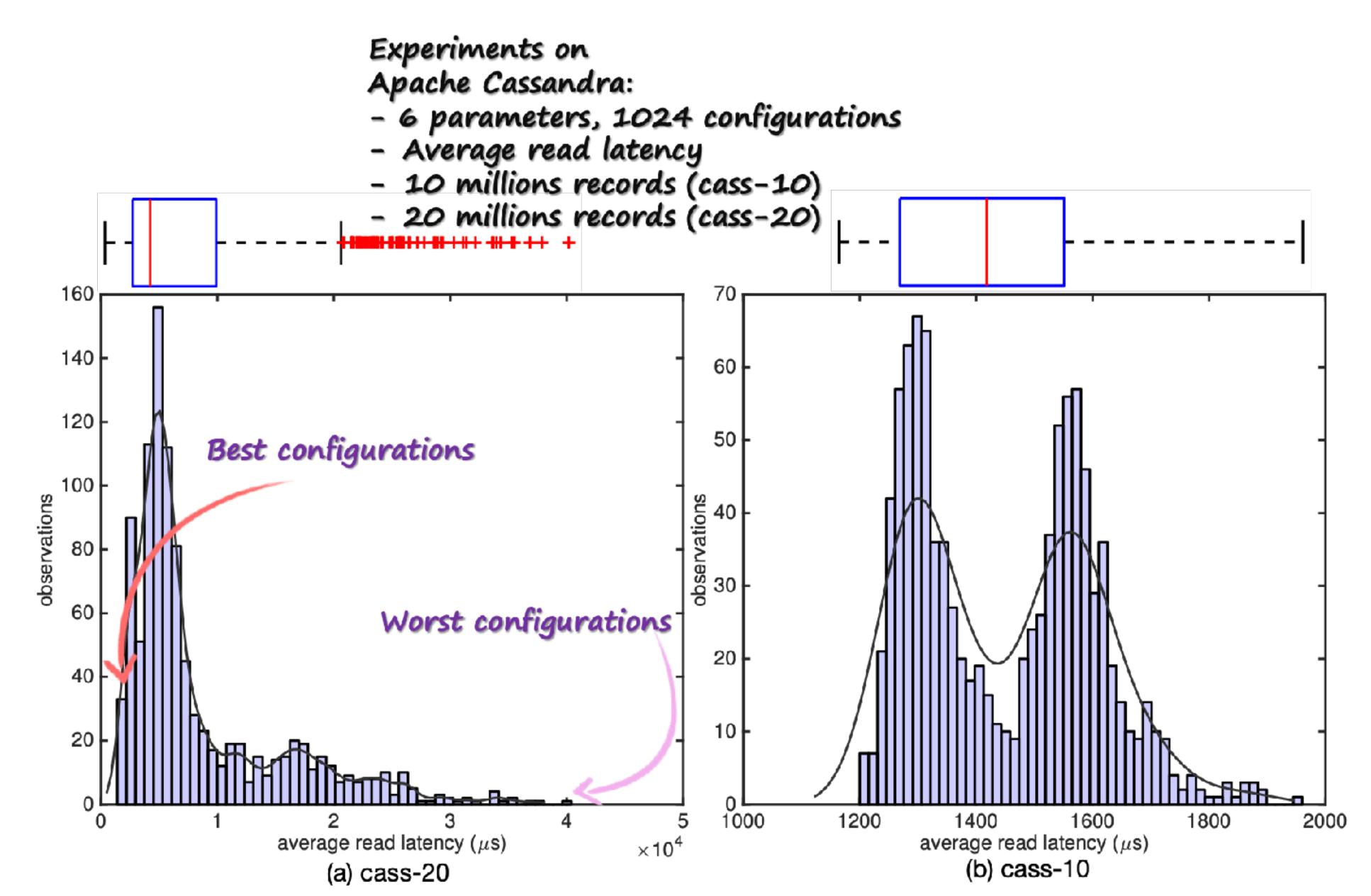
Default configuration was bad, so was the expert'







Performance behavior varies in different environments





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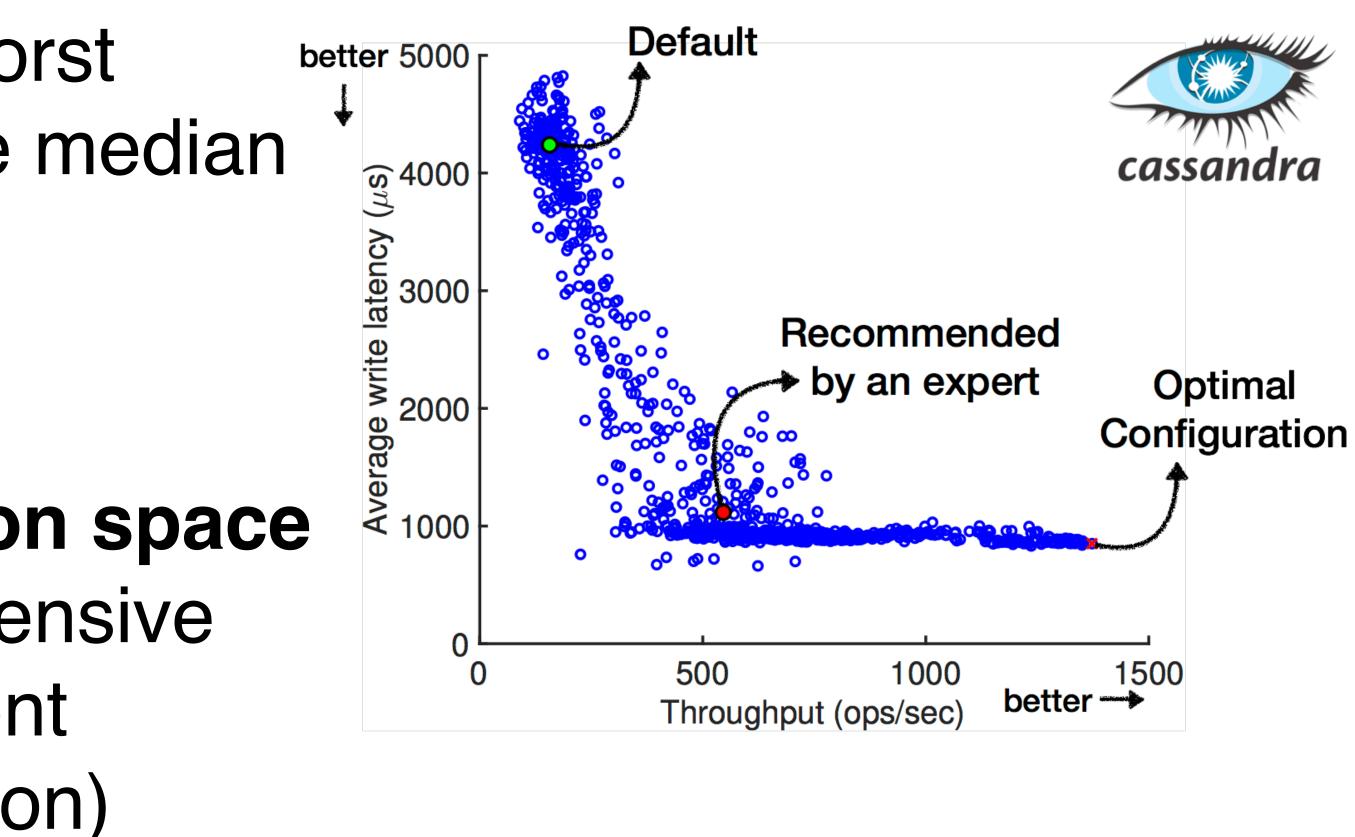
Why this is an important problem?

Optimal configuration

- 2X-10X faster than the worst
- Noticeably faster than the median
- Default is bad
- Expert's is not optimal

Exploring large configuration space

- Exhaustive search is expensive
- Specific to the environment (hardware/workload/version)



Misconfiguration and its Effects

- hardware
- These can result in non-functional faults
 - Affecting non-functional system properties like Ο latency, throughput, energy consumption, etc.

The system doesn't crash or exhibit an obvious misbehavior

Misconfigurations can elicit unexpected interactions between software and



Systems are still operational but with a degraded performance, e.g., high latency, low throughput, high energy consumption, high heat dissipation, or a combination of several



Motivating Example



CUDA performance issue on tx2

Home > Autonomous Machines > Jetson & Embedded Systems > Jetson TX2



william_wu

When we are trying to transplant our CUDA source code from TX1 to TX2, it behaved strange. The target hardware is faster than the the source hardware. We noticed that TX2 has twice computing-ability as TX1 in GPU, as expectation, we think TX2 will 30% - 40% faster than TX1 at least. User expects the code to run at least 30-40% faster. Unfortunately, most of our code base spent twice the time as TX1, in other words,

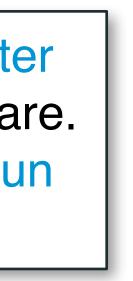
TX2 only has 1/2 speed as TX1, mostly. We believe that TX2's CUDA API runs much slower than TX1 in many cases.



The user is transferring the code from one hardware to another

The code ran 2x slower on the more powerful hardware

Jun '17





Motivating Example



william_wu Any suggestions on how to improve my performance? Thanks!

June 4th

June 4th



AastaLLL 🗘 Moderator

TX2 is pascal architecture. Please update your CMakeLists:

- + set(CUDA_STATIC_RUNTIME OFF)
- + -gencode=arch=compute_62,code=sm_62

william_wu

We have already tried this. We still have high latency.

Any other suggestions?

C June 5th NVIDIA AastaLLL () Moderator

Please do the following and let us know if it works

- 1. Install JetPack 3.0
- 2. Set nvpmodel=MAX-N
- 3. Run jetson_clock.sh

The user had several misconfigurations

In Software:

- Wrong compilation flags ×
- Wrong SDK version *

In Hardware:

- Wrong power mode ×
- Wrong clock/fan settings *

The discussions took 2 days



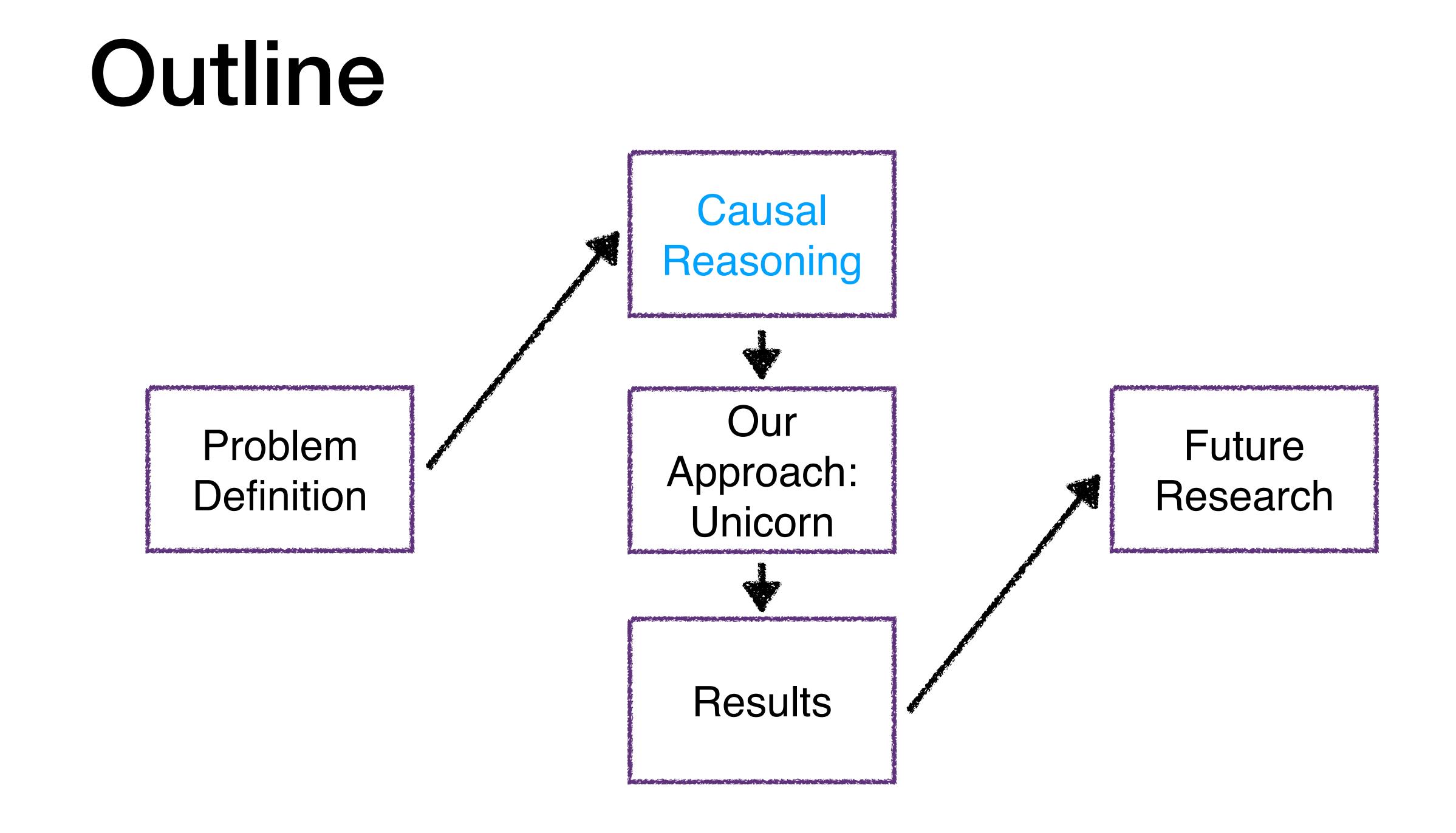
How to resolve such issues faster?



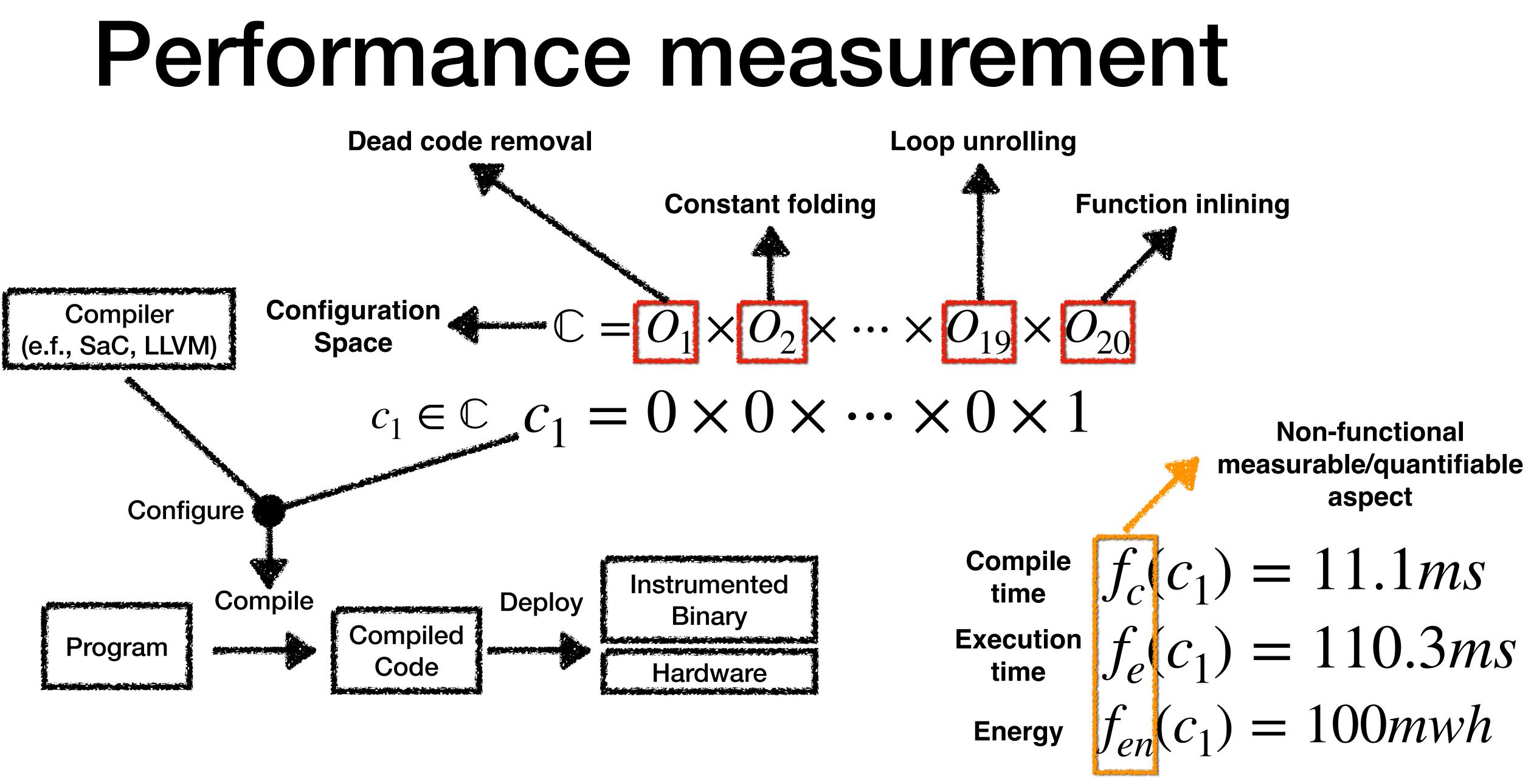




How to resolve these issues faster?





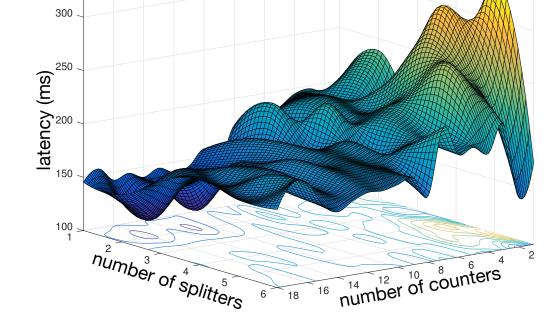




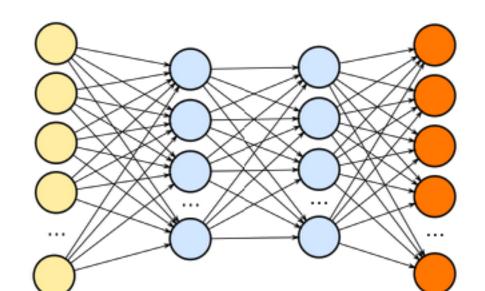
Blackbox Performance Modeling

	Bitrate (bits/s)	EnableP adding	 Cache Misses	 Throughput (fps)
C ₁	1k	1	 42m	 7
C ₂	2k	1	 32m	 22
Cn	5k	0	 12m	 25

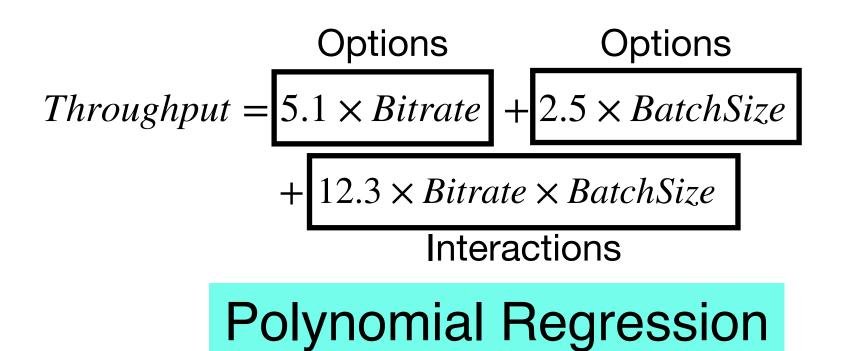
Observational Data



Gaussian Process



Neural Network





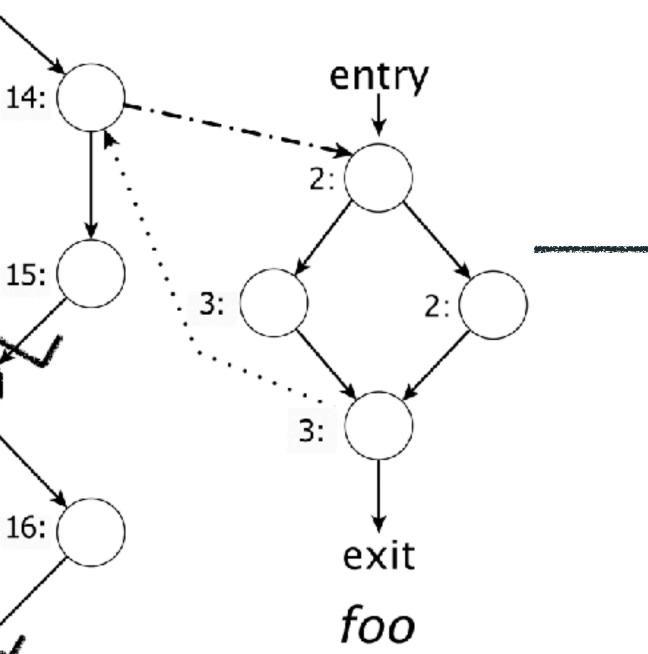
These methods rely on statistical correlations to extract meaningful information required for performance tasks.



Whitebox Performance Modeling

def foo(boolean x) // Begin region R ₁ if(x) // execution: 4s $\Pi_{R_1} = 1A + 3AC$ else // execution 1s // End region R ₁ def main(List workload) a = get0pt("A"); b = get0pt("B"); c = get0pt("C"); d = get0pt("D"); e = get0pt("C"); f = get0pt("F"); g = get0pt("G"); h = get0pt("H"); i = get0pt("I"); j = get0pt("J"); // execution: 1s boolean x = false; // Begin region R ₂ if(a) // variable depends on option A // execution: 2s foo(c); // variable depends on option B x = true; $\Pi_{R_2} = 2A$ // End region R ₃ if(b & x) // execution: 3s $\Pi_{R_3} = 3AB$ // End region R ₃		entry
<pre>// Begin region R₁ if (x) // execution: 4s $\Pi_{R_1} = 1A + 3AC$ else // execution 1s // End region R₁ def main(List workload) a = getOpt("A"); b = getOpt("B"); c = getOpt("C"); d = getOpt("D"); e = getOpt("C"); f = getOpt("F"); g = getOpt("G"); h = getOpt("H"); i = getOpt("I"); j = getOpt("J"); // execution: 1s boolean x = false; // Begin region R₂ if (a) // variable depends on option A // execution: 2s foo(c); // variable depends on option B x = true; $\Pi_{R_2} = 2A$ // End region R₂ if (b kk x) // execution: 3s $\Pi_{R_3} = 3AB$ // End region R₃ if (b kk x) // execution: 3s $\Pi_{R_3} = 3AB$</pre>		11: $\left\{ A, C \right\}$
if (x) // execution: 4s $\Pi_{R_1} = 1A + 3AC$ else // execution 1s // End region R ₁ def main(List workload) a = getOpt("A"); b = getOpt("B"); c = getOpt("C"); d = getOpt("D"); e = getOpt("E"); f = getOpt("F"); g = getOpt("G"); h = getOpt("H"); i = getOpt("I"); j = getOpt("J"); // execution: 1s boolean x = false; // Begin region R ₂ if(a) // variable depends on option A // execution: 2s foo(c); // variable depends on option B x = true; $\Pi_{R_2} = 2A$ // End region R ₃ if(b && x) // execution: 3s $\Pi_{R_3} = 3AB$ // End region R ₃ if(b && x) // execution: 3s $\Pi_{R_3} = 3AB$		
else // execution 1s // End region R_1 def main(List workload) a = get0pt("A"); b = get0pt("B"); c = get0pt("C"); d = get0pt("D"); e = get0pt("E"); f = get0pt("F"); g = get0pt("G"); h = get0pt("H"); i = get0pt("I"); j = get0pt("J"); // execution: 1s boolean x = false; // Begin region R_2 if(a) // variable depends on option A // execution: 2s foo(c); // variable depends on option B x = true; $\Pi_{R_2} = 2A$ // End region R_3 if(b && x) // execution: 3s $\Pi_{R_3} = 3AB$ // End region R_3 if(b && x) // execution: 3s $\Pi_{R_3} = 3AB$		
<pre>// End region R₁ def main(List workload) a = getOpt("A"); b = getOpt("B"); c = getOpt("C"); d = getOpt("D"); e = getOpt("C"); f = getOpt("F"); g = getOpt("G"); h = getOpt("H"); i = getOpt("I"); j = getOpt("J"); // execution: 1s boolean x = false; // Begin region R₂ if(a) // variable depends on option A // execution: 2s foo(c); // variable depends on option B x = true; $\Pi_{R_2} = 2A$ // End region R₃ if(b && x) // execution: 3s $\Pi_{R_3} = 3AB$ // End region R₃ exit</pre>		^o 12:
a = getOpt("A"); b = getOpt("B"); c = getOpt("C"); d = getOpt("D"); e = getOpt("E"); f = getOpt("F"); g = getOpt("G"); h = getOpt("H"); i = getOpt("I"); j = getOpt("J"); // execution: 1s boolean x = false; // Begin region R_2 if(a) // variable depends on option A // execution: 2s foo(c); // variable depends on option B x = true; $\Pi_{R_2} = 2A$ // End region R_2 if(b && x) // execution: 3s $\Pi_{R_3} = 3AB$ // End region R_3 if(b && x) // execution: 3s $\Pi_{R_3} = 3AB$		
c = getOpt("C"); d = getOpt("D"); e = getOpt("E"); f = getOpt("F"); g = getOpt("G"); h = getOpt("H"); i = getOpt("I"); j = getOpt("J"); // execution: 1s boolean x = false; // Begin region R ₂ if(a) // variable depends on option A // execution: 2s foo(c); // variable depends on option B x = true; $\Pi_{R_2} = 2A$ // End region R ₃ if(b && x) // execution: 3s $\Pi_{R_3} = 3AB$ // End region R ₃ if(b && x) // execution: 3s $\Pi_{R_3} = 3AB$		
e = getOpt("E"); f = getOpt("F"); g = getOpt("G"); h = getOpt("H"); i = getOpt("I"); j = getOpt("J"); // execution: 1s boolean x = false; // Begin region R ₂ if(a) // variable depends on option A // execution: 2s foo(c); // variable depends on option B x = true; $\Pi_{R_2} = 2A$ // End region R ₃ if(b && x) // execution: 3s $\Pi_{R_3} = 3AB$ // End region R ₃ if(b && x) // execution: 3s $\Pi_{R_3} = 3AB$	•••••••	1
g = getOpt("G"); h = getOpt("H"); i = getOpt("I"); j = getOpt("J"); $\dots // execution: 1s$ boolean x = false; // Begin region R ₂ if(a) // variable depends on option A $\dots // execution: 2s$ foo(c); // variable depends on option B x = true; $\Pi_{R_2} = 2A$ // End region R ₂ // Begin region R ₃ if(b && x) // execution: 3s $\Pi_{R_3} = 3AB$ // End region R ₃ if(b && x) // execution: 3s $\Pi_{R_3} = 3AB$		
<pre>i = getOpt("I"); j = getOpt("J"); // execution: 1s boolean x = false; // Begin region R₂ if(a) // variable depends on option A // execution: 2s foo(c); // variable depends on option B x = true;</pre>		
// execution: 1s boolean $x = false;$ // Begin region R_2 if (a) // variable depends on option A // execution: 2s foo(c); // variable depends on option B $x = true;$ $\Pi_{R_2} = 2A$ // End region R_2 // Begin region R_3 if (b && x) // execution: 3s $\Pi_{R_3} = 3AB$ // End region R_3 if (b && x) // execution: 3s $\Pi_{R_3} = 3AB$		
<pre>// Begin region R2 if(a) // variable depends on option A // execution: 2s foo(c); // variable depends on option B x = true; $\Pi_{R_2} = 2A$ // End region R2 // Begin region R3 if(b && x) // execution: 3s $\Pi_{R_3} = 3AB$ // End region R3 if(b && x) // execution: 3s $\Pi_{R_3} = 3AB$</pre>		
if (a) // variable depends on option A // execution: 2s foo(c); // variable depends on option B $x = true;$ $\Pi_{R_2} = 2A$ // End region R ₂ // Begin region R ₃ if (b && x) // execution: 3s $\Pi_{R_3} = 3AB$ // End region R ₃ if we wit	boolean x = false;	
// execution: 2s foo(c); // variable depends on option B x = true; $\Pi_{R_2} = 2A$ // End region R ₂ // Begin region R ₃ if (b && x) // execution: 3s $\Pi_{R_3} = 3AB$ // End region R ₃ if (b model are the secution of the security of the	// Begin region R_2	\downarrow
for (c); // variable depends on option B $x = true$; $\Pi_{R_2} = 2A$ // End region R ₂ // Begin region R ₃ if (b && x) // execution: 3s $\Pi_{R_3} = 3AB$ // End region R ₃ exit		16: $\{ \Delta \mathbf{R} \}$
x = true; $\Pi_{R_2} = 2A$ // End region R ₂ // Begin region R ₃ if (b && x) // execution: 3s $\Pi_{R_3} = 3AB$ // End region R ₃ exit		
// End region R ₂ // Begin region R ₃ if (b && x) // execution: 3s Π_{R_3} = 3AB // End region R ₃ exit		
// Begin region R ₃ if (b && x) // execution: 3s Π_{R_3} = 3AB // End region R ₃ exit		1
if (b && x) // execution: 3s Π_{R_3} = 3AB // End region R ₃ exit		1
// End region R ₃ exit		۷
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main		CAIL
		main

Identify configuration-dependent regions

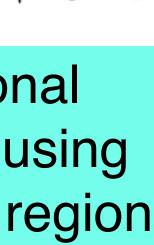


$\Pi = 1 + 3\mathbf{A} + 3\mathbf{AB} + 3\mathbf{AC}$

Build a compositional performance model using local models of each region

Instrumented control flow graph





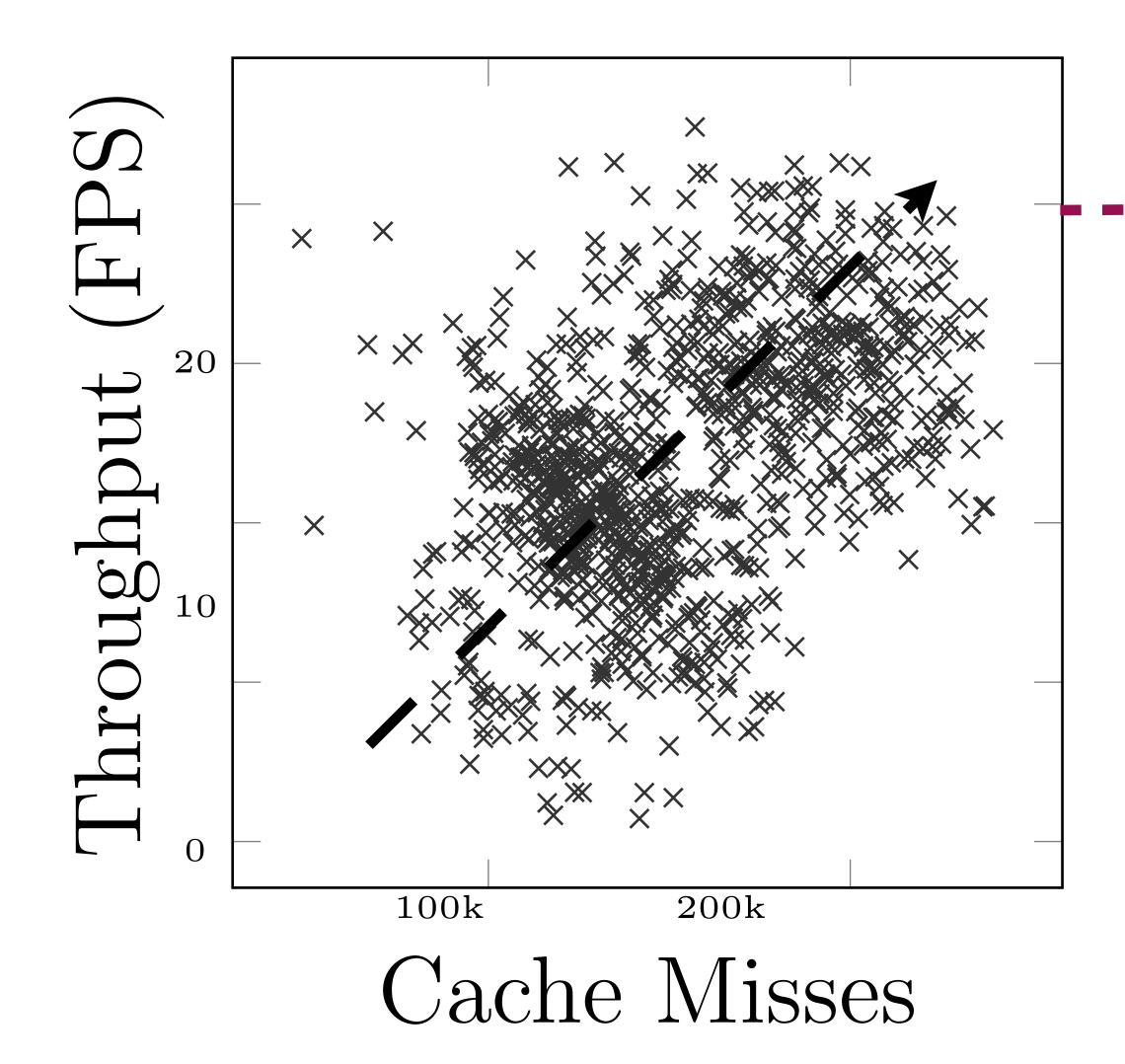
These methods rely on program analysis techniques (static and dynamic analysis of the code) to extract meaningful information required for performance tasks.



Performance models suffer from several shortcomings

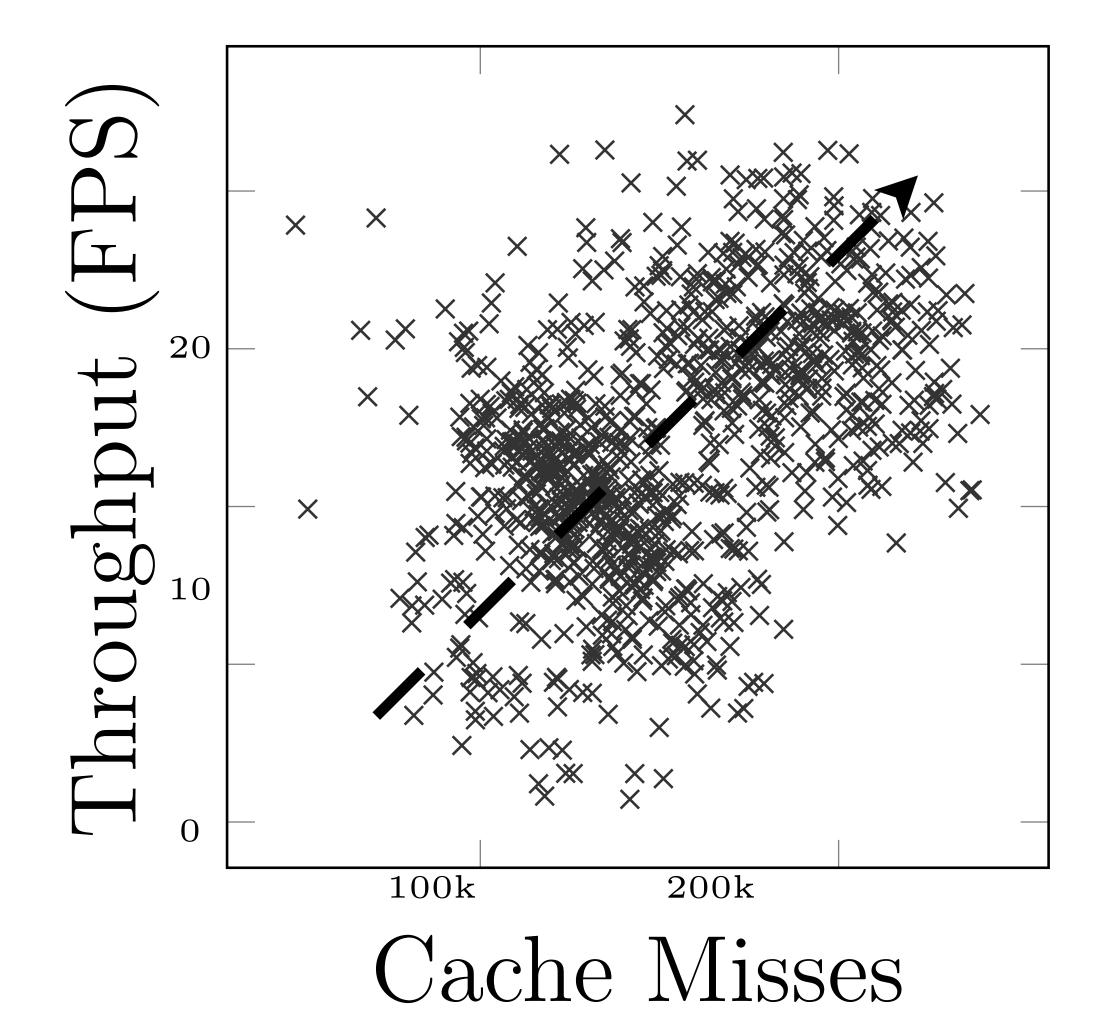
- Blackbox performance models could produce incorrect explanations and unreliable/unstable predictions across environments and in the presence of measurement noise.
- Whitebox performance models do not scale well to real-world systems (with many configuration options and large code bases.

Incorrect explanation

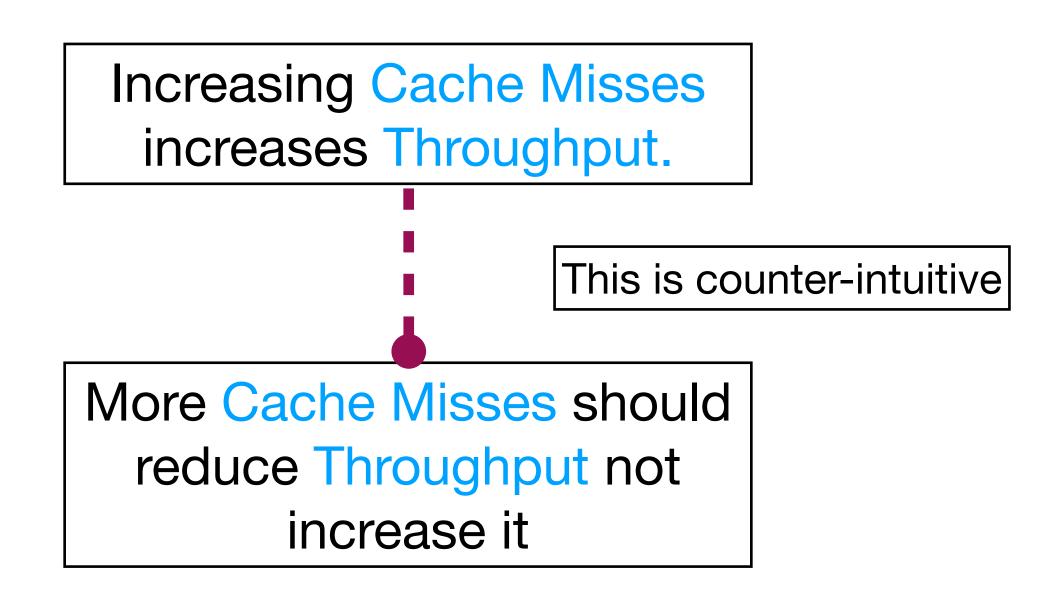


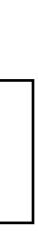


Incorrect explanation

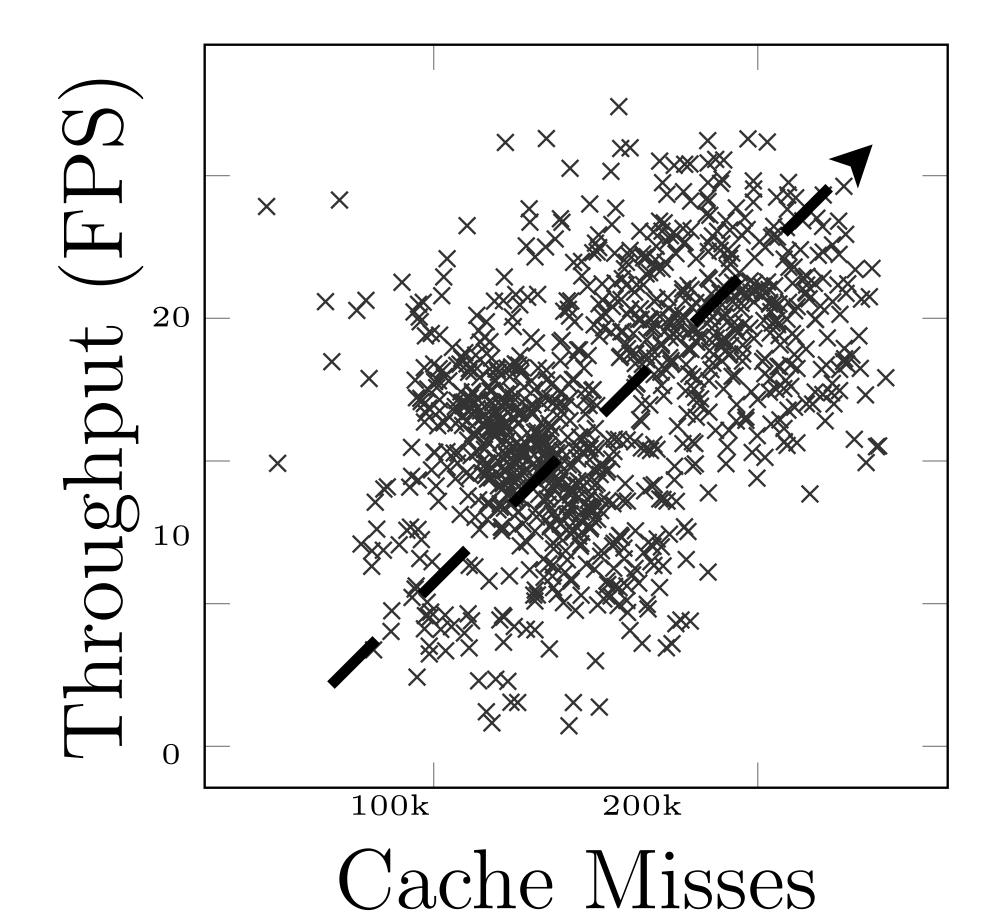




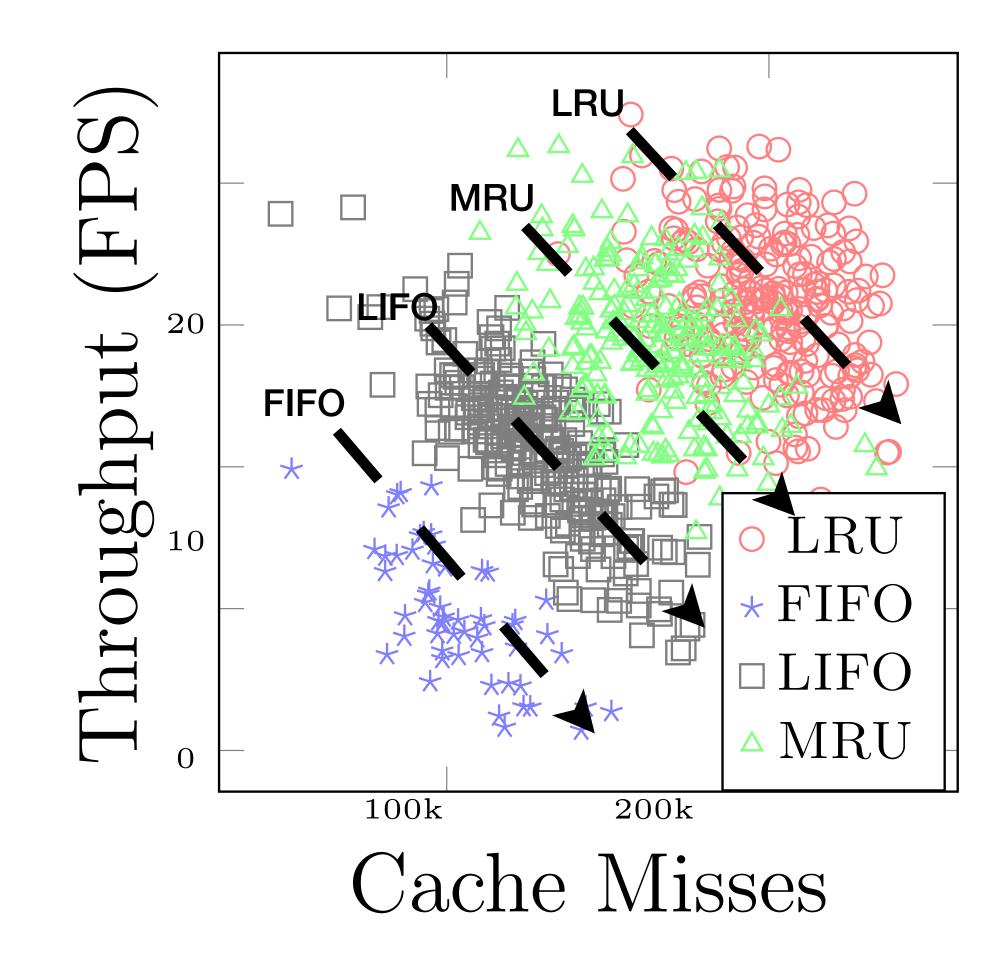




Incorrect explanation







Segregating data on Cache Policy indicates that within each group **Increase of Cache Misses result in a decrease in Throughput.**

Unstable predictions

Performance influence model in TX2:

Performance influence model in Xavier:

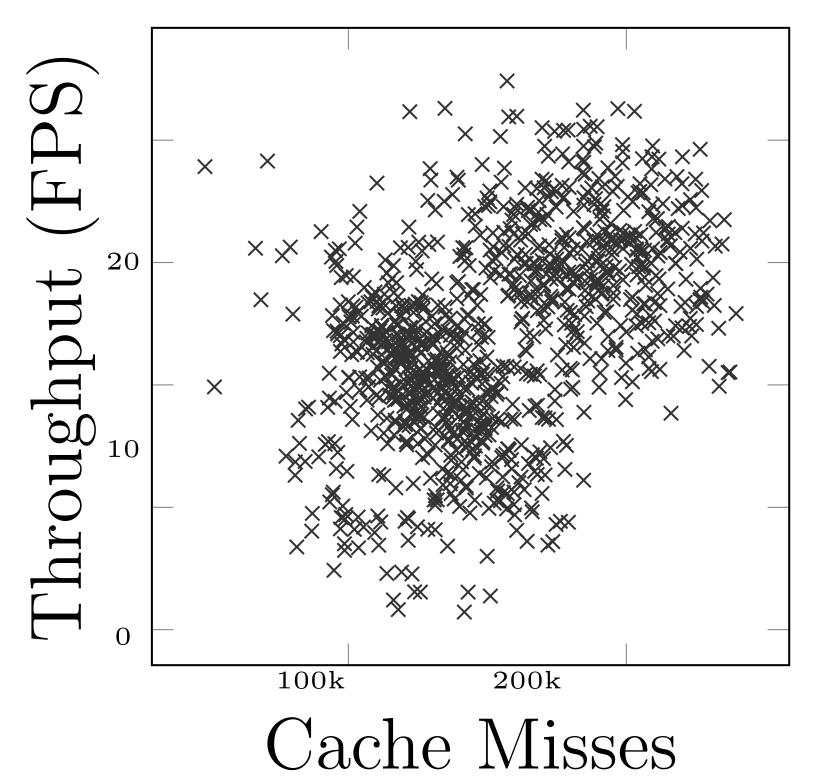
Throughput = $5.1 \times Bitrate + 2.5 \times BatchSize + 12.3 \times Bitrate \times BatchSize$

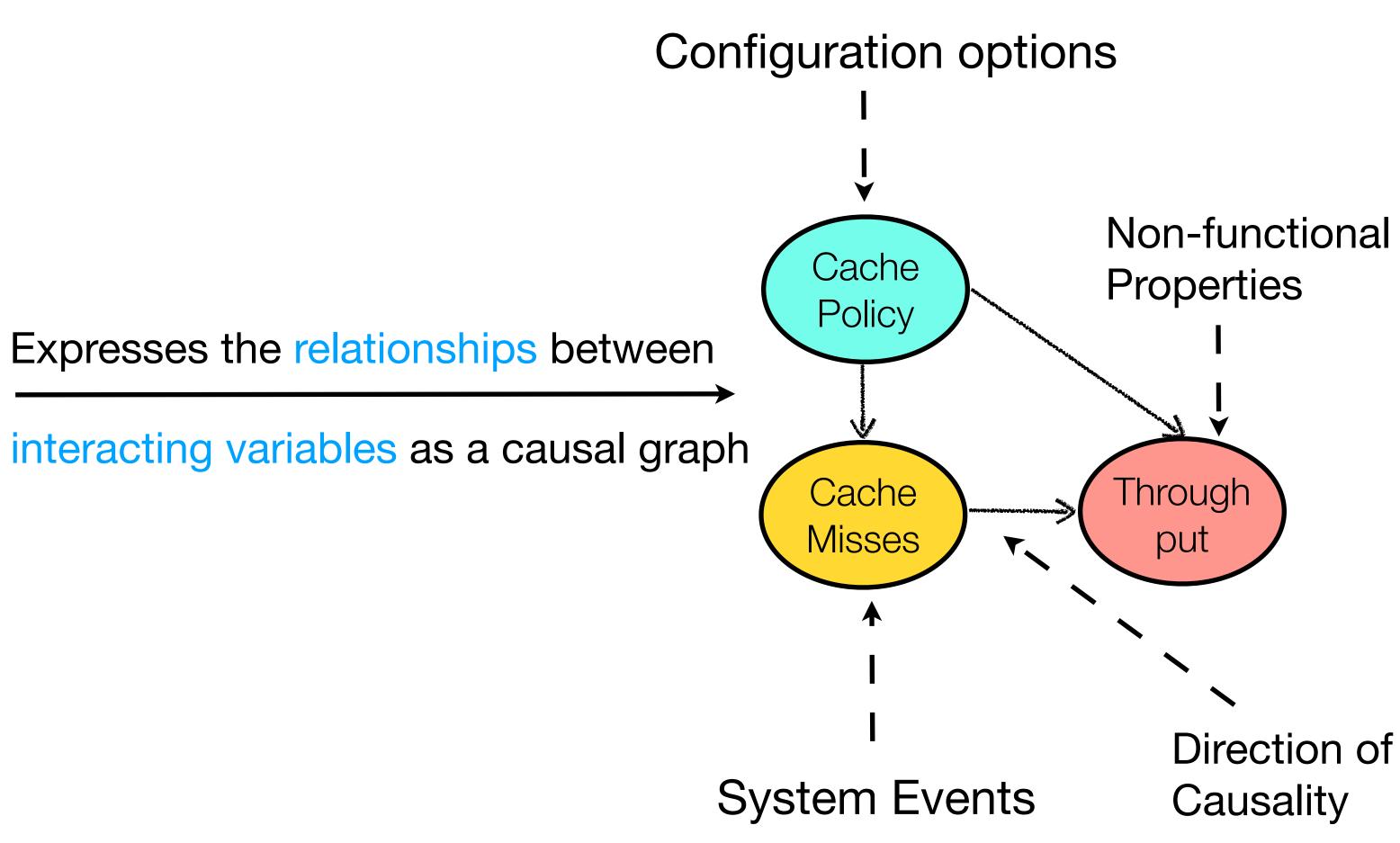




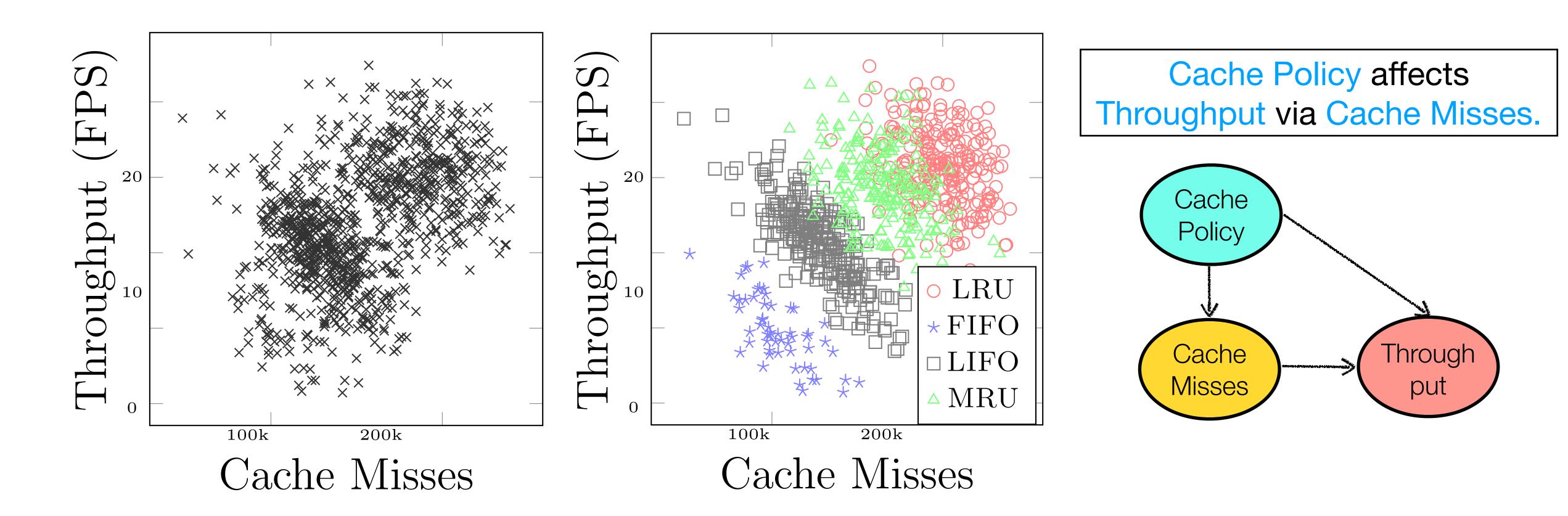
Performance influence models change significantly across environments, resulting in low accuracy in new environments.

Causal performance modeling





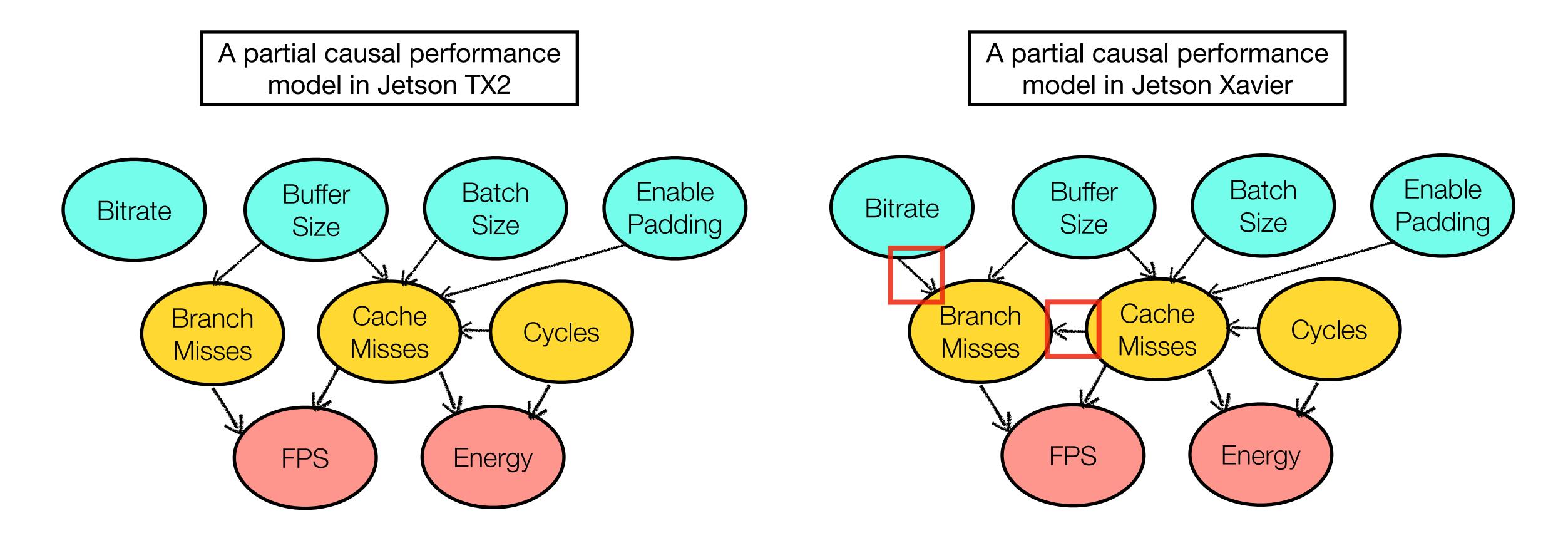
Causal performance models produce correct explanations

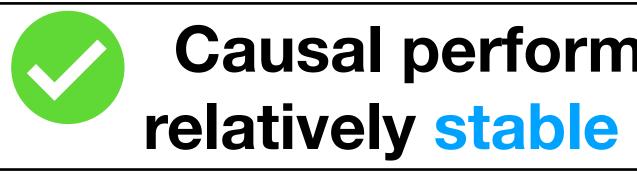




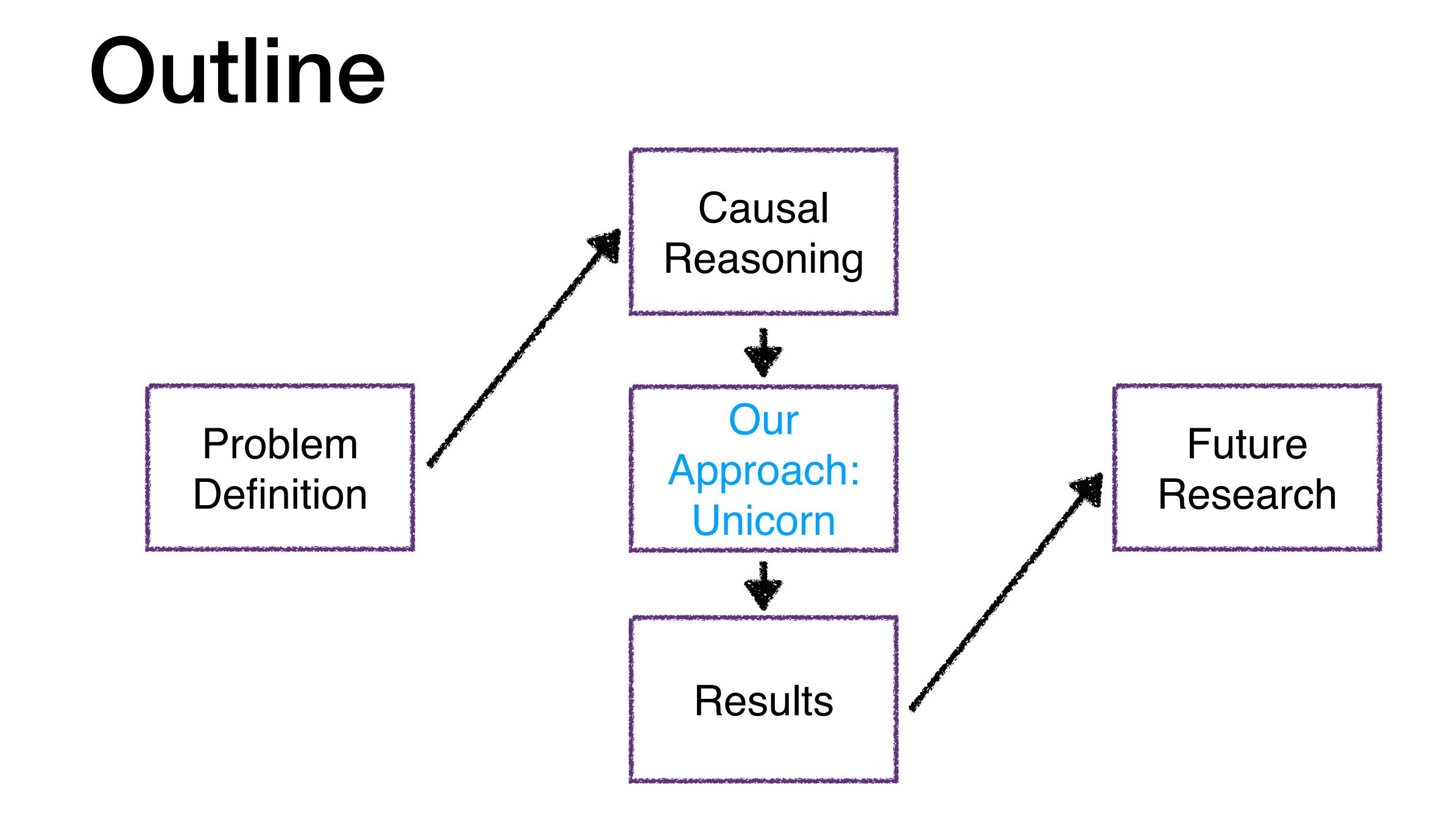
Causal performance models capture correct interactions.

Causal performance models are transferable across environments



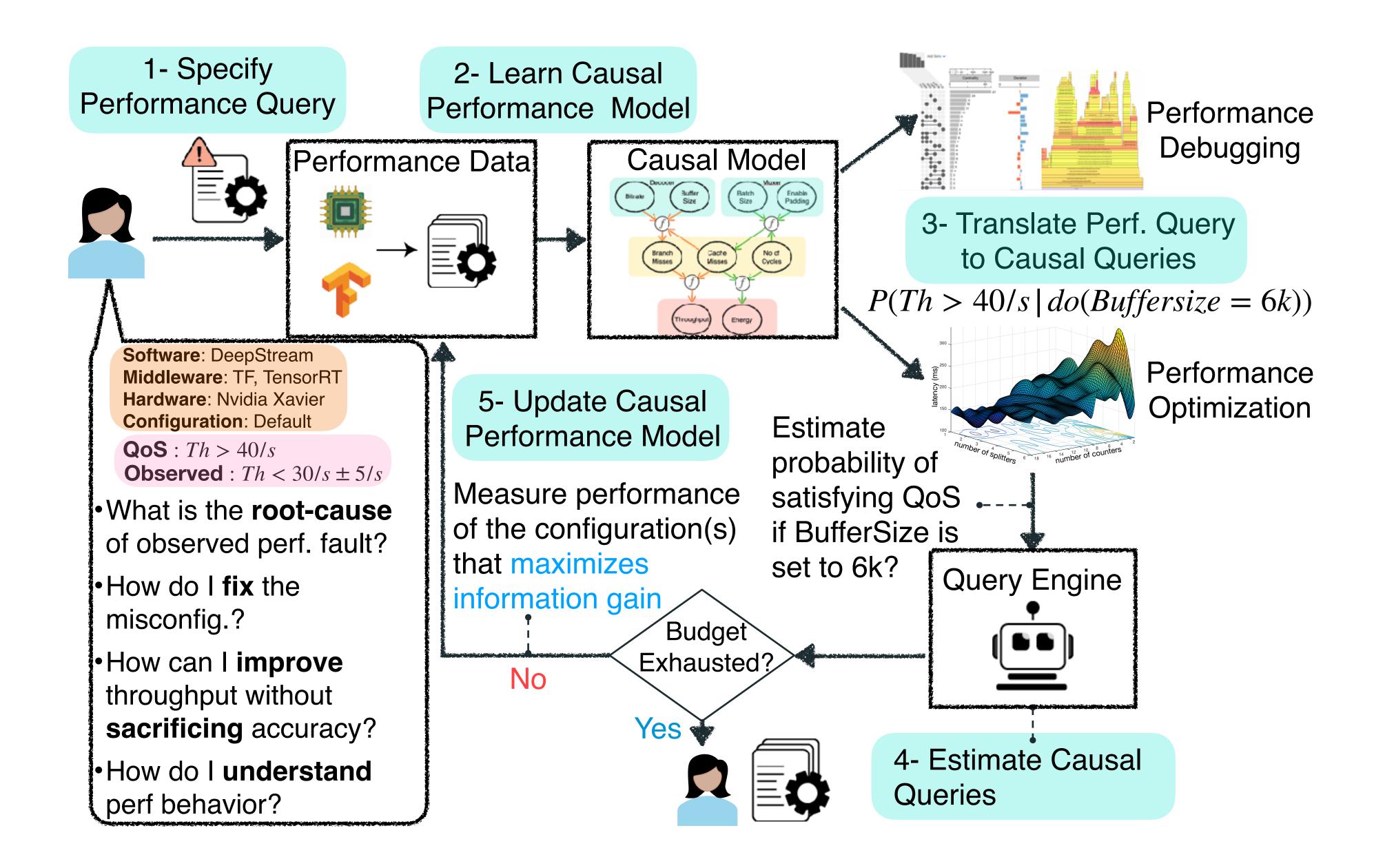


Causal performance models remain relatively stable across environments.



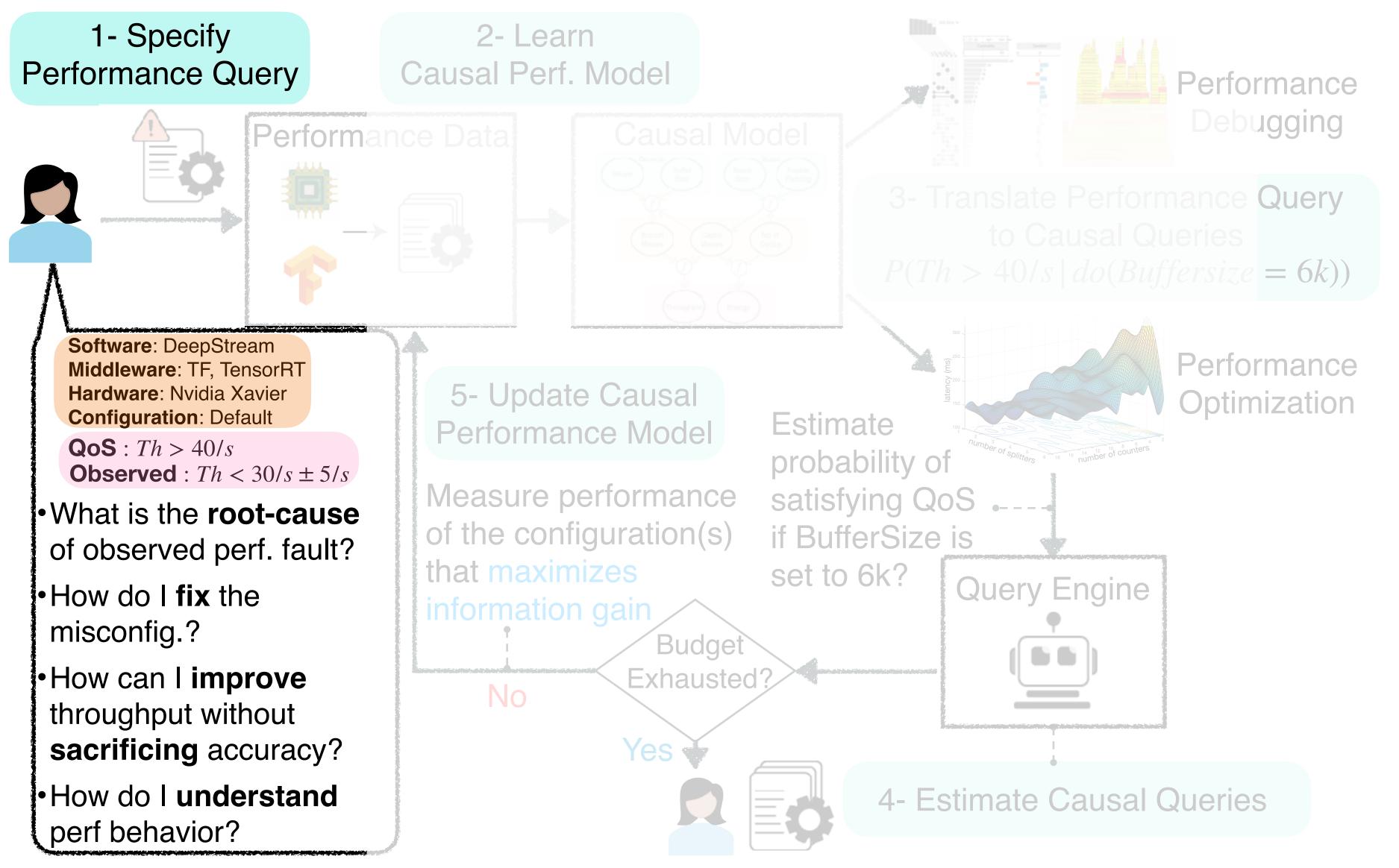


UNICORN: Performance Reasoning through the Lens of Causality



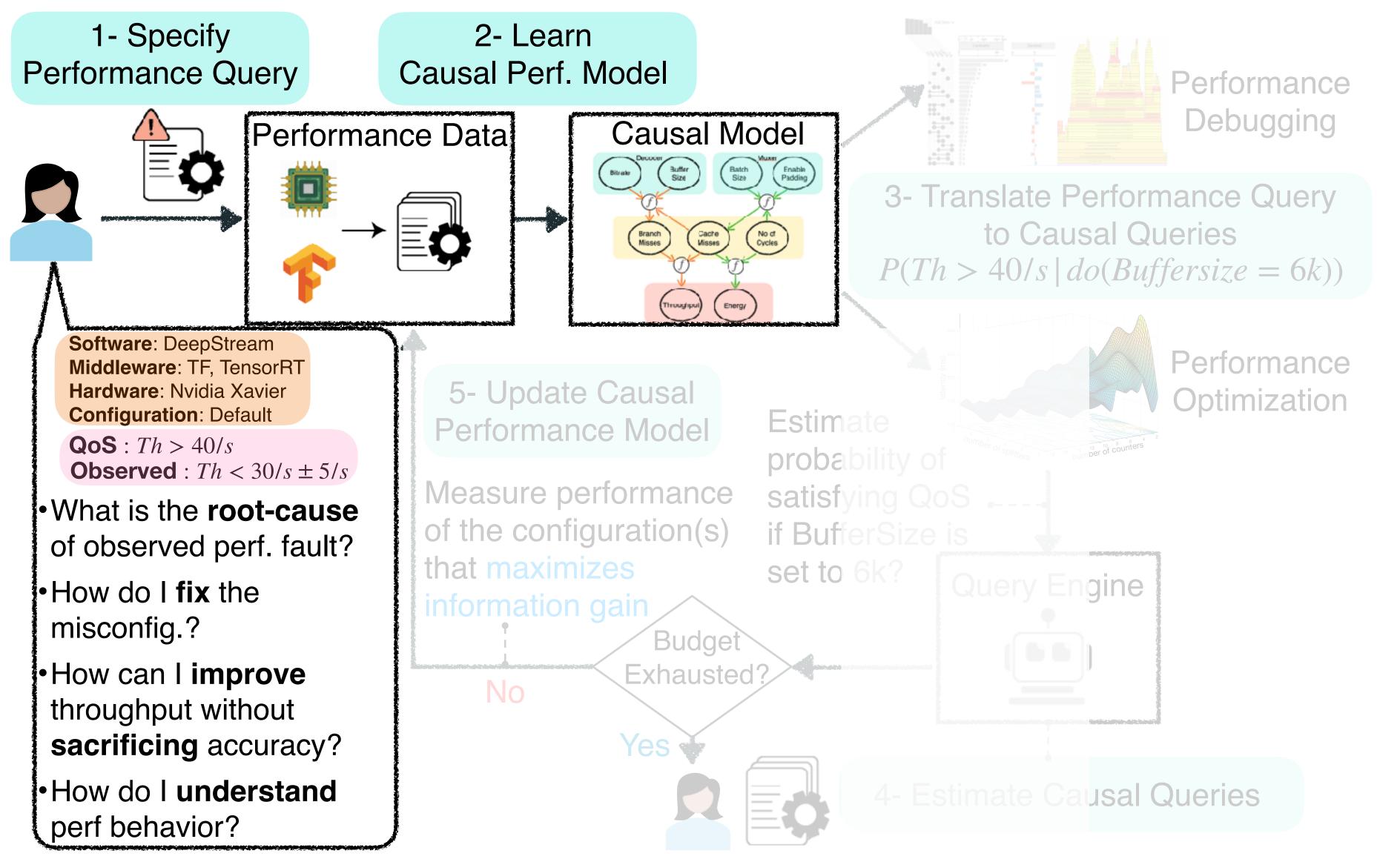


UNICORN: Performance Reasoning through the Lens of Causality



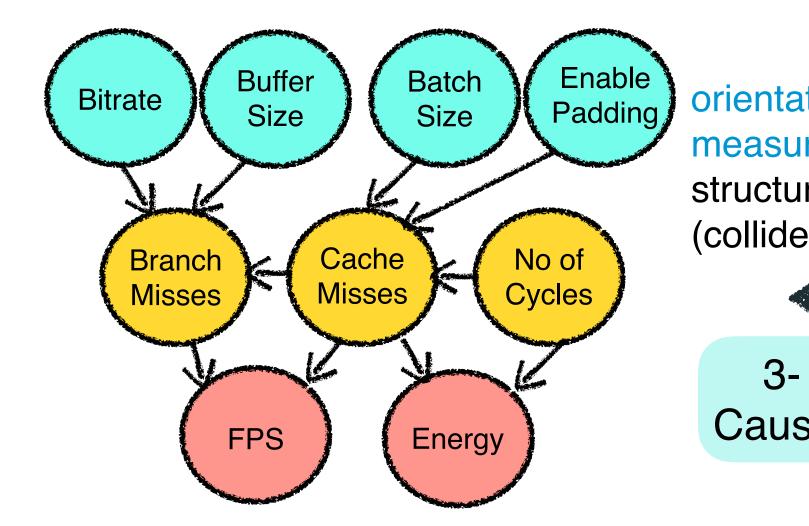


UNICORN: Performance Reasoning through the Lens of Causality

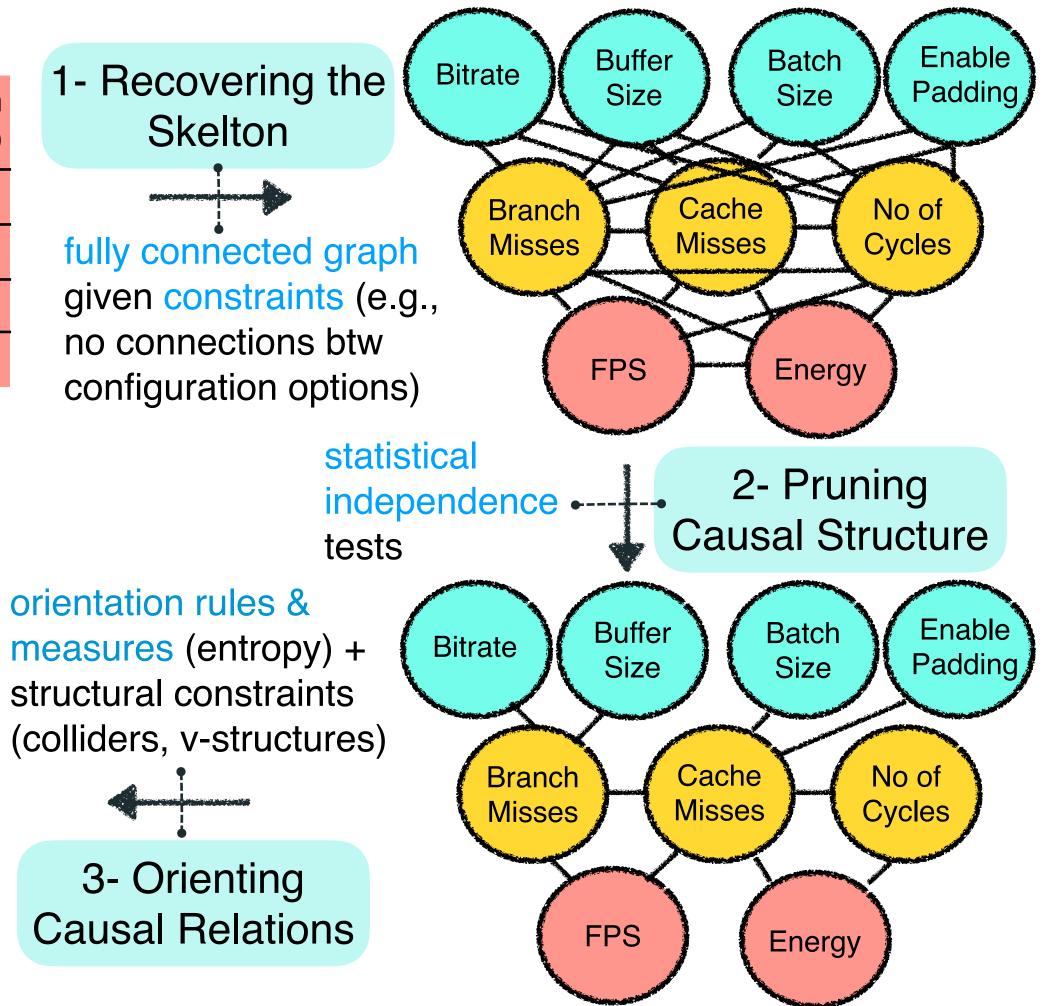




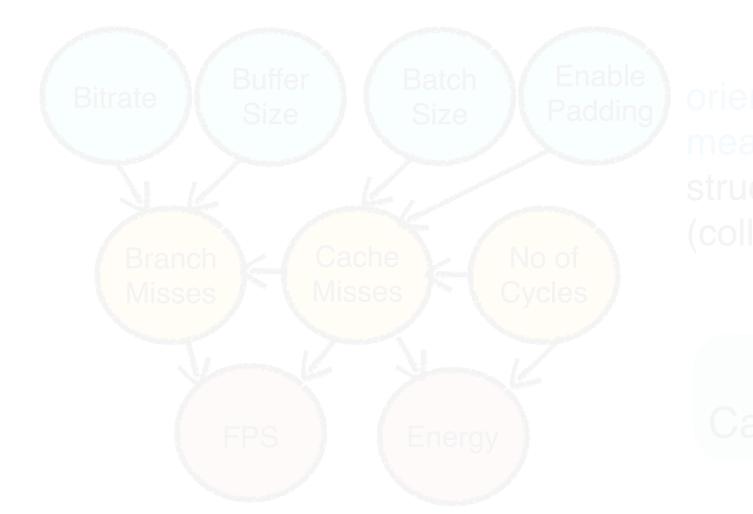
			Enable Padding	••••	Cache Misses	 Through put (fps)
_	C ₁	1k	1	•••	42m	 7
_	C ₂	2k	1	•••	32m	 22
_						
_	C n	5k	0		12m	 25



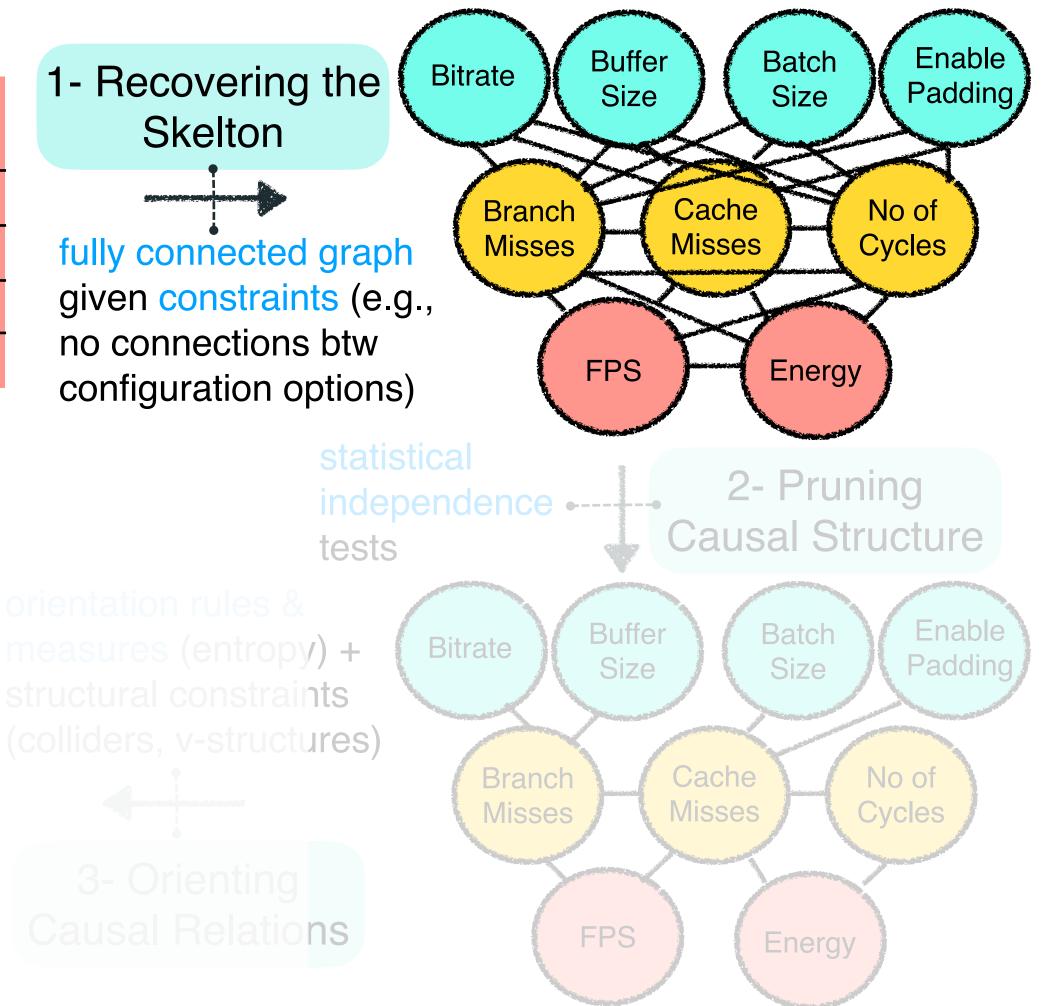
Learning Causal Performance Model



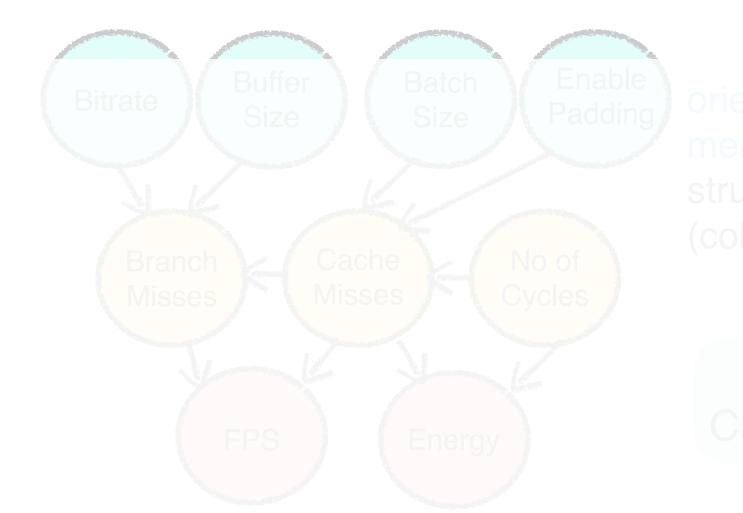
		Enable Padding	 Cache Misses	 Through put (fps)
C ₁	1k	1	 42m	 7
C ₂	2k	1	 32m	 22
Cn	5k	0	 12m	 25



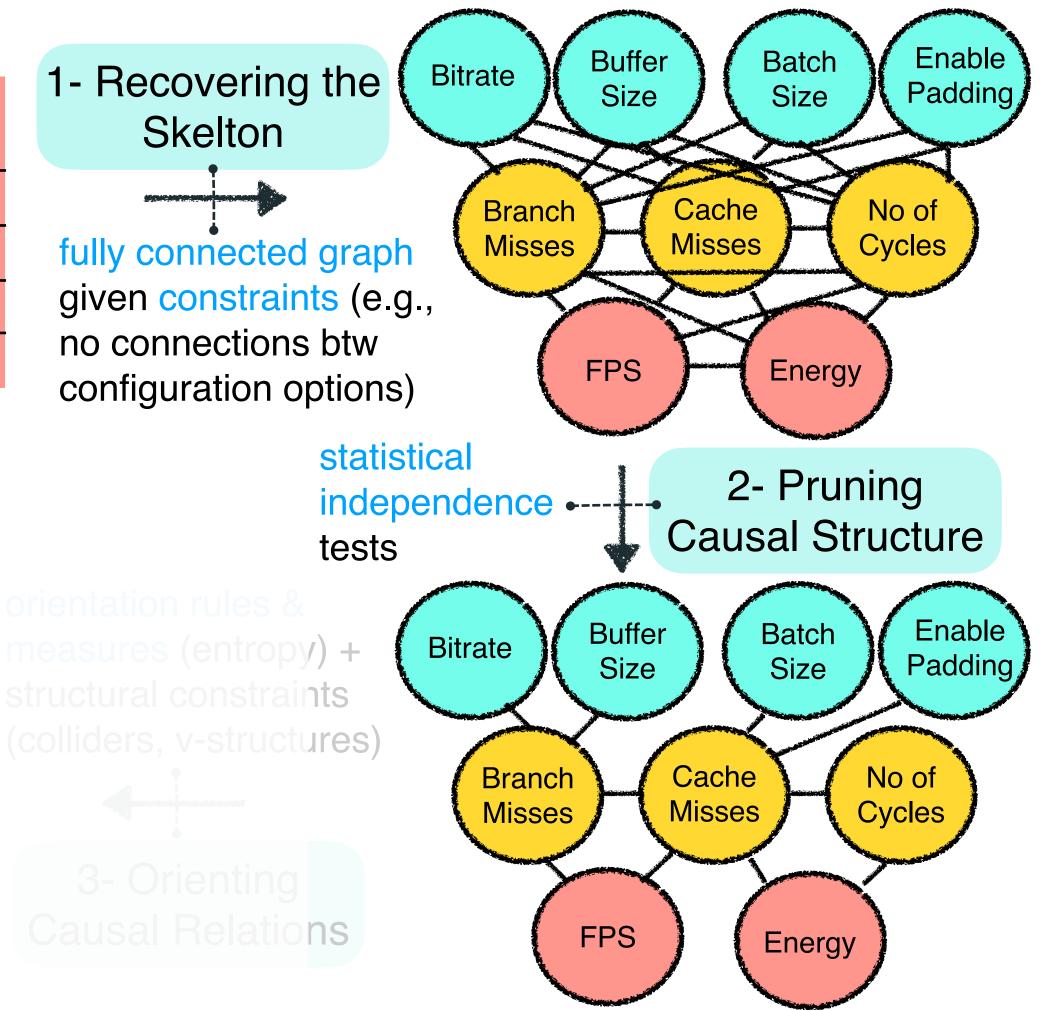
Learning Causal Performance Model



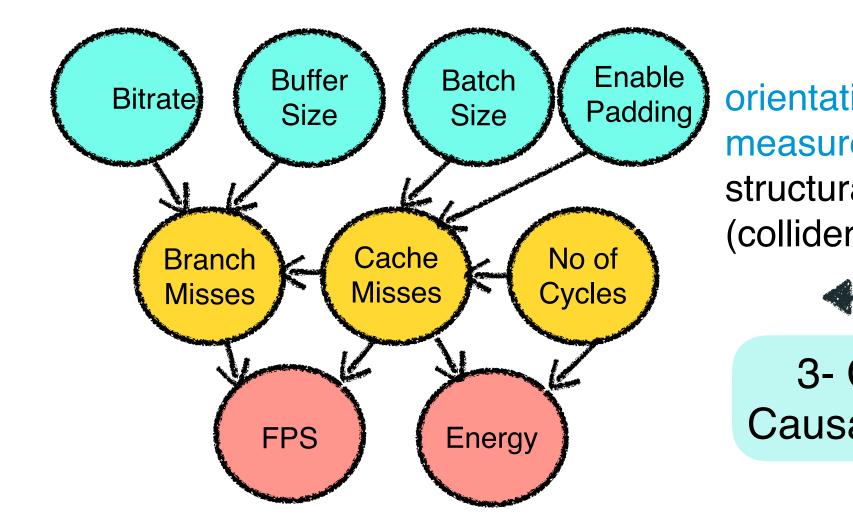
		Enable Padding	 Cache Misses	 Through put (fps)
C ₁	1k	1	 42m	 7
C ₂	2k	1	 32m	 22
Cn	5k	0	 12m	 25



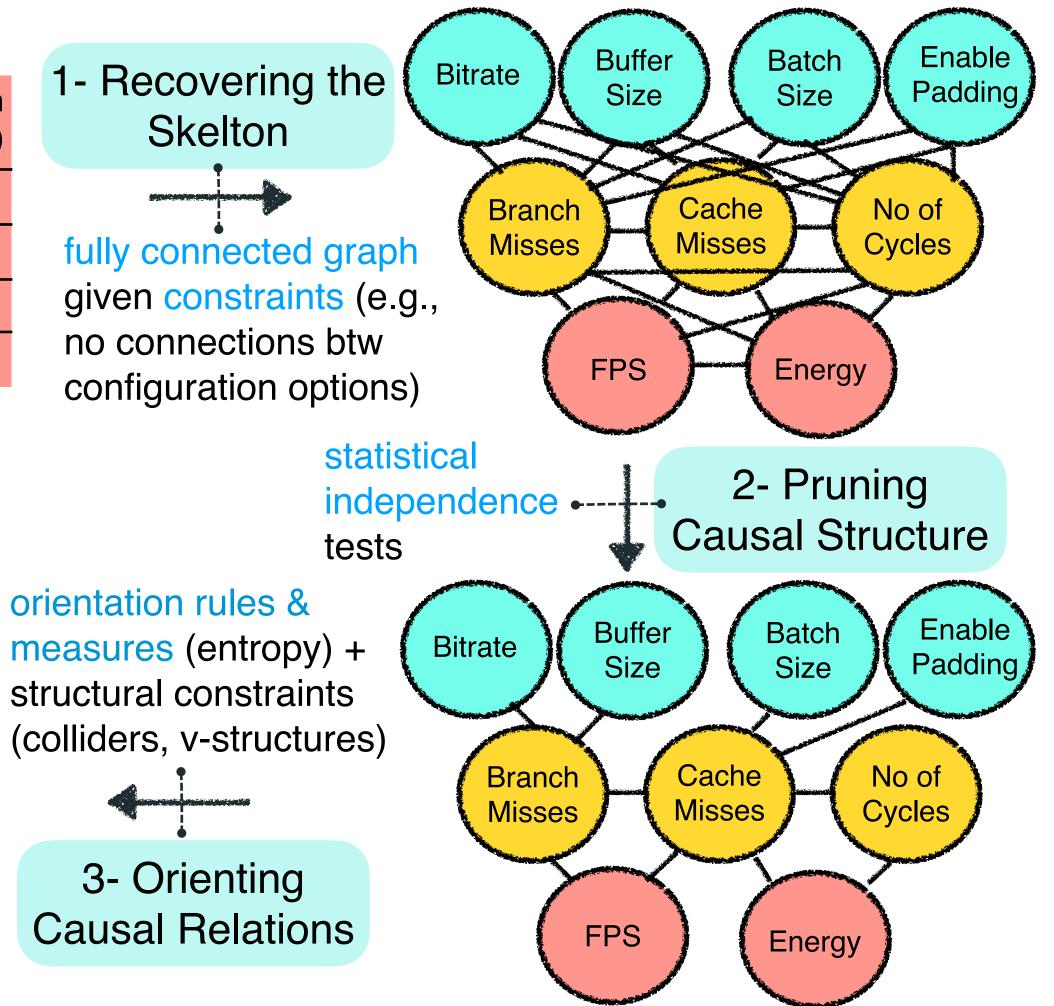
Learning Causal Performance Model



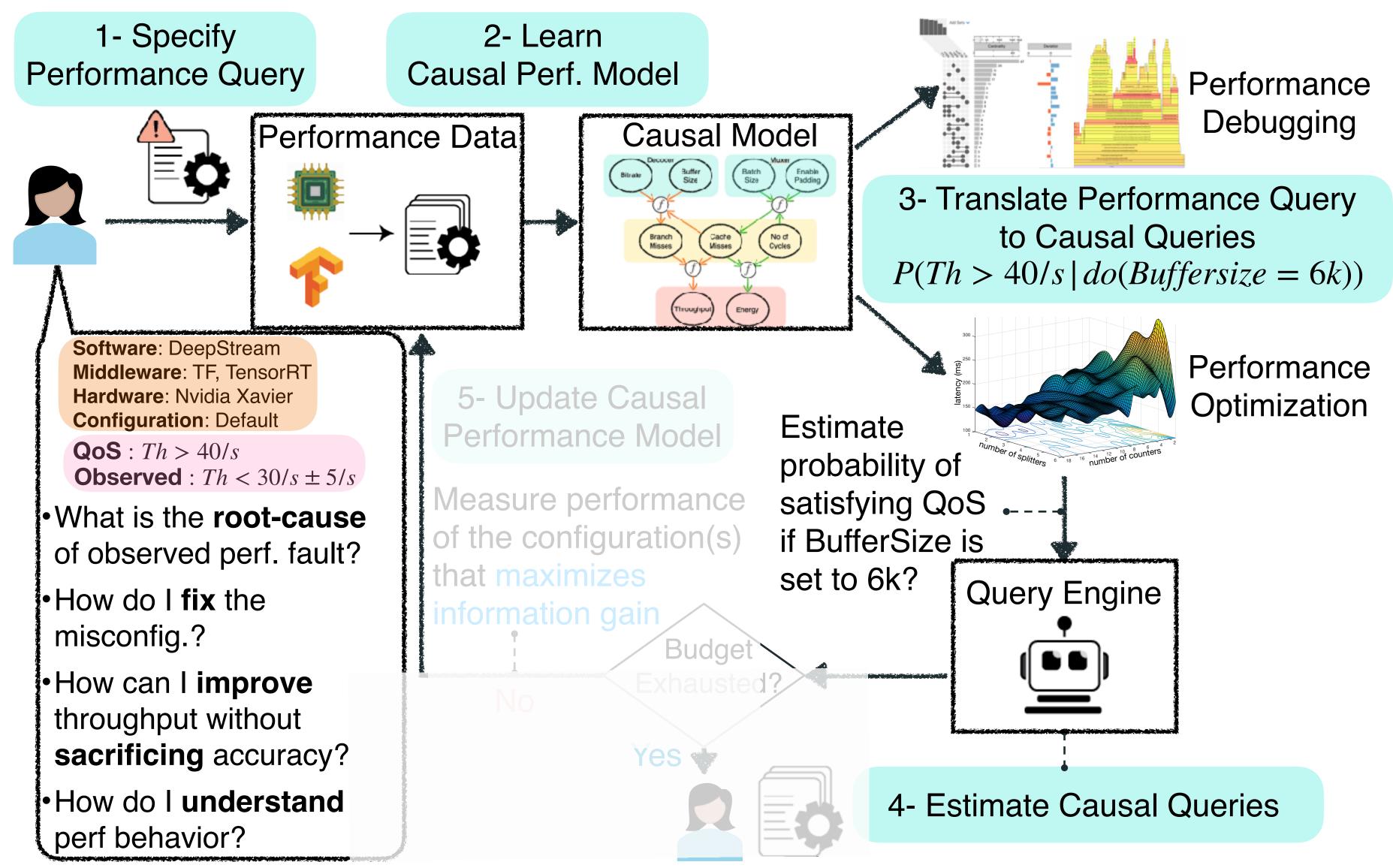
	Bitrate (bits/s)	Enable Padding	 Cache Misses	 Through put (fps)
C ₁	1k	1	 42m	 7
C ₂	2k	1	 32m	 22
C _n	5k	0	 12m	 25



Learning Causal Performance Model



UNICORN: Performance Reasoning through the Lens of Causality





misconfigurations

Example

We are interested in the scenario where:

We hypothetically have low latency; \bullet

Conditioned on the following events:

- \bullet
- Swap Memory was initially set to 2 Gb \bullet
- \bullet
- Everything else remains the same \bullet

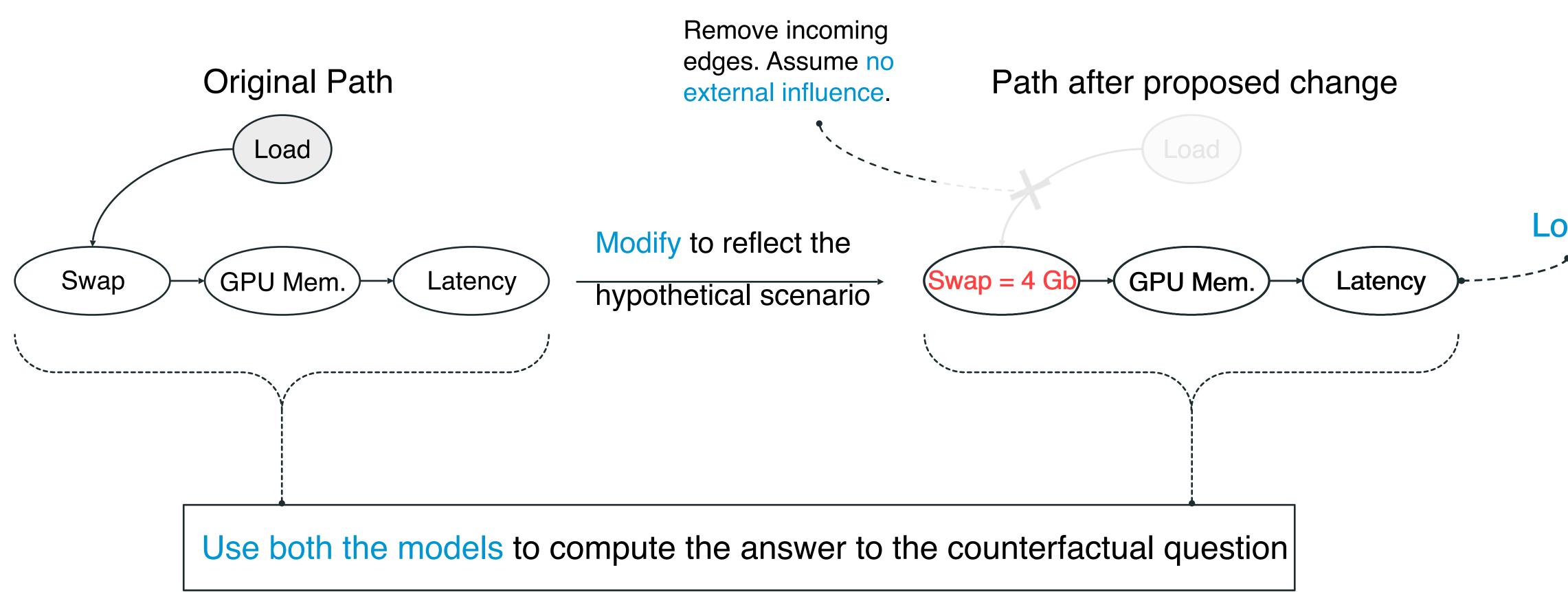
Counterfactual inference asks "what if" questions about changes to the

Given that my current swap memory is 2 Gb, and I have high latency. What is the probability of having low latency if swap memory was increased to 4 Gb?

We hypothetically set the new Swap memory to 4 Gb

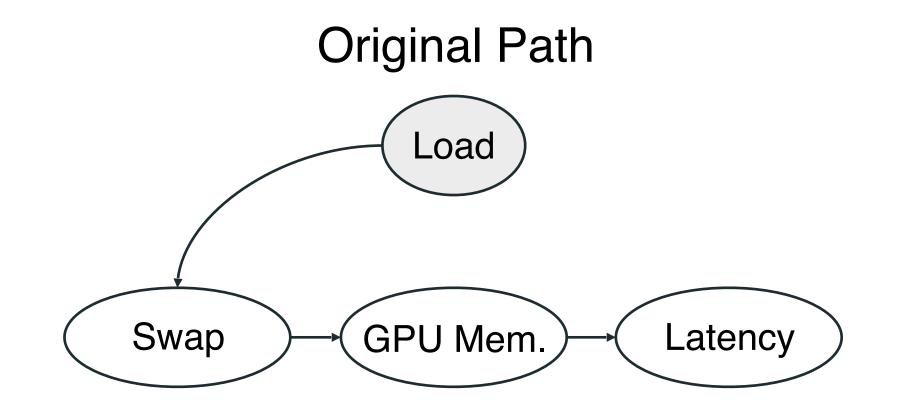
We observed high latency when Swap was set to 2 Gb



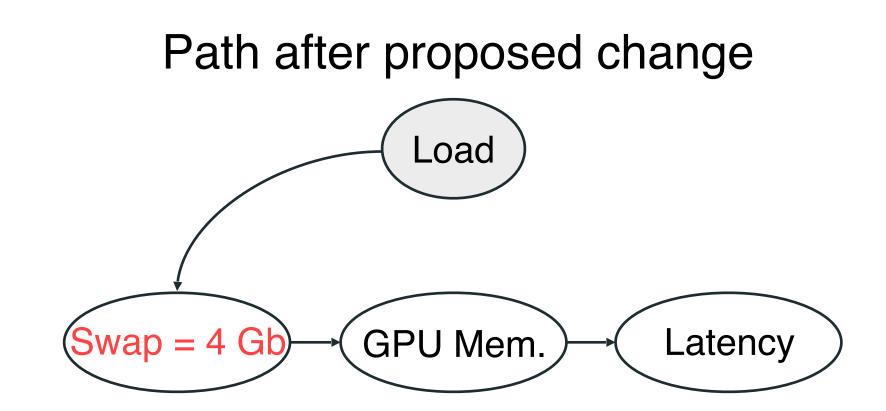


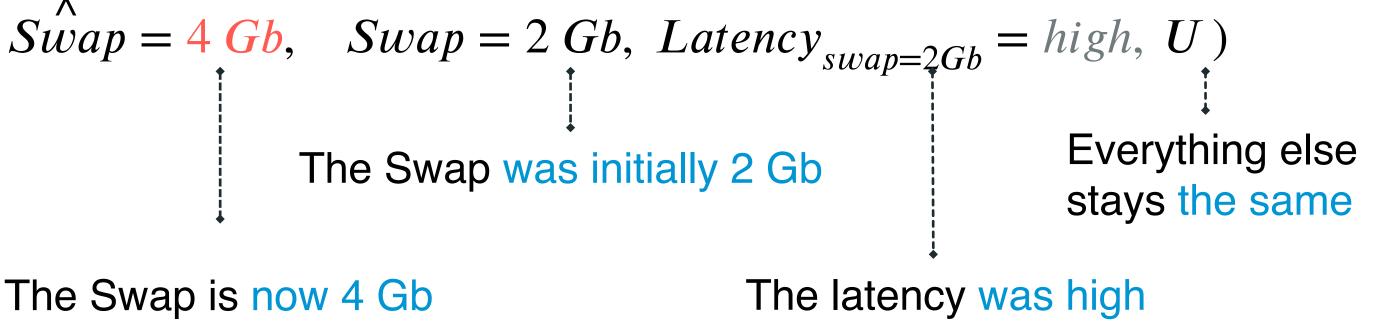






Potential =
$$P\left(\begin{array}{c} Latency = low \\ \downarrow \end{array}\right)$$
 $Swap = 4$
We expect a low latency







$$\mathsf{Potential} = P\Big(out \widehat{come} = \operatorname{good}^{\mathsf{out}} chan$$

Probability that the outcome is good after a change, conditioned on the past

$$Control = P(out com)$$

Probability that the outcome was bad before the change

 $nge, outcome_{\neg change} = bad, \neg change, U$

 $ne = bad | \neg change, U)$

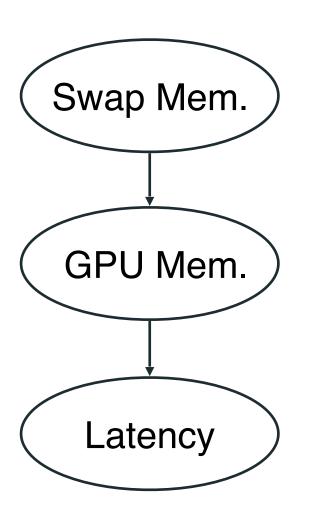
Individual Treatment Effect = Potential – Outcome

If this difference is large, then our change is useful



• • •

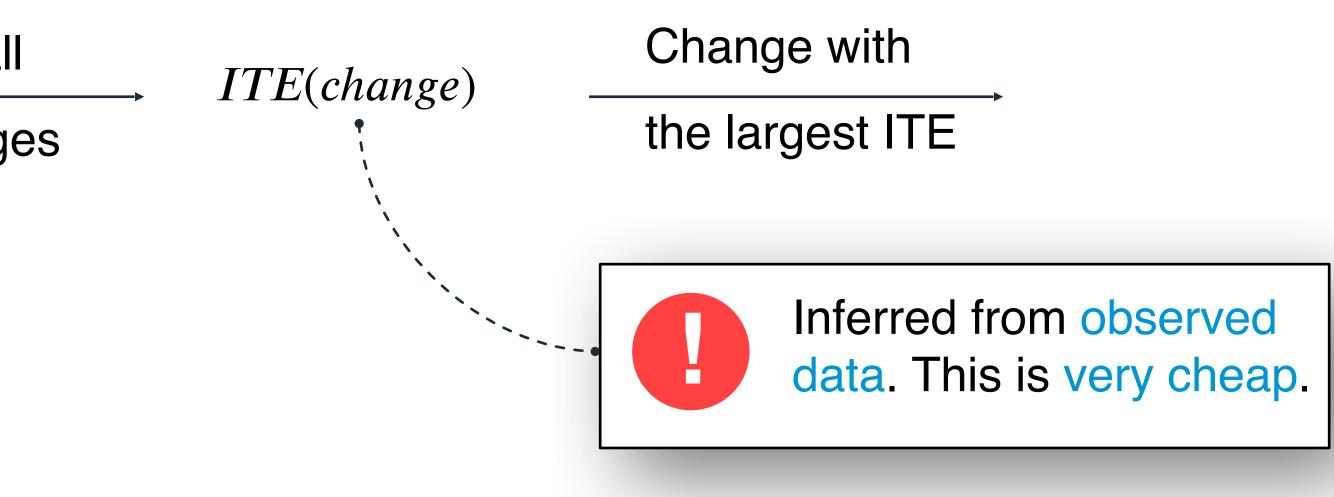
Top K paths



Enumerate all

possible changes

Set every configuration option in the path to all permitted values

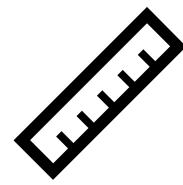


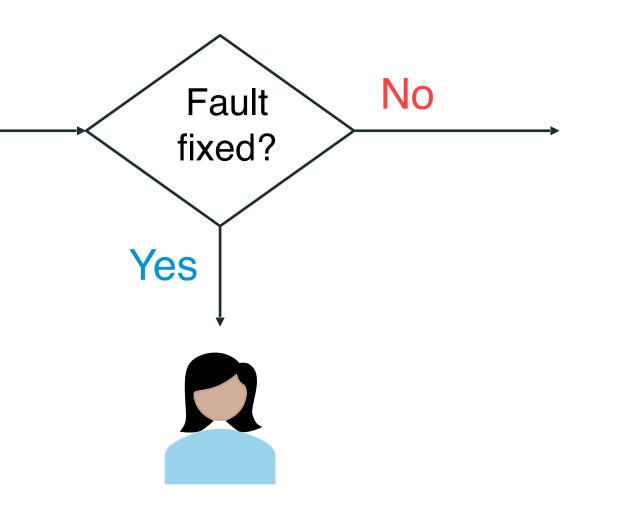


Measure Performance

Change with

the largest ITE

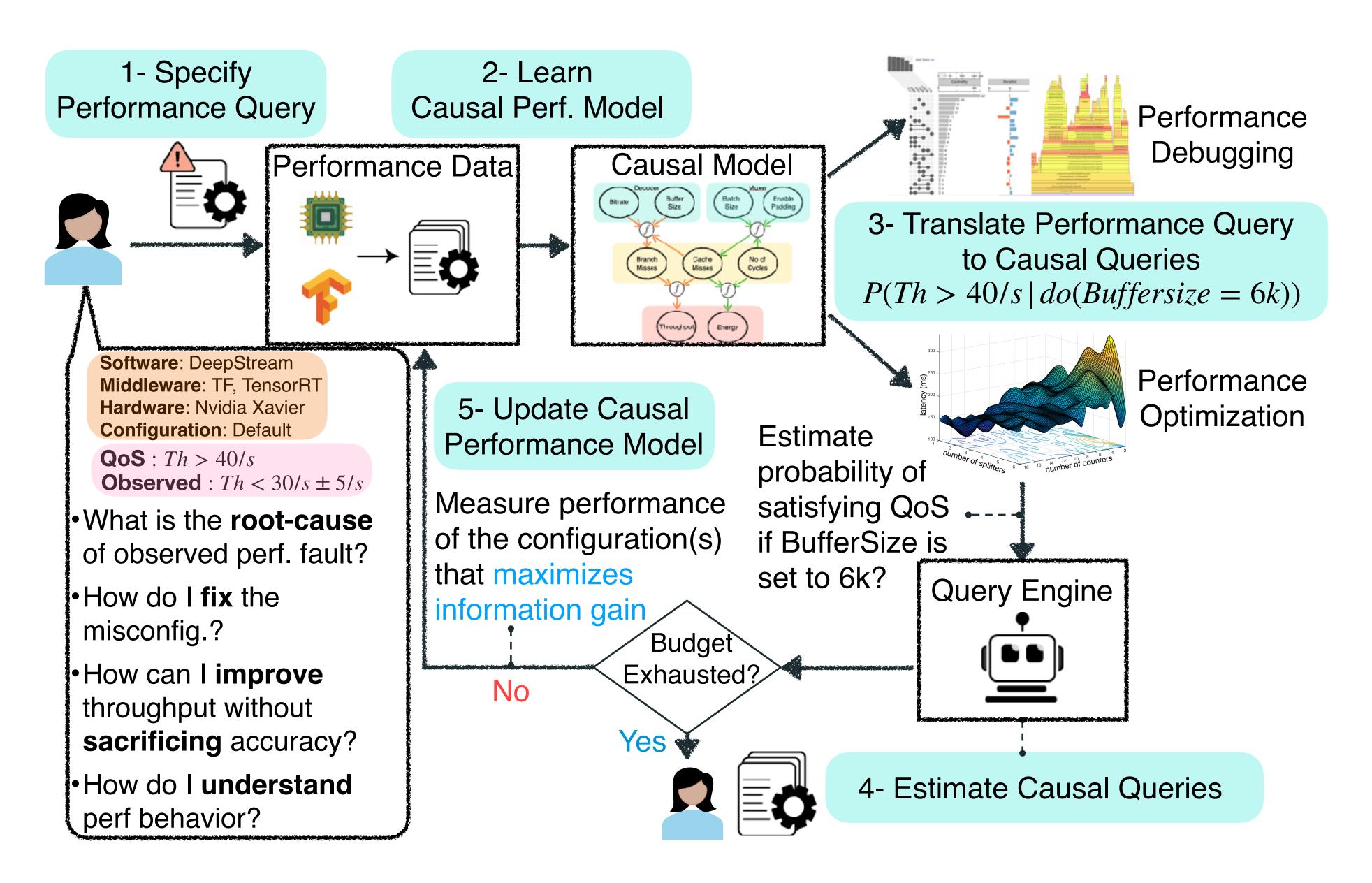




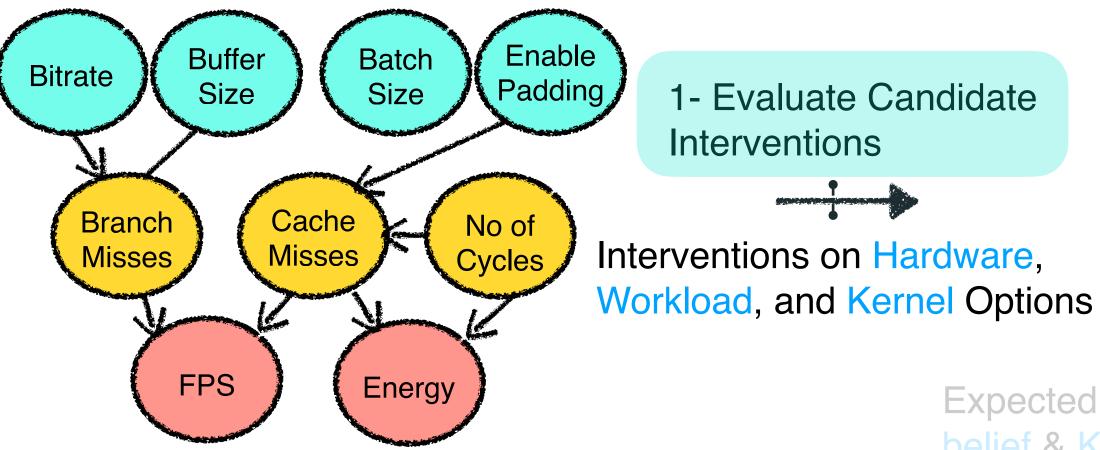
- Add to observational data \bullet
- Update causal model \bullet
- Repeat... \bullet

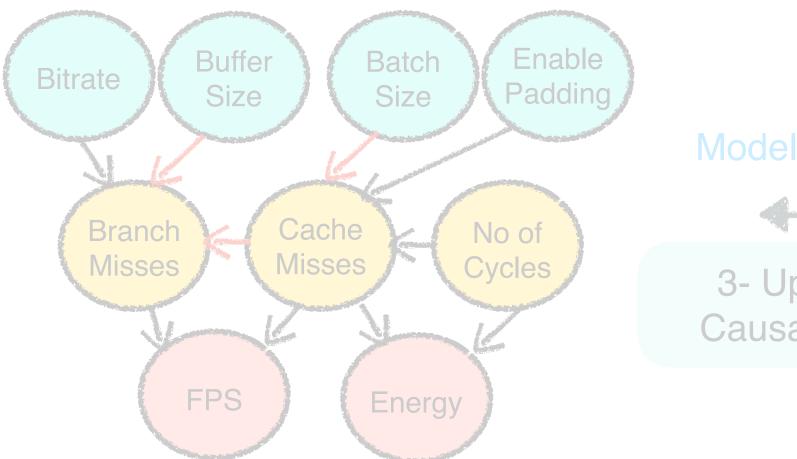


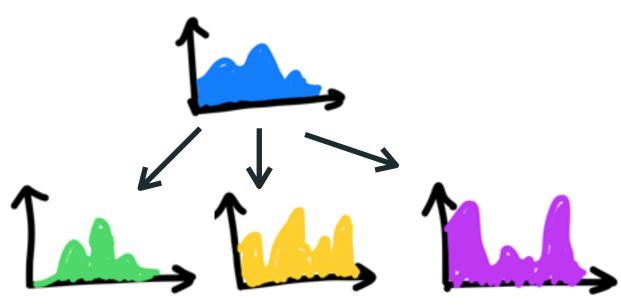
UNICORN: Our Causal AI for Systems Method



Active Learning for Updating Causal Performance Model







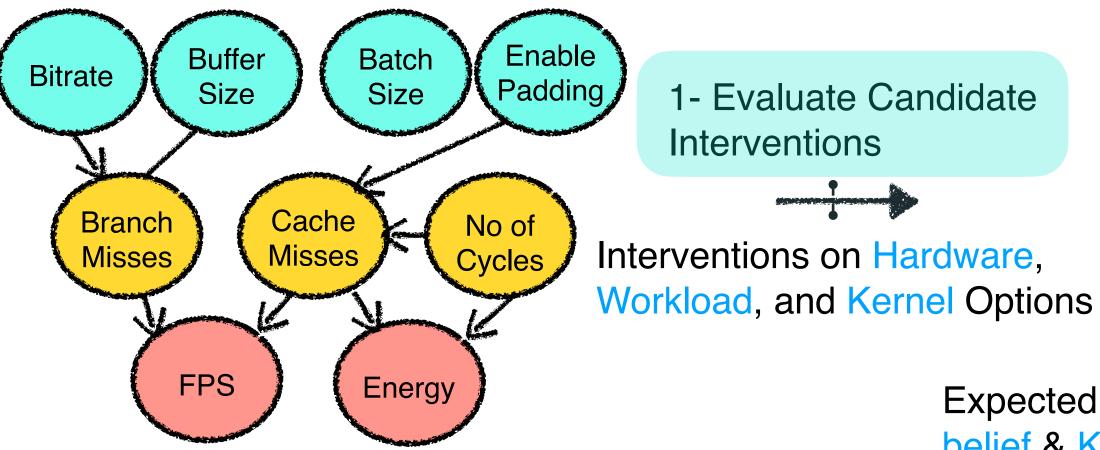
Expected change in belief & KL; Causal • • offects on objectives

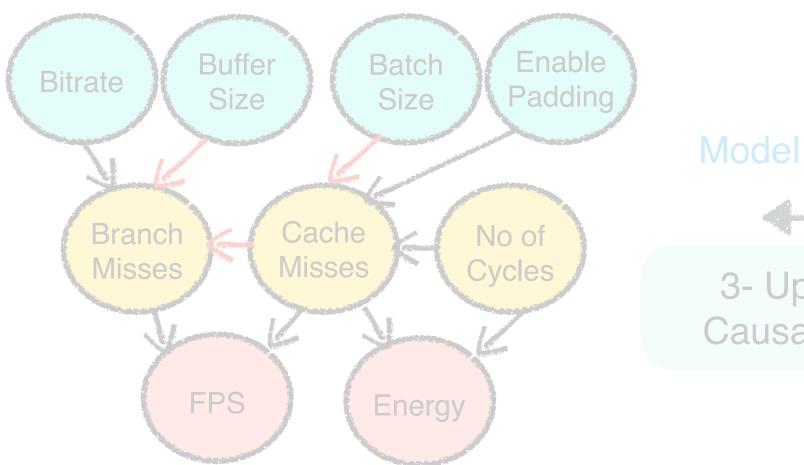
2- Determine & Perform next Perf Measurement

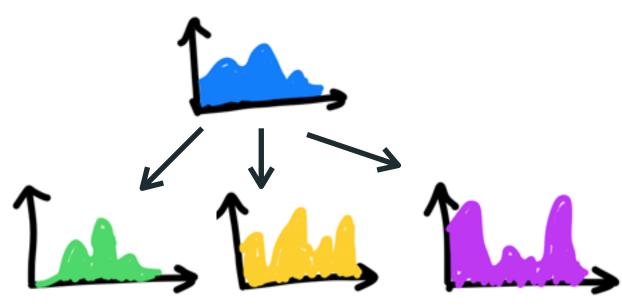
Lovereging			
averaging		Enable Padding	1
		Branch Misses	24m
pdating		Cache Misses	42m
al Model	Performance	No of Cycles	73b
	Data	FPS	31/s
		Energy	42J



Active Learning for Updating Causal Performance Model







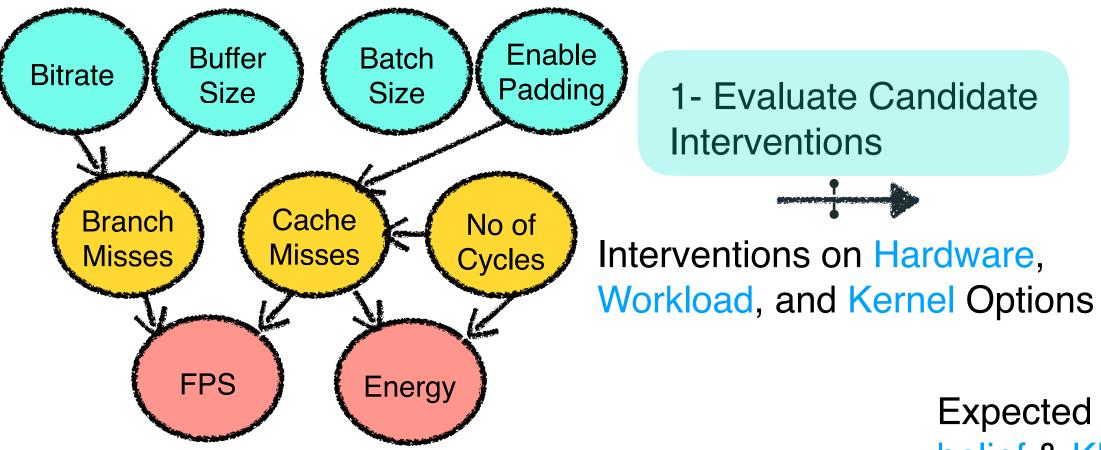
Expected change in belief & KL; Causal •--• effects on objectives *****

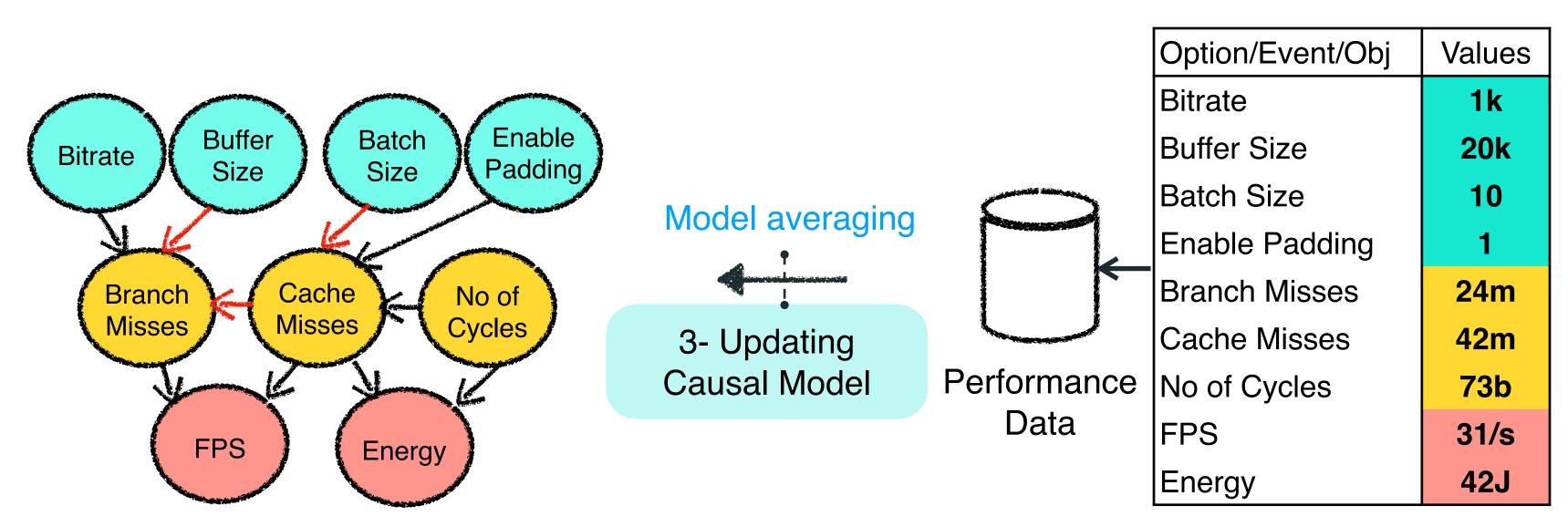
2- Determine & Perform next Perf Measurement

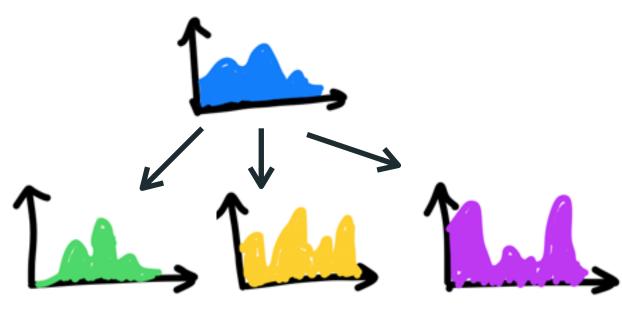
		Option/Event/Obj	Values
		Bitrate	1k
		Buffer Size	20k
Lovoroging		Batch Size	10
l averaging		Enable Padding	1
		Branch Misses	24m
pdating		Cache Misses	42m
al Model	Performance	No of Cycles	73b
	Data	FPS	31/s
		Energy	42J



Active Learning for Updating Causal Performance Model



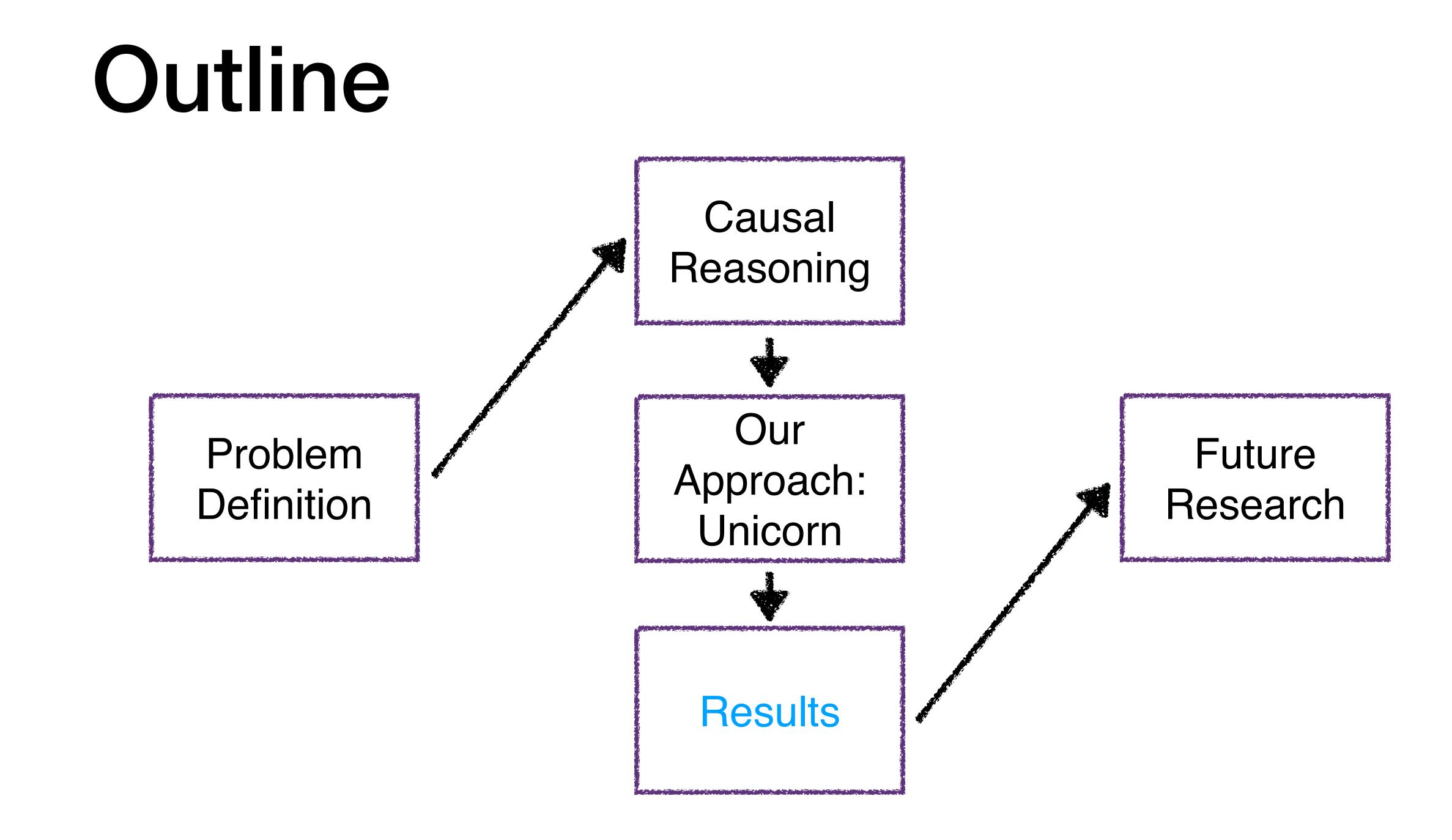




Expected change in belief & KL; Causal ••• effects on objectives *

2- Determine & Perform next Perf Measurement







Results: Case Study

NVIDIA. DEVELOPER

CUDA performance issue on tx2

Home > Autonomous Machines > Jetson & Embedded Systems > Jetson TX2



william_wu

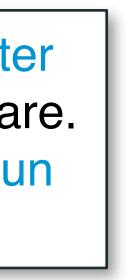
When we are trying to transplant our CUDA source code from TX1 to TX2, it behaved strange. The target hardware is faster than the the source hardware. We noticed that TX2 has twice computing-ability as TX1 in GPU, as expectation, we think TX2 will 30% - 40% faster than TX1 at least. User expects the code to run at least 30-40% faster. Unfortunately, most of our code base spent twice the time as TX1, in other words,

TX2 only has 1/2 speed as TX1, mostly. We believe that TX2's CUDA API runs much slower than TX1 in many cases.

The user is transferring the code from one hardware to another

The code ran 2x slower on the more powerful hardware

Jun '17





Results: Case Study





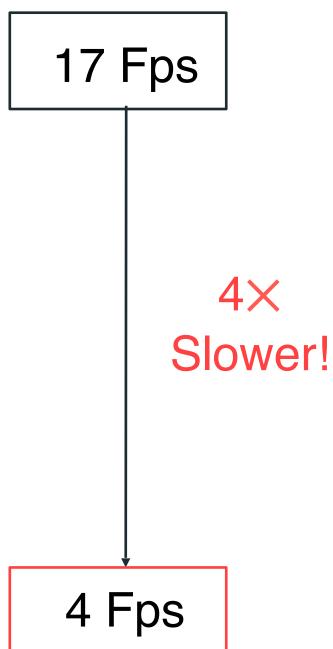
:	
	2]e .

Nvidia TX1		
CPU	4 cores, 1.3 GHz	
GPU	128 Cores, 0.9 GHz	
Memory	4 Gb, 25 Gb/s	





Nvidia TX2		
CPU	6 cores, 2 GHz	
GPU	256 Cores, 1.3 GHz	
Memory	8 Gb, 58 Gb/s	







Results: Case Study

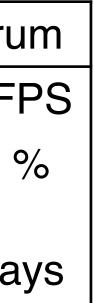
Configuration	UNICO RN	Decision Tree	Forum
CPU Cores	✓	✓	\checkmark
CPU Freq.	\checkmark	\checkmark	\checkmark
EMC Freq.	\checkmark	\checkmark	\checkmark
GPU Freq.	\checkmark	\checkmark	\checkmark
Sched. Policy		\checkmark	
Sched. Runtime		\checkmark	
Sched. Child Proc		\checkmark	
Dirty Bg. Ratio		\checkmark	
Drop Caches		\checkmark	
CUDA_STATIC_RT	\checkmark	\checkmark	\checkmark
Swap Memory		\checkmark	

	UNICORN	Decision Tree	Foru
Throughput (on TX2)	26 FPS	20 FPS	23 F
Throughput Gain (over TX1)	53 %	21 %	39 9
Time to resolve	24 min.	3 ¹ / ₂ Hrs.	2 da

`--• The user expected 30-40% gain

Results

- X Finds the root-causes accurately
- X No unnecessary changes
- X Better improvements than forum's recommendation
- X Much faster







Evaluation: Experimental Setup

Hardware

Nvidia TX1		
CPU	4 cores, 1.3 GHz	
GPU	128 Cores, 0.9 GHz	
Memory	4 Gb, 25 GB/s	

Nvidia TX2		
CPU	6 cores, 2 GHz	
GPU	256 Cores, 1.3 GHz	
Memory	8 Gb, 58 GB/s	

Systems



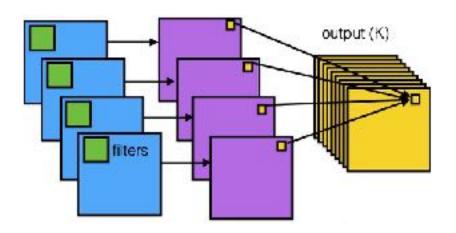


Image recognition (50,000 test images)

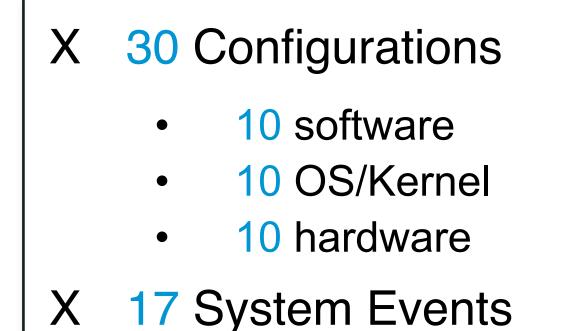
DeepSpeech



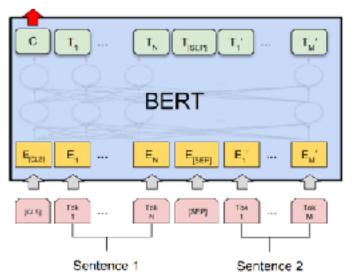
Voice recognition (5 sec. audio clip)

Nvidia Xavier		
CPU	8 cores, 2.26 GHz	
GPU	512 cores, 1.3 GHz	
Memory	32 Gb, 137 GB/s	

Configuration Space



BERT



Sentiment Analysis (10000 IMDb reviews)

x264



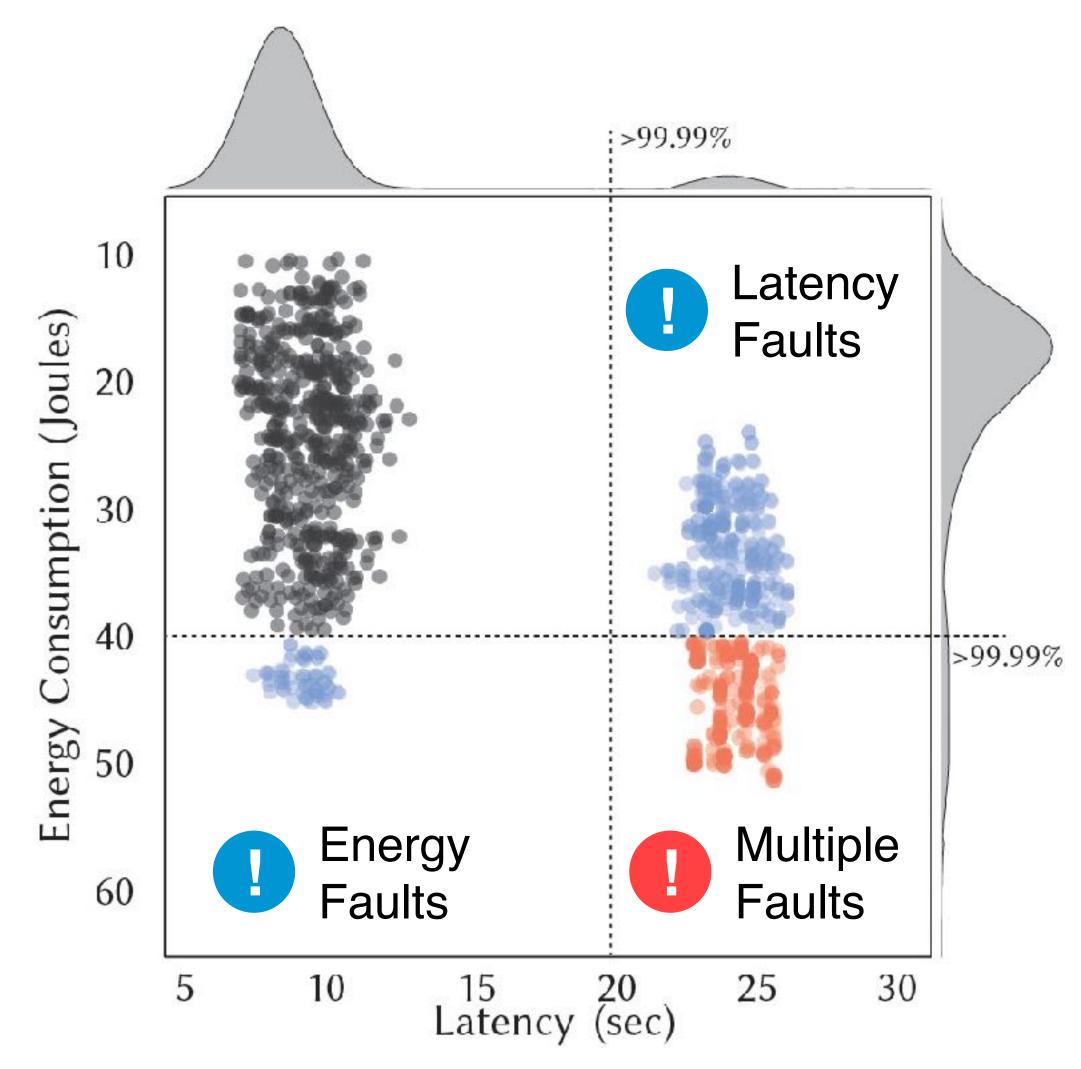
Video Encoder (11 Mb, 1080p video)





Evaluation: Data Collection

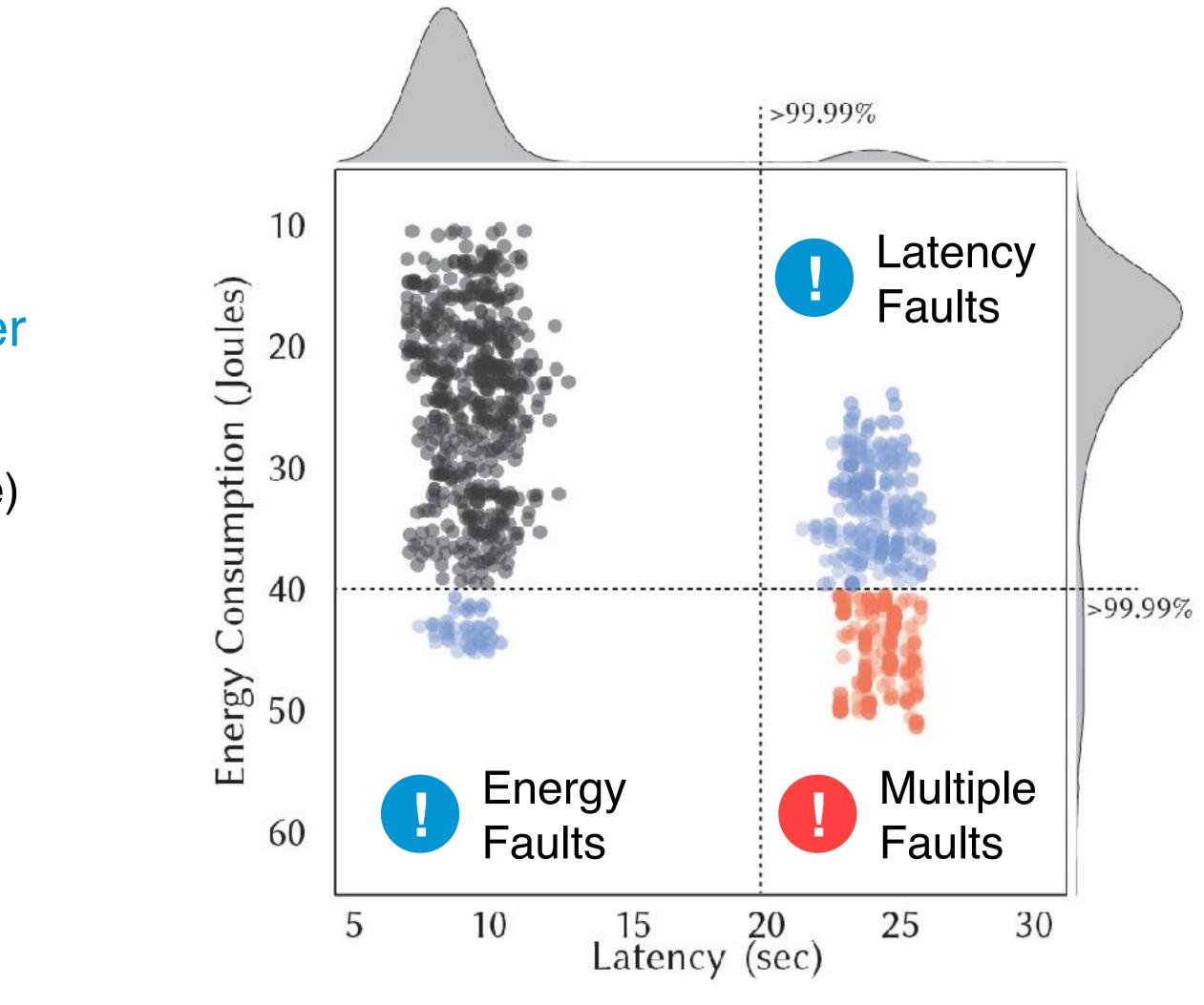
- For each software/hardware combination create a benchmark dataset
 - Exhaustively set each of configuration option to all permitted values.
 - For continuous options (e.g., GPU memory Mem.), sample 10 equally spaced values between [min, max]
- Measure the latency, energy consumption, and heat dissipation
 - Repeat 5x and average





Evaluation: Ground Truth

- For each performance fault:
 - Manually investigate the root-cause
 - "Fix" the misconfigurations
- A "fix" implies the configuration no longer has tail performance
 - User defined benchmark (i.e., 10th percentile)
 - Or some QoS/SLA benchmark
- Record the configurations that were changed





Experimental Setup: Baselines

Debugging

BugDoc: A System for Debugging Computational Pipelines

Raoni Lourenço New York University raoni@nyu.edu

Juliana Freire New York University juliana.freire@nyu.edu Dennis Shasha New York University shasha@courant.nyu.edu

Statistical Debugging for Real-World Performance Problems

Linhai Song Shan Lu*

University of Wisconsin-Madison {songlh, shanlu}@cs.wisc.edu

Optimization

Sequential Model-Based Optimization for General Algorithm Configuration (extended version)

Frank Hutter, Holger H. Hoos and Kevin Leyton-Brown

University of British Columbia, 2366 Main Mall, Vancouver BC, V6T 1Z4, Canada {hutter, hoos, kevinlb}@cs.ubc.ca

EnCore: Exploiting System Environment and Correlation Information for Misconfiguration Detection

Jiaqi Zhang[†], Lakshminarayanan Renganarayana[§], Xiaolan Zhang[§], Niyu Ge[§], Vasanth Bala[§], Tianyin Xu[†], Yuanyuan Zhou[†]

[†]University of California San Diego {jiz013, tixu, yyzhou}@cs.ucsd.edu [§]IBM Watson Research Center {Irengan, cxzhang, niyuge, vbala}@us.ibm.com

Iterative Delta Debugging

Cyrille Artho

Research Center for Information Security (RCIS), AIST, Tokyo, Japan

Predictive Entropy Search for Multi-objective Bayesian Optimization

Daniel Hernández-Lobato Universidad Autónoma de Madrid, Francisco Tomás y Valiente 11, 28049, Madrid, Sp	DANIEL.HERNANDEZ@UAM.ES ain.
José Miguel Hernández-Lobato Harvard University, 33 Oxford street, Cambridge, MA 02138, USA.	JMHL@SEAS.HARVARD.EDU
Amar Shah Cambridge University, Trumpington Street, Cambridge CB2 1PZ, United Kingdom.	AS793@CAM.AC.UK
Ryan P. Adams Harvard University and Twitter, 33 Oxford street Cambridge, MA 02138, USA.	RPA@SEAS.HARVARD.EDU



Results: Efficiency (Debugging; Single objective)

				A	ccura	cy			P	recisio	on				Recall					Gain			Tim	ie†
			UNICORN	CBI	DD	ENCORE	BugDoc	UNICORN	CBI	DD	ENCORE	BucDoc	Unicorn	CBI	DD	ENCORE	BugDoc	UNICORN	CBI	DD	ENCORE	BucDoc	UNICORN	Others
		DeepStream	87	61	62	65	81	83	66	59	60	71	80	61	65	60	70	88	66	67	68	79	0.8	4
	atency	XCEPTION	86	53	42	62	65	86	67	61	63	67	83	64	68	69	62	82	48	42	57	59	0.6	4
TX2		BERT	81	56	59	60	57	76	57	55	61	73	71	74	68	67	65	74	54	59	62	58	0.4	4
E		Deepspeech	81	61	59	60	72	76	58	69	61	71	81	73	61	63	69	76	59	53	55	66	0.7	4
	Γ	x264	83	59	63	62	62	82	69	58	65	66	78	64	67	63	72	85	69	72	68	71	1.4	4
		DeepStream	91	81	79	77	87	81	61	62	64	73	85	63	61	62	75	86	68	62	61	78	0.7	4
н	Y	XCEPTION	84	66	63	63	81	78	56	58	66	65	80	69	55	63	68	83	59	50	51	62	0.4	4
/IER	19 19	BERT	66	59	53	63	72	70	62	64	64	65	79	61	54	63	66	62	49	36	49	53	0.5	4
XAV	Ene	Deepspeech	73	68	63	72	71	75	55	59	54	68	78	53	52	59	71	78	64	48	65	63	1.2	4
\sim	Н	x264	77	71	70	74	74	83	63	53	61	66	78	67	53	54	72	87	73	71	76	76	0.3	4
					•	•																	+	

Find root causes more accurately than **ML-based methods**

Better gain

Up to 20x faster









Results: Efficiency (Debugging; Multi-objective)

	Accuracy			Precision			Recall			Gain (Latency)			Gain (Energy)			7)	Time [†]					
	UNICORN	CBI	EnCore	BucDoc	UNICORN	CBI	ENCORE	BuGDoc	UNICORN	CBI	EnCore	BuGDoc	UNICORN	CBI	EnCore	BugDoc	UNICORN	CBI	EnCore	BugDoc	UNICORN	Others
+ > XCEPTION	89	76	81	79	77	53	54	62	81	59	59	62	84	53	61	65	75	38	46	44	0.9	4
ACEPTION AG US BERT HI DEEPSPEECH HI X264	71	72	73	71	77	42	56	63	79	59	62	65	84	53	59	61	67	41	27	48	0.5	4
DEEPSPEECH	86	69	71	72	80	44	53	62	81	51	59	64	88	55	55	62	77	43	43	41	1.1	4
на на x264	85	73	83	81	83	50	54	67	80	63	62	61	75	62	64	66	76	64	66	64	1	4
[†] Wallclock time in hou	ırs								-								•		•	_	tivos	

Multiple Faults in Latency & Energy usage

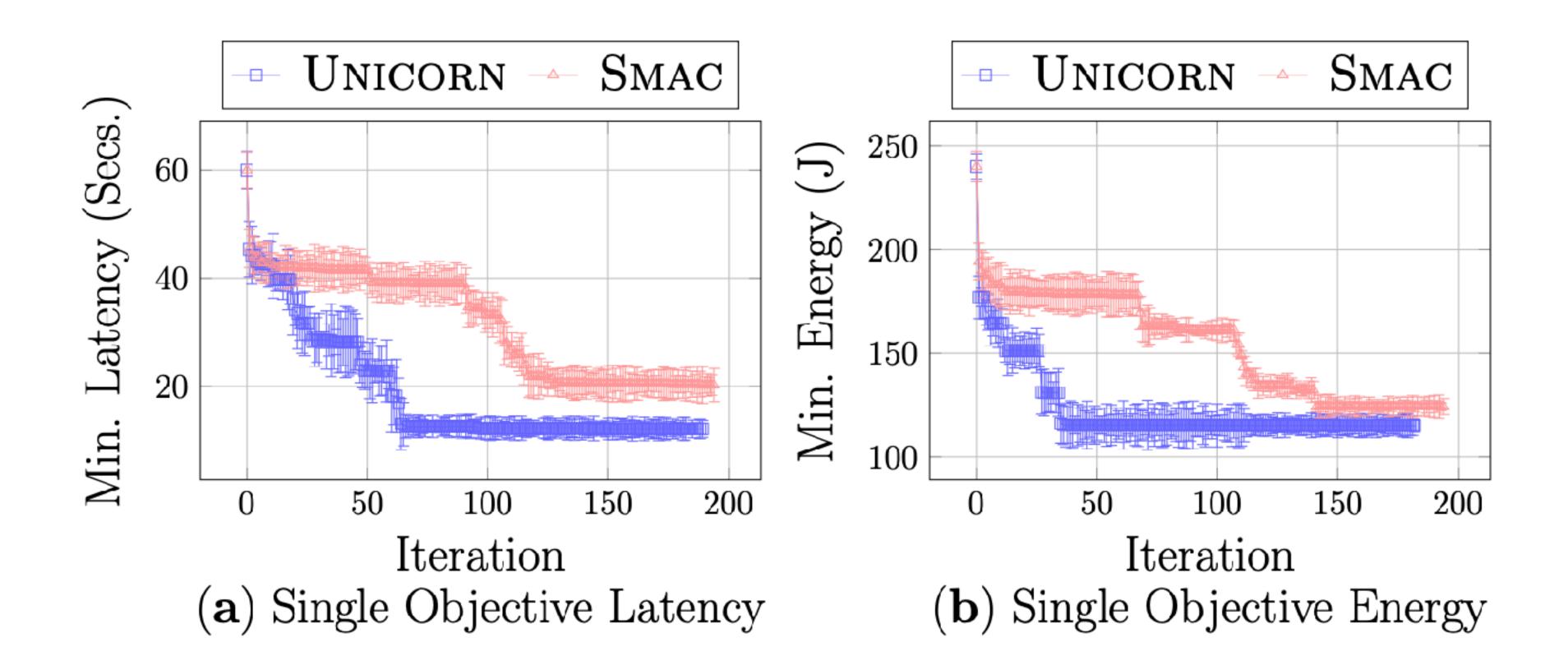
Deller gain across both objectives







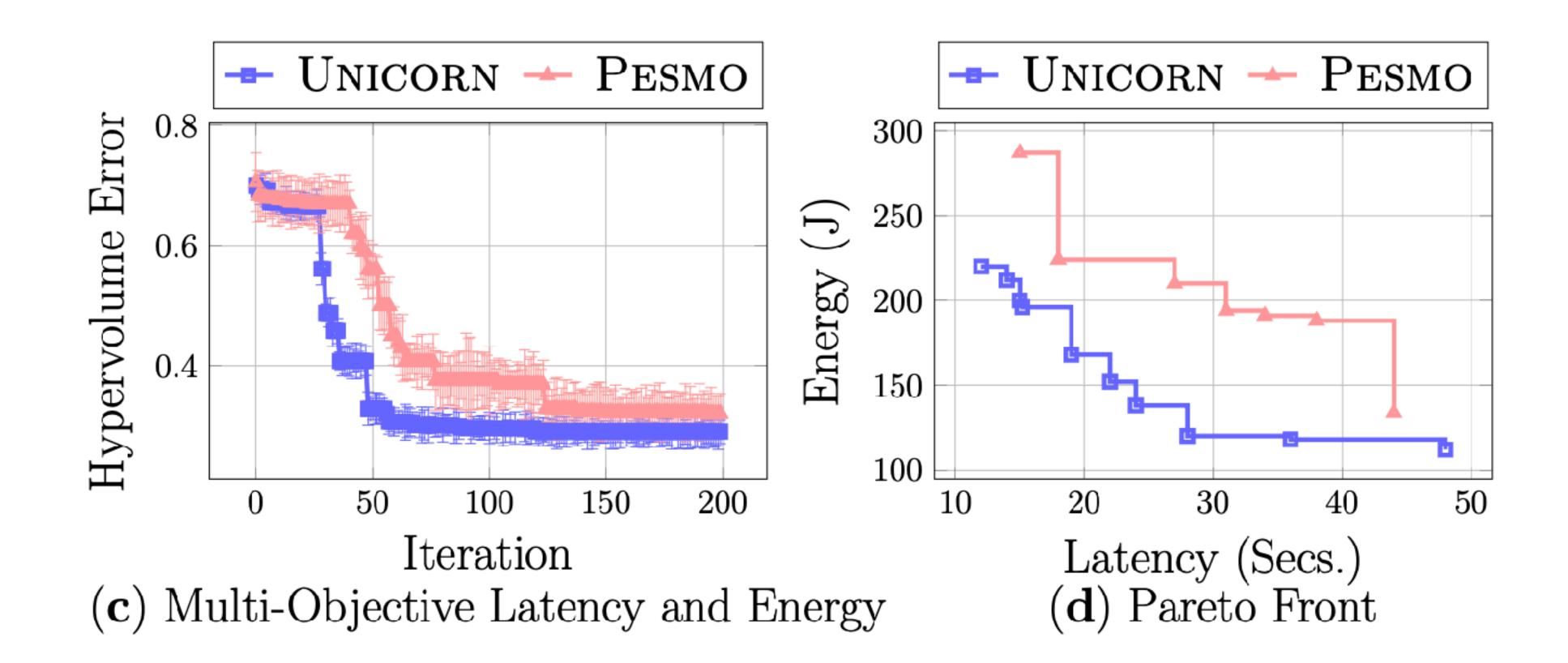
Results: Efficiency (Optimization; Single objective)







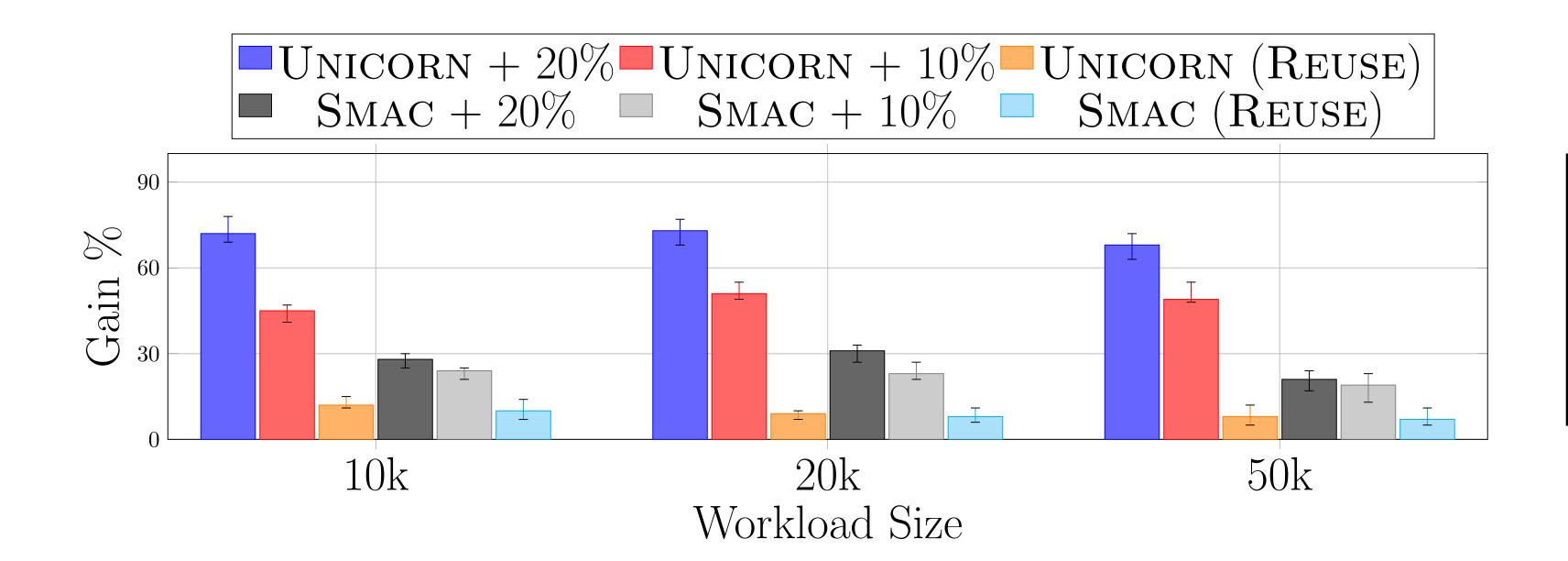
Results: Efficiency (Optimization; Multi-objective)





96

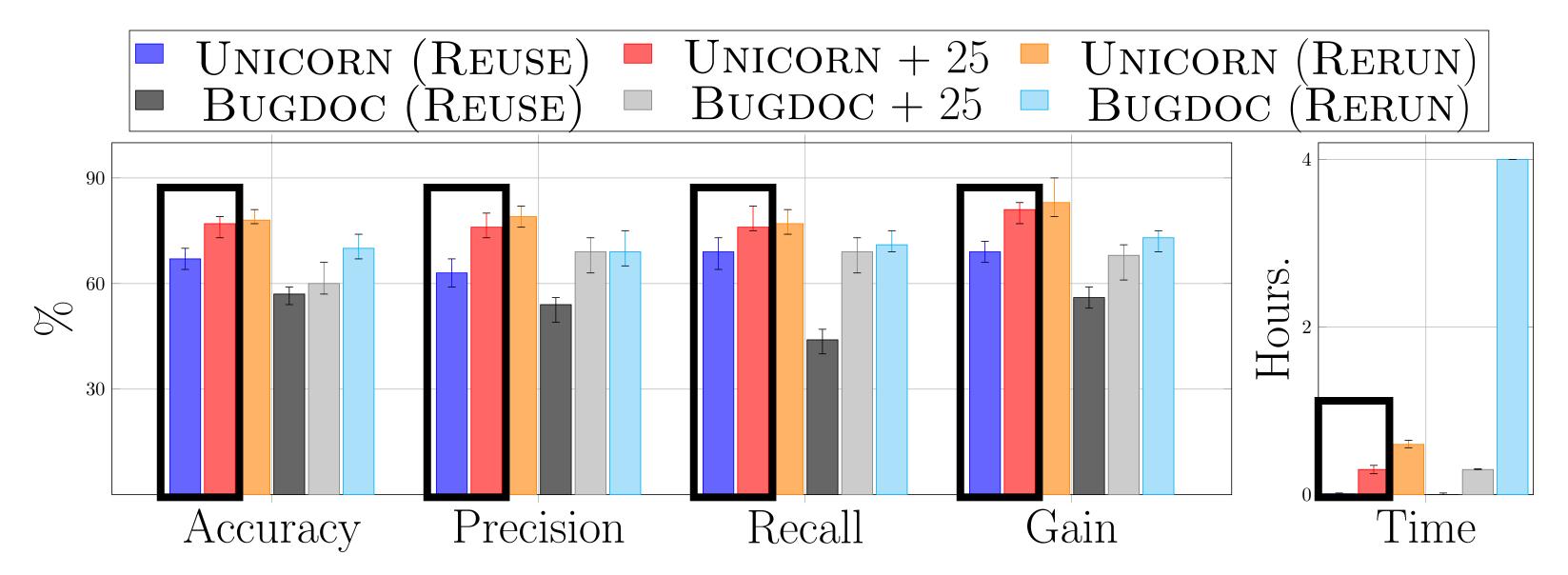
Results: Transferability





UNICORN finds configuration with higher gain when workload changes.

Results: Transferability





UNICORN quickly fixes the bug and achieves higher gain, accuracy, precision and recall when hardware changes

98



Results: Scalability

							Time	e/Fault	t (in sec.)
System	Configs	Events	Paths	Queries	Degree	Gain (%)	Discovery	Query Eval	Total
SQLite	34	19	32	191	3.6	93	9	14	291
	242	19	111	2234	1.9	94	57	129	1345
	242	288	441	22372	1.6	92	111	854	5312
Deepstream	53	19	43	497	3.1	86	16	32	1509
	53	288	219	5008	2.3	85	97	168	3113

Discovery time, query evaluation time and total time do not increase exponentially as the number of configuration options and systems events are increased



Results: Scalability

							Time	e/Fault	t (in sec.)
System	Configs	Events	Paths	Queries	Degree	Gain (%)	Discovery	Query Eval	Total
SQLite	34	19	32	191	3.6	93	9	14	291
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	53	288	219	5008	2.3	85	97	168	3113

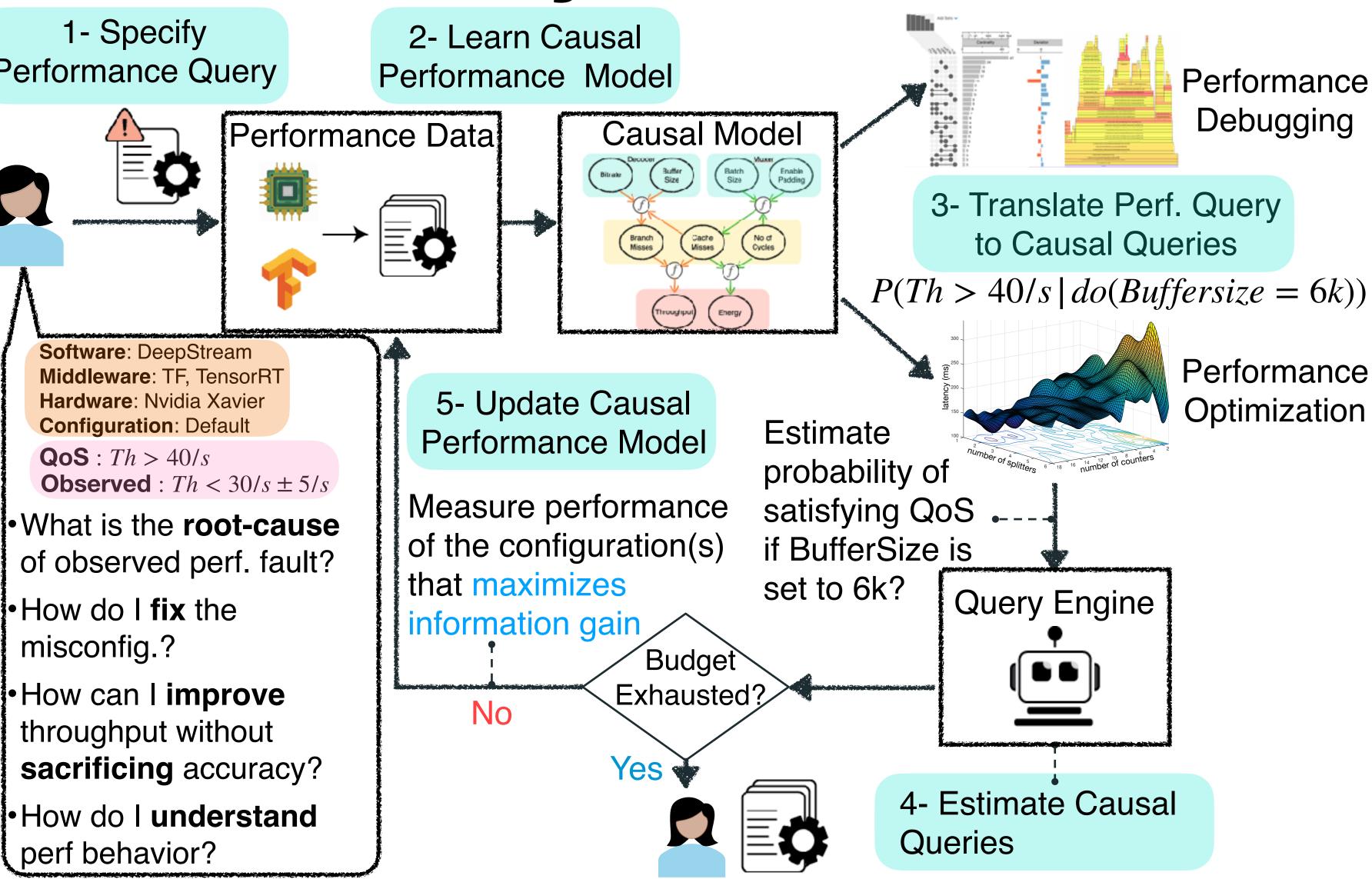
Causal graphs are

sparse

Summary: Causal AI for Systems

- 1. Learning a causal performance model for different downstream systems tasks.
- 2. The learned causal model is **transferable** across different environments.
- 3. The causal reasoning approach is scalable to largescale systems.

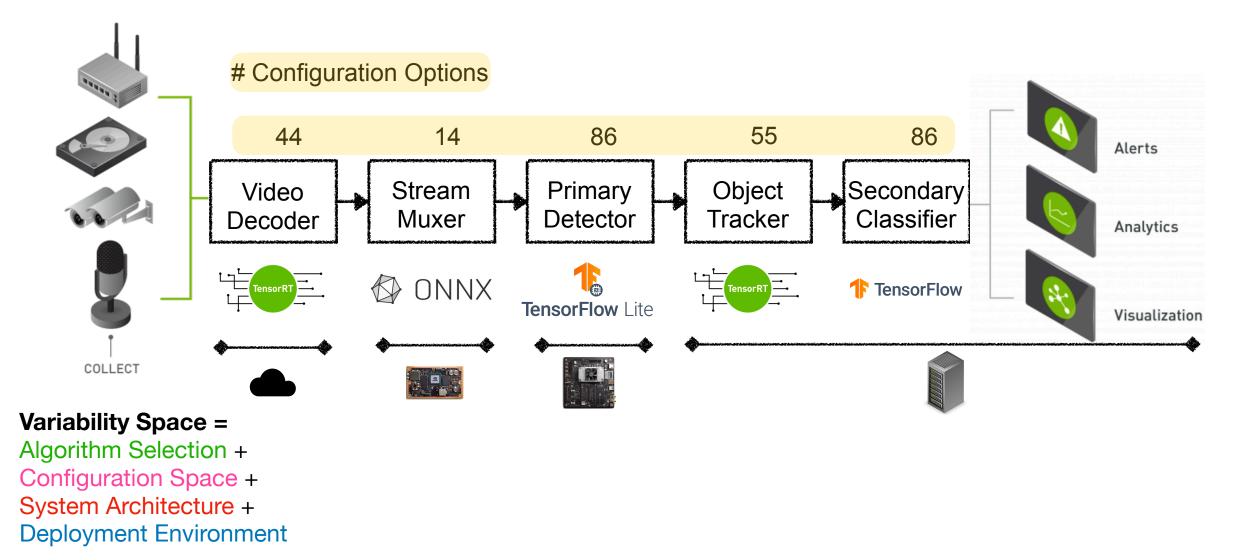
1- Specify Performance Query



101

The variability space of today's systems is exponentially increasing Causal performance models produce correct explanations

Systems are heterogeneous, multiscale, multi-modal, and multi-stream



Evaluation: Experimental Setup

Hardware

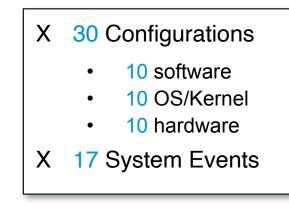
1	Nvidia TX1
CPU	4 cores, 1.3 GHz
GPU	128 Cores, 0.9 GHz
Memory	4 Gb, 25 GB/s

CPU	6 cores, 2 GHz									
GPU	256 Cores, 1.3 GHz									
Memory	8 Gb, 58 GB/s									

NI 1.11. **T**M

N	vidia Xavier						
CPU	8 cores, 2.26 GHz						
GPU	512 cores, 1.3 GHz						
Memory	32 Gb, 137 GB/s						

Configuration Space



Systems

Xception

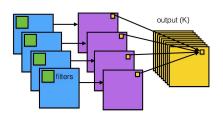


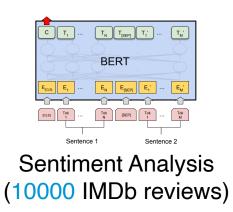
Image recognition (50,000 test images)

DeepSpeech



Voice recognition (5 sec. audio clip)

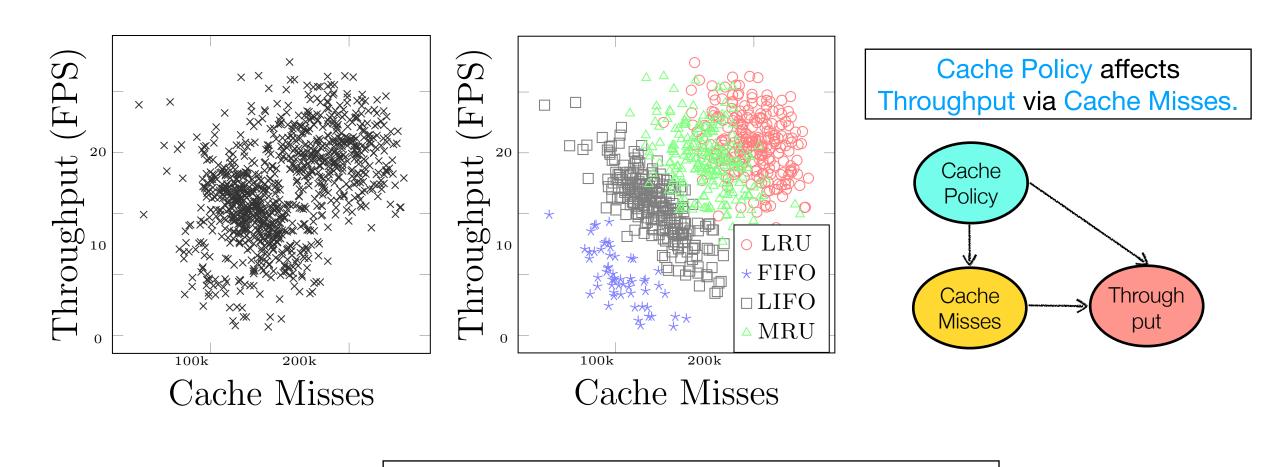
BERT



x264

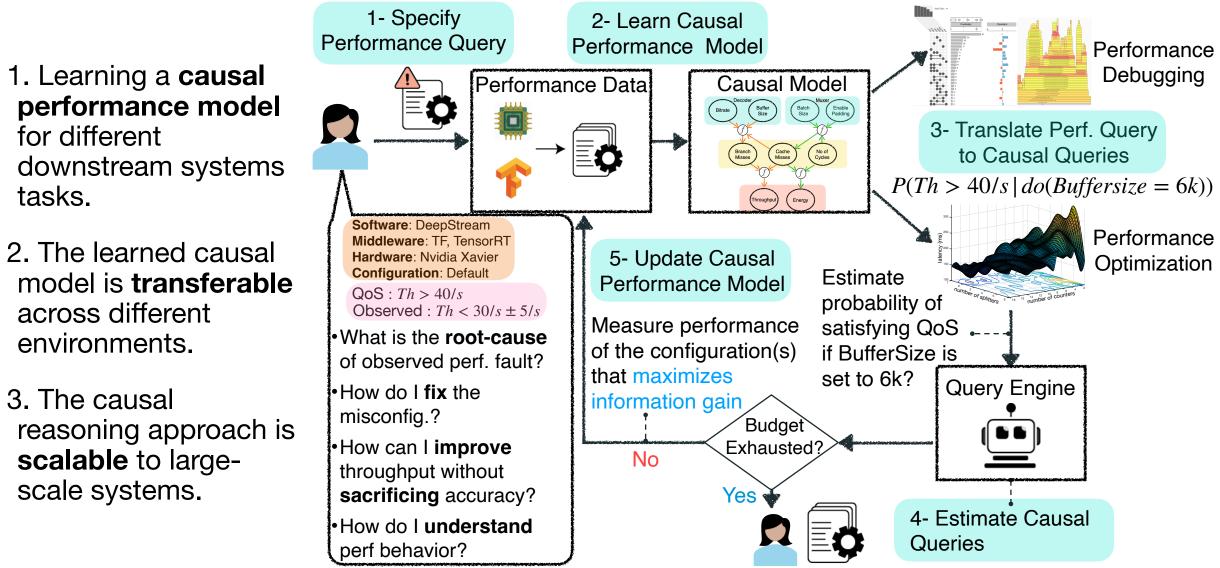


Video Encoder (11 Mb, 1080p video)



Causal performance models capture correct interactions.

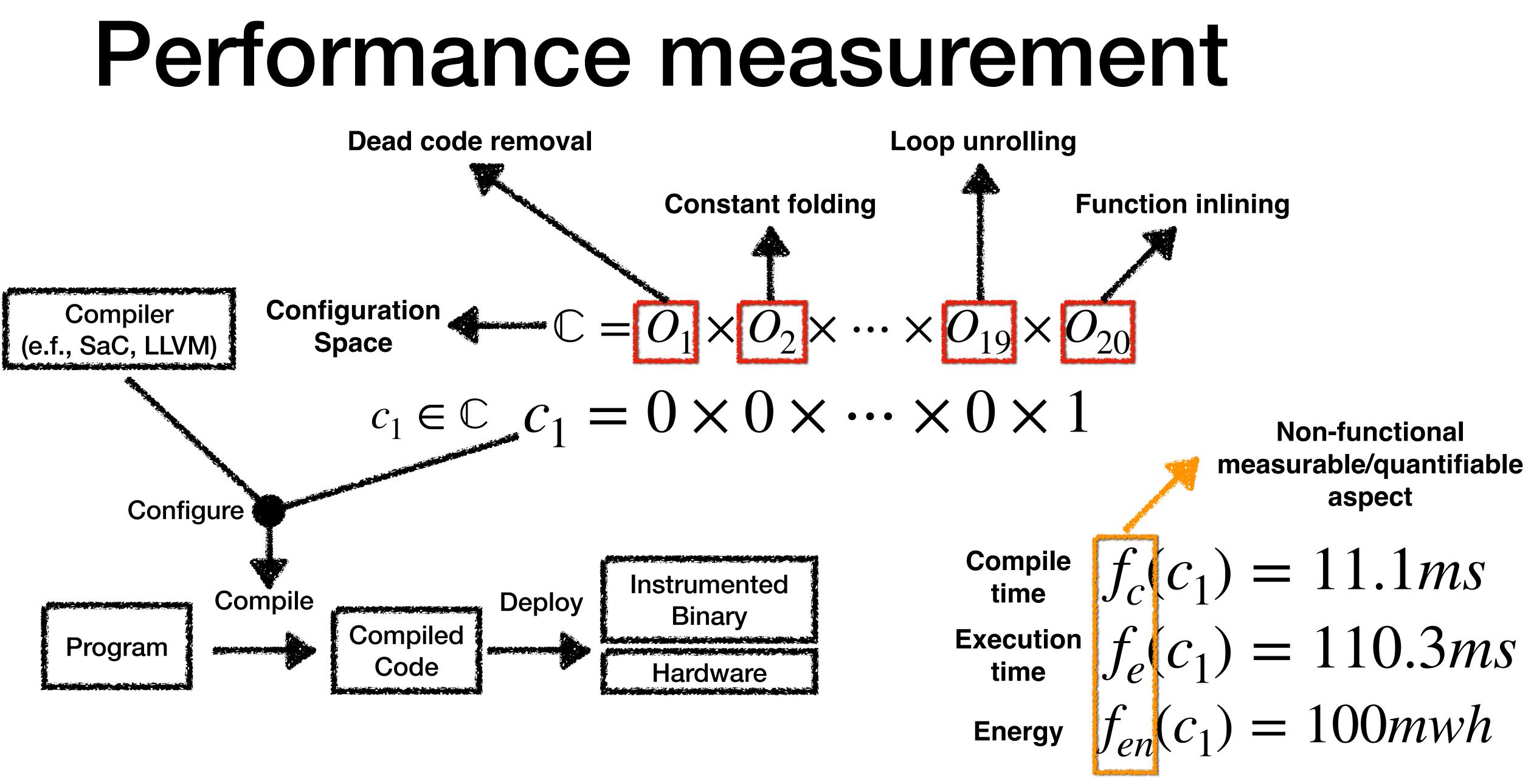
Summary: Causal AI for Systems



tasks.

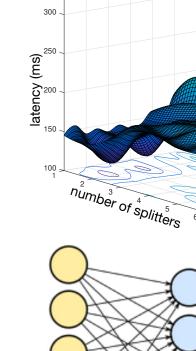


How to resolve these issues faster?

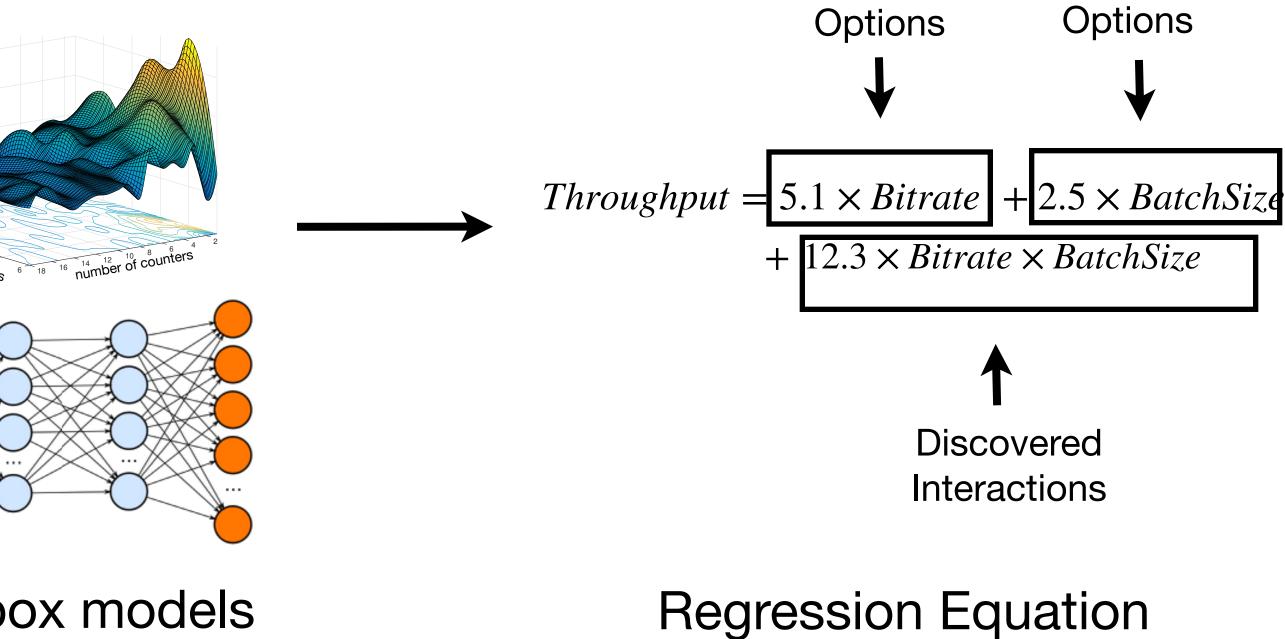


Performance Influence Models

		Enable Padding	 Cache Misses	 Through put (fps)
C ₁	1k	1	 42m	 7
C ₂	2k	1	 32m	 22
Cn	5k	0	 12m	 25



Observational Data

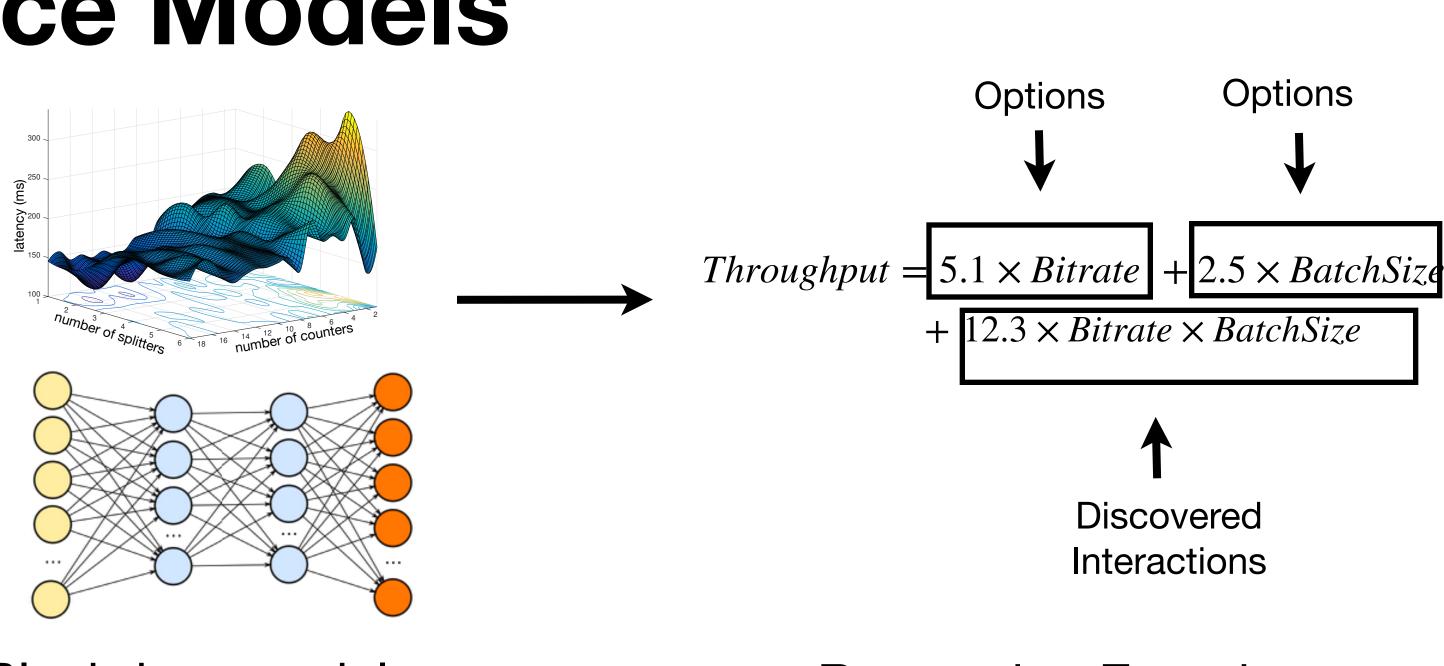


Black-box models

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Performance Influence Models

		Enable Padding	 Cache Misses	 Through put (fps)
C ₁	1k	1	 42m	 7
C ₂	2k	1	 32m	 22
Cn	5k	0	 12m	 25



Observational Data

These methods rely on statistical correlations to extract meaningful information required for performance tasks.

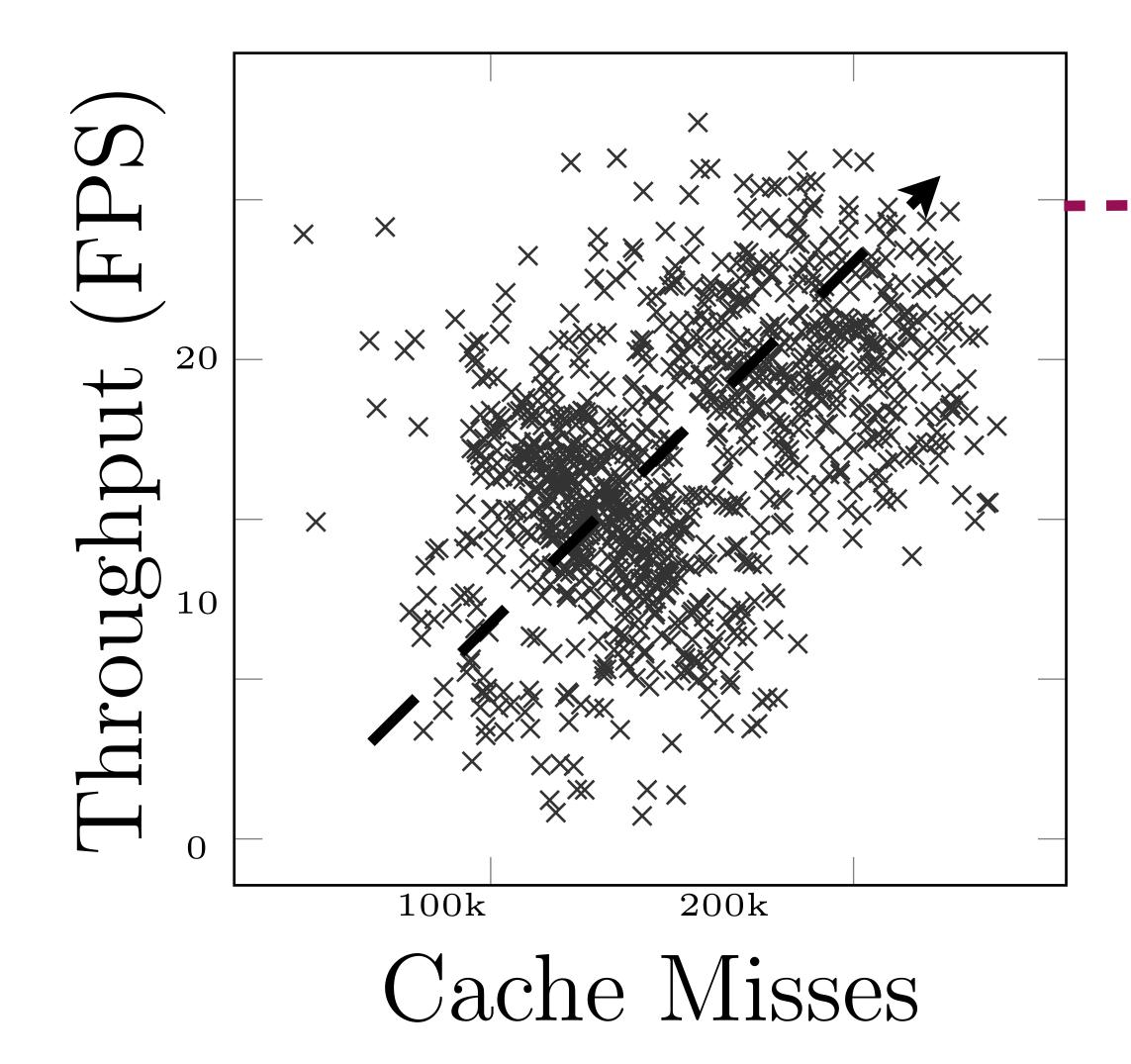
Black-box models

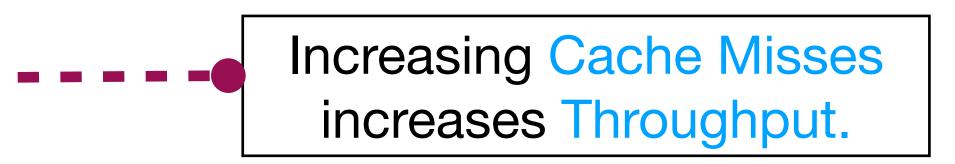
Regression Equation

Performance Influence Models suffer from several shortcomings

- Performance influence models could produce incorrect explanations
- Performance influence models could produce unreliable predictions.
- Performance influence models could produce unstable predictions across environments and in the presence of measurement noise.

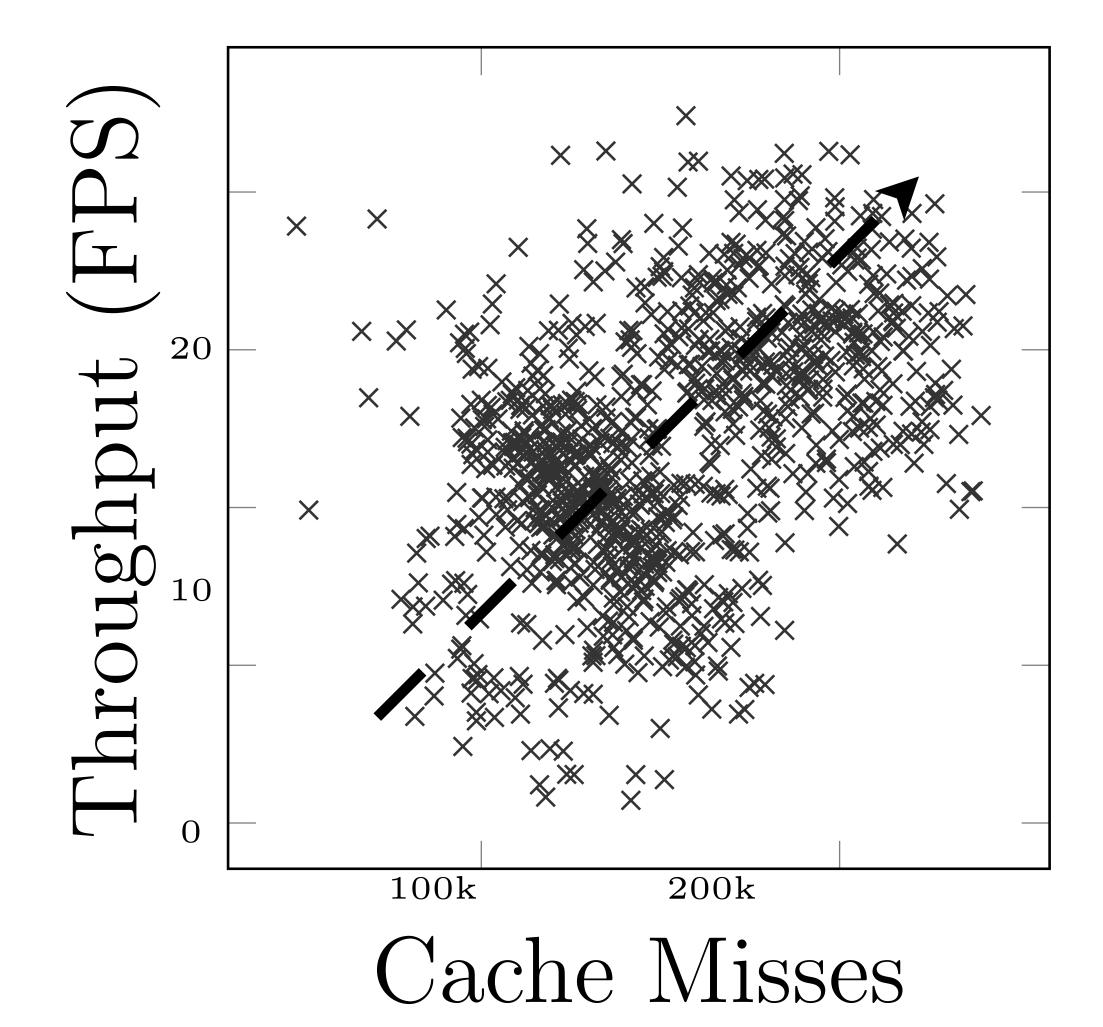
Performance Influence Models Issue: Incorrect Explanation



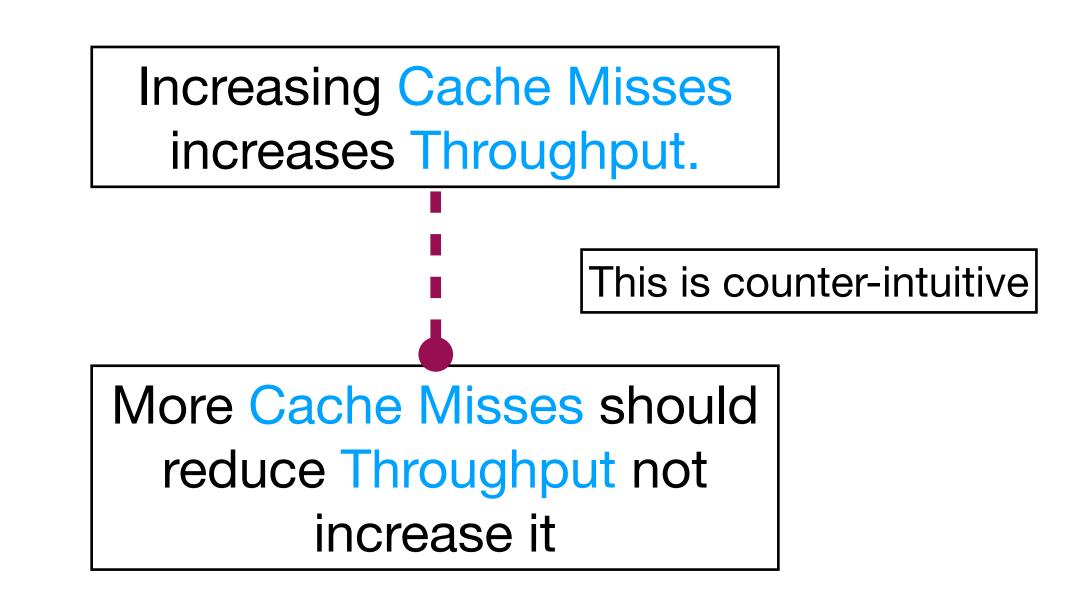




Performance Influence Models Issue: Incorrect Explanation

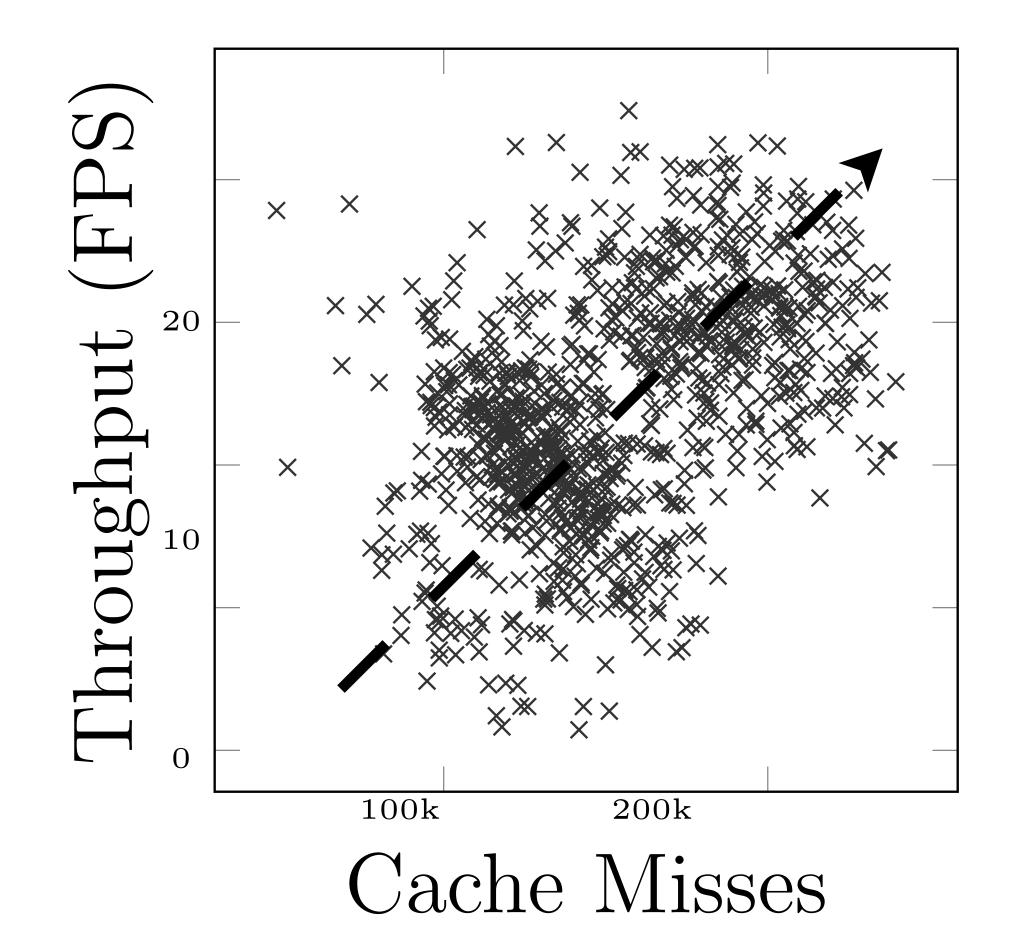




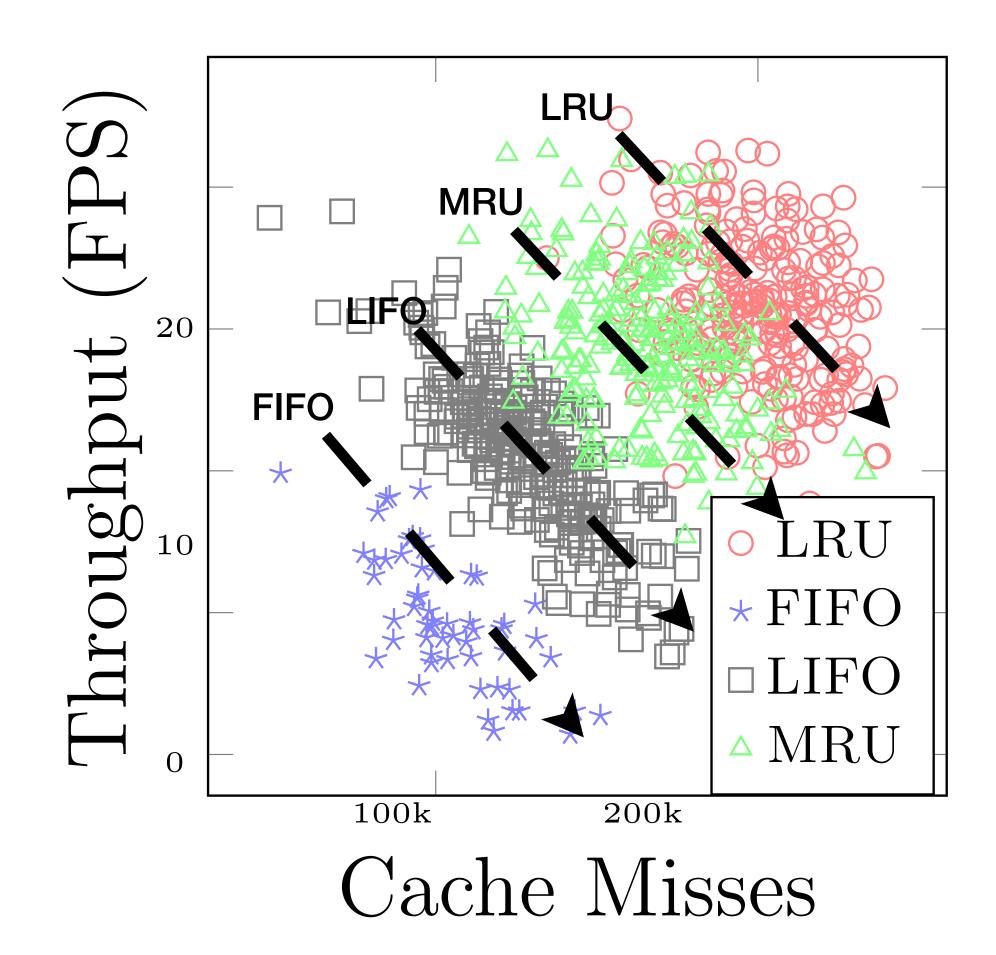




Performance Influence Models Issue: Incorrect Explanation







Segregating data on Cache Policy indicates that within each group **Increase of Cache Misses result in a decrease in Throughput.**



Performance Influence Models Issue: Unstable Predictors

Performance influence model in TX2.

 $+6.2 \times Bitrate \times EnablePadding + 4.1 \times Bitrate \times BufferSize \times EnablePadding$

Performance influence model in Xavier.

Throughput = $5.1 \times Bitrate + 2.5 \times BatchSize + 12.3 \times Bitrate \times BatchSize$





Performance Influence Models change significantly in new environments resulting in less accuracy.



Performance Influence Models Issue: Unstable Predictors

Performance influence model in TX2.

 $+6.2 \times Bitrate \times EnablePadding + 4.1 \times Bitrate \times BufferSize \times EnablePadding$

Performance influence model in Xavier.

Throughput = $5.1 \times Bitrate$ + $2.5 \times BatchSize$ + $12.3 \times Bitrate \times BatchSize$



Throughput = $2 \times Bitrate + 1.9 \times BatchSize + 1.8 \times BufferSize + 0.5 \times EnablePadding + 5.9 \times Bitrate \times BufferSize$

Performance influence are cannot be reliably used across environments.



Performance Influence Models Issue: Non-generalizability

Performance influence model in TX2

Throughput = $2 \times Bitrate + 1.9 \times BatchSize + 1.8 \times BufferSize + 0.5 \times EnablePadding + 5.9 \times Bitrate \times BufferSize$ $+6.2 \times Bitrate \times EnablePadding + 4.1 \times Bitrate \times BufferSize \times EnablePadding$

Performance influence model in Xavier.

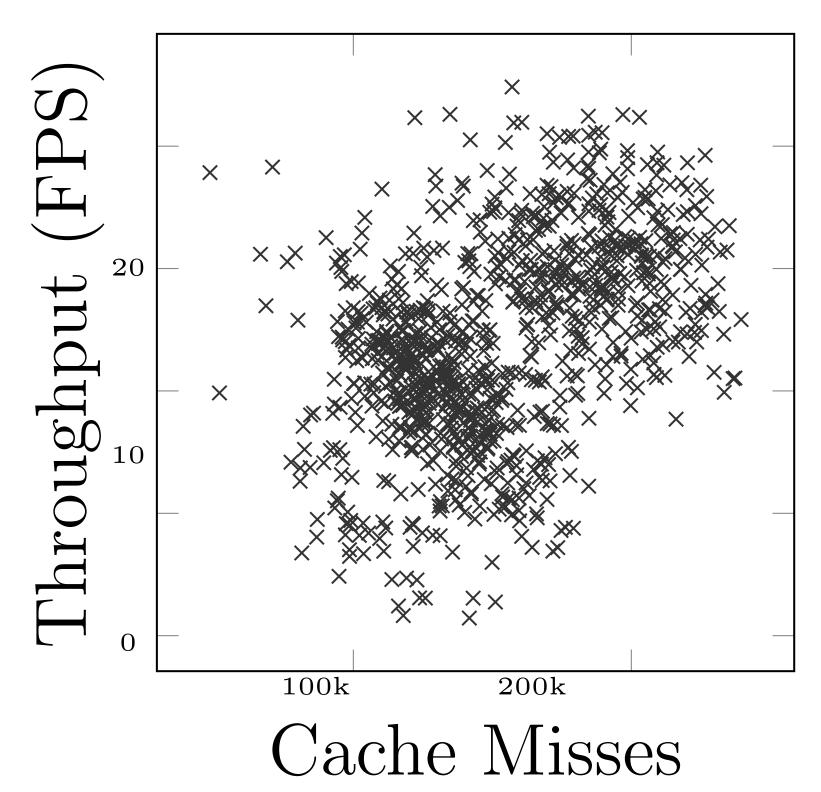
Throughput = $5.1 \times Bitrate + 2.5 \times BatchSize + 12.3 \times Bitrate \times BatchSize$

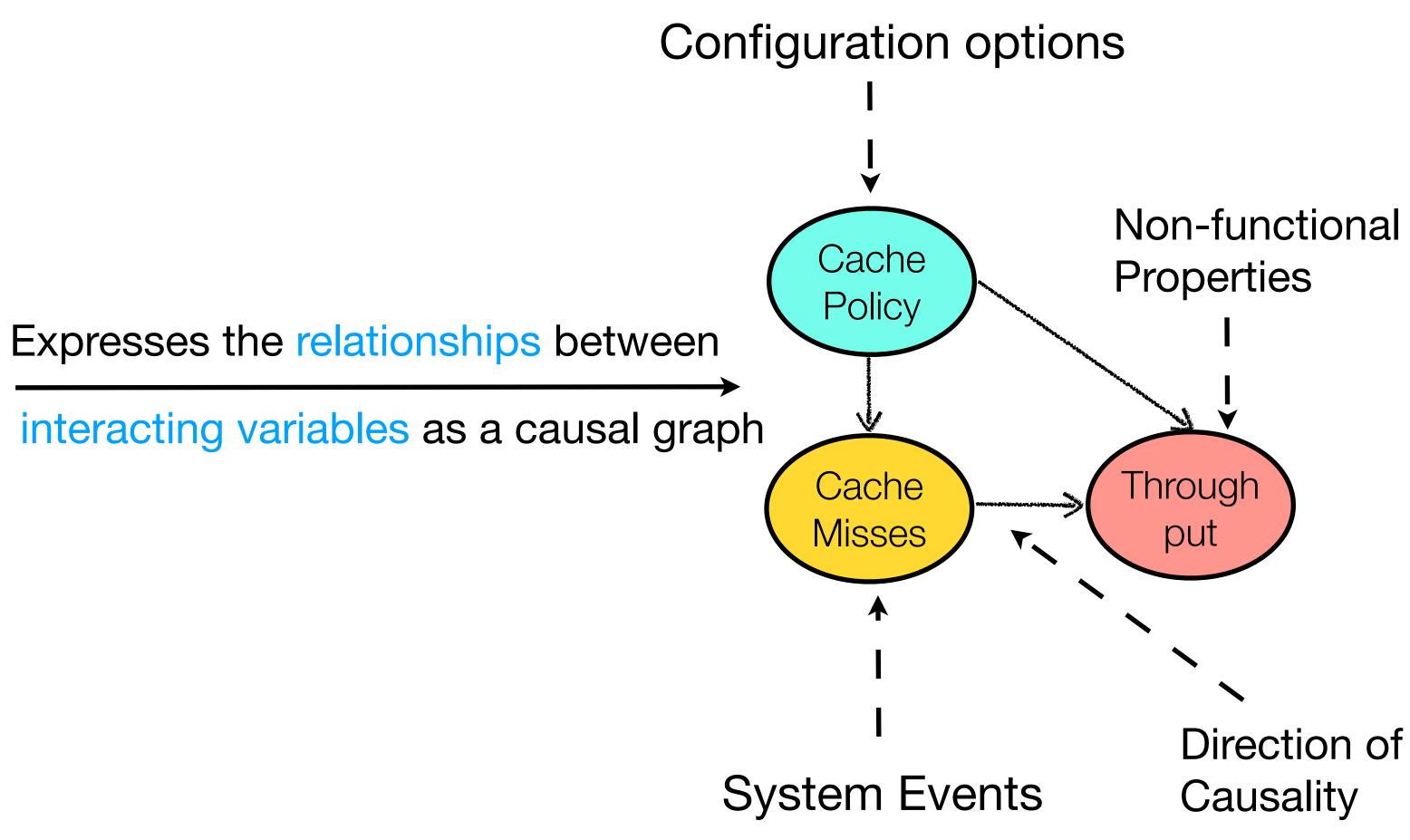


Performance influence models do not generalize well across deployment environments.

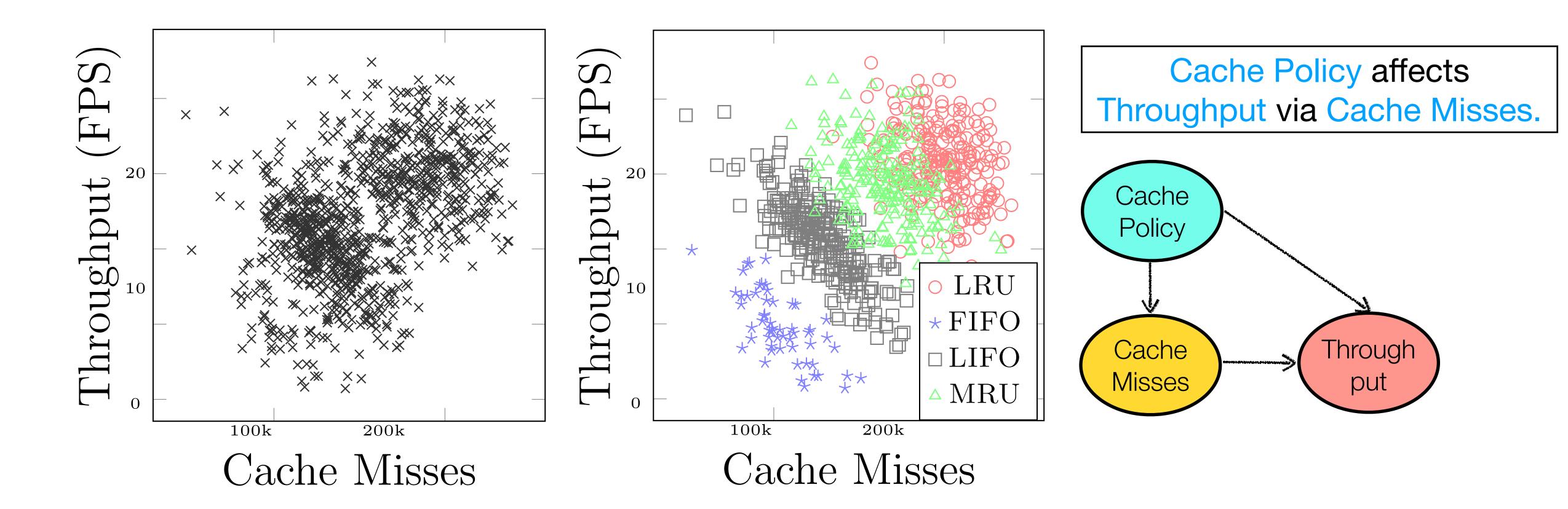


Causal Performance Model





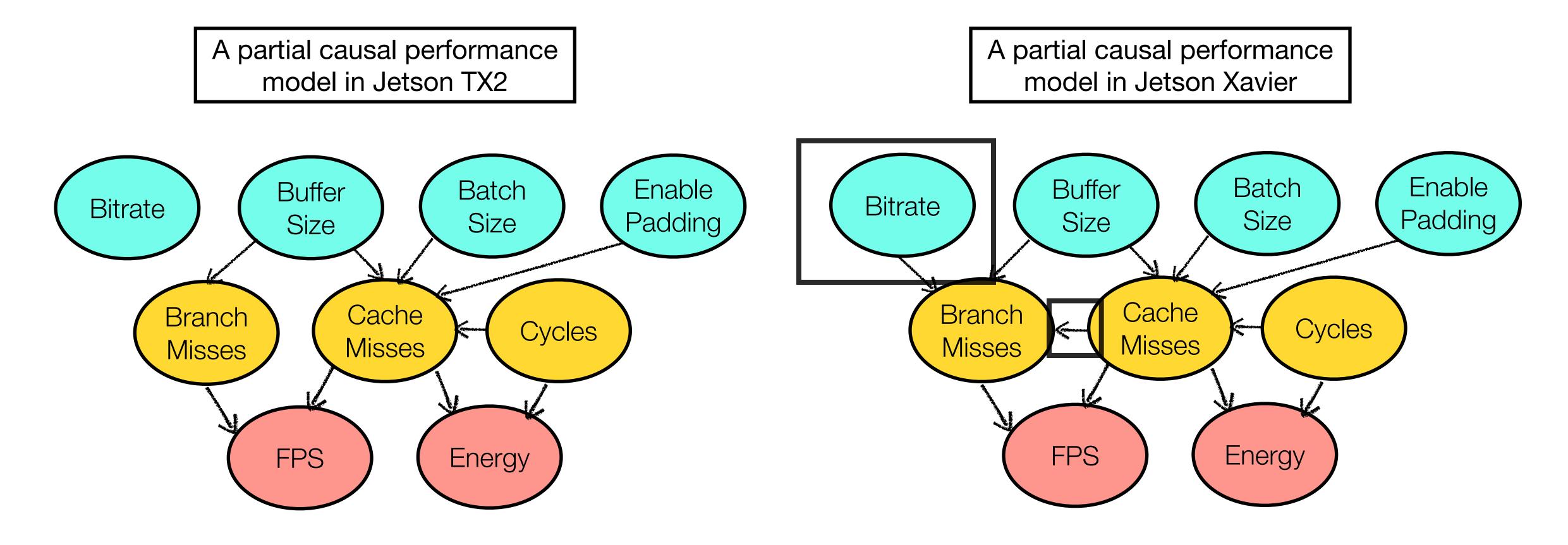
Why Causal Inference? - Produces Correct Explanations





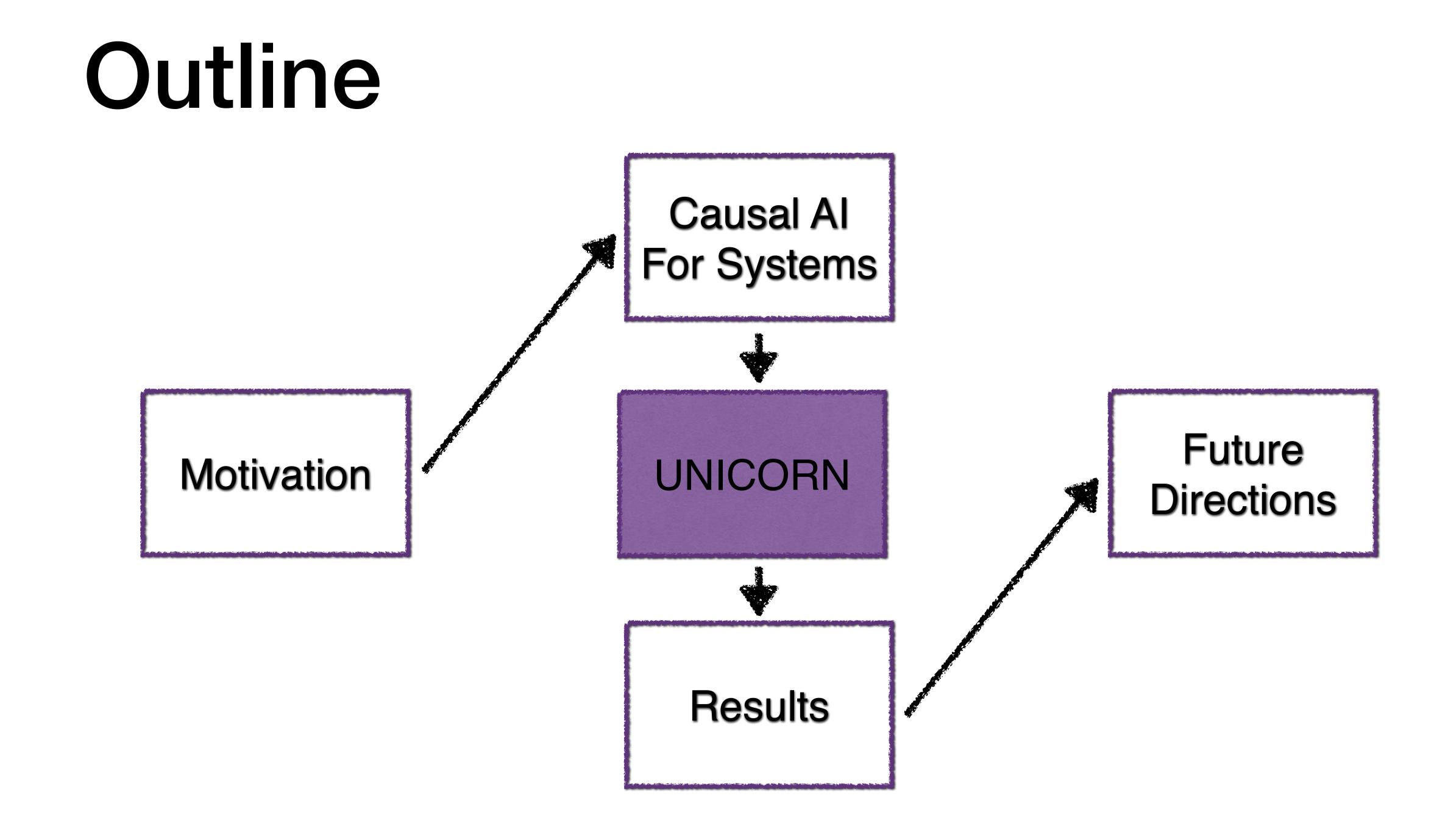
Causal Performance Models recovers the correct interactions.

Why Causal Inference? - Minimal Structure Change





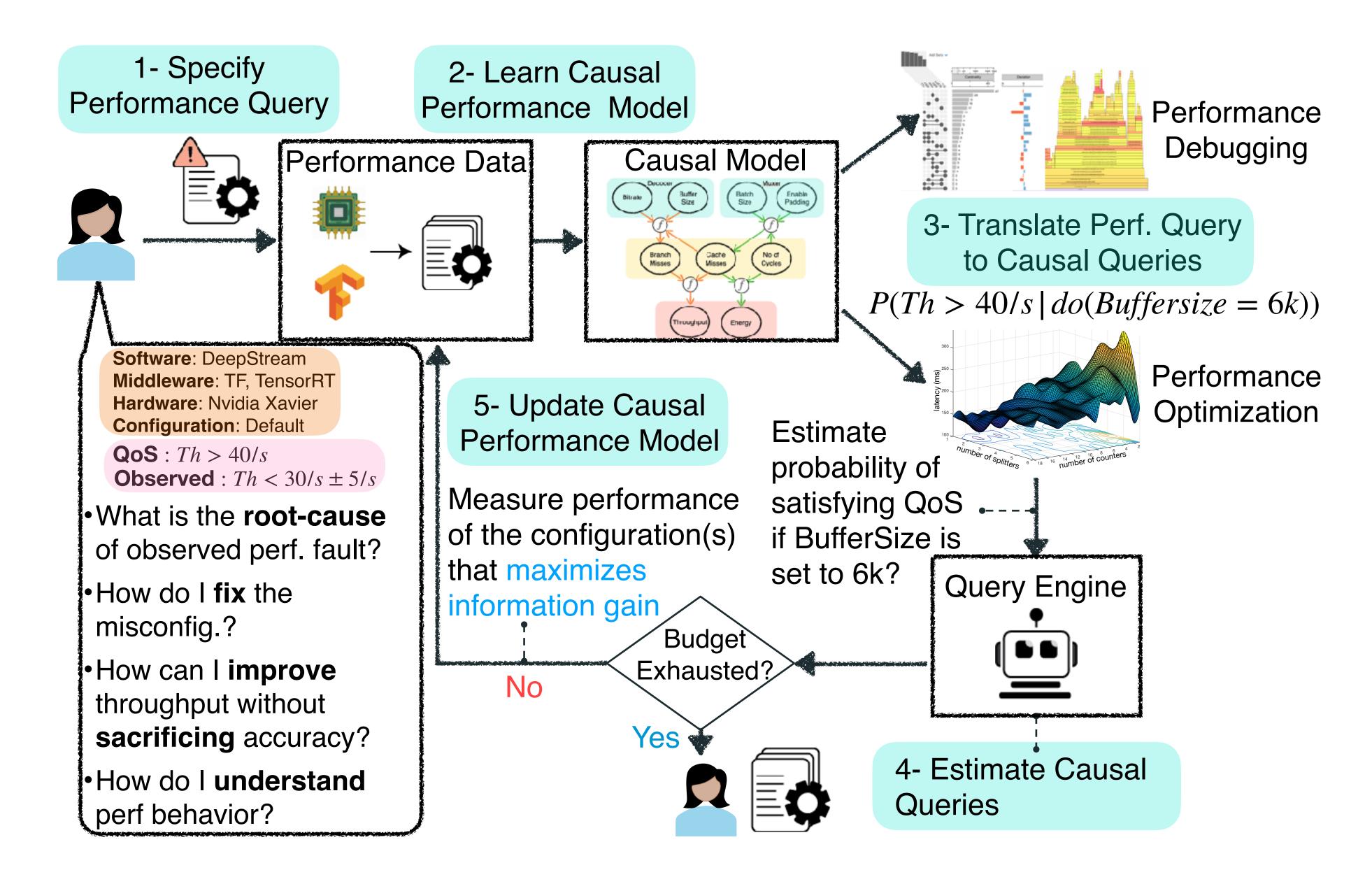
Causal models remain relatively stable



- Build a Causal Performance Model that capture the interactions options in the variability space using the observation performance data.
- Iterative causal performance model evaluation and model update
- Perform downstream performance tasks such as performance debugging & optimization using Causal Reasoning

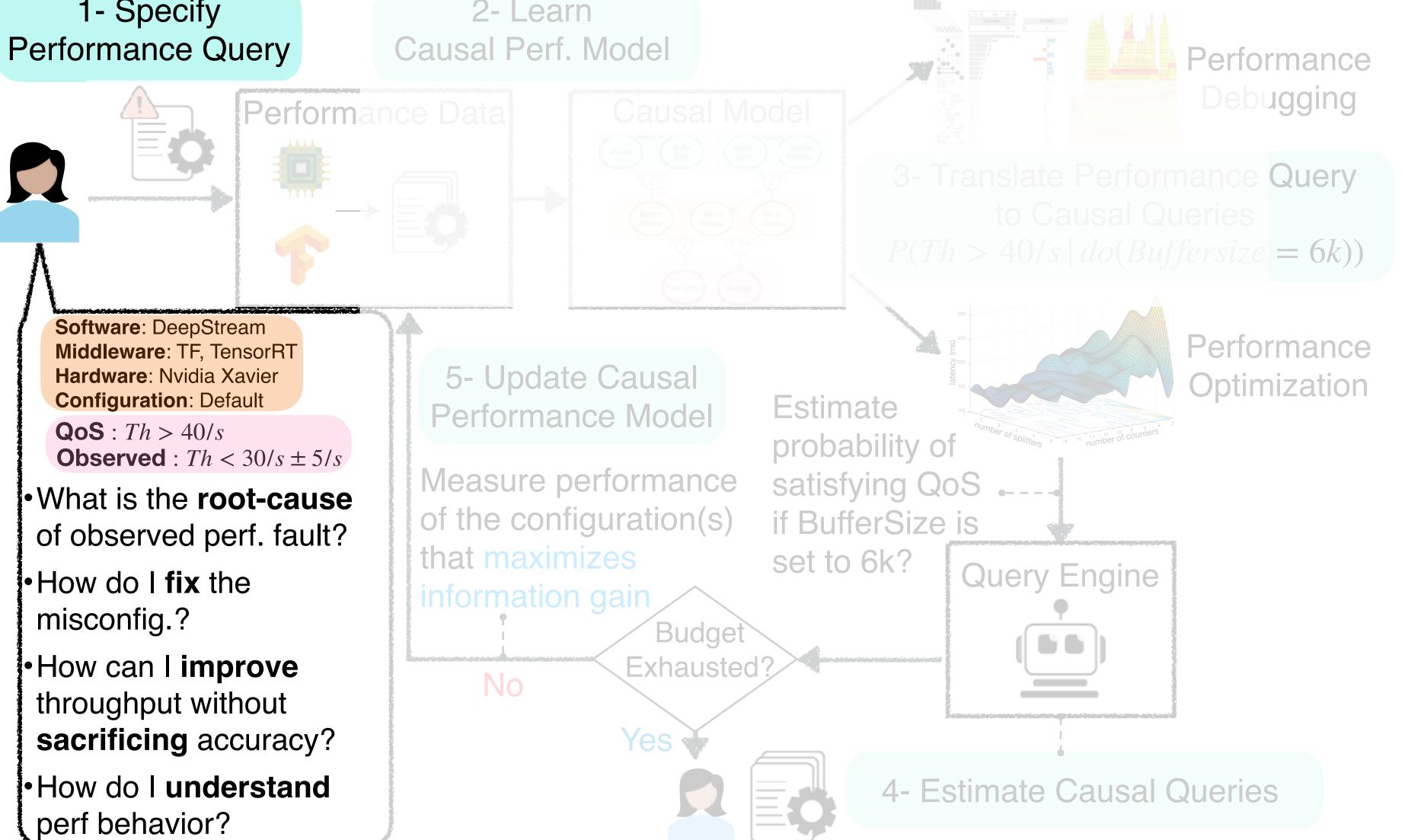


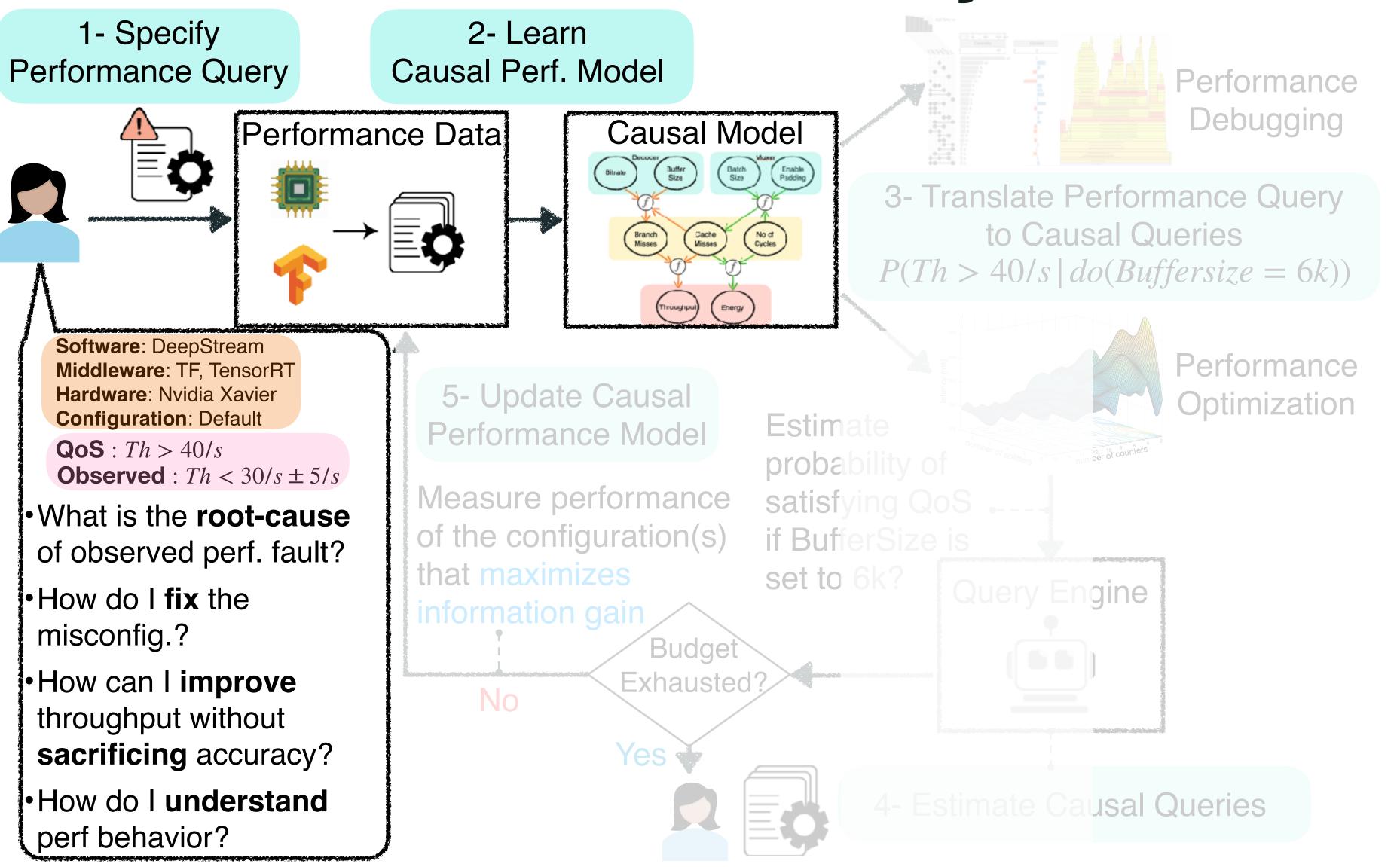




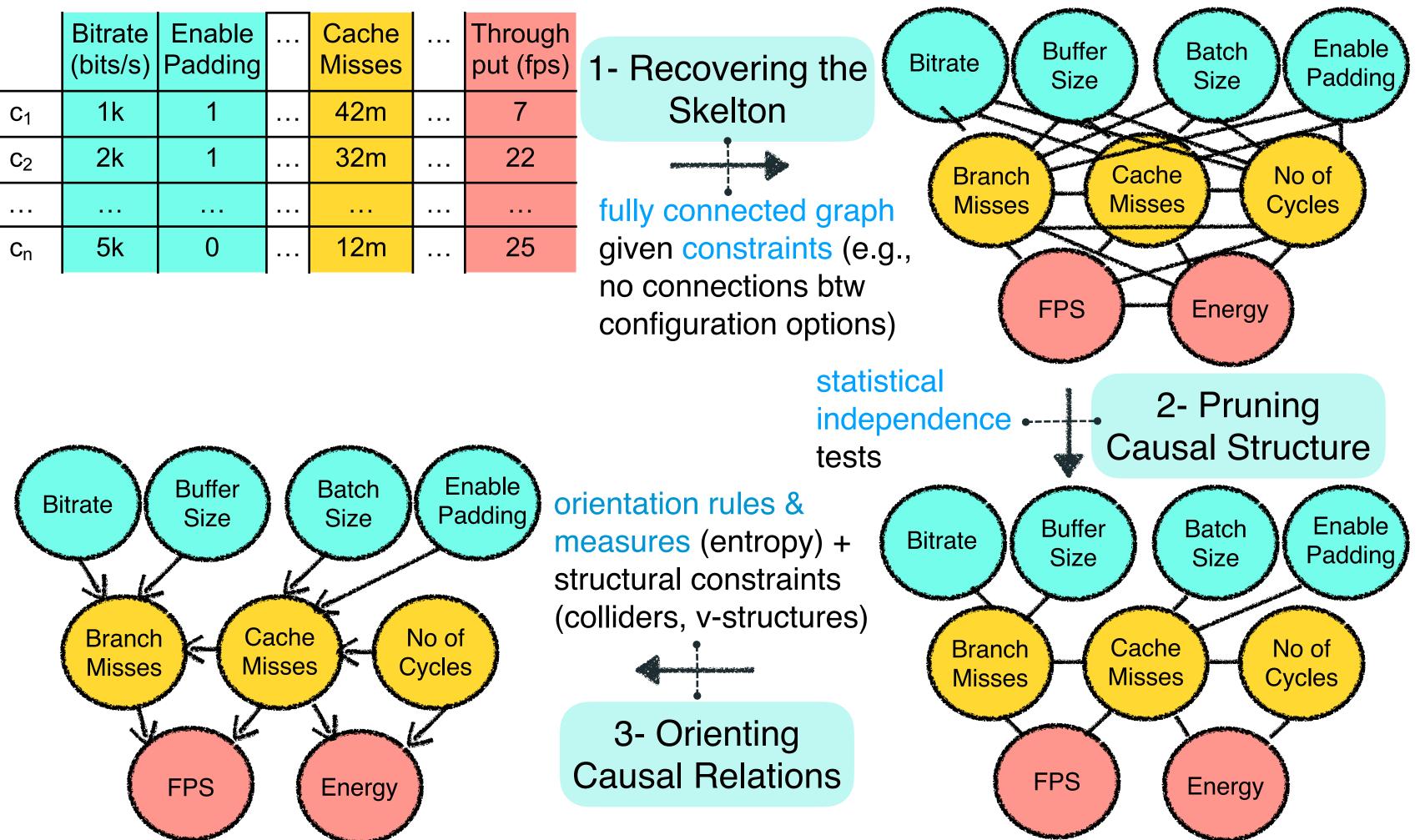
1- Specify

2- Learn

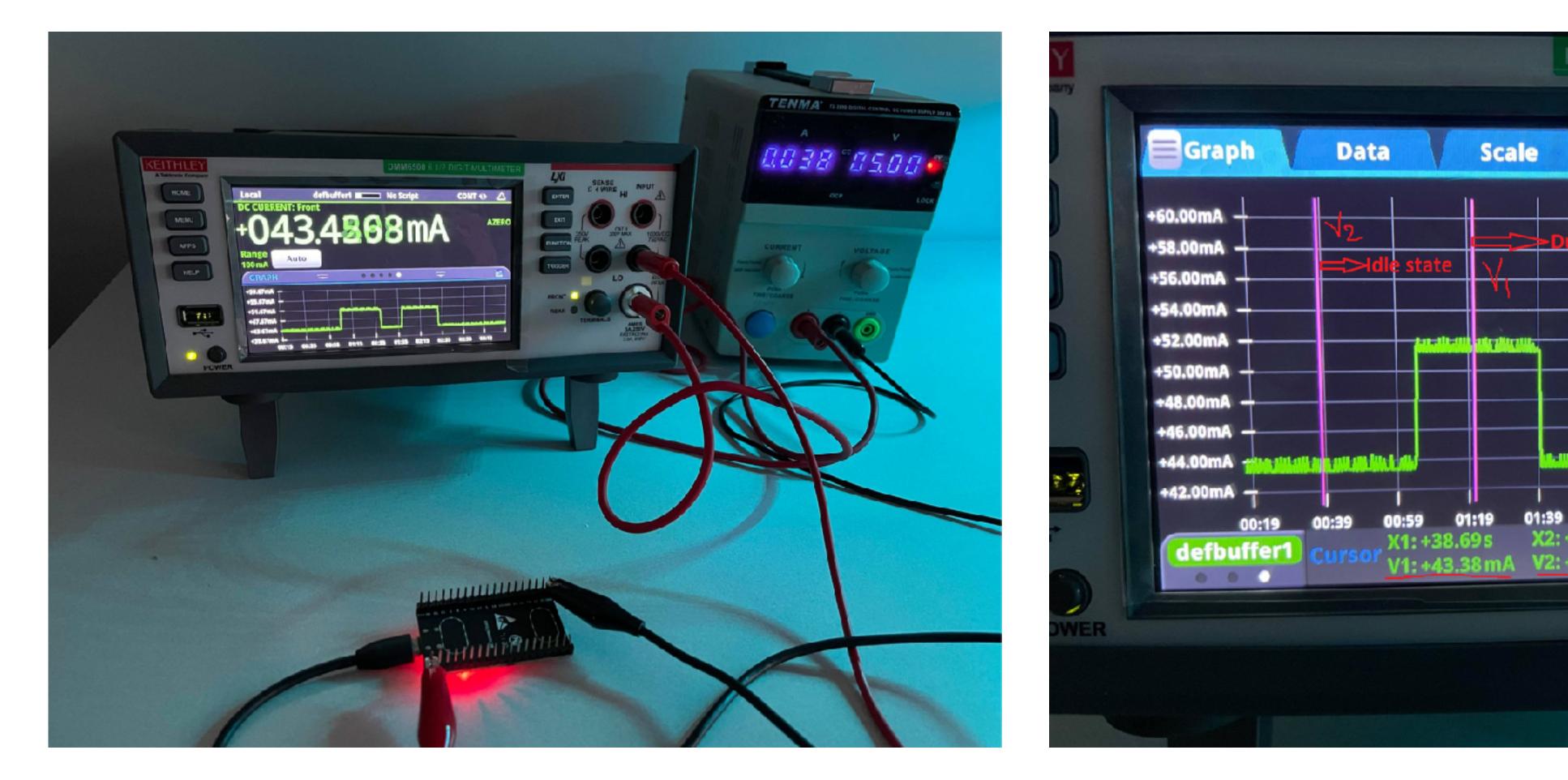




		Bitrate (bits/s)	Enable Padding	 Cache Misses	 Through put (fps)	1- Re
-	C ₁	1k	1	 42m	 7	
-	C ₂	2k	1	 32m	 22	
-				 	 	fully
_	Cn	5k	0	 12m	 25	giver
						no co



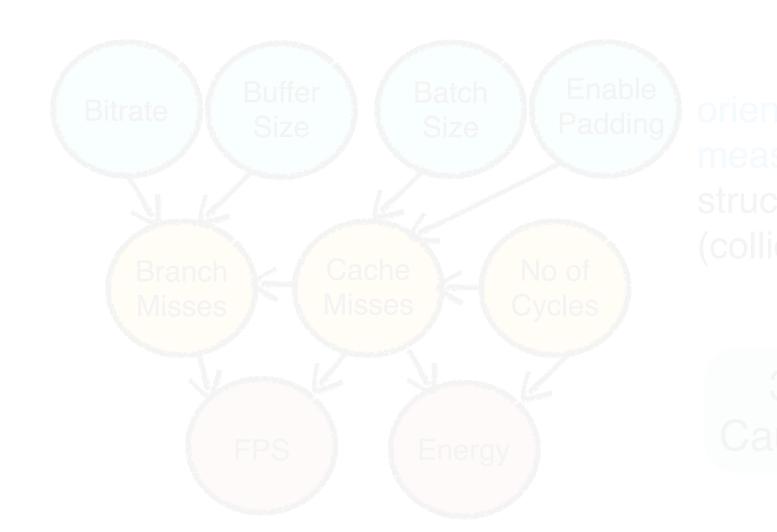
Our setup for performance measurements

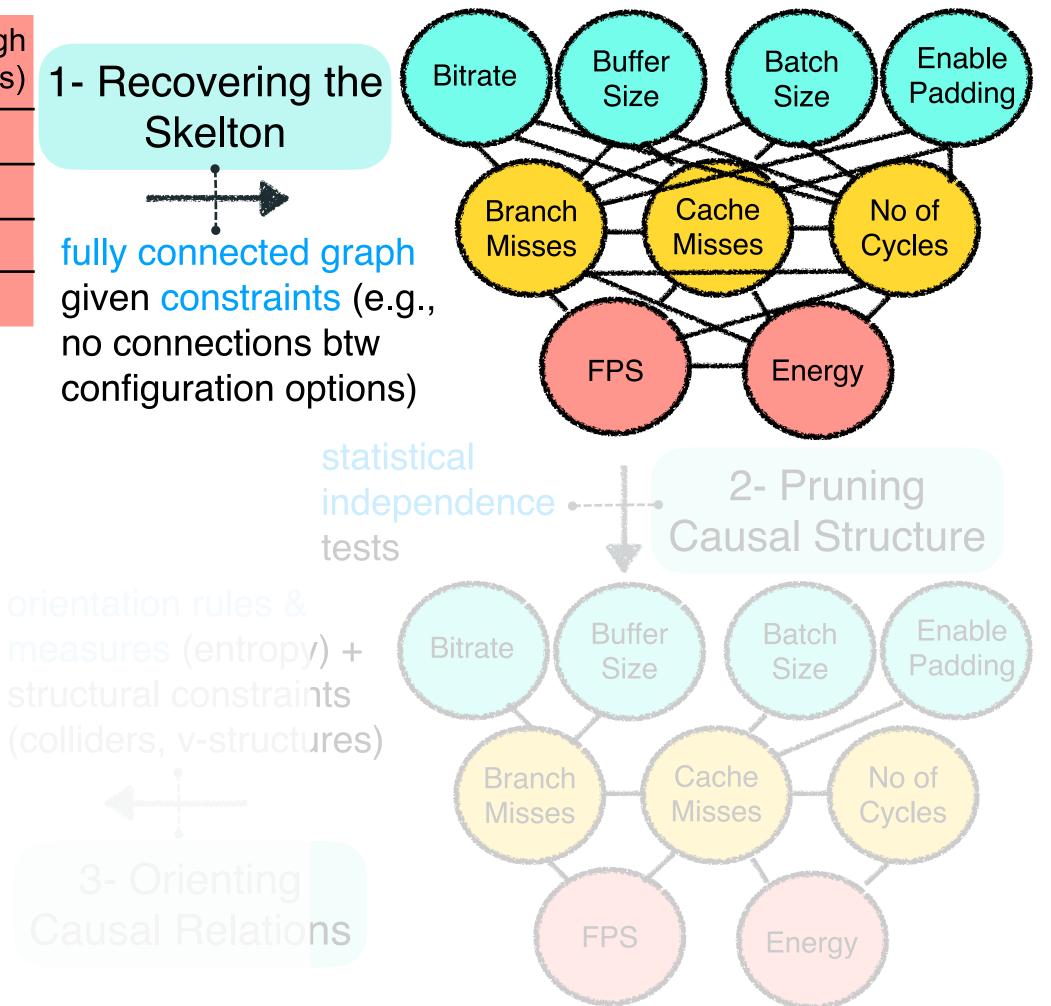




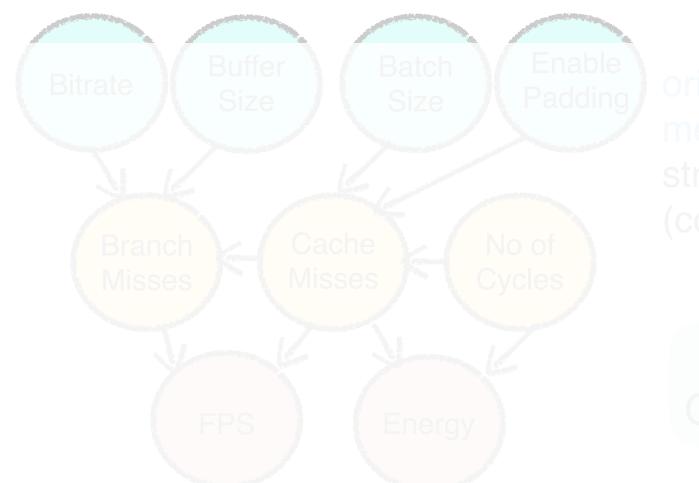


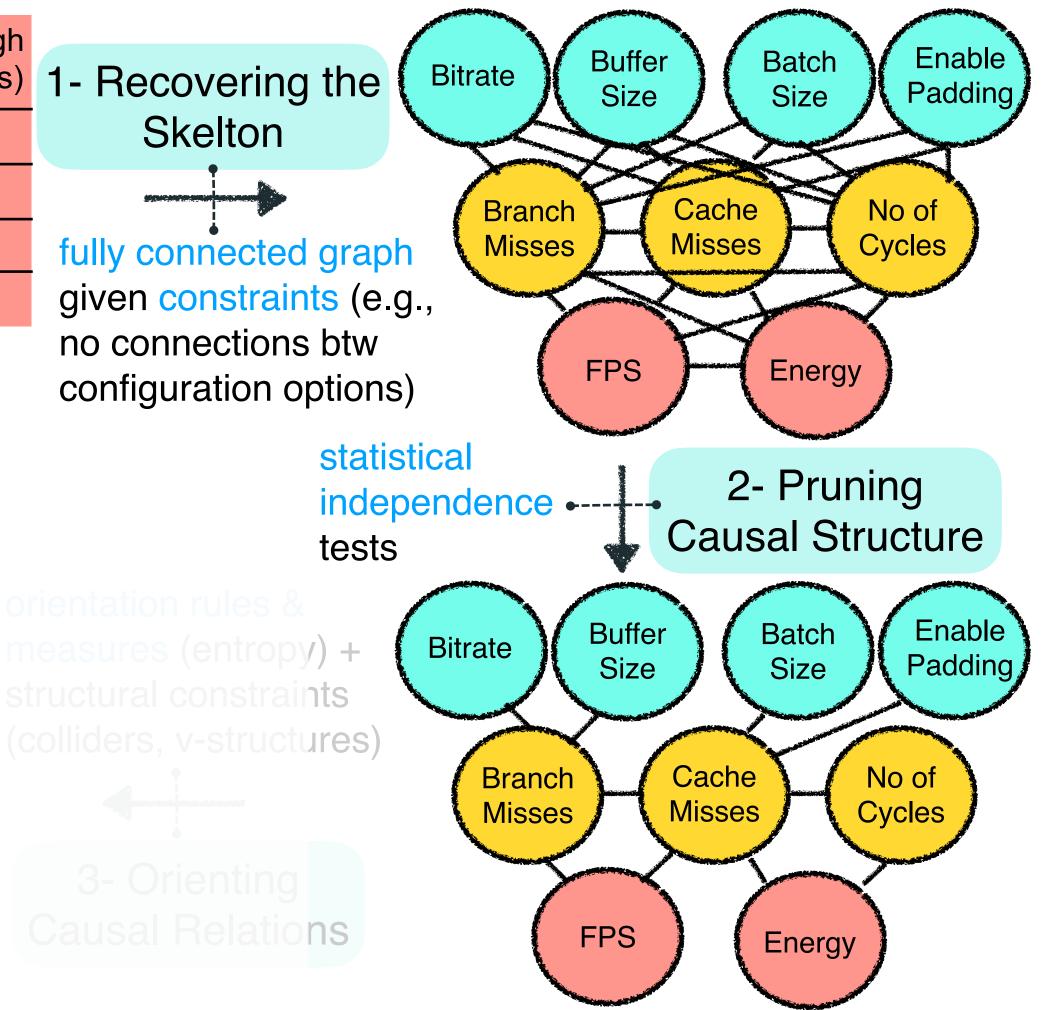
	Bitrate (bits/s)	Enable Padding		Cache Misses		Through put (fps)	1- Re
C ₁	1k	1		42m		7	
C ₂	2k	1		32m		22	
							fully
Cn	5k	0		12m		25	giver
	-		•		•		no co



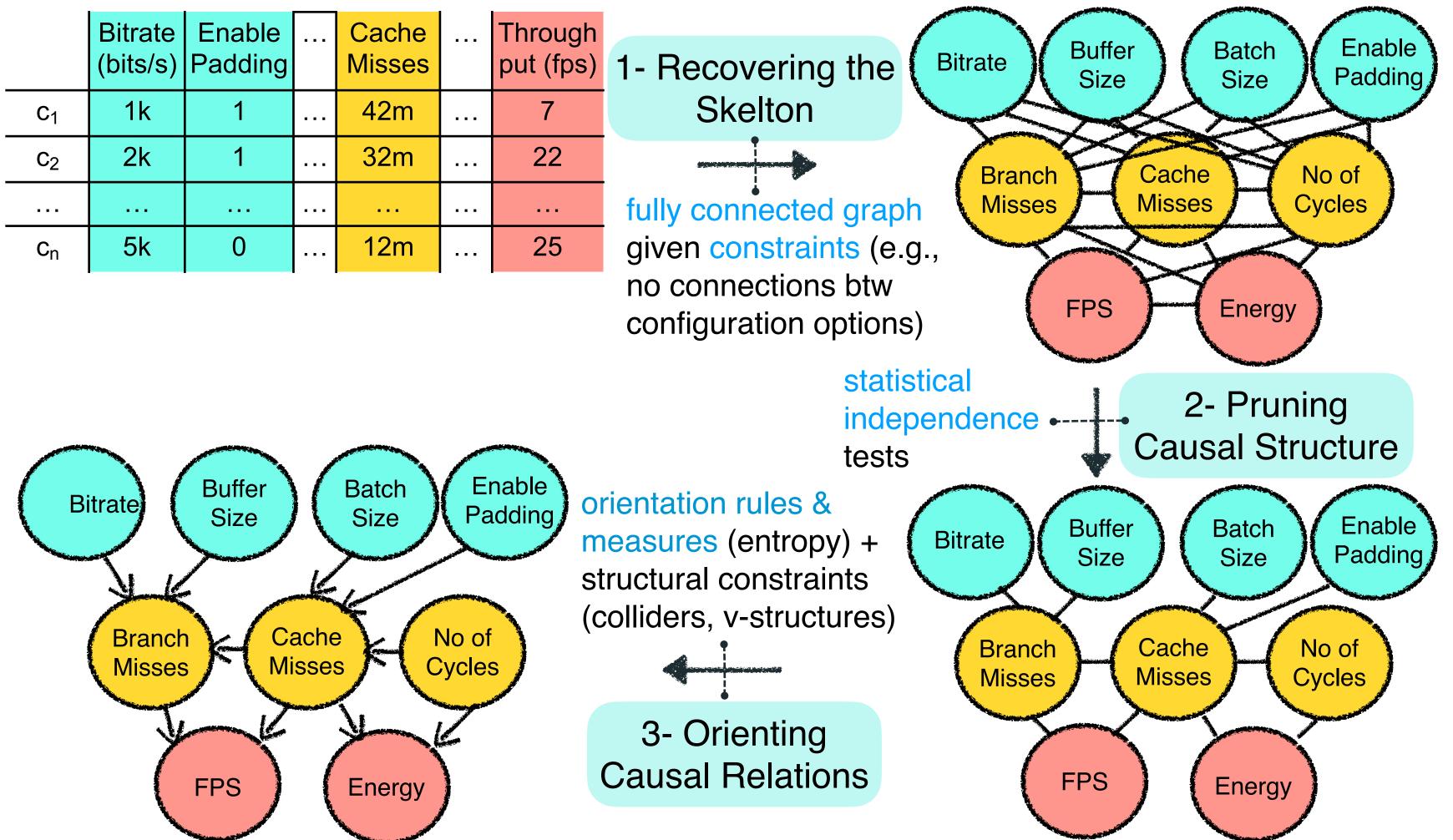


		Enable Padding		Cache Misses	 Through put (fps)	1- Re
C ₁	1k	1		42m	 7	
C ₂	2k	1		32m	 22	
					 	fully
Cn	5k	0		12m	 25	giver
			•			no co



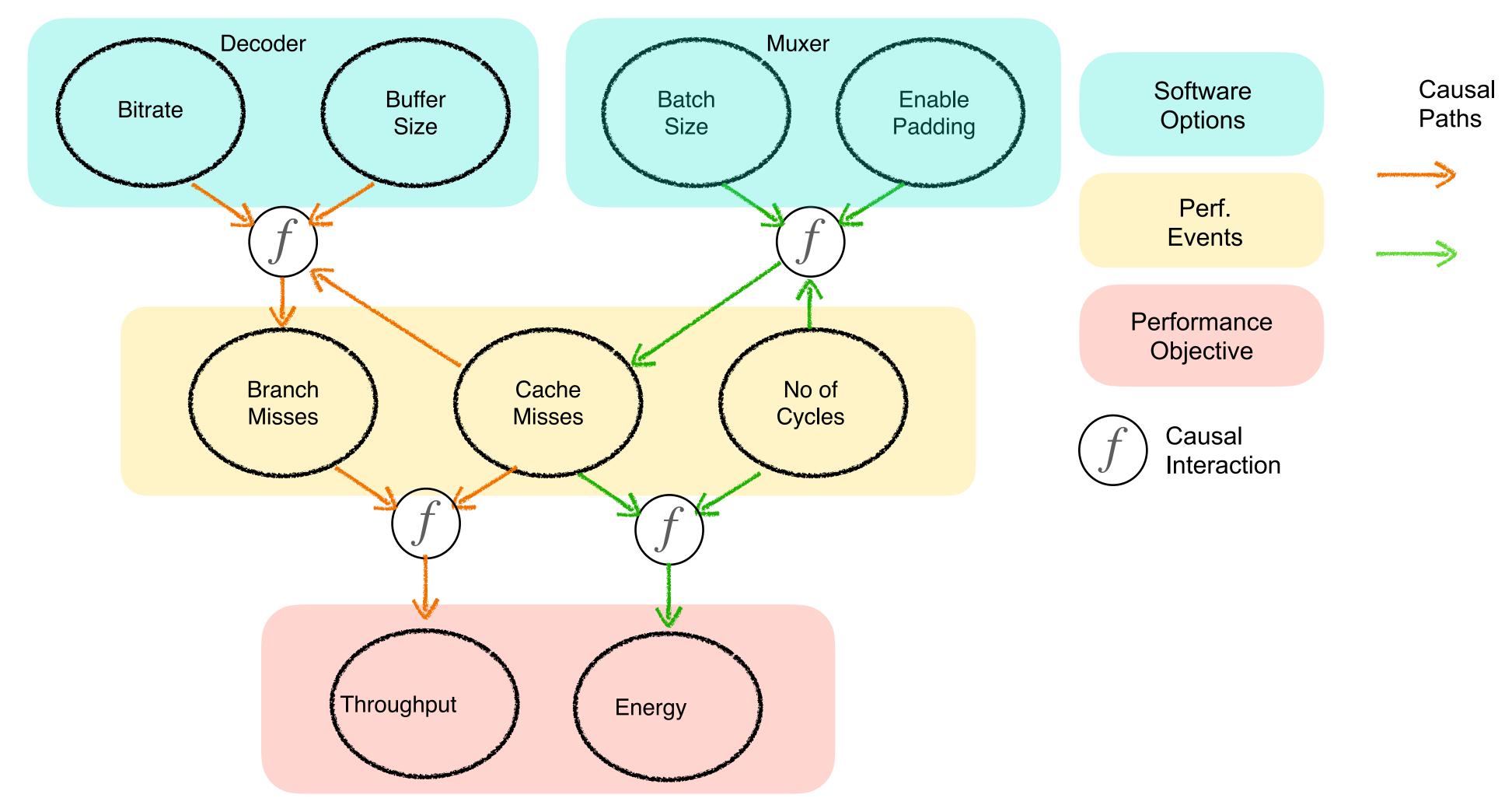


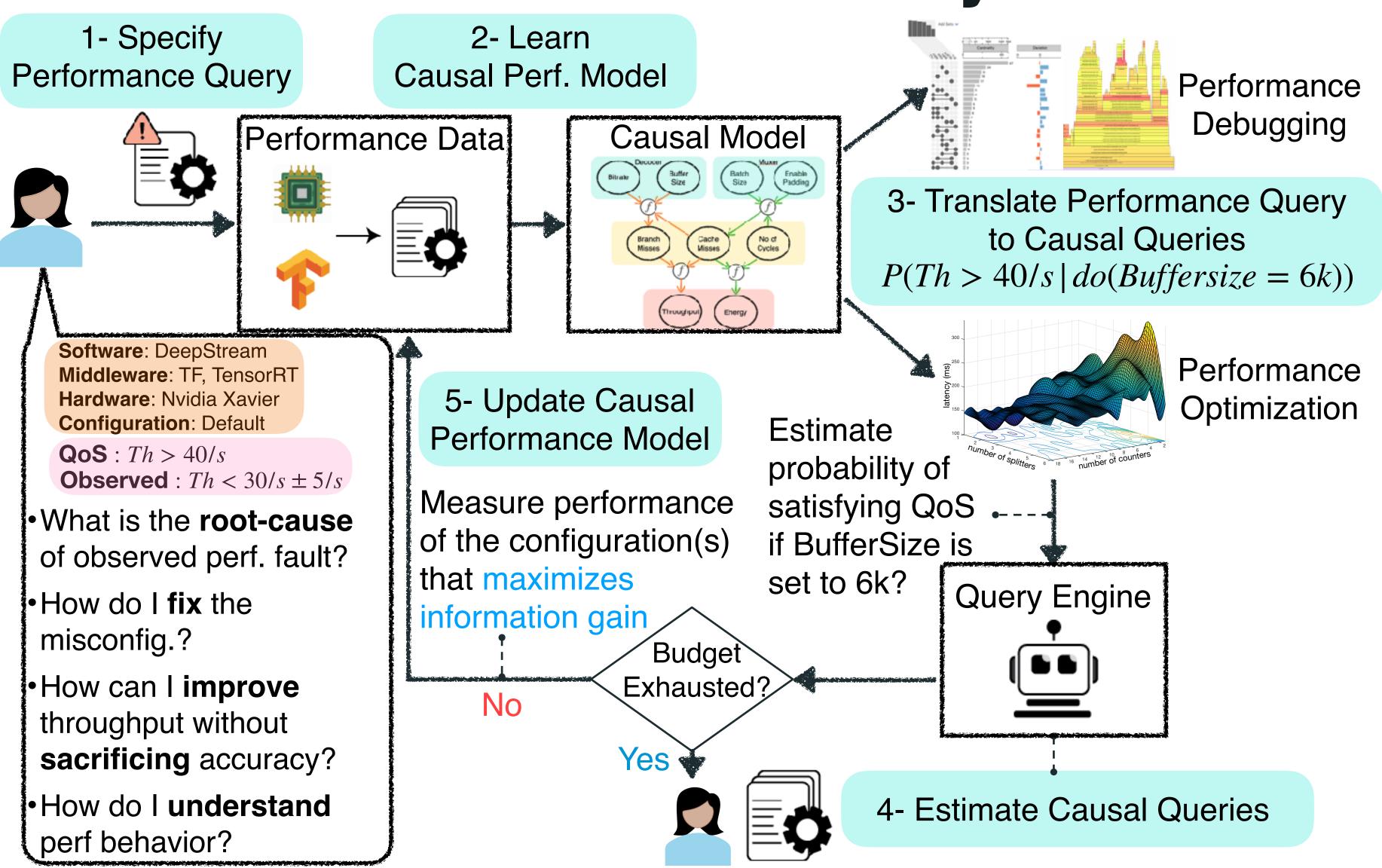
		Bitrate (bits/s)	Enable Padding	 Cache Misses	 Through put (fps)	1- Re
-	С ₁	1k	1	 42m	 7	
-	C ₂	2k	1	 32m	 22	
-				 	 	fully
_	Cn	5k	0	 12m	 25	giver
						no co



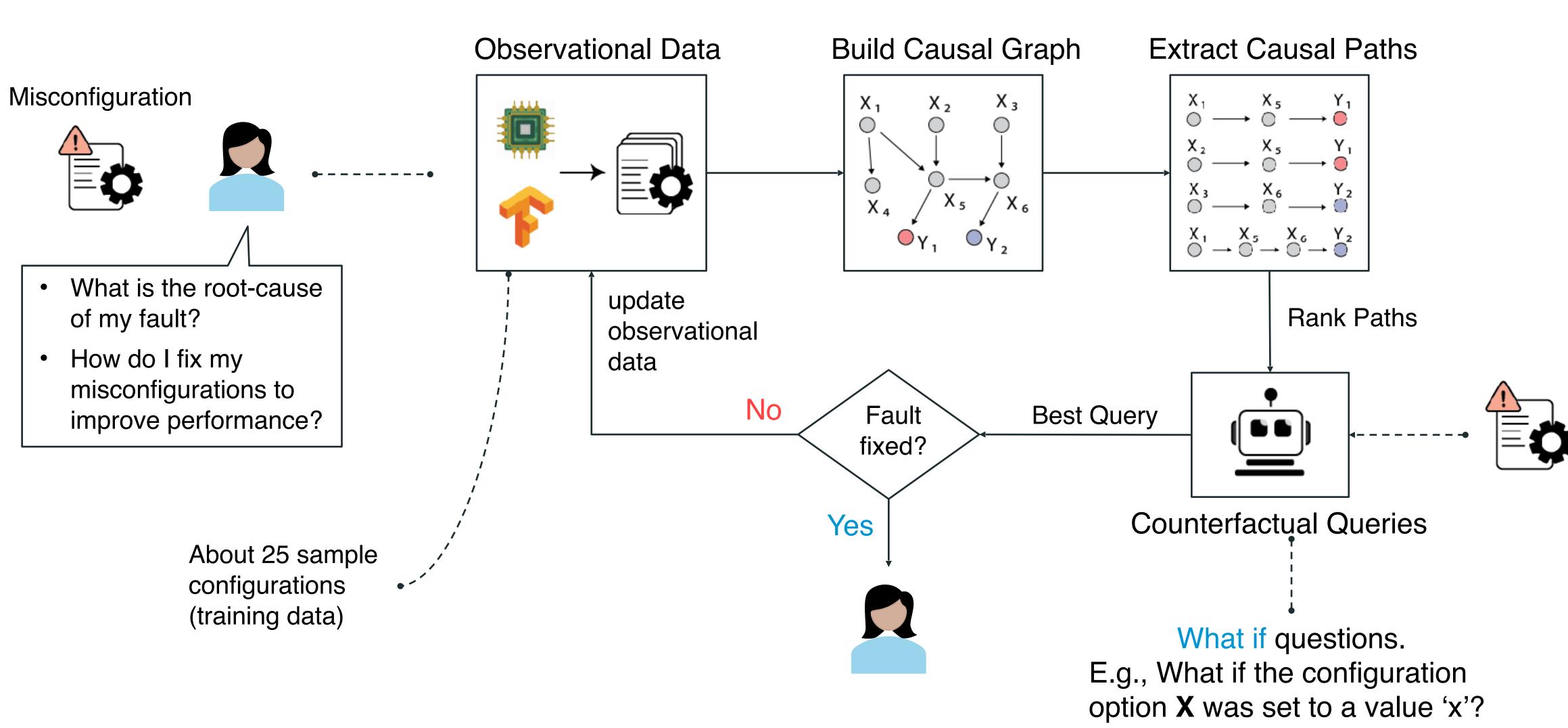
Causal Performance Model

 $Branchmisses = 2 \times Bitrate + 8.1 \times Buffersize + 4.1 \times Bitrate \times Buffersize \times Cachemisses$





Causal Debugging





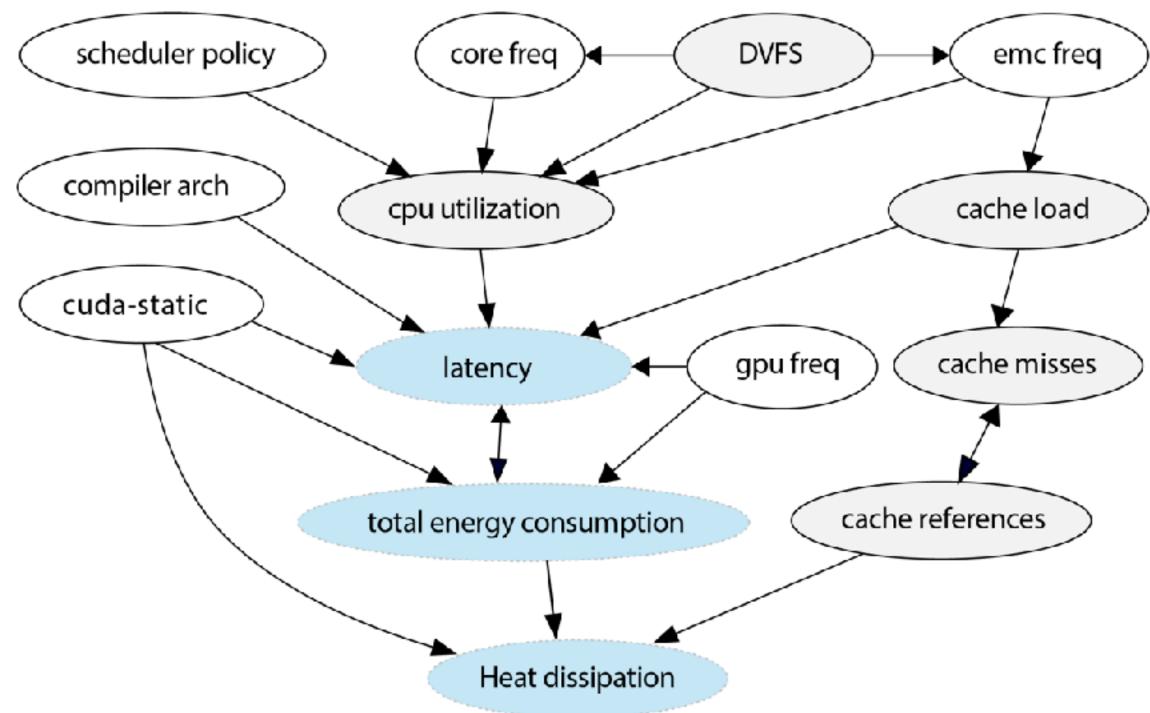
Extracting Causal Paths from the Causal Model

Problem

- In real world cases, this causal graph can be very complex
- × It may be intractable to reason over the entire graph directly

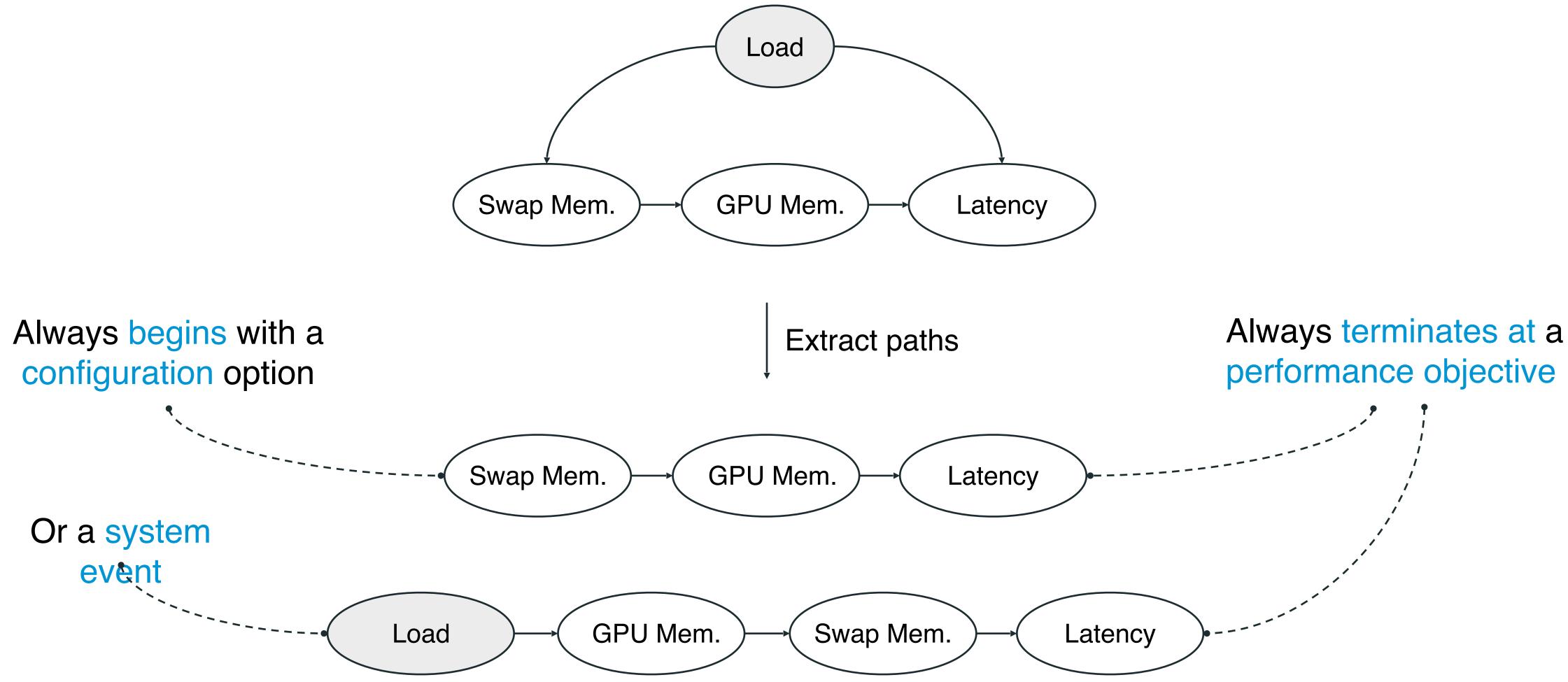
Solution

- ✓ Extract paths from the causal graph
- ✓ Rank them based on their Average Causal Effect on latency, etc.
- ✓ Reason over the top K paths





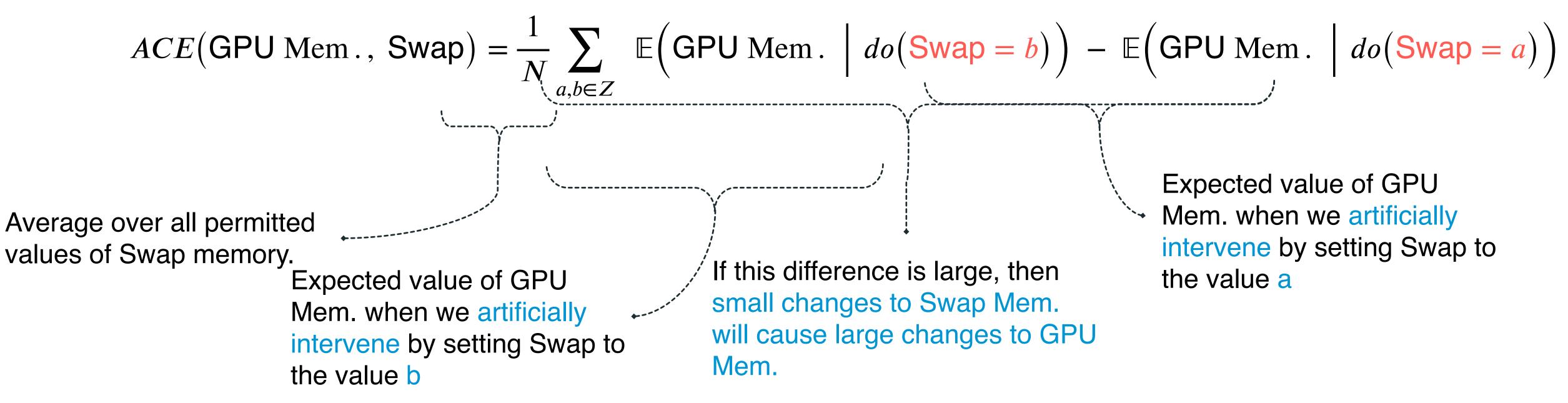
Extracting Causal Paths from the Causal Model

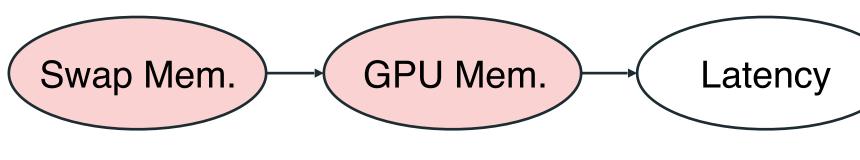




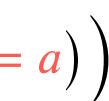
Ranking Causal Paths from the Causal Model

- They may be too many causal paths
- We need to select the most useful ones
- Compute the Average Causal Effect (ACE) of each pair of neighbors in a path





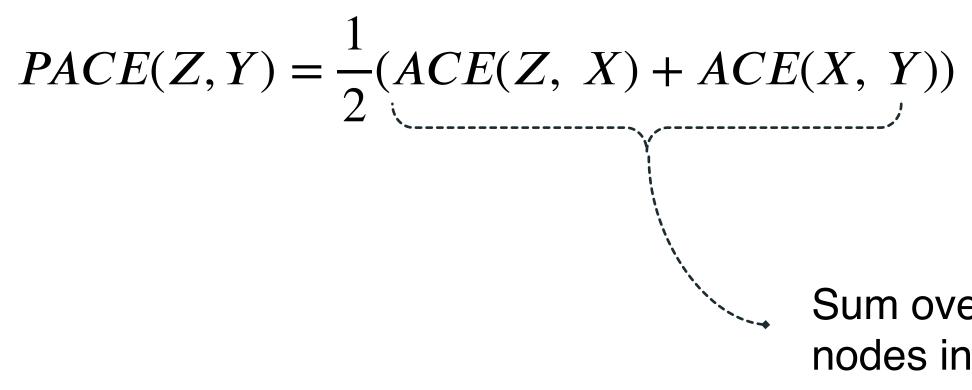




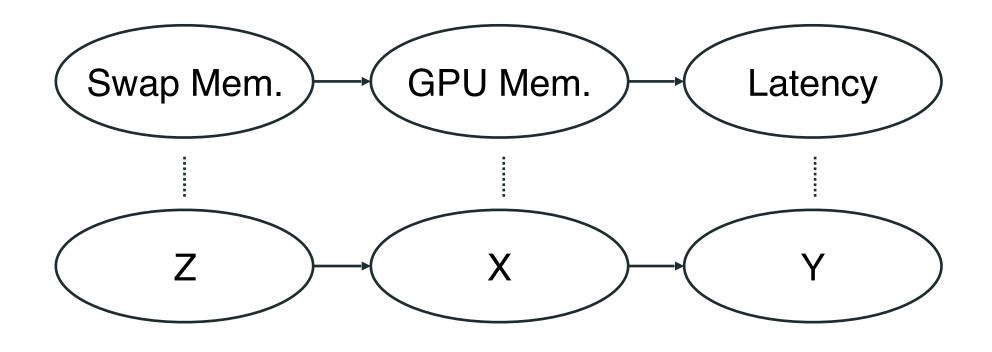


Ranking Causal Paths from the Causal Model

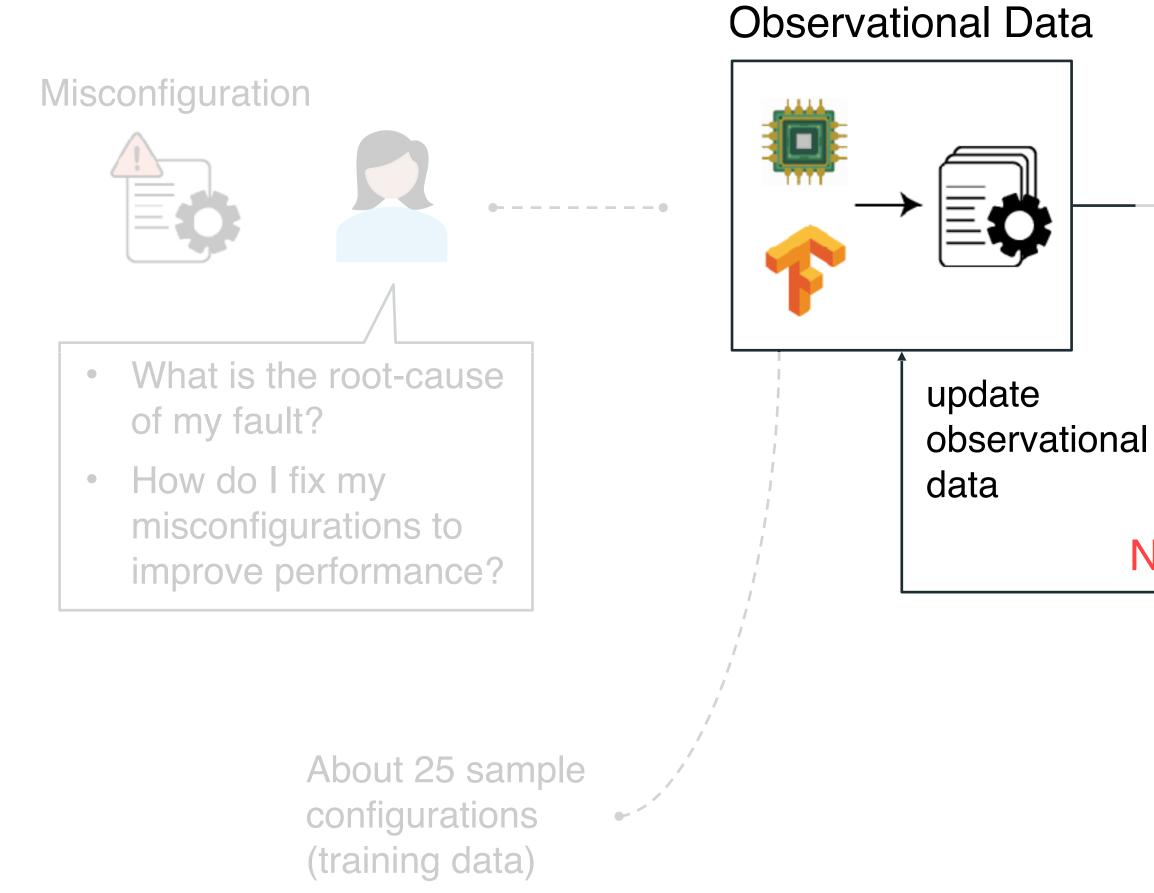
Average the ACE of all pairs of adjacent nodes in the path

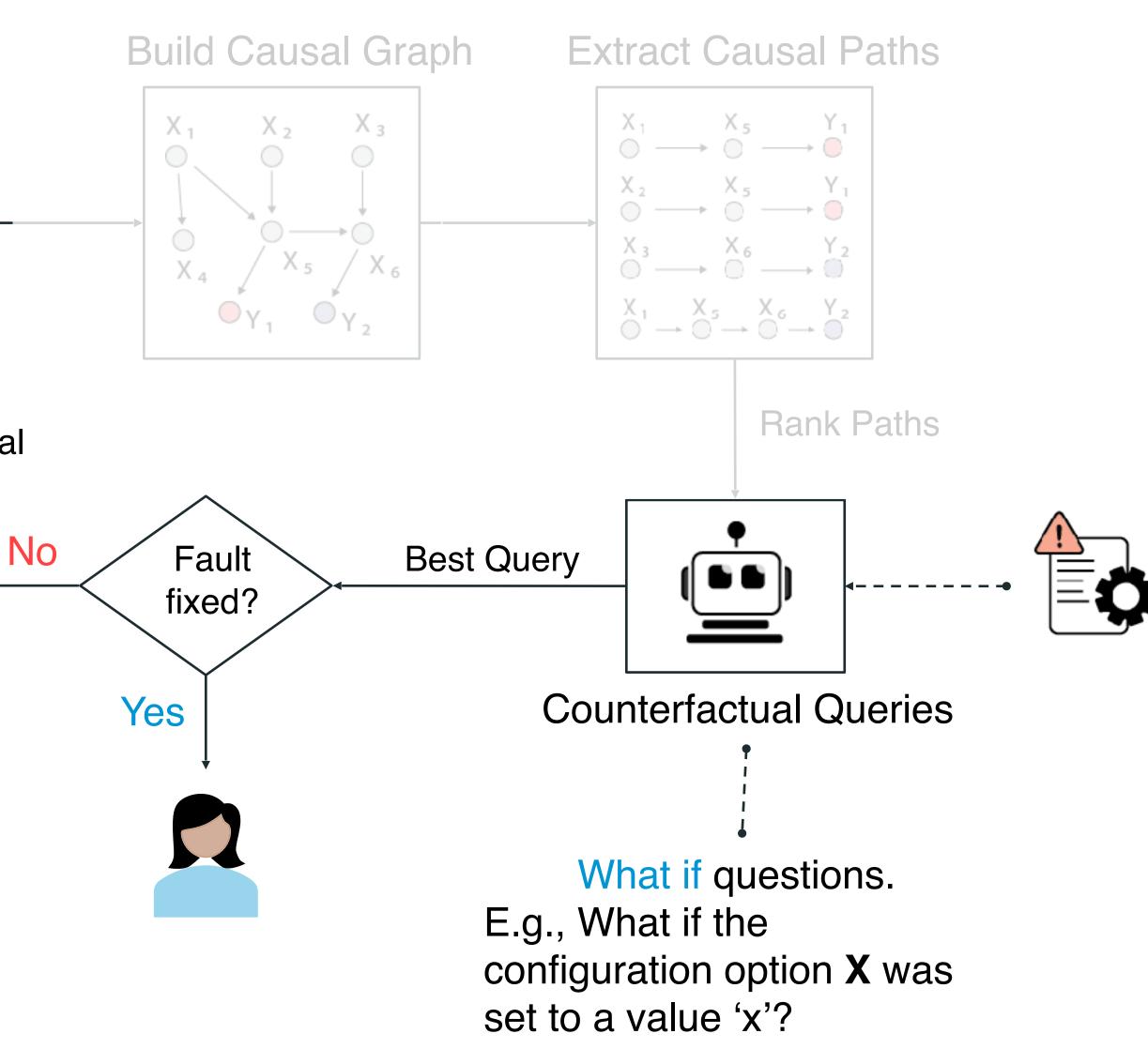


- Rank paths from highest path ACE (PACE) score to the lowest
- Use the top K paths for subsequent analysis



Sum over all pairs of nodes in the causal path.







misconfigurations

Example

We are interested in the scenario where:

We hypothetically have low latency; \bullet

Conditioned on the following events:

- \bullet
- Swap Memory was initially set to 2 Gb \bullet
- \bullet
- Everything else remains the same \bullet

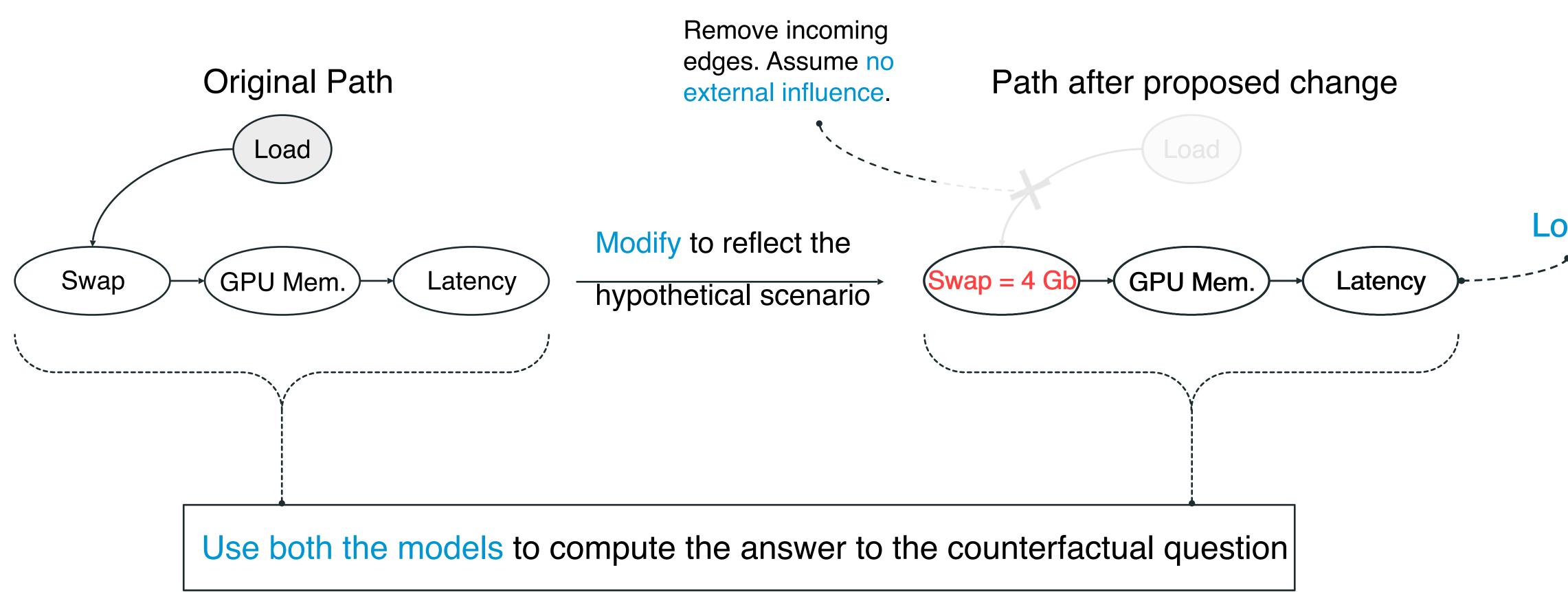
Counterfactual inference asks "what if" questions about changes to the

Given that my current swap memory is 2 Gb, and I have high latency. What is the probability of having low latency if swap memory was increased to 4 Gb?

We hypothetically set the new Swap memory to 4 Gb

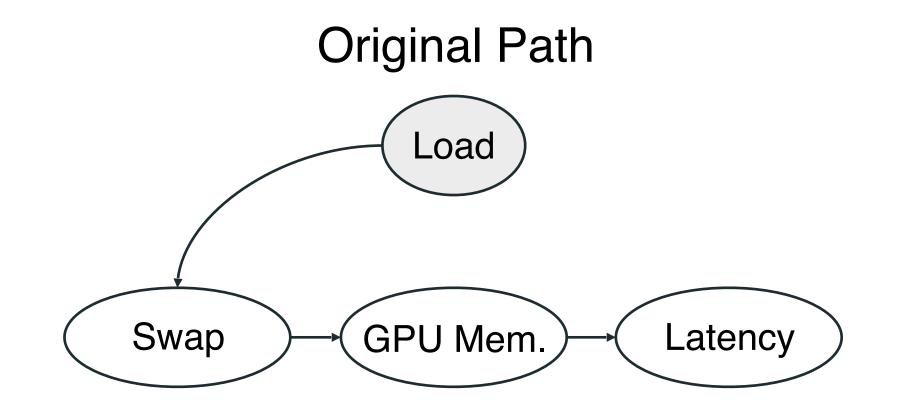
We observed high latency when Swap was set to 2 Gb



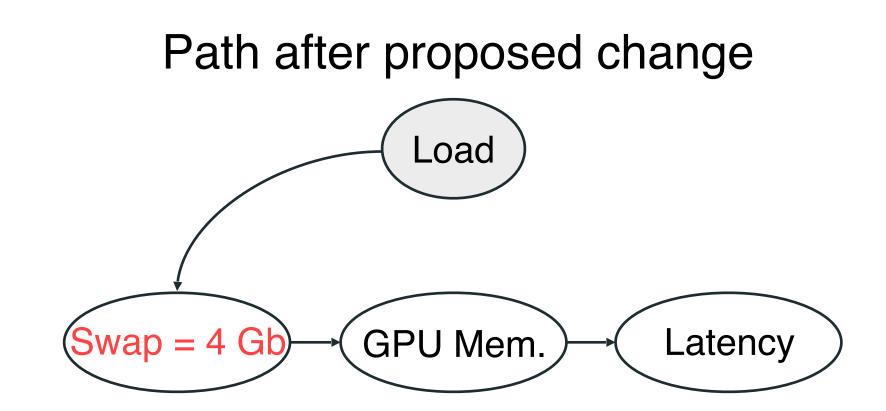


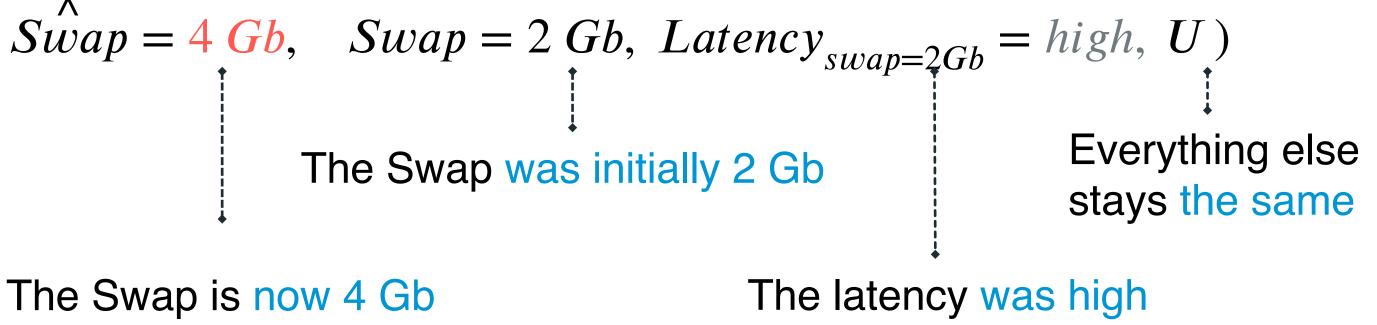






Potential =
$$P\left(\begin{array}{c} Latency = low \\ \downarrow \end{array}\right)$$
 $Swap = 4$
We expect a low latency







$$\mathsf{Potential} = P\Big(out \widehat{come} = \operatorname{good}^{\mathsf{out}} chan$$

Probability that the outcome is good after a change, conditioned on the past

$$Control = P(out com)$$

Probability that the outcome was bad before the change

 $nge, outcome_{\neg change} = bad, \neg change, U$

 $ne = bad | \neg change, U)$

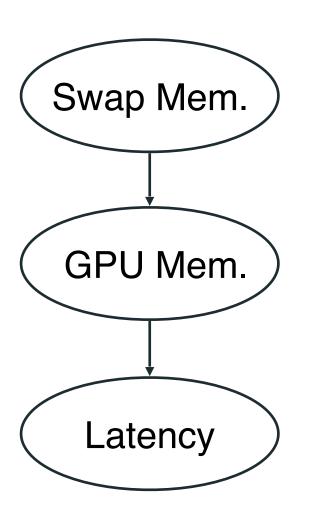
Individual Treatment Effect = Potential – Outcome

If this difference is large, then our change is useful



• • •

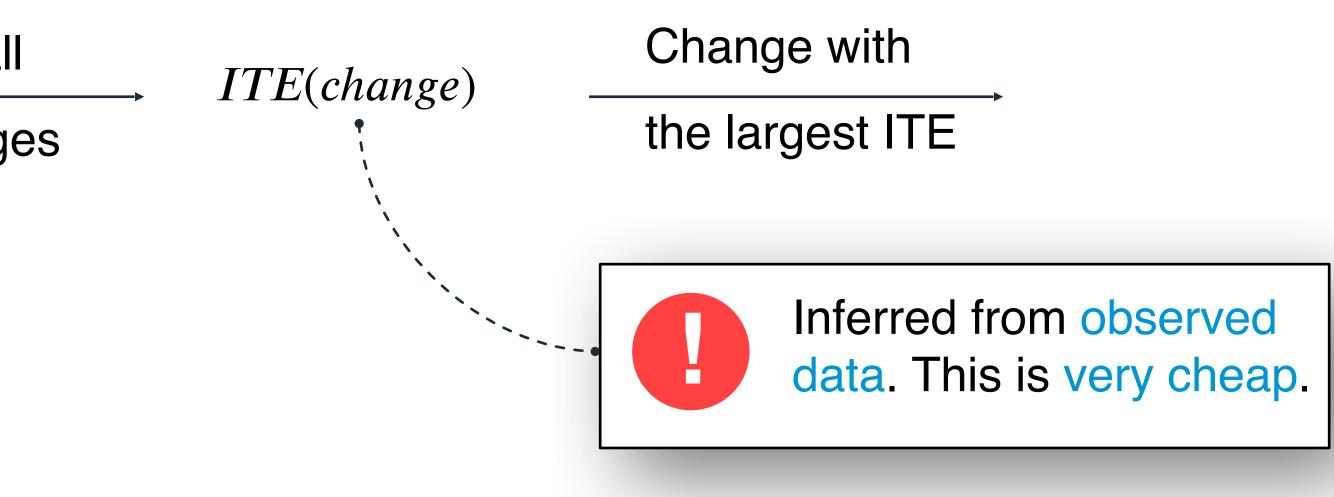
Top K paths



Enumerate all

possible changes

Set every configuration option in the path to all permitted values

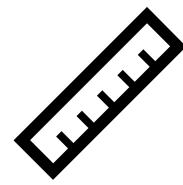


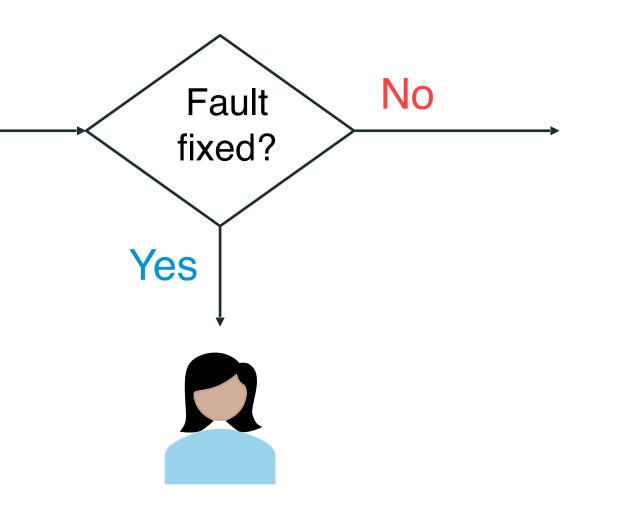


Measure Performance

Change with

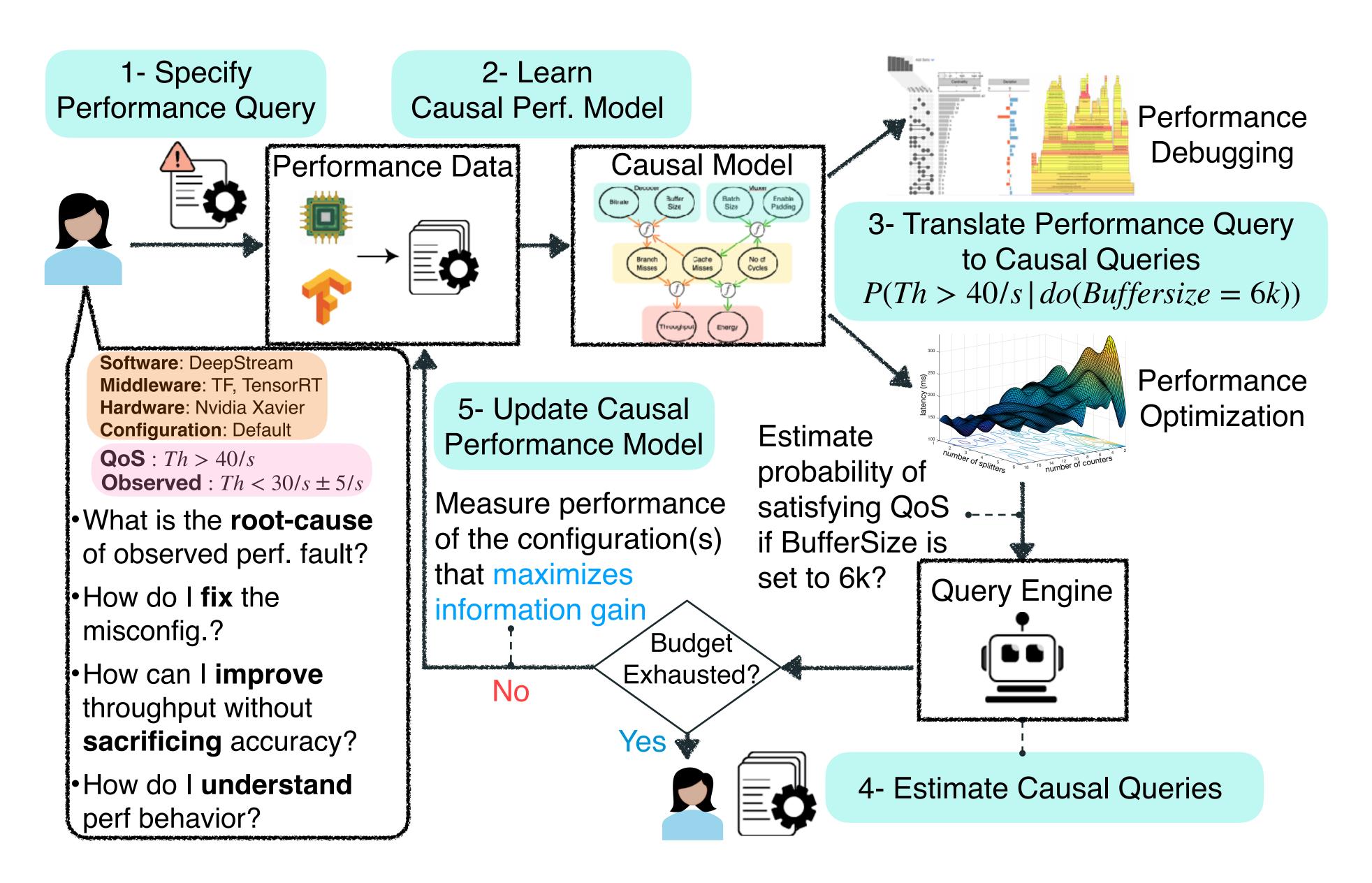
the largest ITE



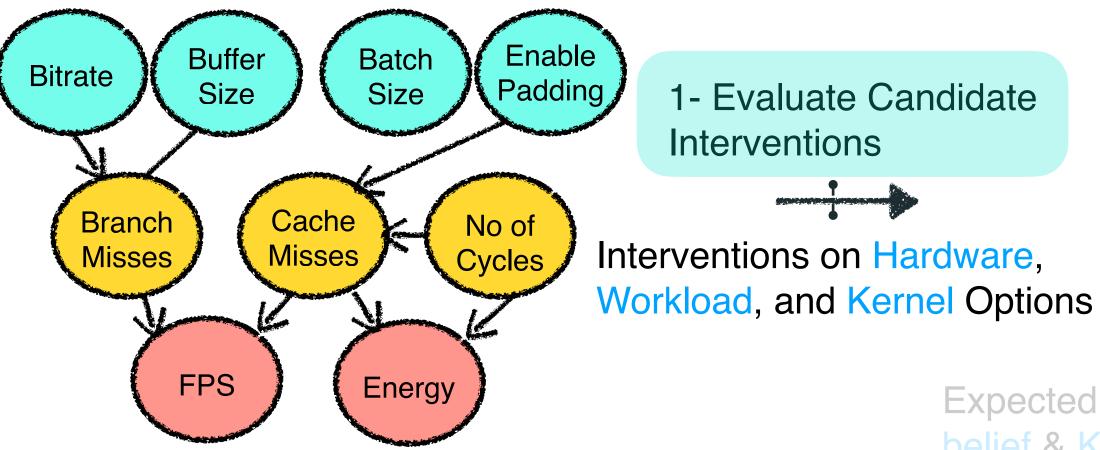


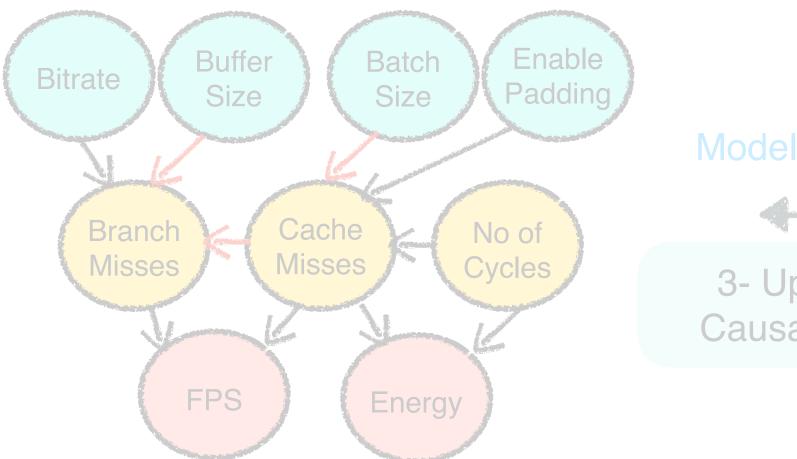
- Add to observational data \bullet
- Update causal model \bullet
- Repeat... \bullet

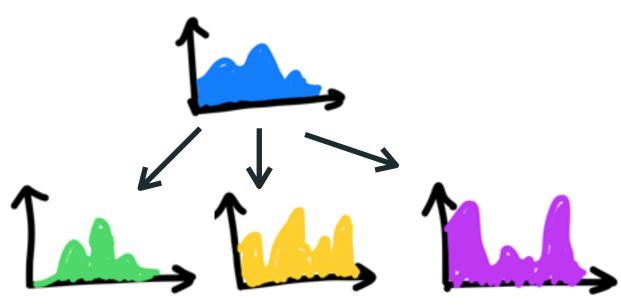




Active Learning for Updating Causal Performance Model







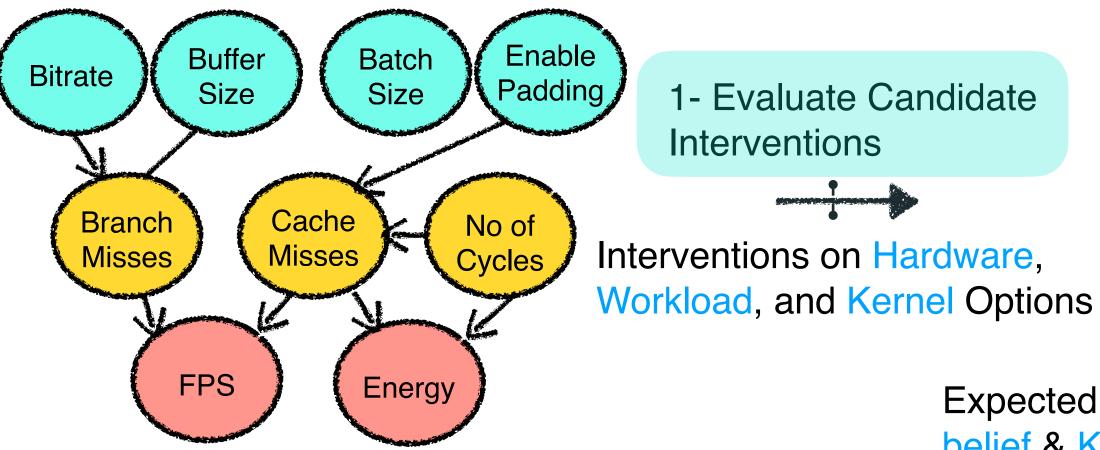
Expected change in belief & KL; Causal • • offects on objectives

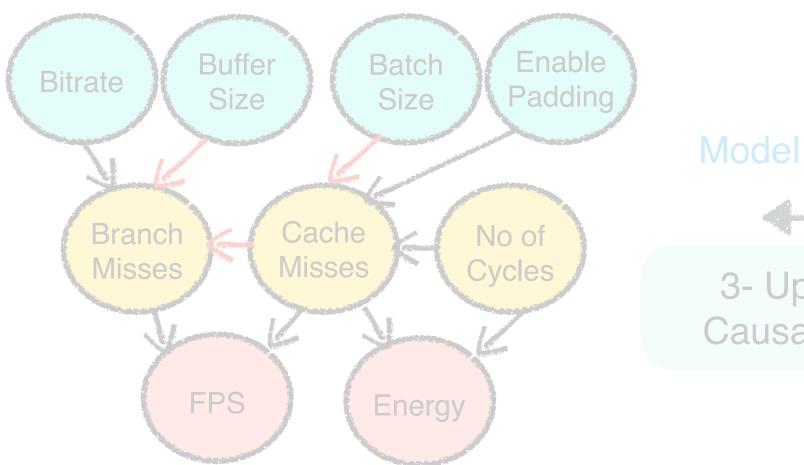
2- Determine & Perform next Perf Measurement

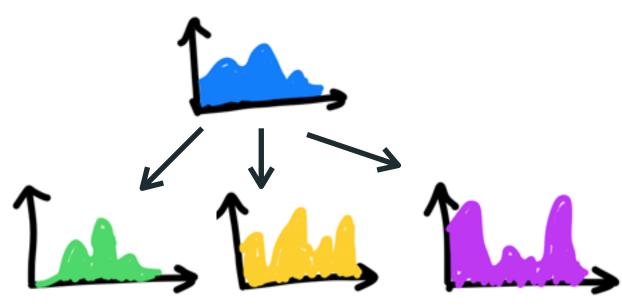
averaging		Enable Padding	1
		Branch Misses	24m
pdating		Cache Misses	42m
al Model	Performance	No of Cycles	73b
	Data	FPS	31/s
		Energy	42J



Active Learning for Updating Causal Performance Model







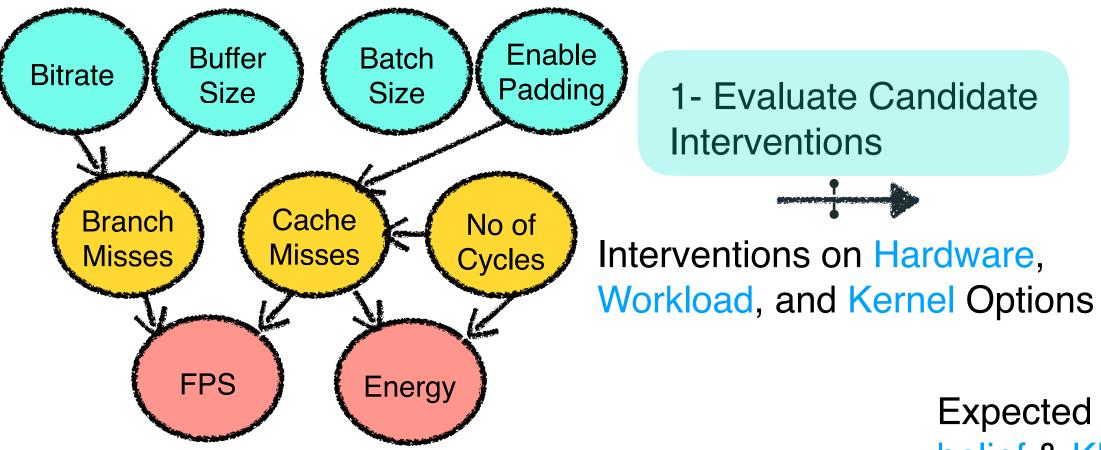
Expected change in belief & KL; Causal •--• effects on objectives *****

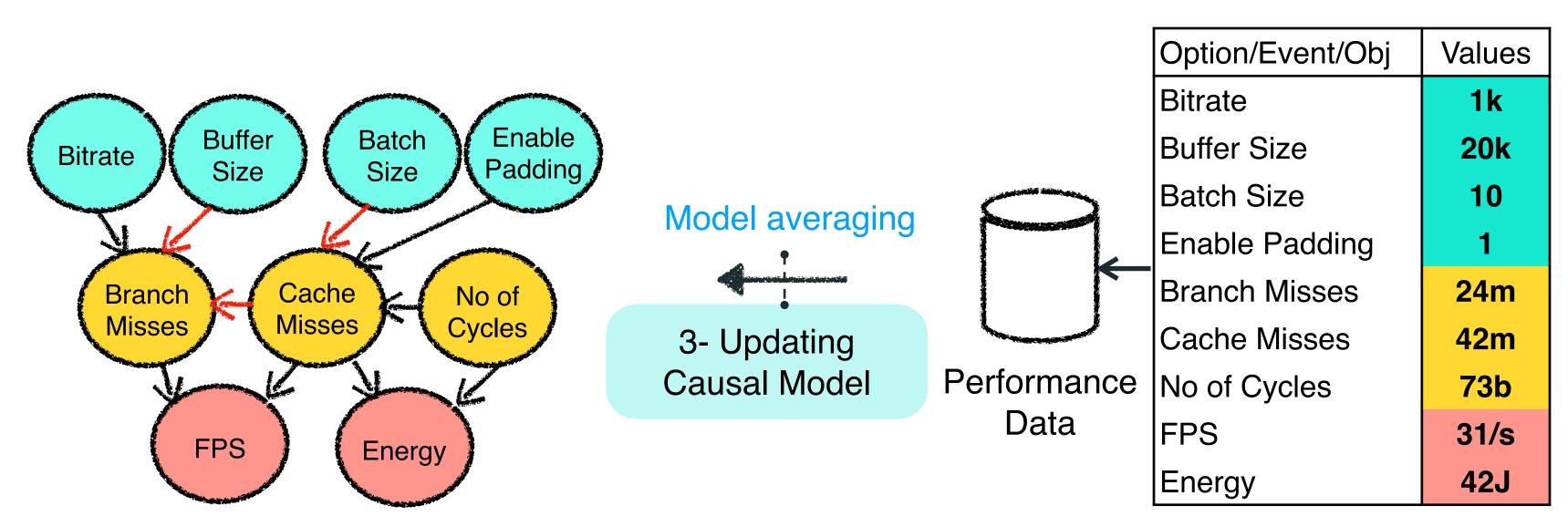
2- Determine & Perform next Perf Measurement

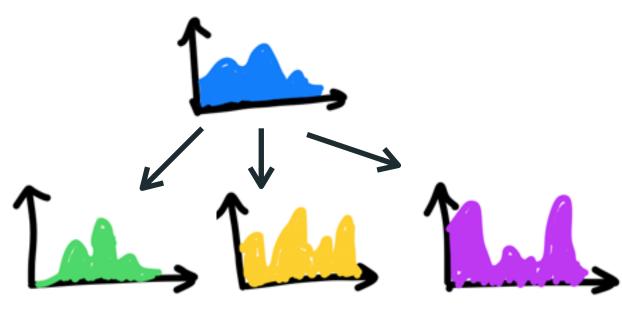
		Option/Event/Obj	Values
		Bitrate	1k
		Buffer Size	20k
Lovoroging		Batch Size	10
l averaging		Enable Padding	1
		Branch Misses	24m
pdating		Cache Misses	42m
al Model	Performance	No of Cycles	73b
	Data	FPS	31/s
		Energy	42J



Active Learning for Updating Causal Performance Model







Expected change in belief & KL; Causal ••• effects on objectives *

2- Determine & Perform next Perf Measurement



Benefits of Causal Reasoning for System Performance Analysis





There are two fundamental benefits that we get by our "Causal Al for Systems" methodology

- performance tasks:
 - Performance **understanding**
 - Performance optimization
 - Performance debugging and repair
- 2. The causal model is transferable across environments.
 - We observed Sparse Mechanism Shift in systems too!
 - are not transferable as they rely on i.i.d. setting.

1. We learn one central (causal) performance model from the data across different

• Performance **prediction** for different environments (e.g., canary-> production)

• Alternative non-causal models (e.g., regression-based models for performance tasks)





UNICORN: Reasoning about Configurable System Performance through the Lens of Causality

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Abstract

Modern computer systems are highly configurable, with the total variability space sometimes larger than the number of atoms in the universe. Understanding and reasoning about the performance behavior of highly configurable systems, over a vast and variable space, is challenging. State-of-theart methods for performance modeling and analyses rely on predictive machine learning models, therefore, they become (i) unreliable in unseen environments (e.g., different hardware,

EuroSys 2022



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