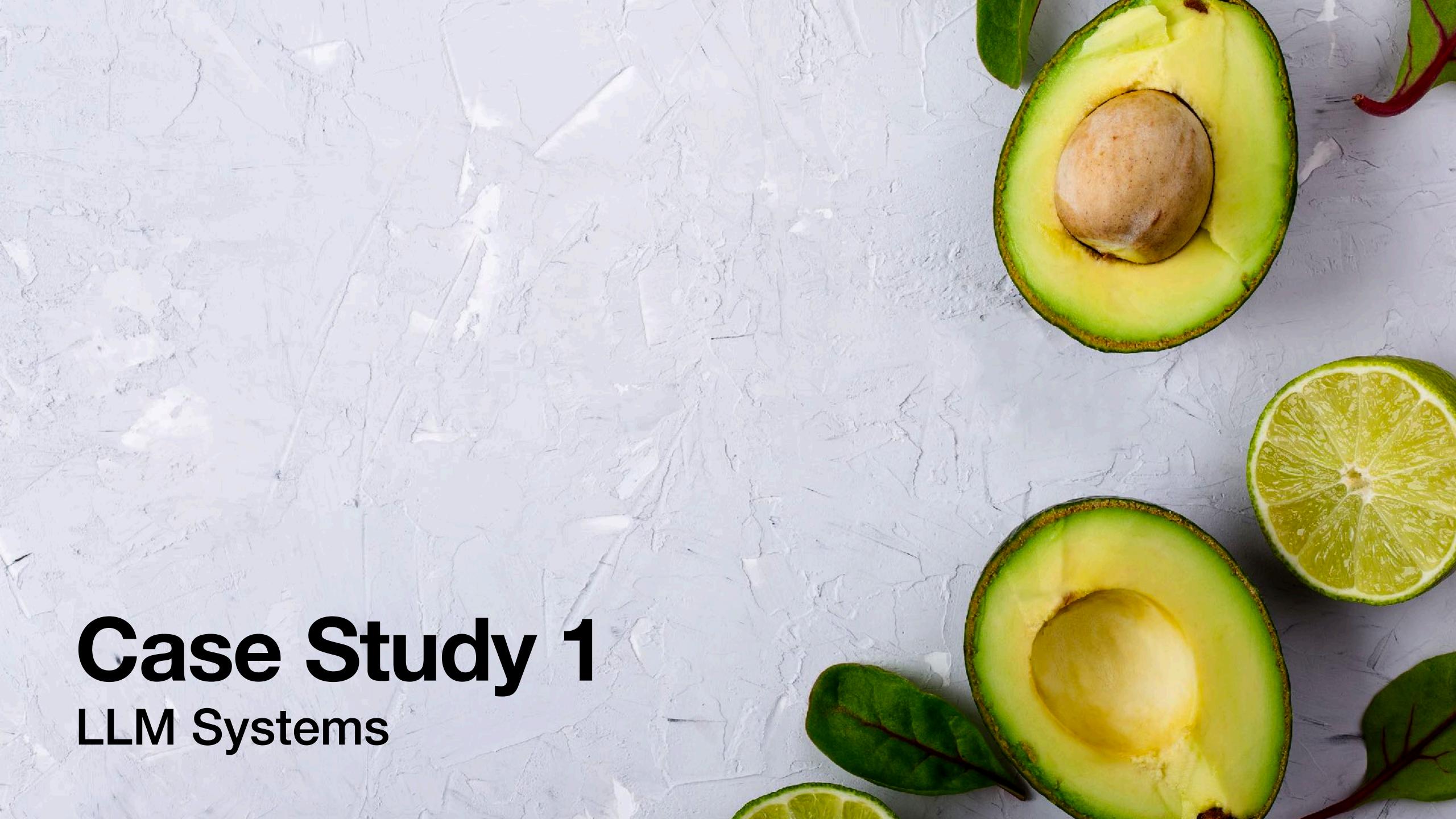


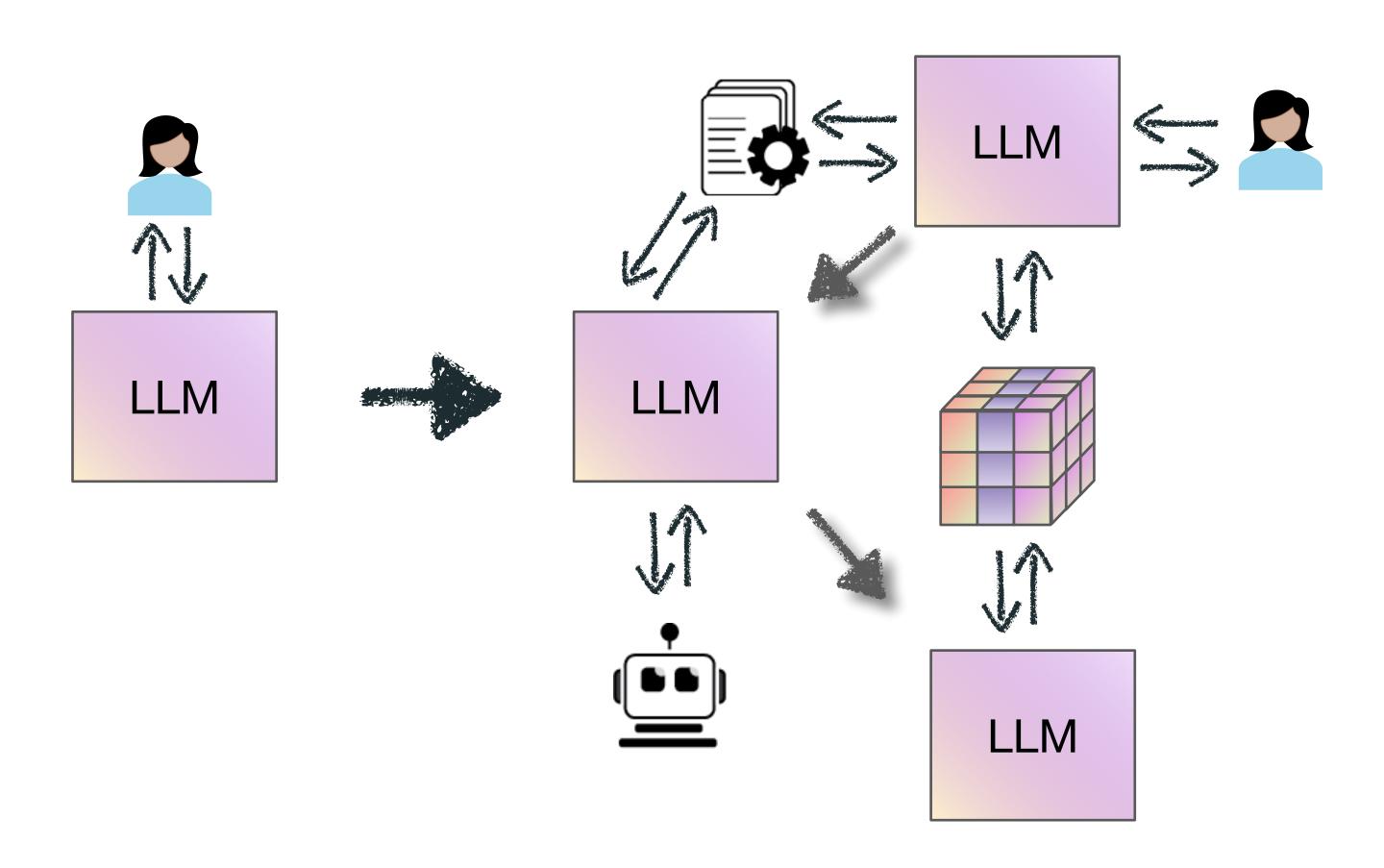
CSCE 585: Machine Learning Systems

Lecture 6: Understanding and Explaining the Root Causes of Performance Faults in ML Systems

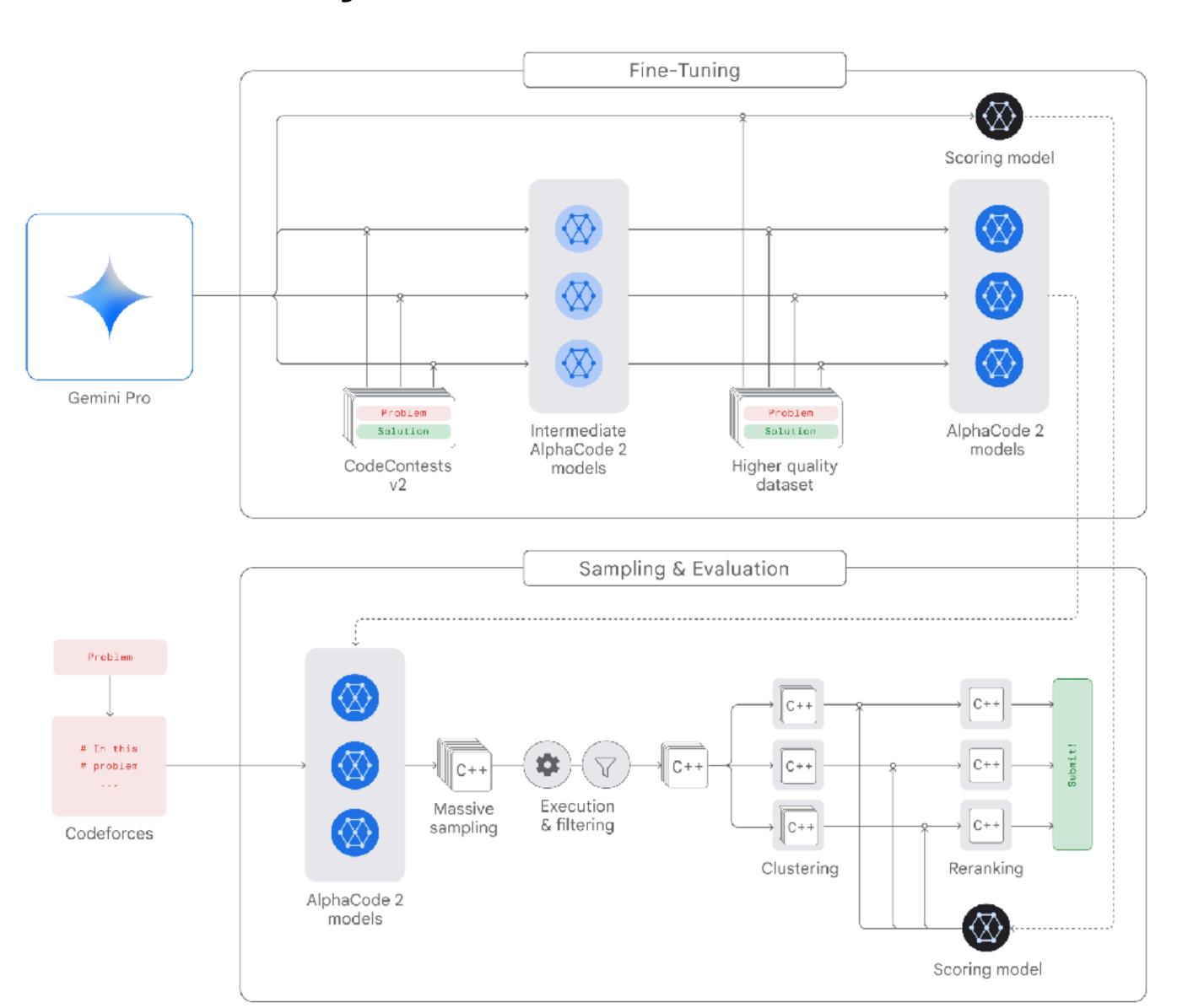
Pooyan Jamshidi



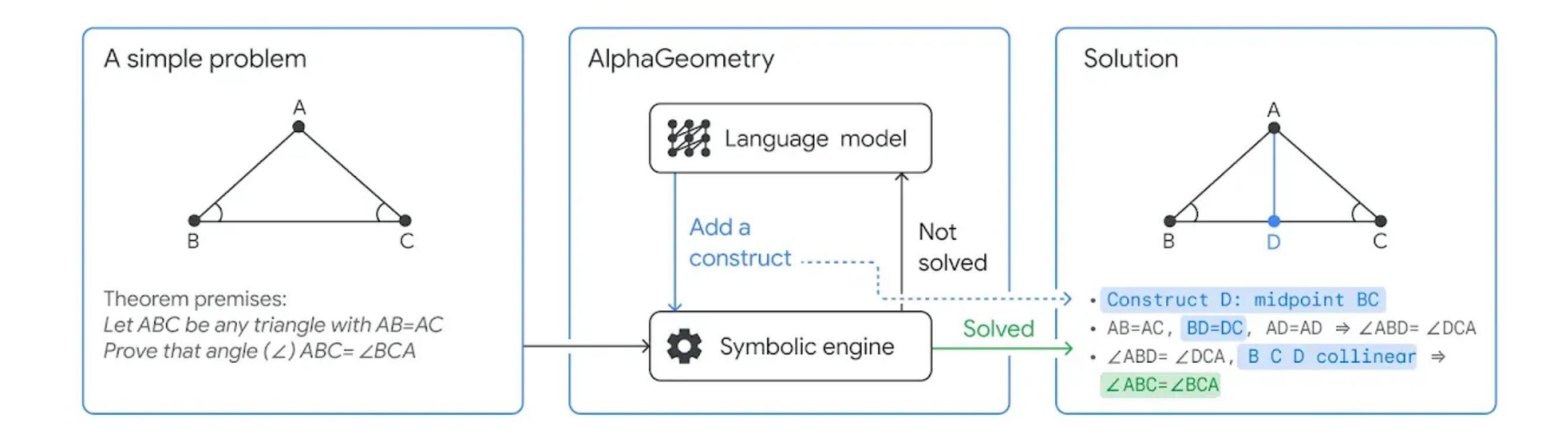




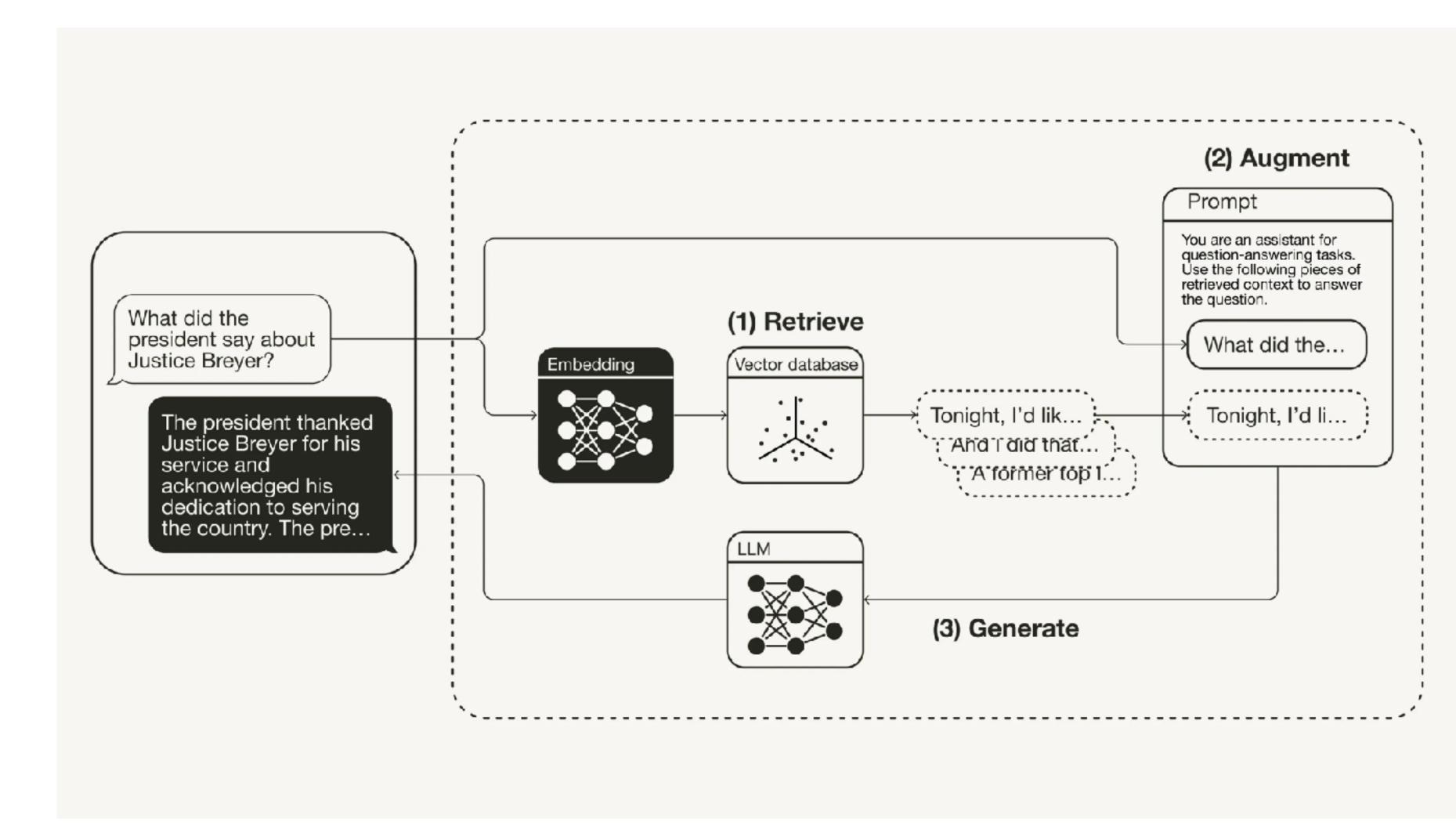
Google's AlphaCode 2 set stateof-the-art results in programming through a carefully engineered system that uses LLMs to generate up to 1 million possible solutions for a task and then filter down the set.



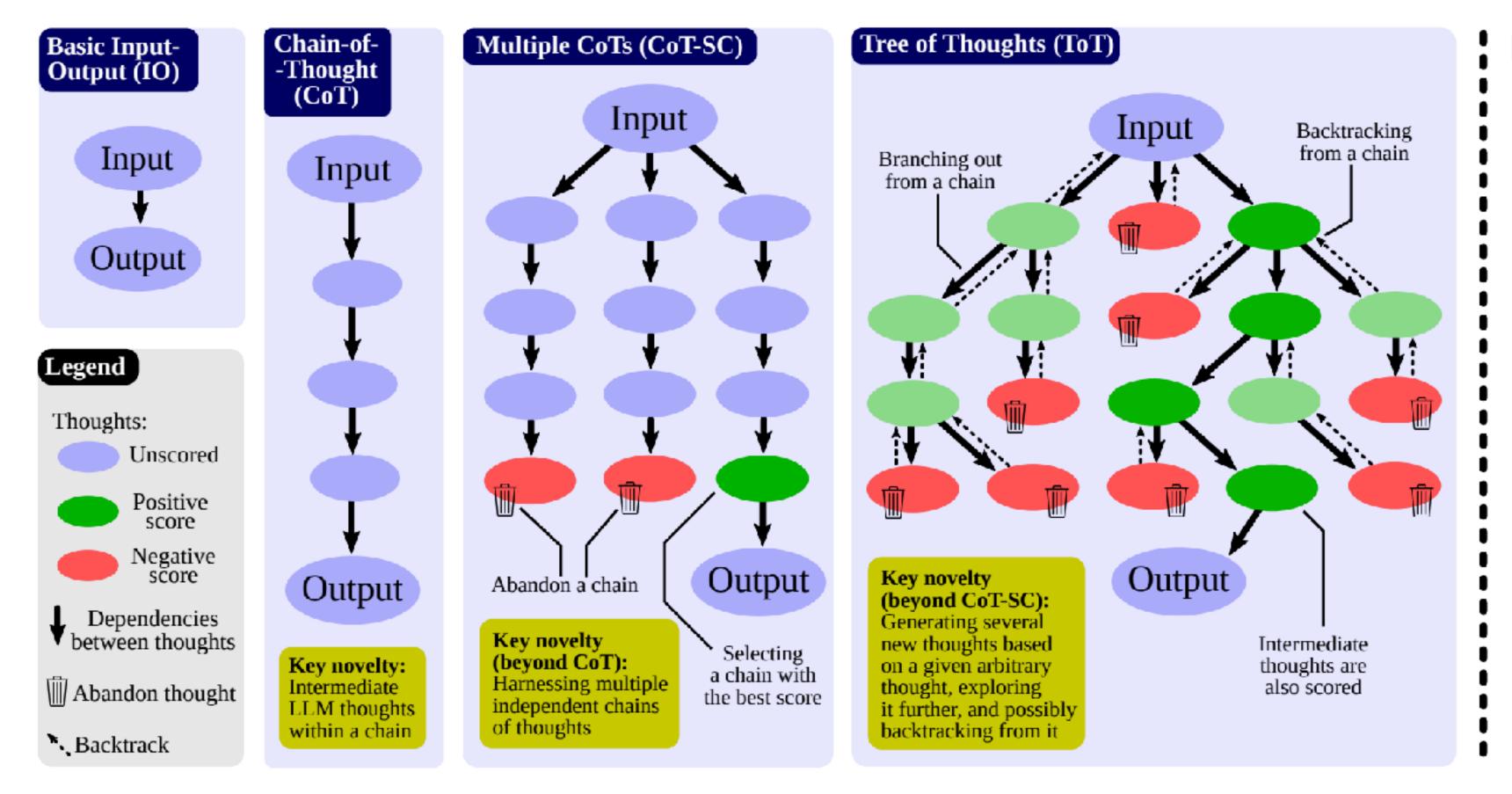
AlphaGeometry combines an LLM with a traditional symbolic solver to tackle Olympiad problems.

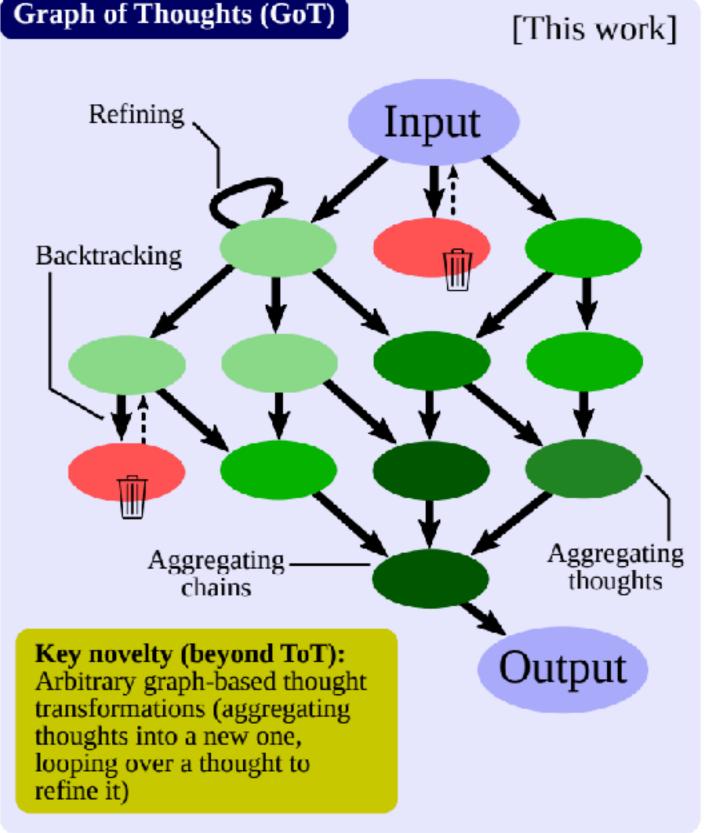


~60% of LLM applications use some form of retrieval-augmented generation (RAG)

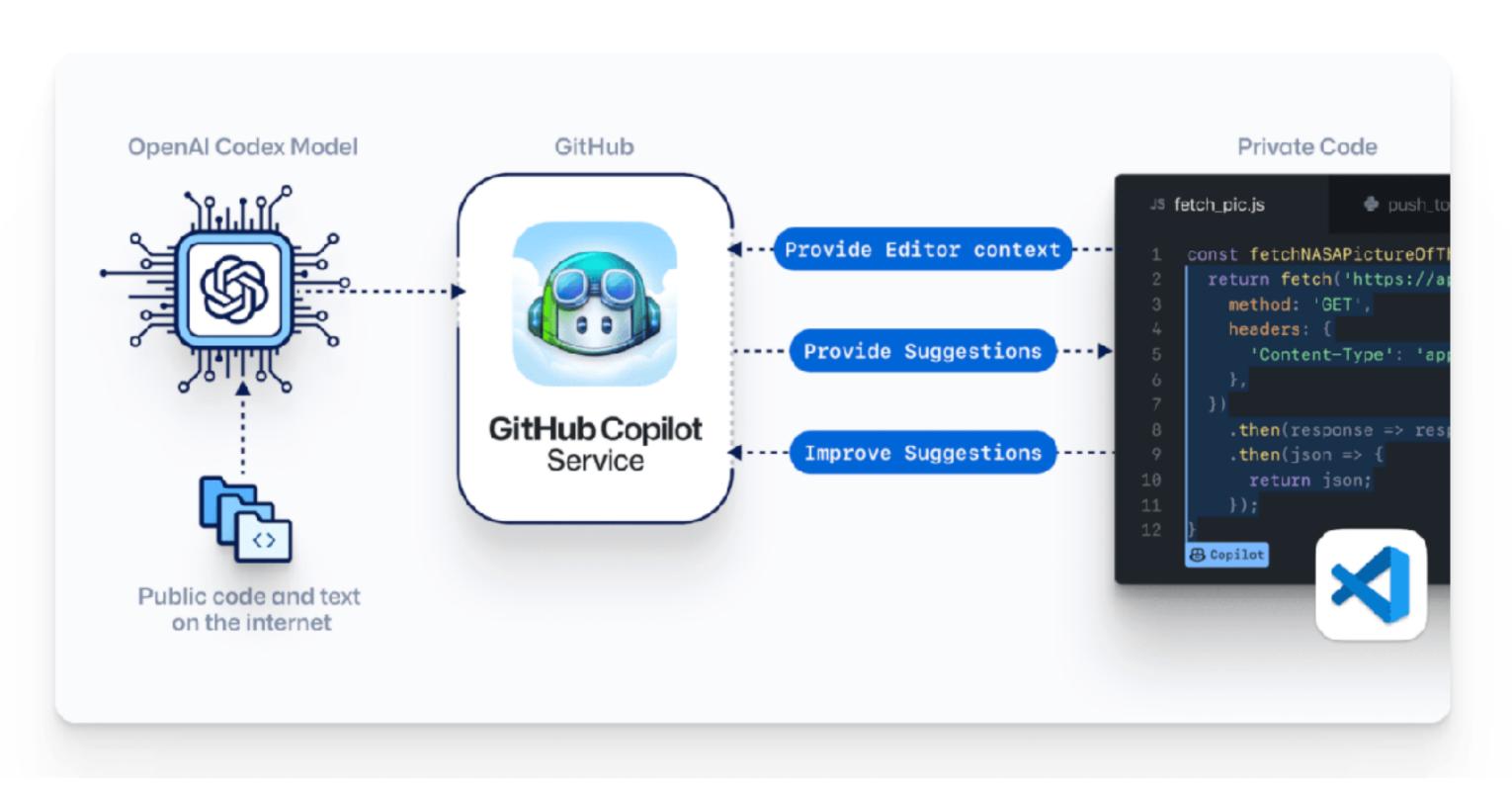


...and 30% use multi-step chains.





Github Copilot uses carefully tuned smaller models and various search heuristics to provide results.

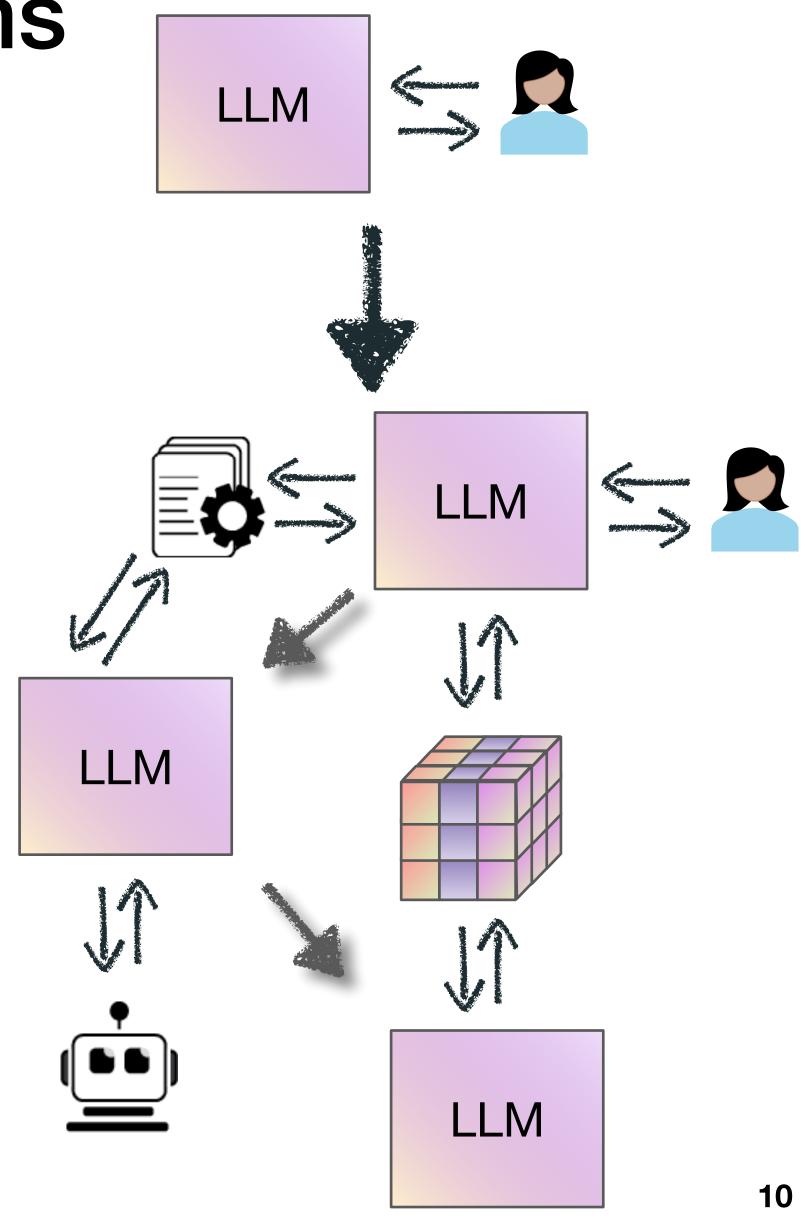


Google's Gemini launch post measured its MMLU (Massive Multitask Language Understanding) benchmark results using a new CoT@32 inference strategy that calls the model 32 times.

	Gemini Ultra	Gemini Pro	GPT-4	GPT-3.5	PaLM 2-L	Claude 2	Inflect- ion-2	Grok 1	LLAMA-2
MMLU Multiple-choice questions in 57 subjects (professional & academic) (Hendrycks et al., 2021a)	90.04% CoT@32*	79.13% CoT@8*	87.29% CoT@32 (via API**)	70% 5-shot	78.4% 5-shot	78.5% 5-shot CoT	79.6 % 5-shot	73.0% 5-shot	68.0%***
	83.7% 5-shot	71.8% 5-shot	86.4% 5-shot (reported)						

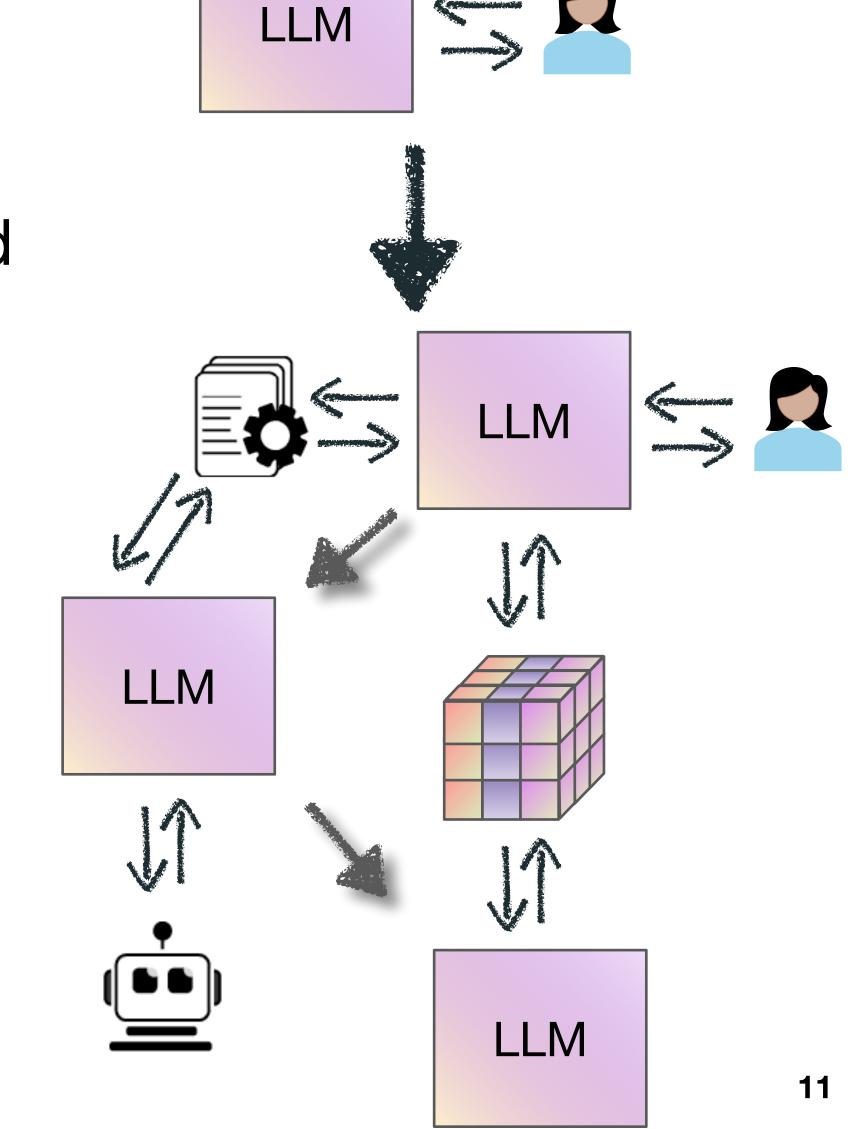
The paradigm shift from monolithic to modularcomposed machine learning systems

- Modular-composed ML Systems are a class of modern computer systems that tackle Al/ML tasks using:
 - Multiple interacting and interdependent components,
 - including multiple calls to models, search & retrieval algorithms, and external tools.
- In contrast, Monolithic ML Systems are simply traditional ML Systems that call a statistical model at the backend.
 - e.g., a **Transformer** that predicts the next token in text.



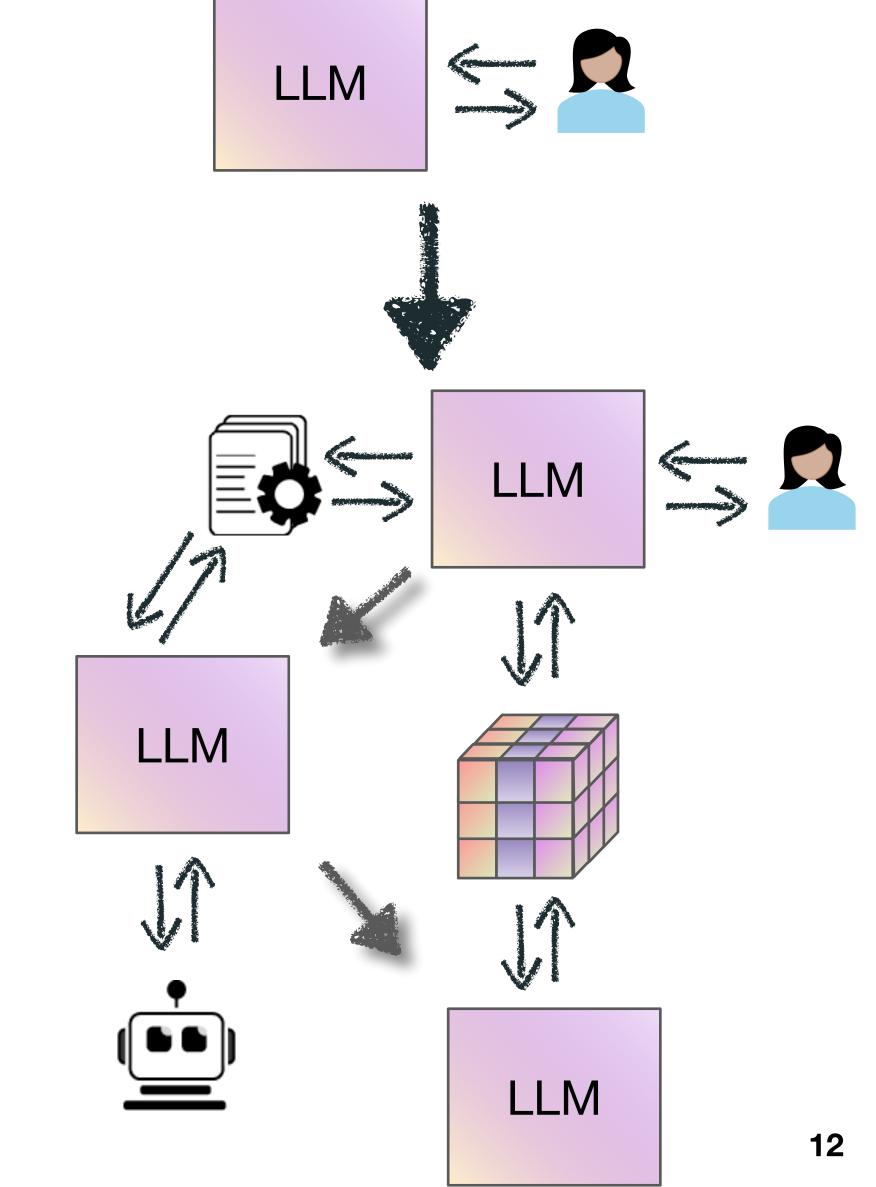
This paradigm shift to modular-composed ML systems opens up new opportunities for computer systems research

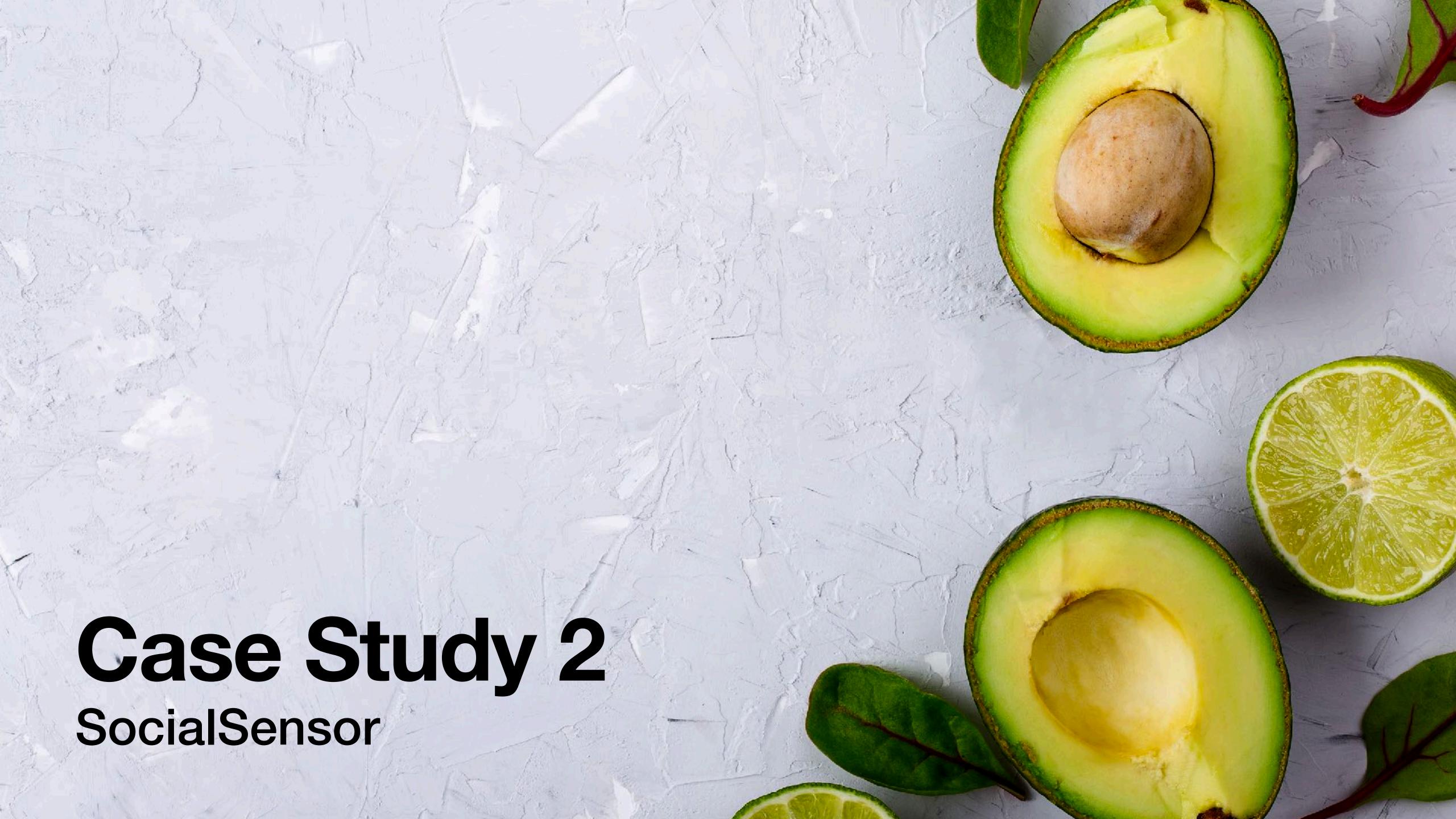
- Design space exploration
 - With an SLA of 100 milliseconds for RAG, should we budget to spend 20 ms on the retriever and 80 on the LLM, or the other way around?
- Performance tradeoff and optimization
 - Modular-composed systems contain nondifferentiable components.
 - Performance optimization for pipelines of pretrained LLMs and other components.



This paradigm shift to modular-composed ML systems opens up new opportunities for computer systems research

- This shift to modular-composed systems opens many interesting systems questions.
- It is also exciting because it means leading Al results can be achieved through clever systems ideas, not just scaling up training.





SocialSensor









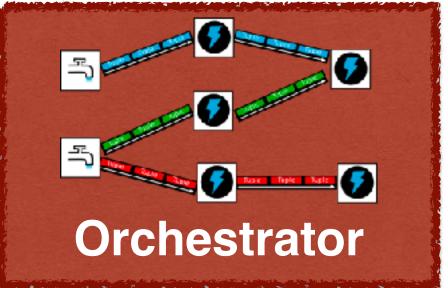


Tweets: [5k-20k/min]

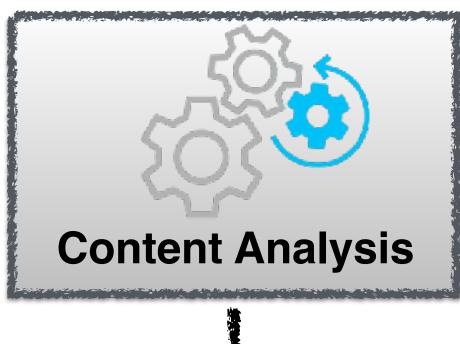












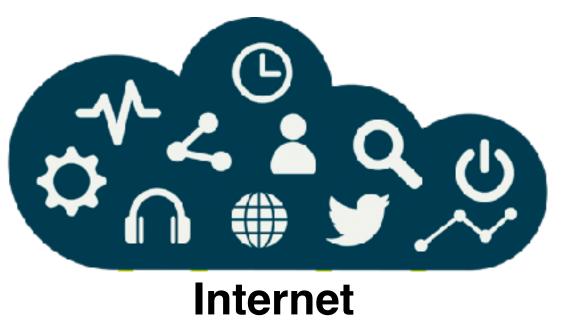






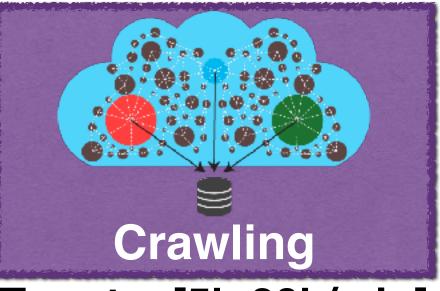


Challenges





10X

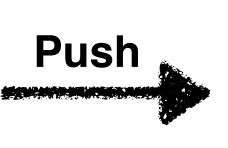












Store



Every 10 min: [100k tweets]













How can we gain a better performance without using more resources?

Let's try out different system configurations!

Opportunity: Data processing engines in the pipeline were all configurable



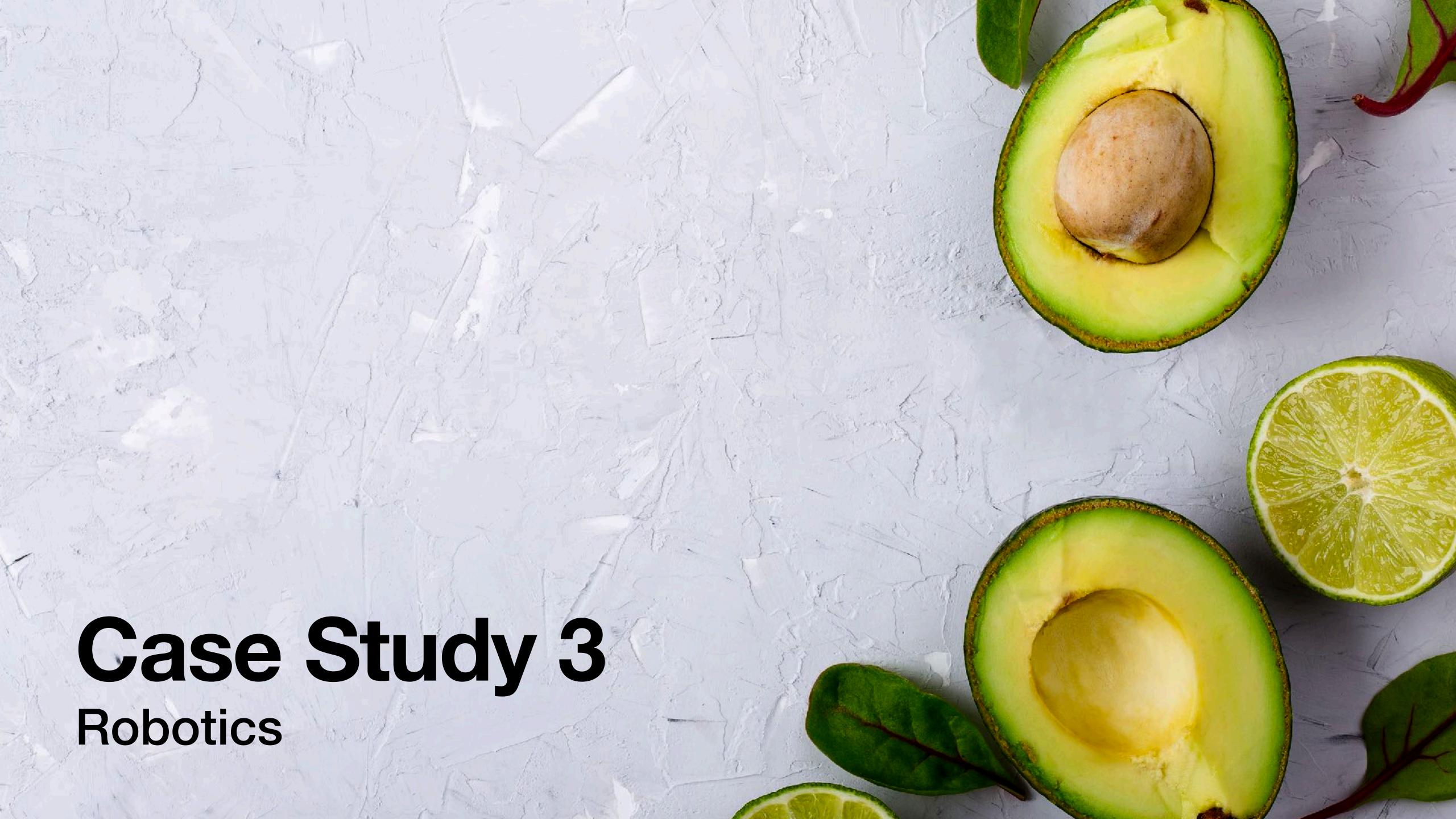




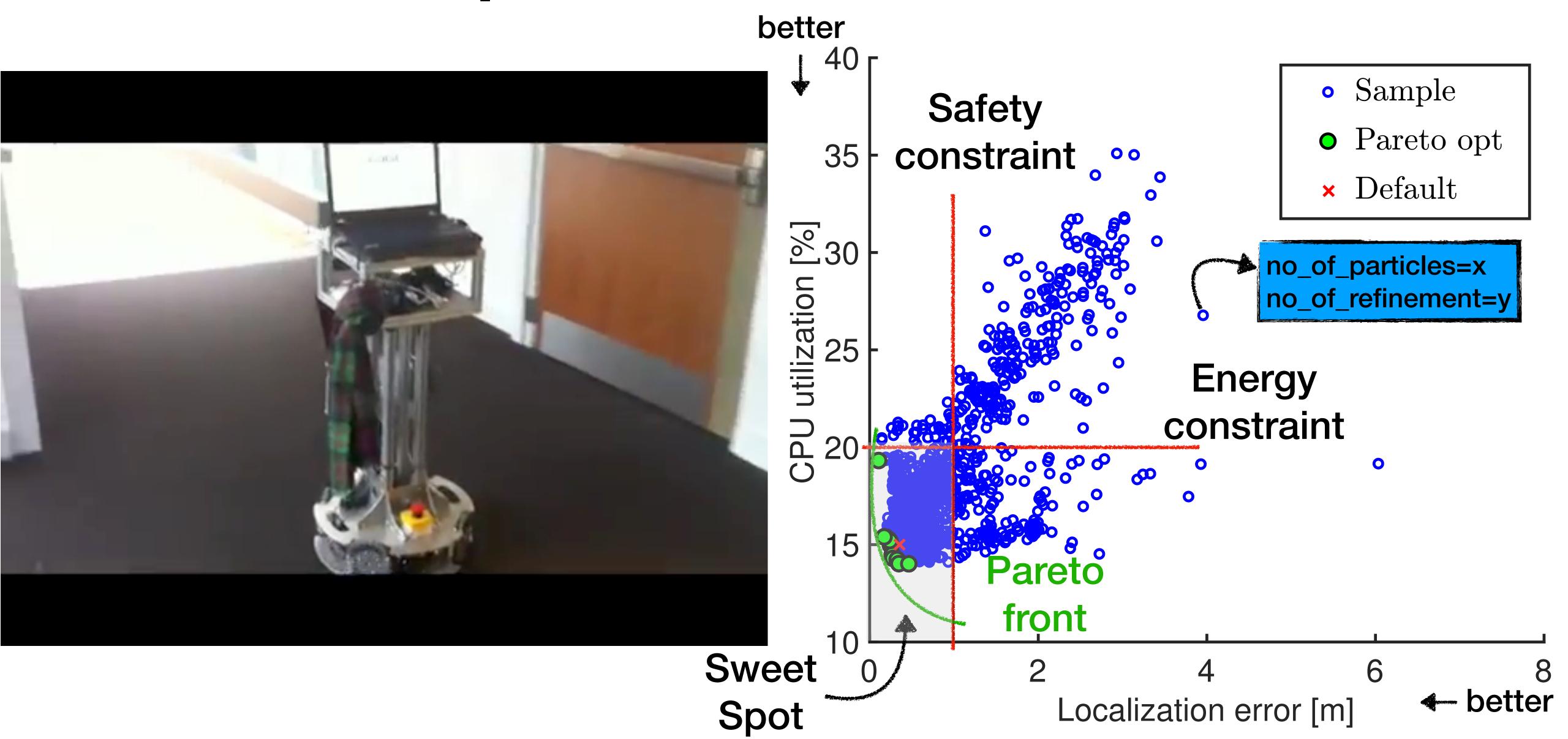


 2^{300}

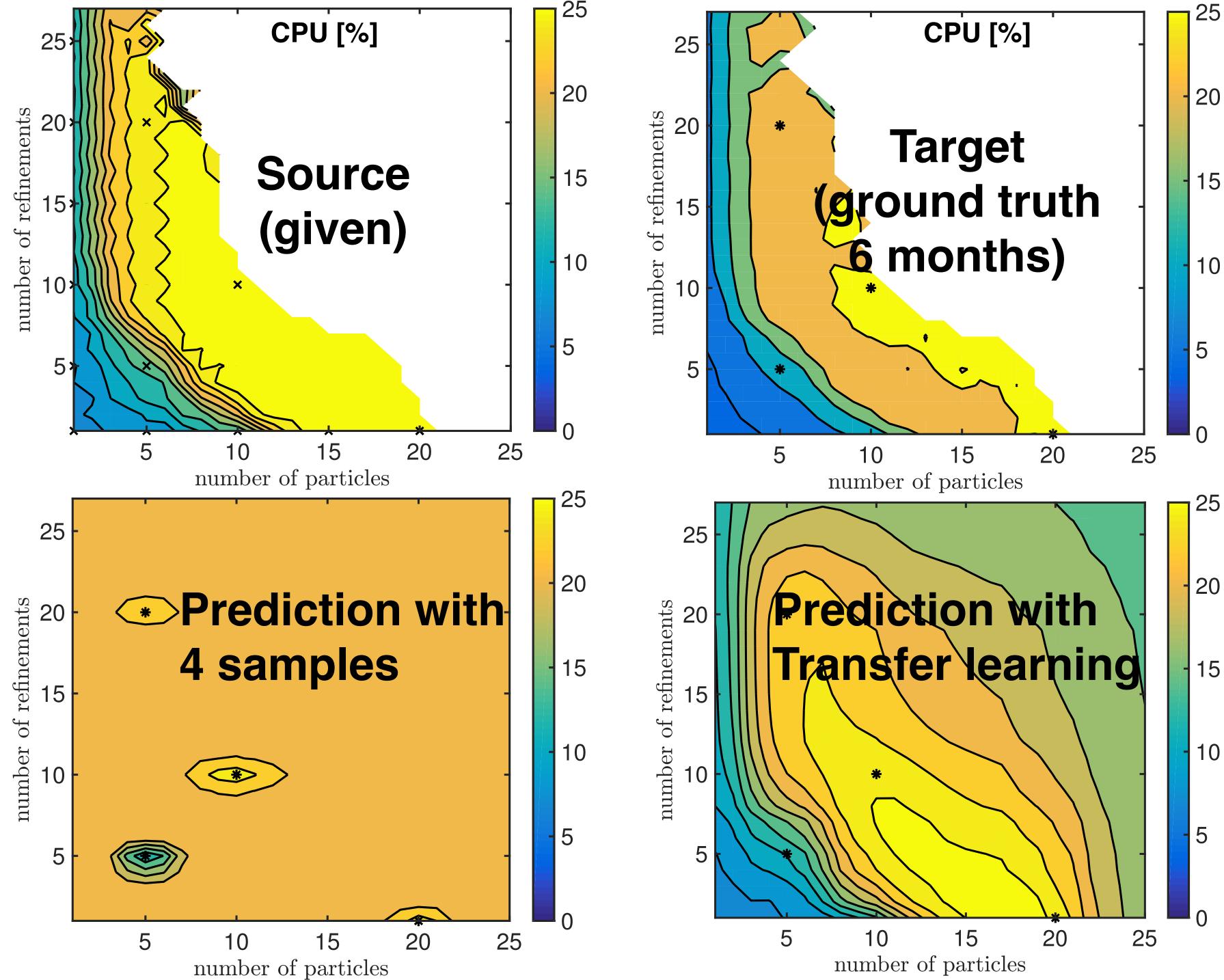
More configurations than estimated atoms in the universe



CoBot experiment: DARPA BRASS



CoBot 25 CoBot experiment 25 CoBot experiment



Details: [SEAMS '17]

Transfer Learning for Improving Model Predictions in Highly Configurable Software

Pooyan Jamshidi, Miguel Velez, Christian Kästner Carnegie Mellon University, USA {pjamshid,mvelezce,kaestner}@cs.cmu.edu

Norbert Siegmund Bauhaus-University Weimar, Germany norbert.siegmund@uni-weimar.de Prasad Kawthekar Stanford University, USA pkawthek@stanford.edu

Abstract—Modern software systems are built to be used in dynamic environments using configuration capabilities to adapt to changes and external uncertainties. In a self-adaptation context, we are often interested in reasoning about the performance of the systems under different configurations. Usually, we learn a black-box model based on real measurements to predict the performance of the system given a specific configuration. However, as modern systems become more complex, there are many configuration parameters that may interact and we end up learning an exponentially large configuration space. Naturally, this does not scale when relying on real measurements in the actual changing environment. We propose a different solution:

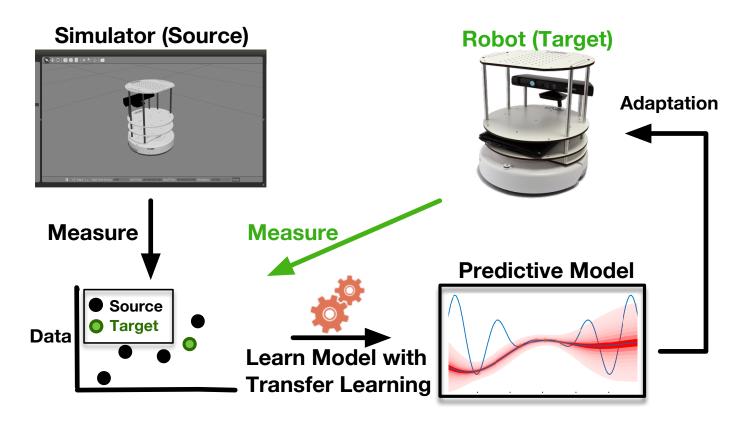
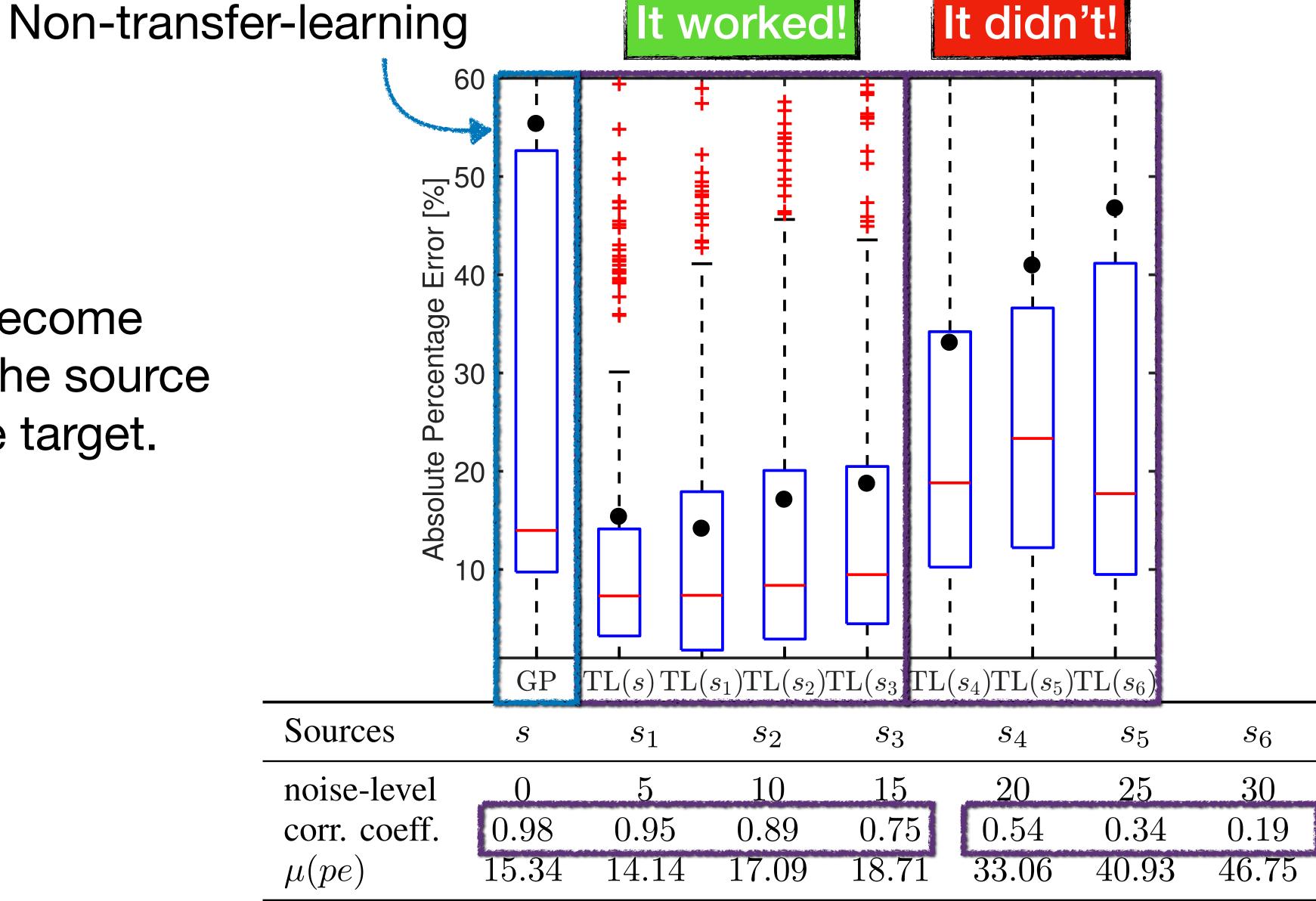
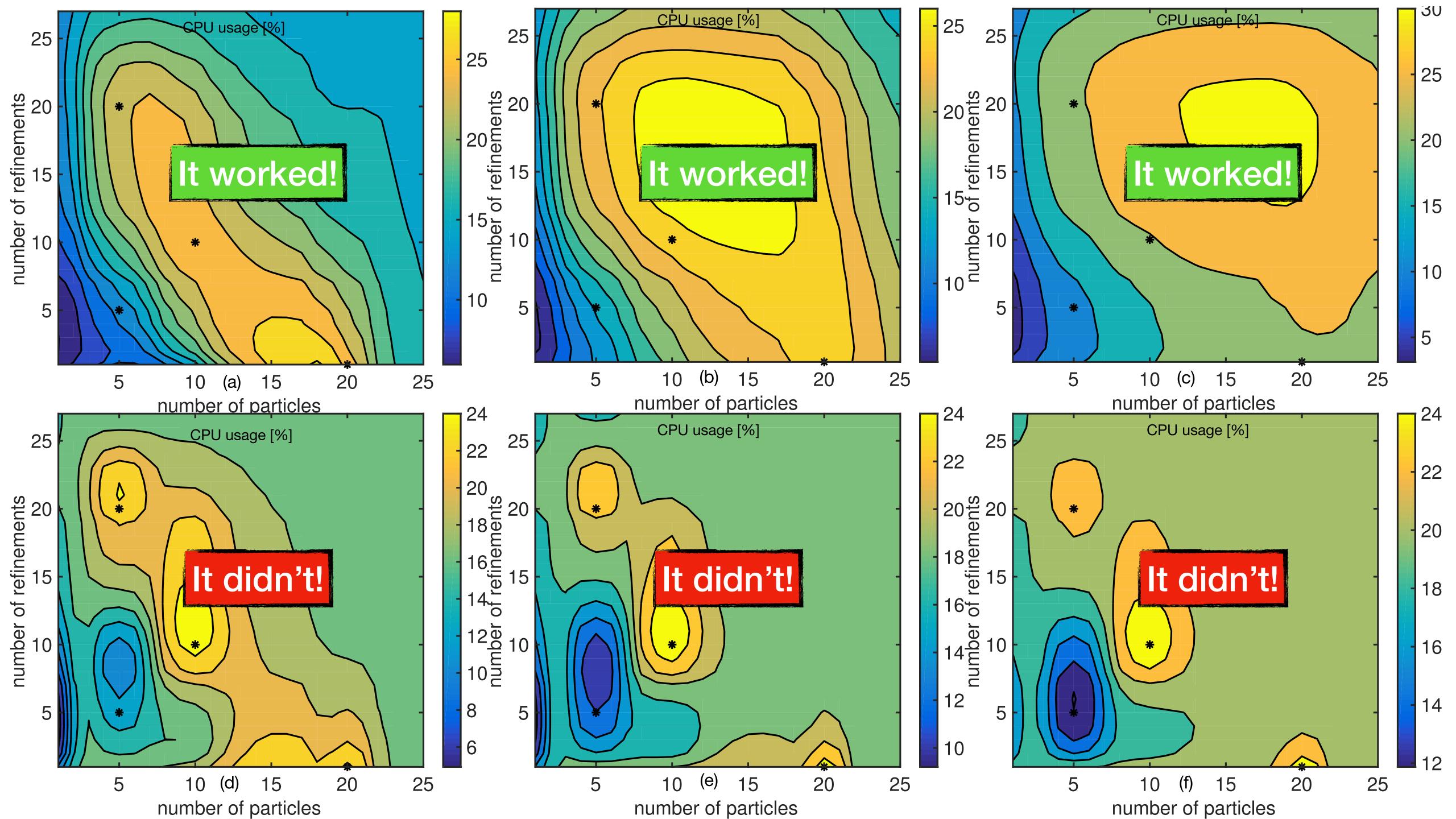


Fig. 1: Transfer learning for performance model learning.

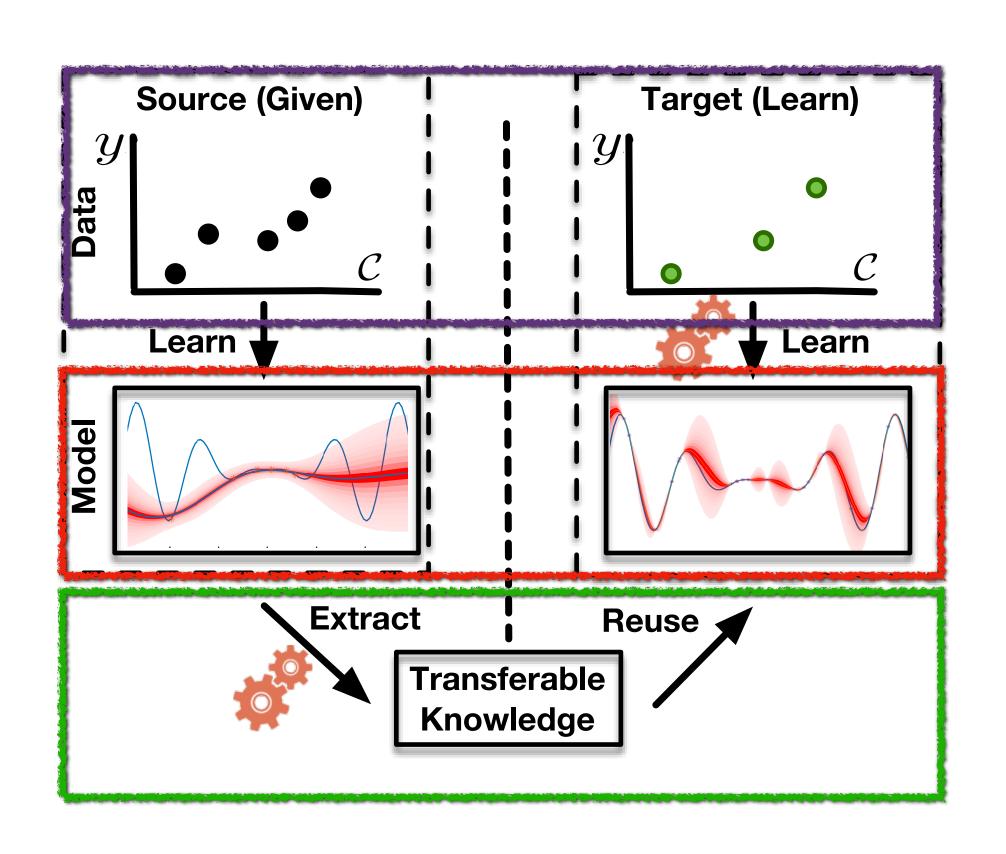
Looking further: When transfer learning goes wrong

Insight: Predictions become more accurate when the source is more related to the target.





Key question: Can we develop a theory to explain when transfer learning works?



Q1: How source and target

are "related"?

Q2: What characteristics are preserved?

Q3: What are the actionable insights?

Details: [ASE '17]

Transfer Learning for Performance Modeling of Configurable Systems: An Exploratory Analysis

Pooyan Jamshidi Carnegie Mellon University, USA Norbert Siegmund Bauhaus-University Weimar, Germany Miguel Velez, Christian Kästner Akshay Patel, Yuvraj Agarwal Carnegie Mellon University, USA

Abstract—Modern software systems provide many configuration options which significantly influence their non-functional properties. To understand and predict the effect of configuration options, several sampling and learning strategies have been proposed, albeit often with significant cost to cover the highly dimensional configuration space. Recently, transfer learning has been applied to reduce the effort of constructing performance models by transferring knowledge about performance behavior across environments. While this line of research is promising to learn more accurate models at a lower cost, it is unclear why and when transfer learning works for performance modeling. To shed light on when it is beneficial to apply transfer learning, we conducted an empirical study on four popular software systems, varying software configurations and environmental conditions, such as hardware, workload, and software versions, to identify the key knowledge pieces that can be exploited for transfer learning. Our results show that in small environmental changes (e.g., homogeneous workload change), by applying a linear transformation to the performance model, we can understand the performance behavior of the target environment, while for severe environmental changes (e.g., drastic workload change) we

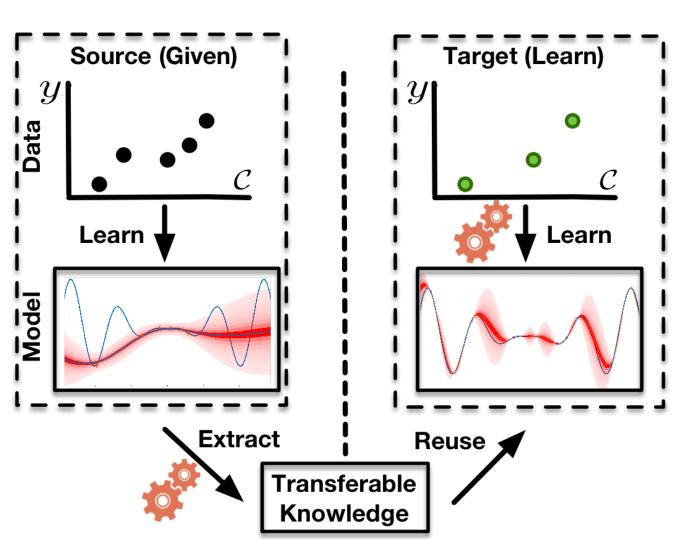


Fig. 1: Transfer learning is a form of machine learning that takes advantage of transferable knowledge from source to learn an accurate, reliable, and less costly model for the target environment.

Details: [AAAI Spring Symposium '19]

Transfer Learning for Performance Modeling of Configurable Systems: A Causal Analysis

Mohammad Ali Javidian, Pooyan Jamshidi, Marco Valtorta

Department of Computer Science and Engineering University of South Carolina, Columbia, SC, USA

Abstract

Modern systems (e.g., deep neural networks, big data analytics, and compilers) are highly configurable, which means they expose different performance behavior under different configurations. The fundamental challenge is that one cannot simply measure all configurations due to the sheer size of the configuration space. Transfer learning has been used to reduce the measurement efforts by transferring knowledge about performance behavior of systems across environments. Previously, research has shown that statistical models are indeed transferable across environments. In this work, we investigate identifiability and transportability of causal effects and statistical relations in highly-configurable systems. Our causal analysis agrees with previous exploratory analysis (Jamshidi et al. 2017) and confirms that the causal effects of configuration options be carried over across environments with high

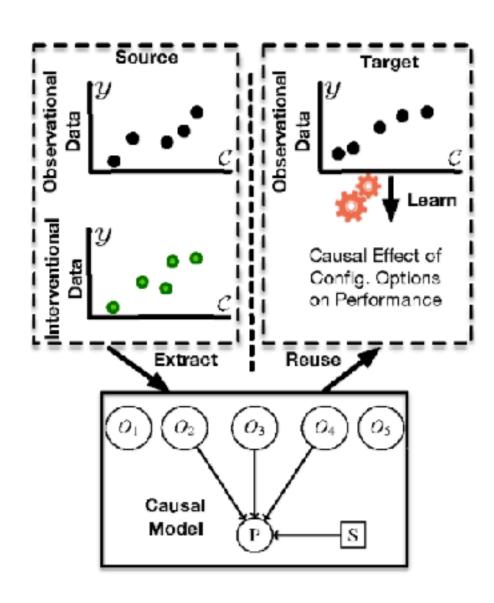
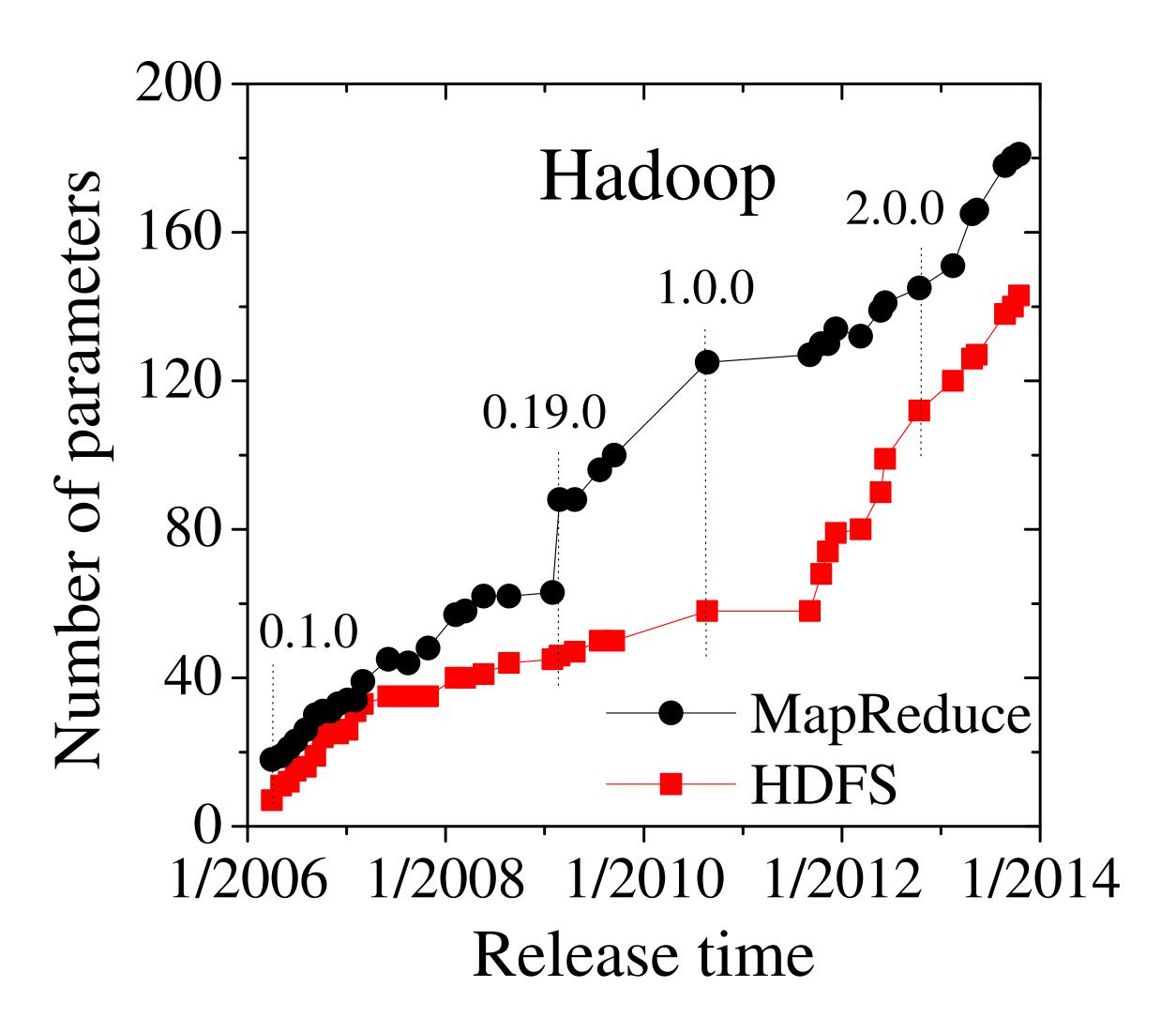


Figure 1: Exploiting causal inference for performance analysis.

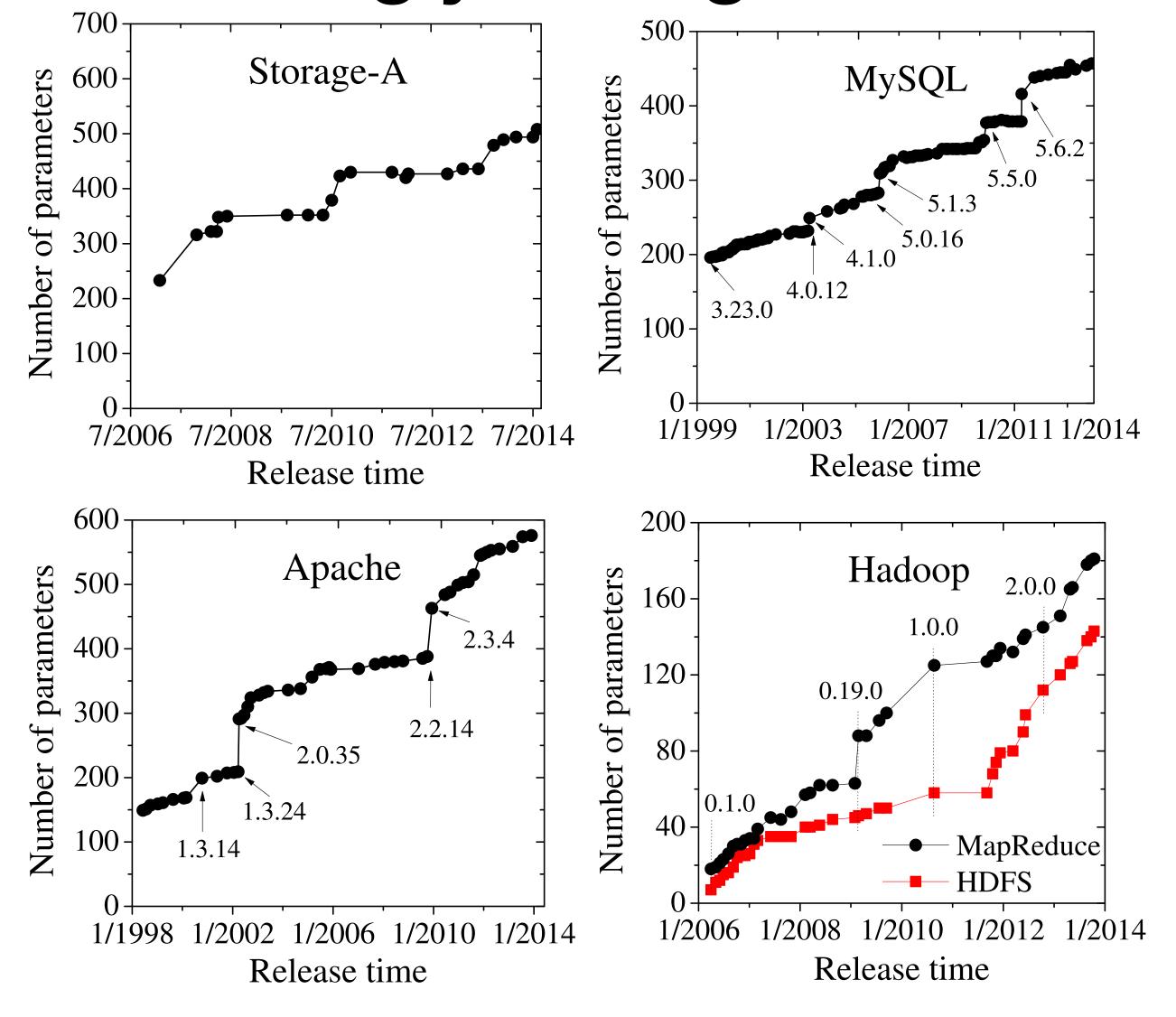


```
102
103
      drpc.port: 3772
104
     drpc.worker.threads: 64
    drpc.max buffer size: 1048576
105
     drpc.queue.size: 128
106
     drpc.invocations.port: 3773
107
     drpc.invocations.threads: 64
108
     drpc.request.timeout.secs: 600
109
     drpc.childopts: "-Xmx768m"
110
     drpc.http.port: 3774
111
     drpc.https.port: -1
112
     drpc.https.keystore.password:
113
     drpc.https.keystore.type: "JKS"
114
     drpc.http.creds.plugin: org.apache.storm.security.auth.DefaultHttpCredentialsPlugi
115
     drpc.authorizer.acl.filename: "drpc-auth-acl.yaml"
116
      drpc.authorizer.acl.strict: false
117
118
      transactional.zookeeper.root: "/transactional"
119
      transactional.zookeeper.servers: null
120
      transactional.zookeeper.port: null
121
122
123
     ## blobstore configs
     supervisor.blobstore.class: "org.apache.storm.blobstore.NimbusBlobStore"
124
125 supervisor.blobstore.download.thread.count: 5
     supervisor.blobstore.download.max_retries: 3
     supervisor.localizer.cache.target.size.mb: 10240
127
     supervisor.localizer.cleanup.interval.ms: 600000
128
129
```

Empirical observations confirm that systems are becoming increasingly configurable



Empirical observations confirm that systems are becoming increasingly configurable



[Tianyin Xu, et al., "Too Many Knobs...", FSE'15]

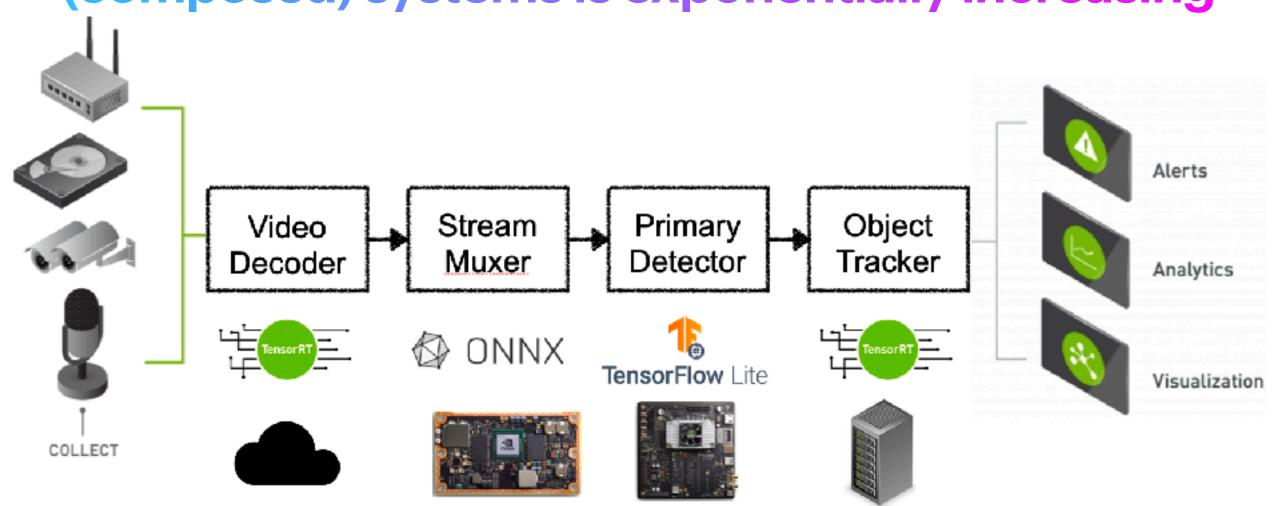
Configurations determine the performance behavior

```
void Parrot setenv(. . . name,. . . value){
#ifdef PARROT HAS SETENV
 my_setenv(name, value, 1);
                                             Speed
#else
  int name len=strlen(name);
  int val_len=strlen(value);
  char* envs=glob env;
  if(envs==NULL){
    return;
  strcpy(envs,name);
  strcpy(envs+name_len,"=");
  strcpy(envs+name_len + 1,value);
                                                                   Energy
  putenv(envs);
#endif
```

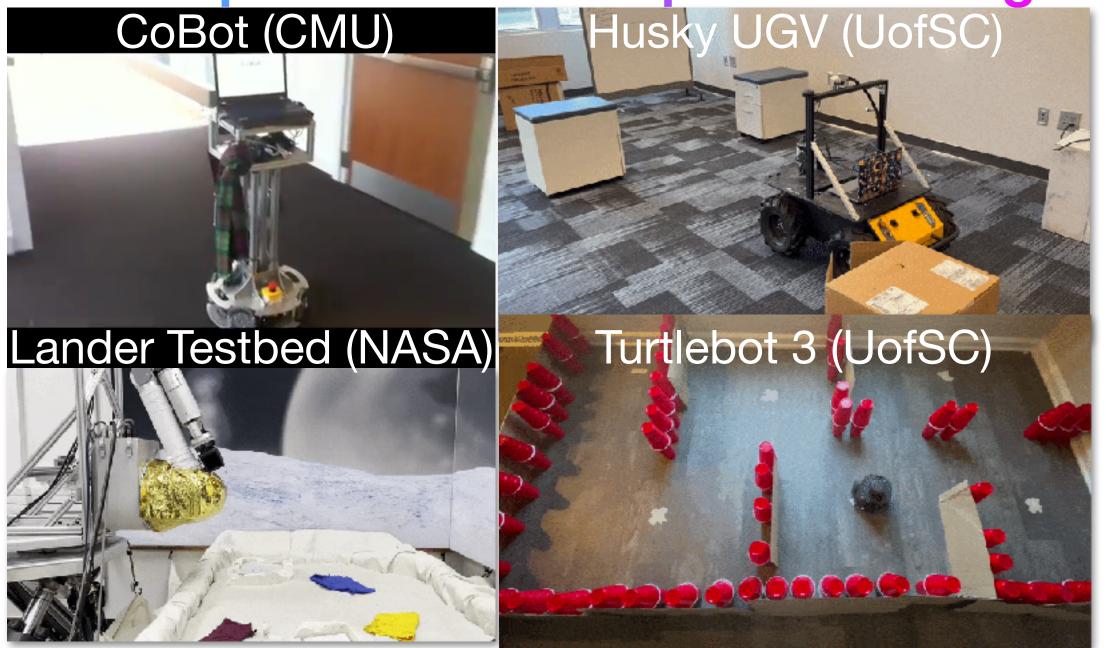
Challenges of configurations

- Difficulties in knowing which parameters should be set
- Setting the parameters to obtain the intended behavior
- Reasoning about multiple objectives (energy, speed)

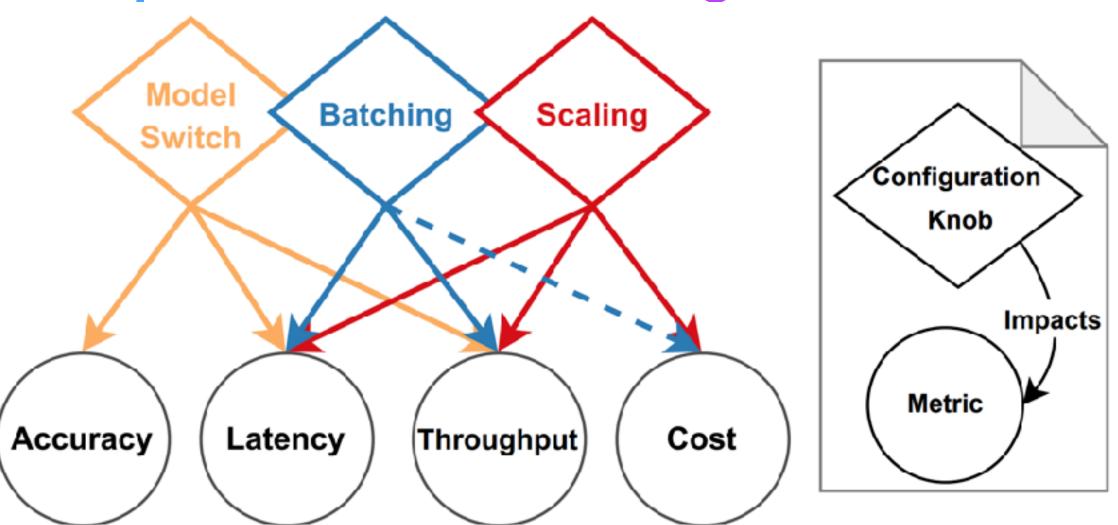
The variability space (design space) of (composed) systems is exponentially increasing



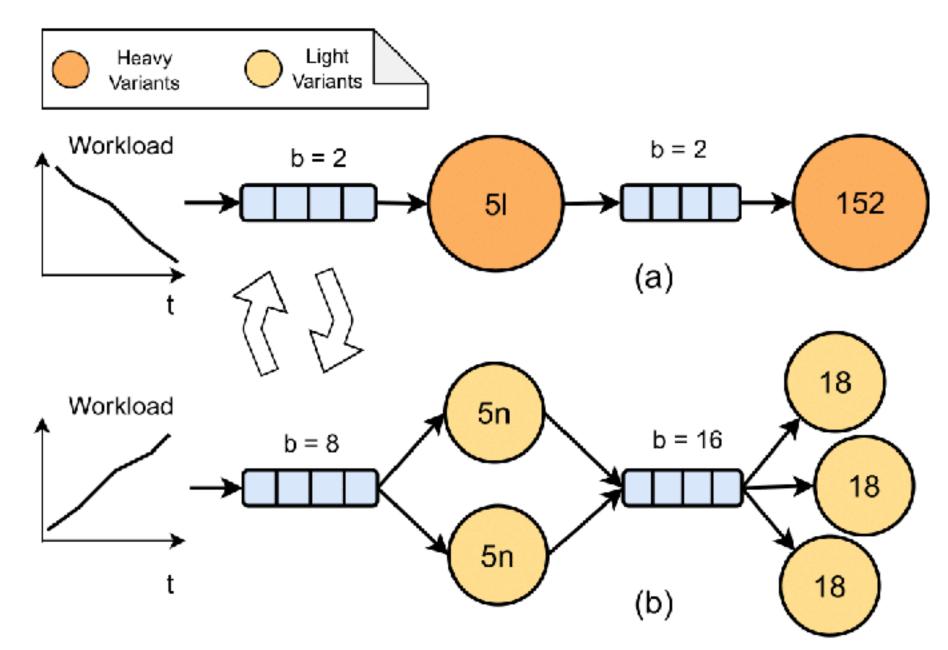
Systems operate in uncertain environments with imperfect and incomplete knowledge



Performance goals are competing and users have preferences over these goals



Goal: Enabling users to find the right quality tradeoff

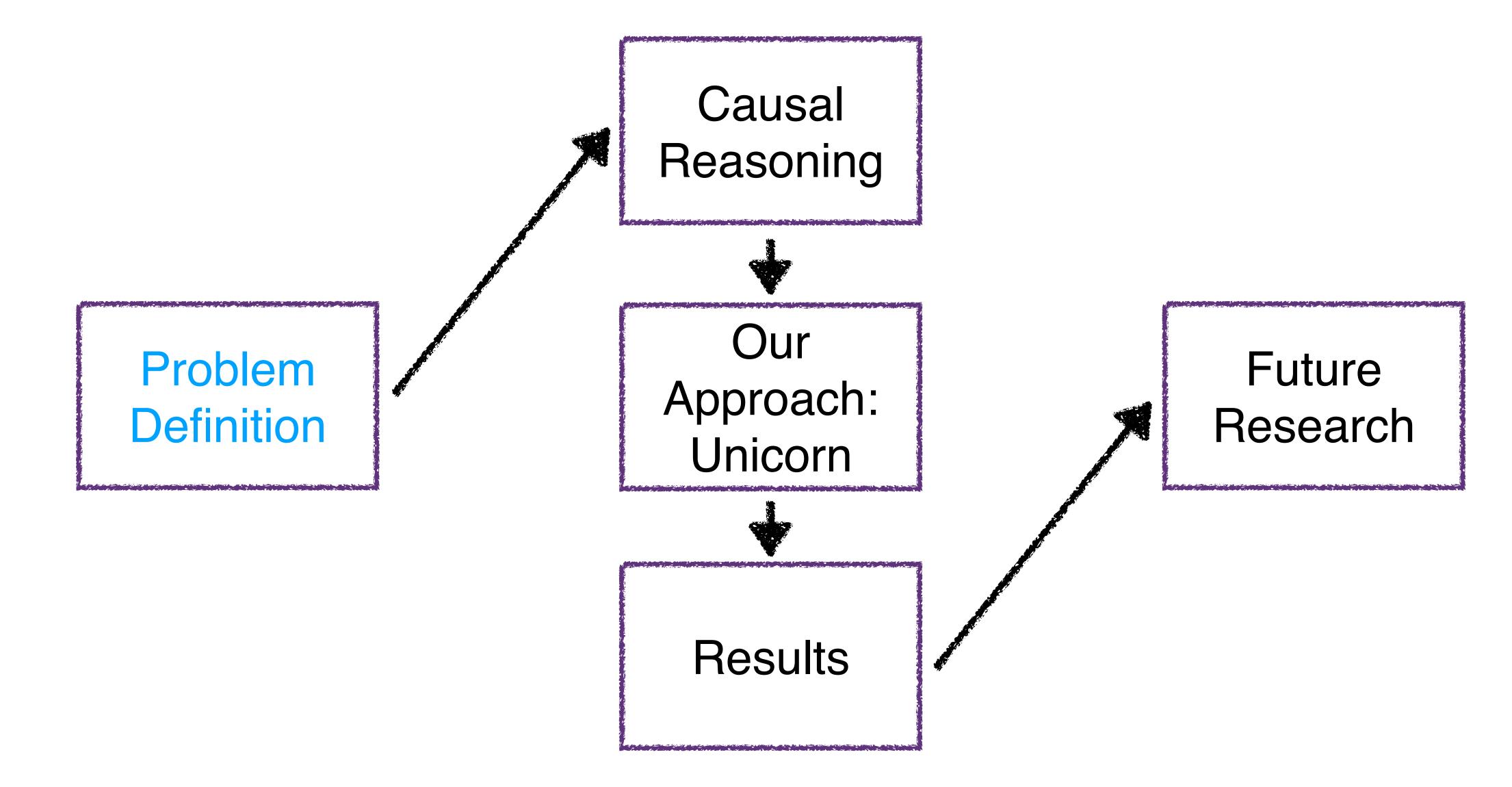


The goal of our research is...

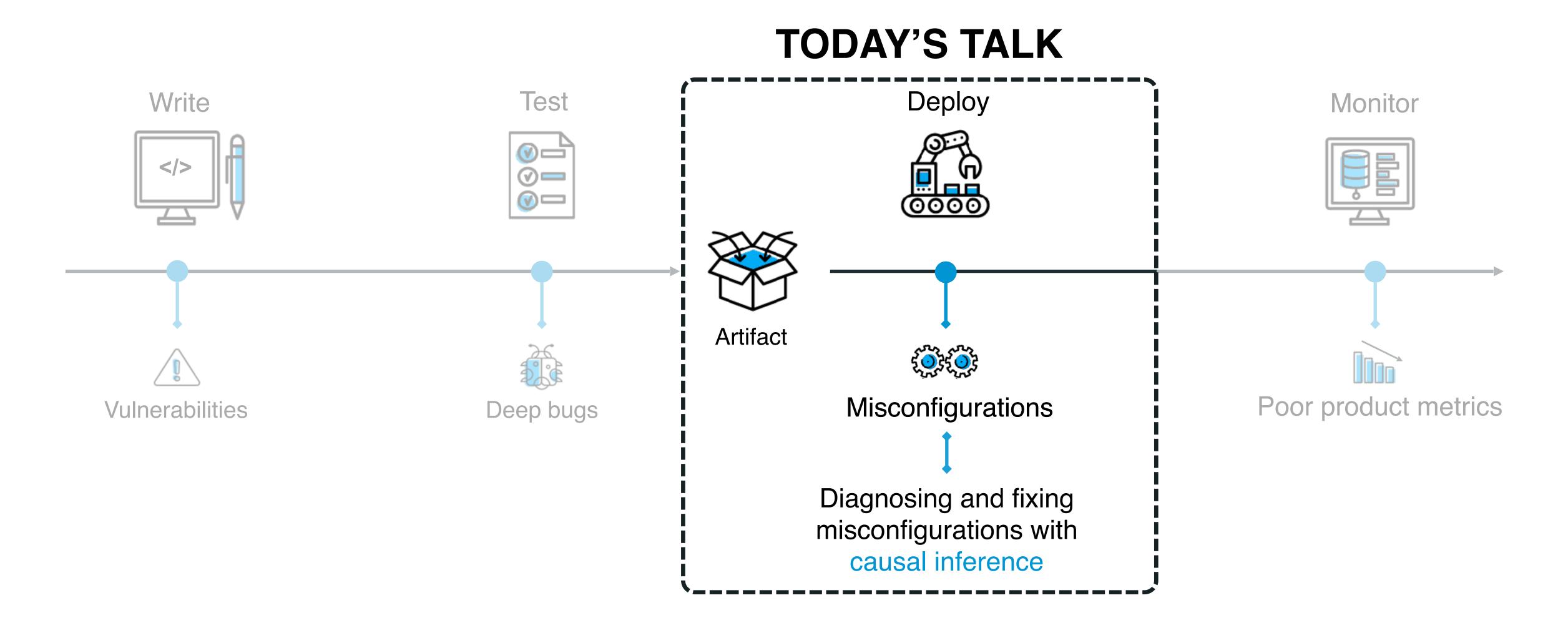
Understanding the performance behavior of real-world highly-configurable systems that scale well...

... and enabling developers/users to reason about qualities (performance, energy) and to make tradeoffs?

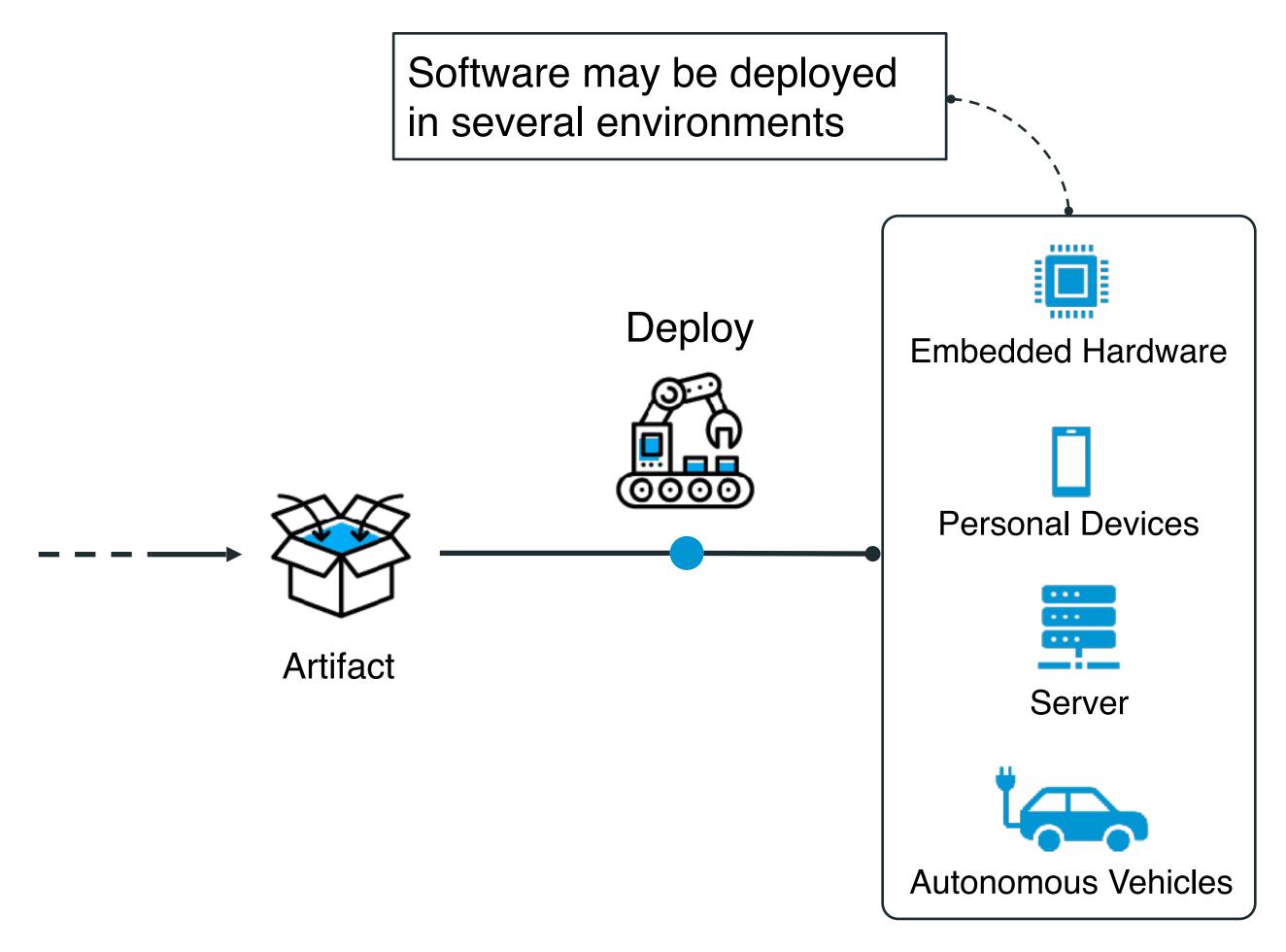
Outline



A Typical Software Lifecycle



Today's Talk

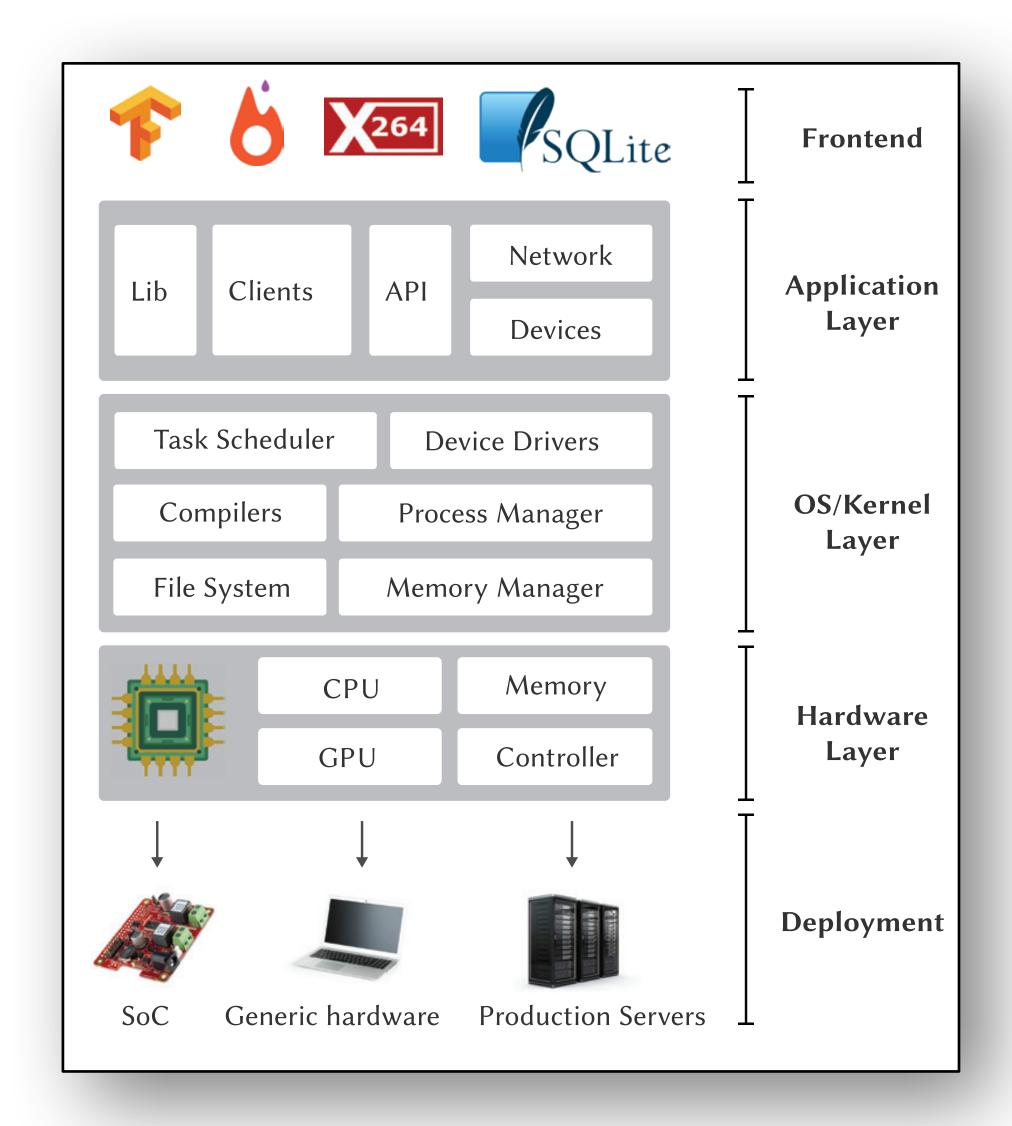


Deployment Environments

Challenge

- Each deployment environment must be configured correctly
- This is challenging and prone to misconfigurations

Today's Talk



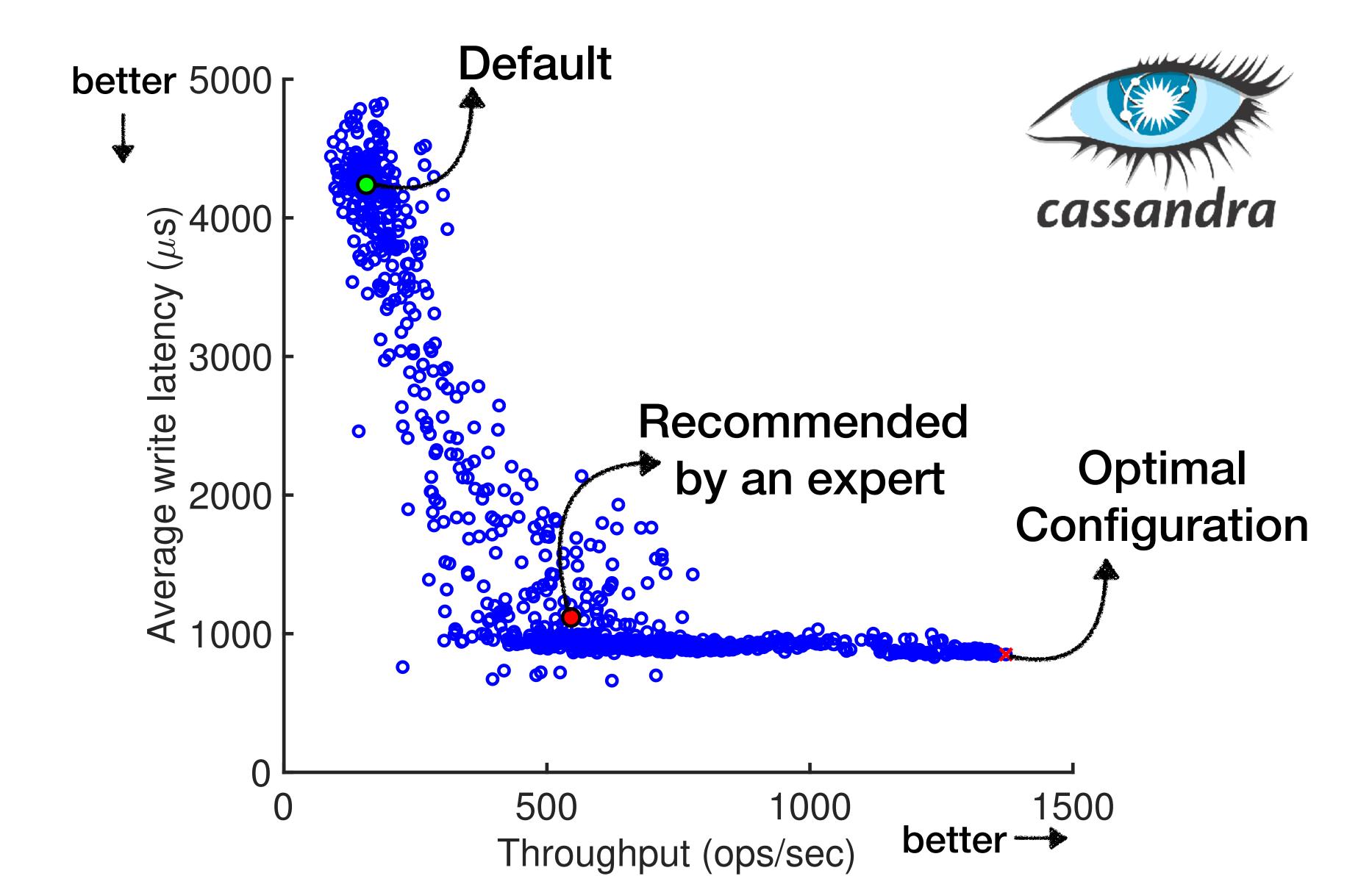
Problem

- Each deployment environment must be configured correctly
- This is challenging and prone to misconfigurations

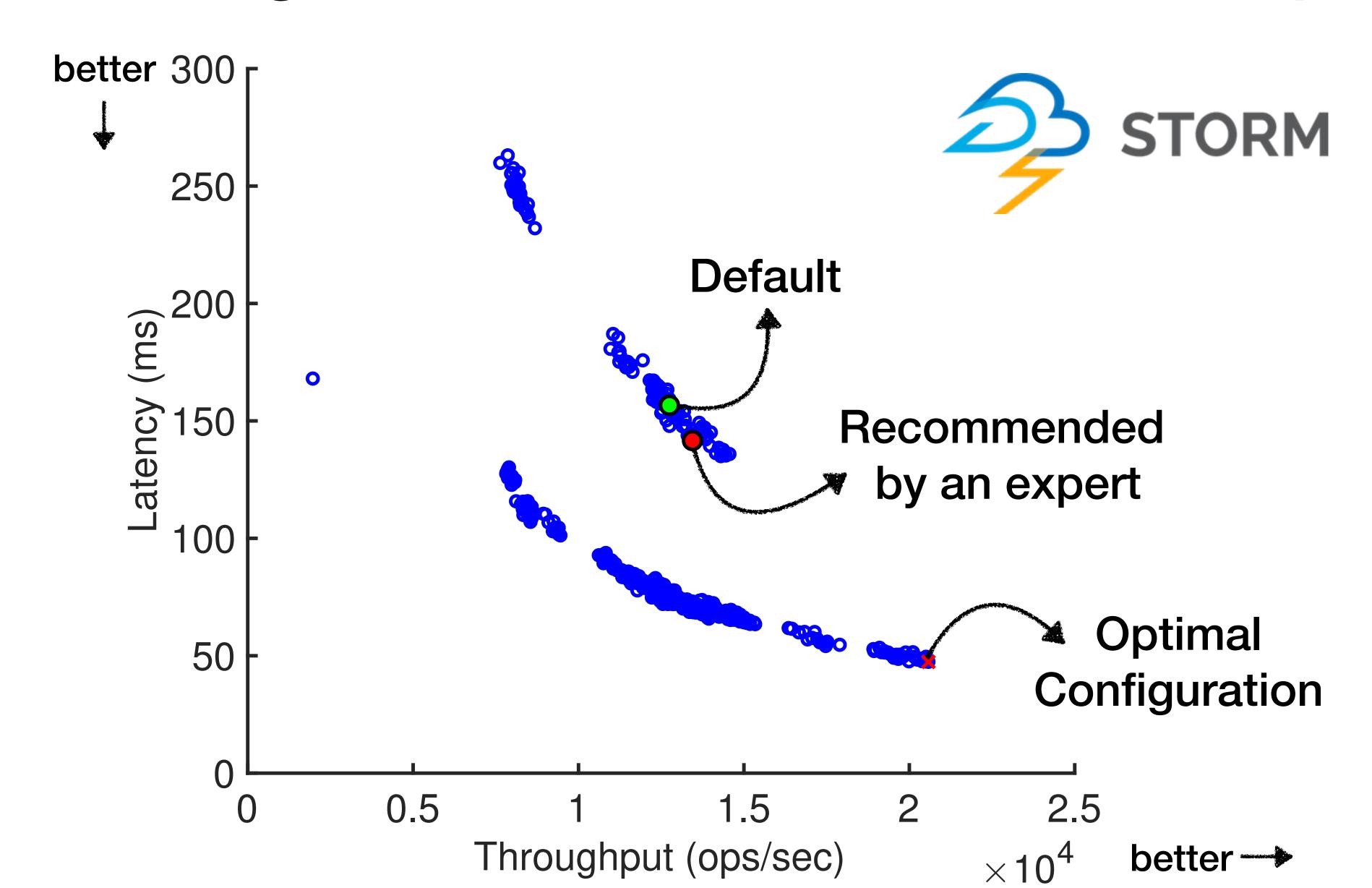
Why?

- The configuration options lie across the software stack
- There are several non-trivial interactions with one another
- The configuration space is combinatorially large with 100's of configuration options

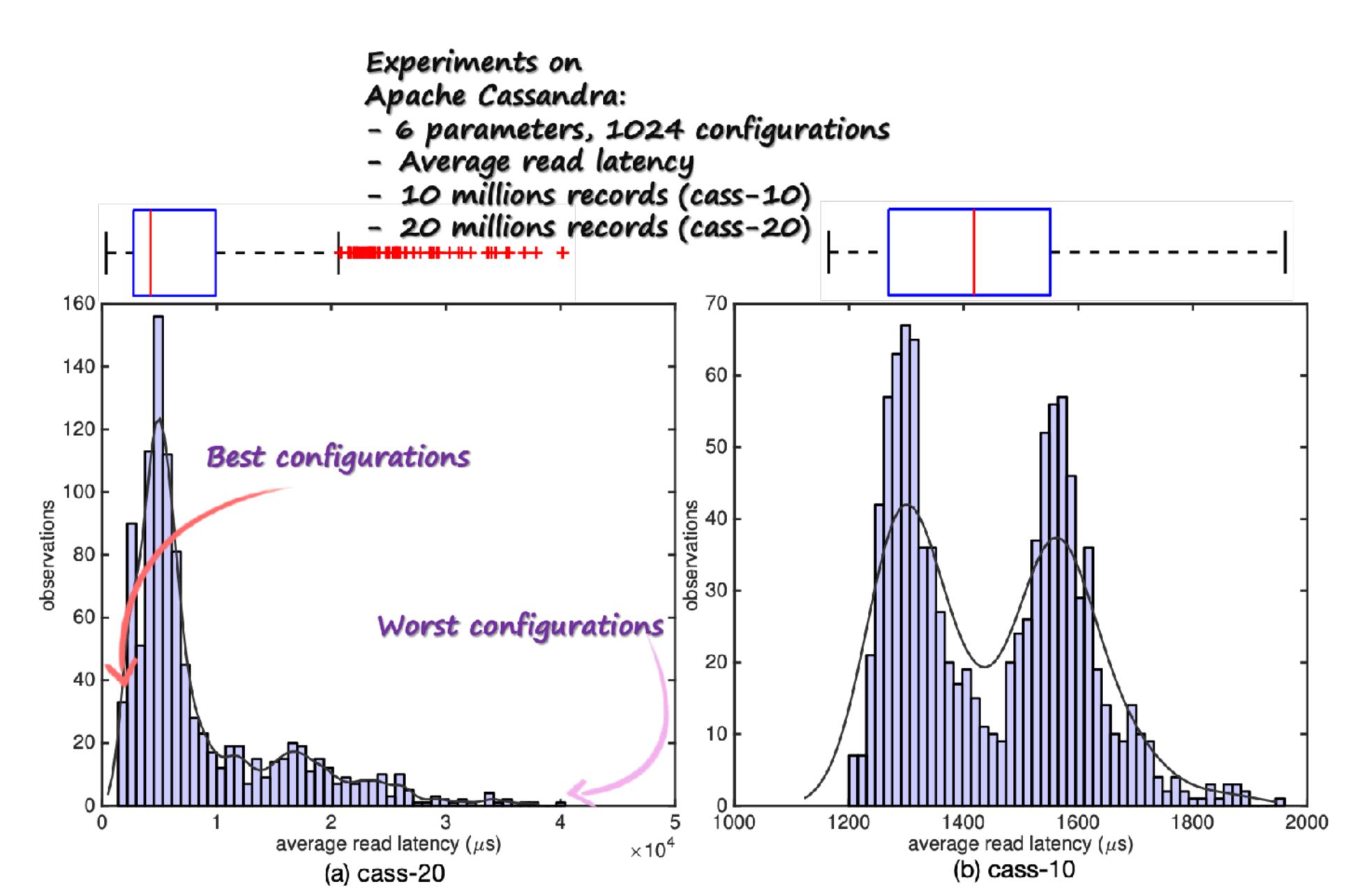
Default configuration was bad, so was the expert'



Default configuration was bad, so was the expert'



Performance behavior varies in different environments



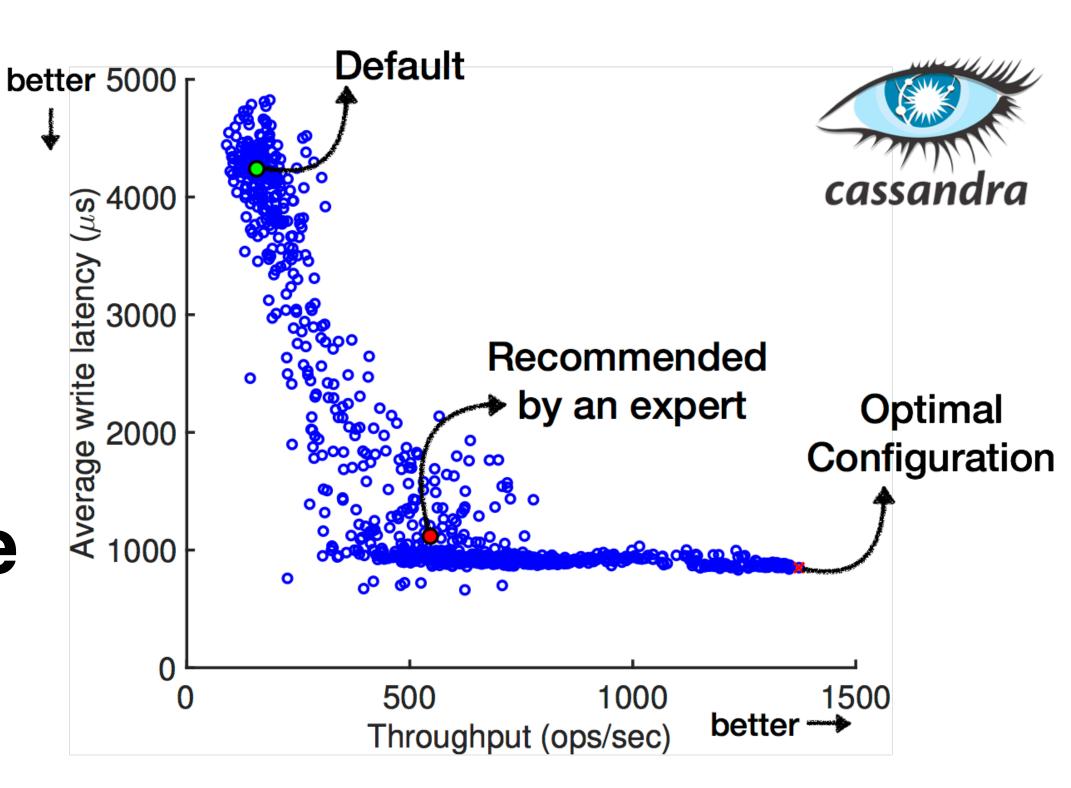
Why this is an important problem?

Optimal configuration

- 2X-10X faster than the worst
- Noticeably faster than the median
- Default is bad
- Expert's is not optimal

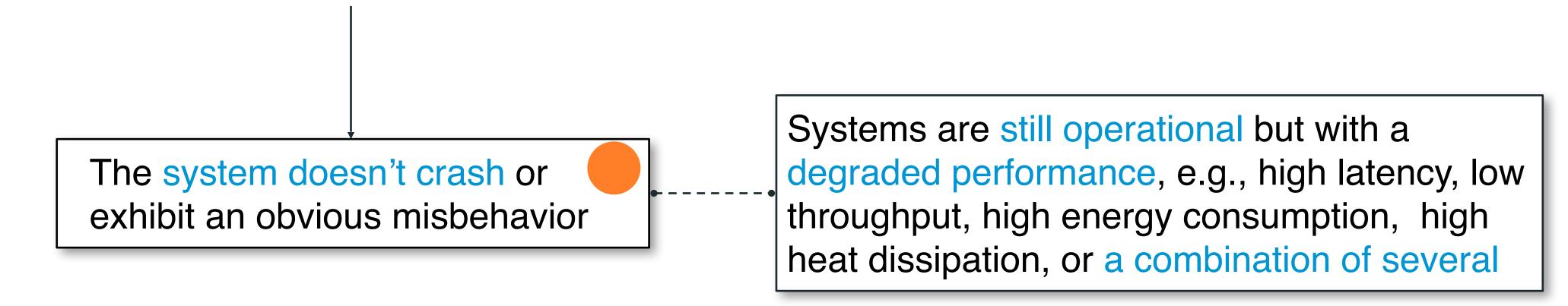
Exploring large configuration space

- Exhaustive search is expensive
- Specific to the environment (hardware/workload/version)



Misconfiguration and its Effects

- Misconfigurations can elicit unexpected interactions between software and hardware
- These can result in non-functional faults
 - Affecting non-functional system properties like latency, throughput, energy consumption, etc.



Motivating Example



CUDA performance issue on tx2

Home > Autonomous Machines > Jetson & Embedded Systems > Jetson TX2

The user is transferring the code from one hardware to another

william_wu

When we are trying to transplant our CUDA source code from TX1 to TX2, it behaved strange.

We noticed that TX2 has twice computing-ability as TX1 in GPU, as expectation, we think TX2 will 30% - 40% faster than TX1 at least.

Unfortunately, most of our code base spent twice the time as TX1, in other words, TX2 only has 1/2 speed as TX1, mostly. We believe that TX2's CUDA API runs much slower than TX1 in many cases.

The target hardware is faster than the the source hardware. User expects the code to run at least 30-40% faster.

The code ran 2x slower on the more powerful hardware

Jun '17

Motivating Example

June 3rd



william_wu

Any suggestions on how to improve my performance? Thanks!

June 4th



AastaLLL 1 Moderator

TX2 is pascal architecture. Please update your CMakeLists:

+ set(CUDA_STATIC_RUNTIME OFF)

. .

+ -gencode=arch=compute_62,code=sm_62

June 4th



william_wu

We have already tried this. We still have high latency.

Any other suggestions?

June 5th



AastaLLL

Moderator

Please do the following and let us know if it works

- 1. Install JetPack 3.0
- 2. Set nvpmodel=MAX-N
- 3. Run jetson_clock.sh

The user had several misconfigurations

In Software:

- **X** Wrong compilation flags
- ★ Wrong SDK version

In Hardware:

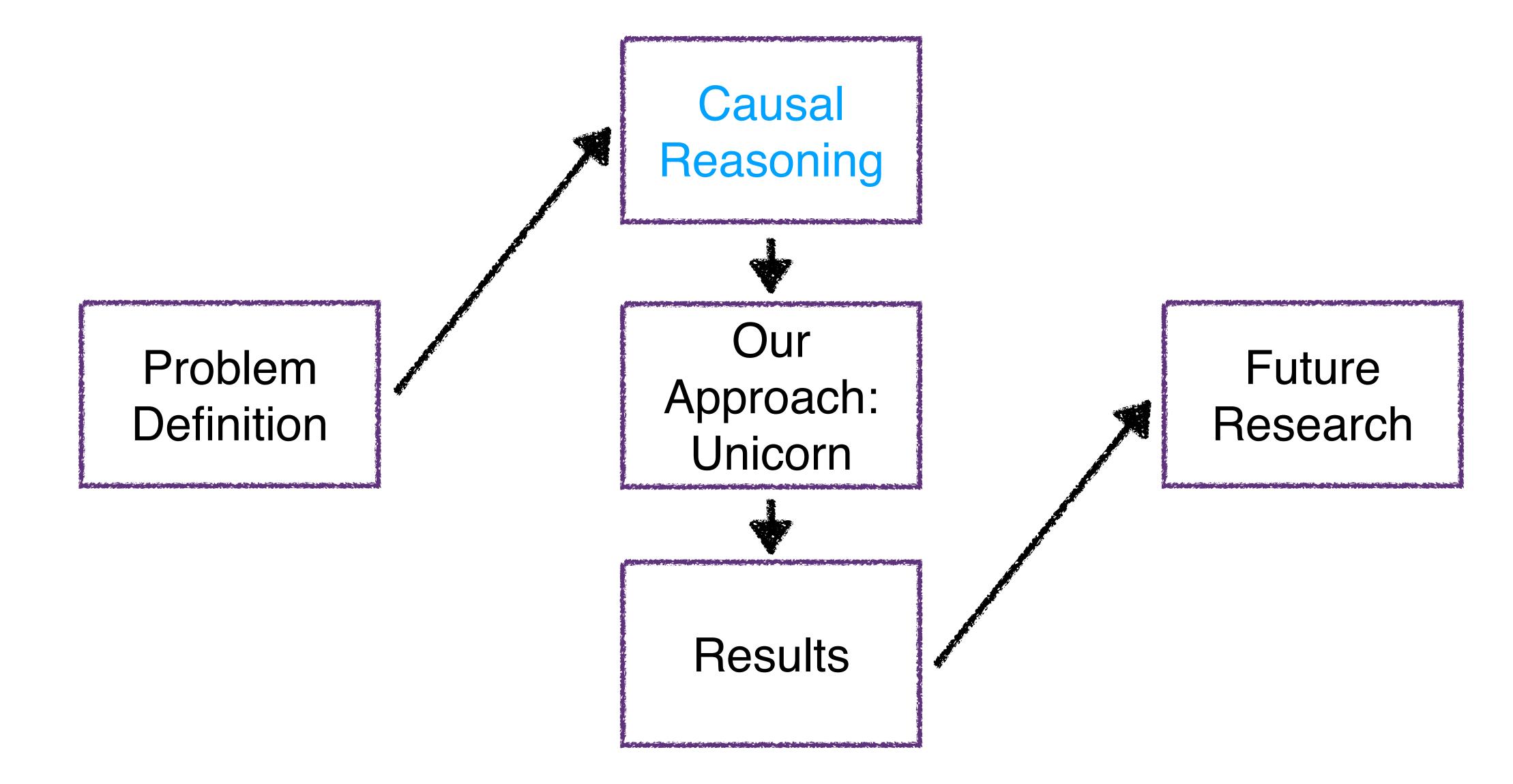
- **X** Wrong power mode
- ★ Wrong clock/fan settings

The discussions took 2 days

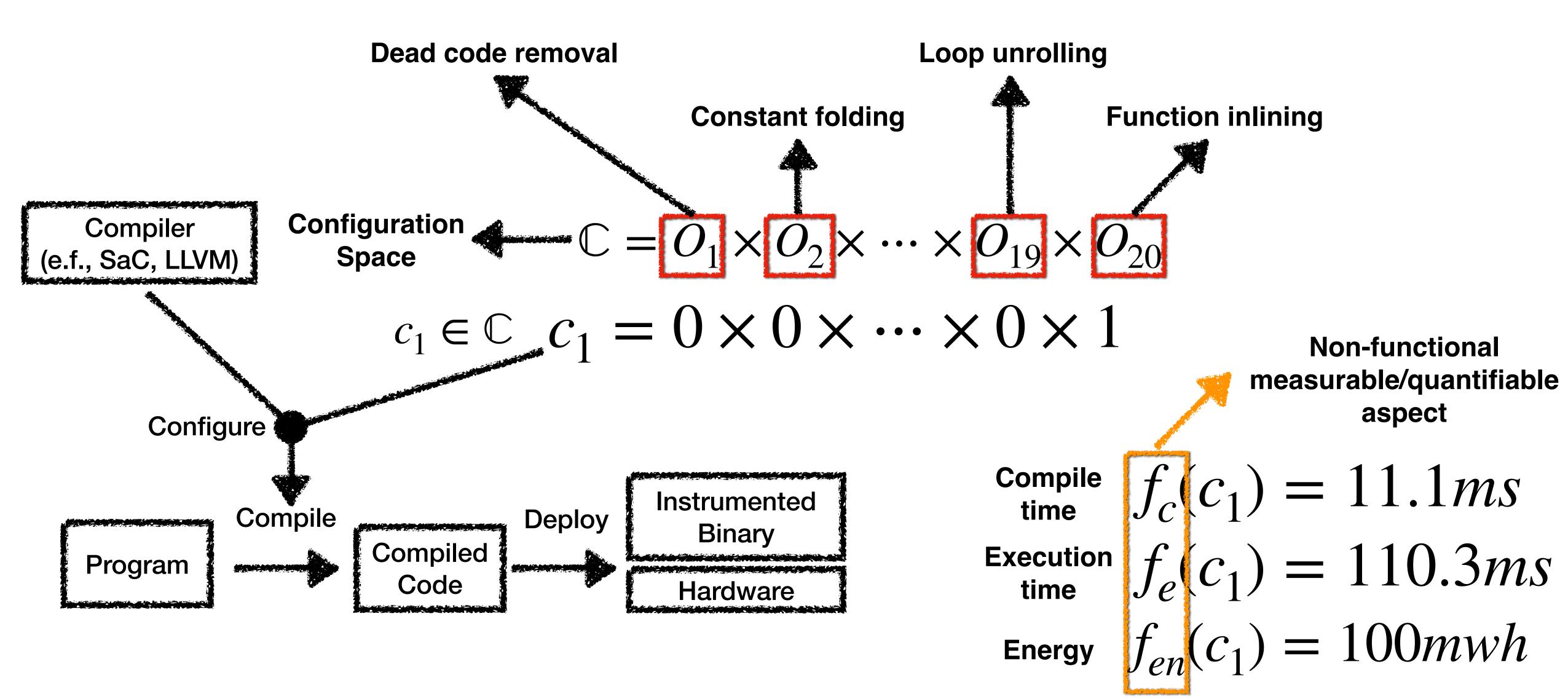
How to resolve such issues faster?

How to resolve these issues faster?

Outline



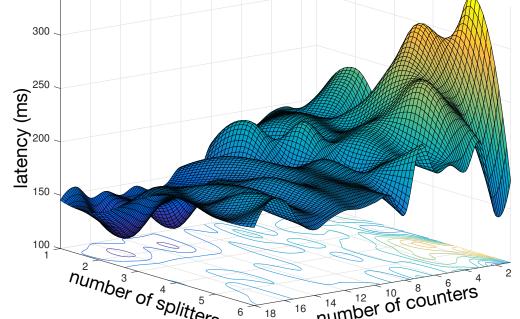
Performance measurement



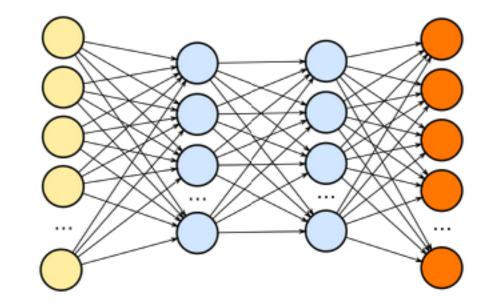
Blackbox Performance Modeling

	Bitrate (bits/s)	EnableP adding	•••	Cache Misses	•••	Throughput (fps)
C ₁	1k	1		42m		7
C ₂	2k	1		32m		22
•••						
Cn	5k	0		12m		25

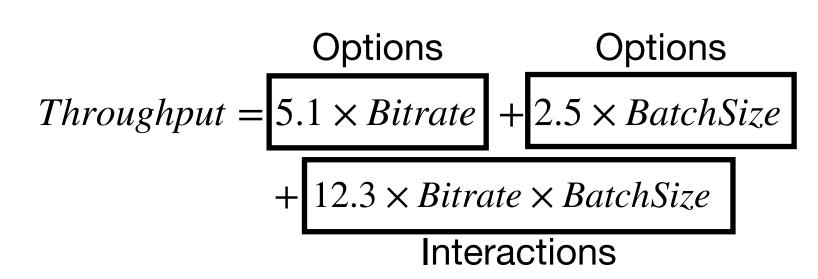
Observational Data



Gaussian Process



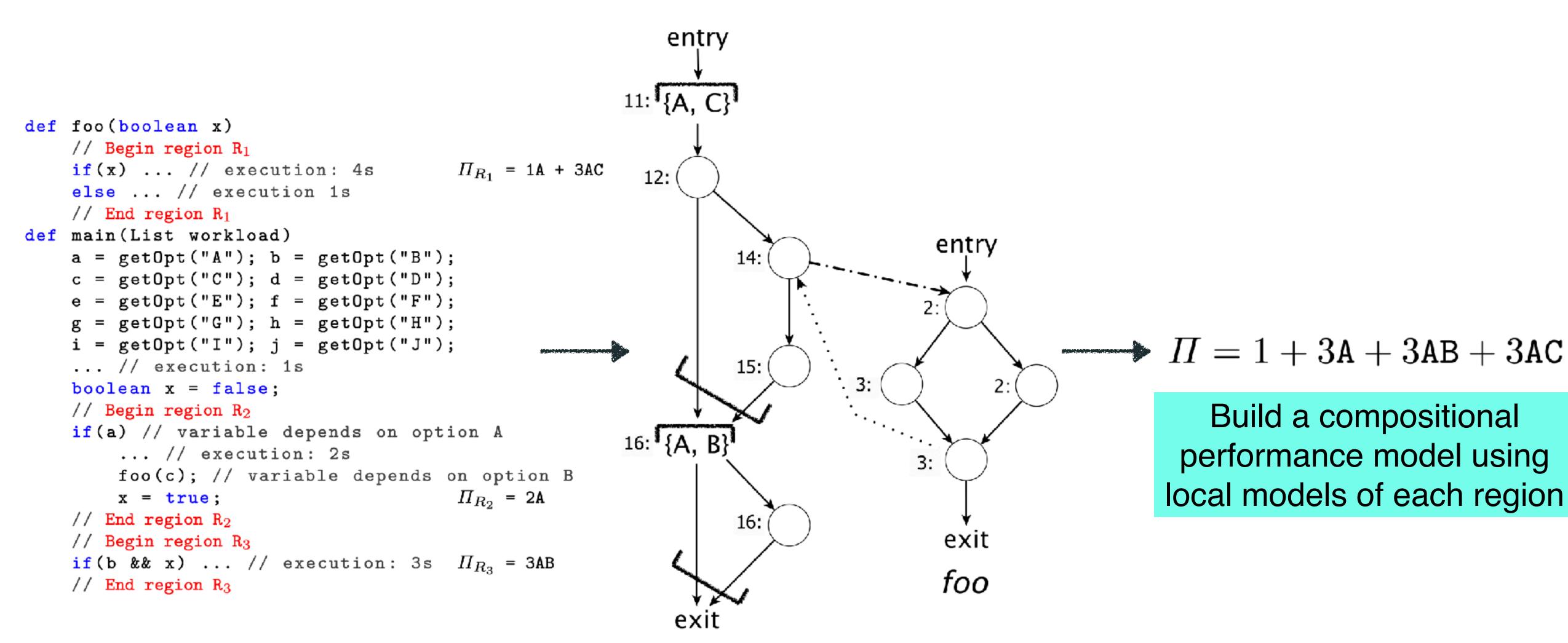
Neural Network



Polynomial Regression

These methods rely on statistical correlations to extract meaningful information required for performance tasks.

Whitebox Performance Modeling



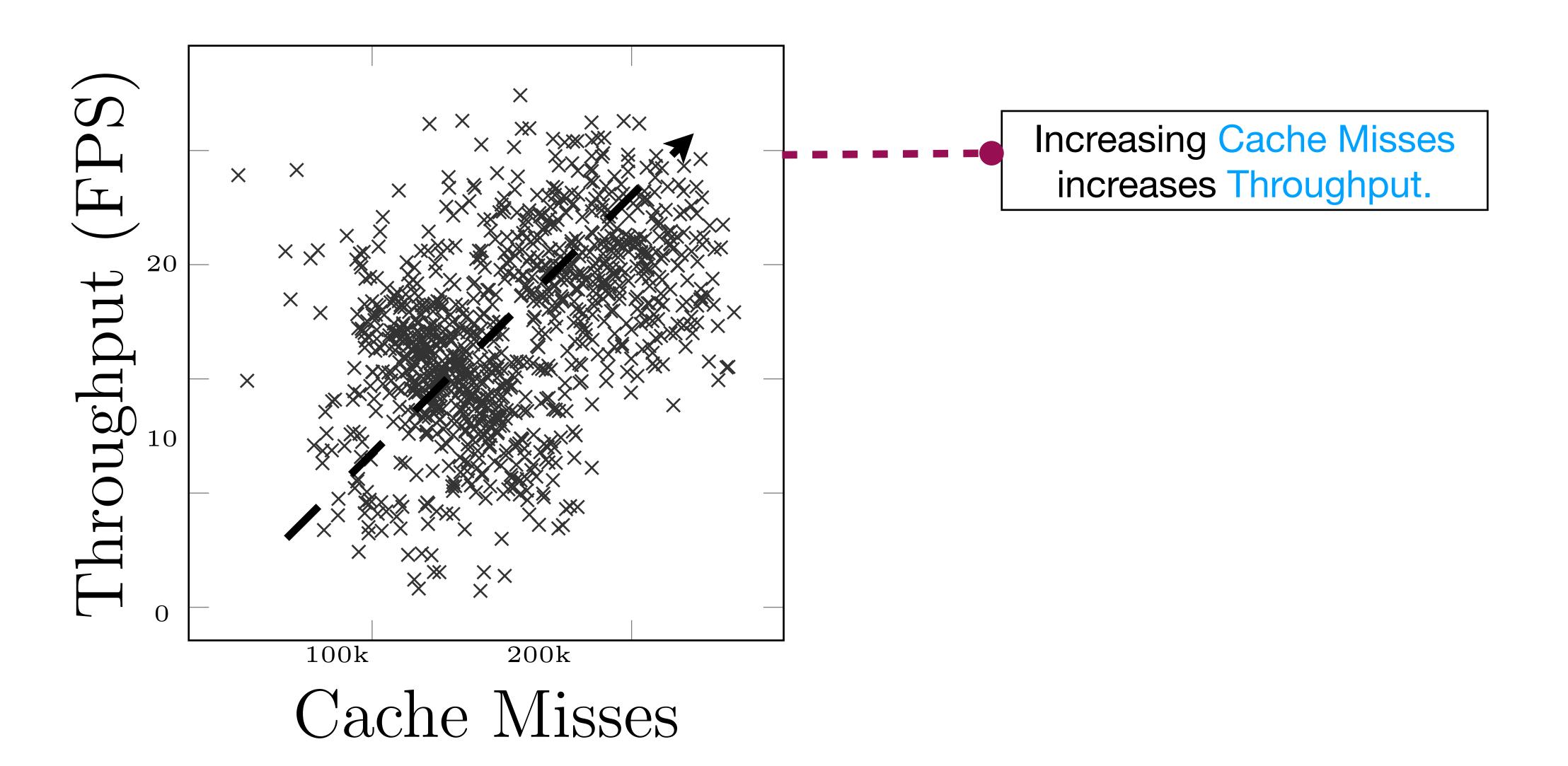
main

These methods rely on program analysis techniques (static and dynamic analysis of the code) to extract meaningful information required for performance tasks.

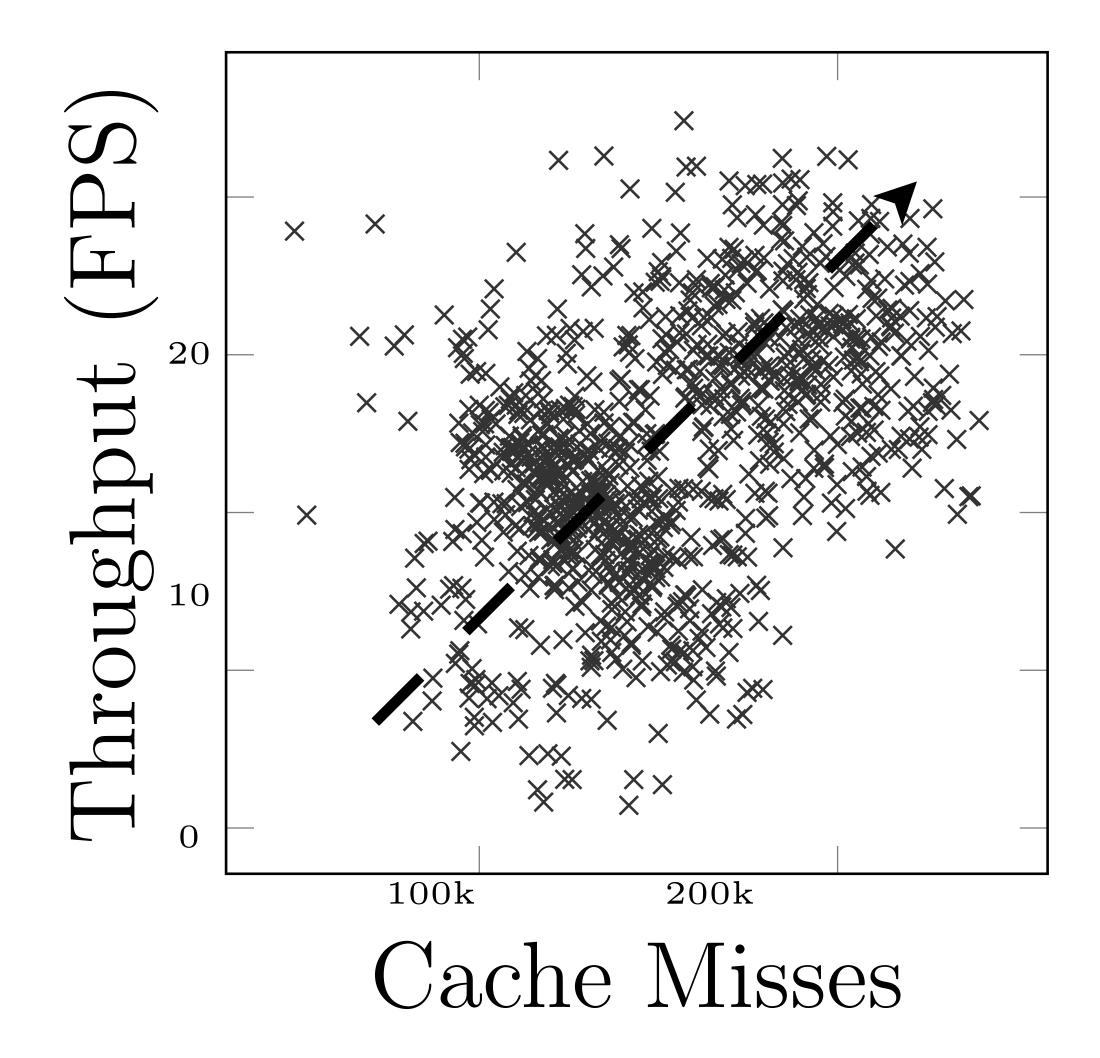
Performance models suffer from several shortcomings

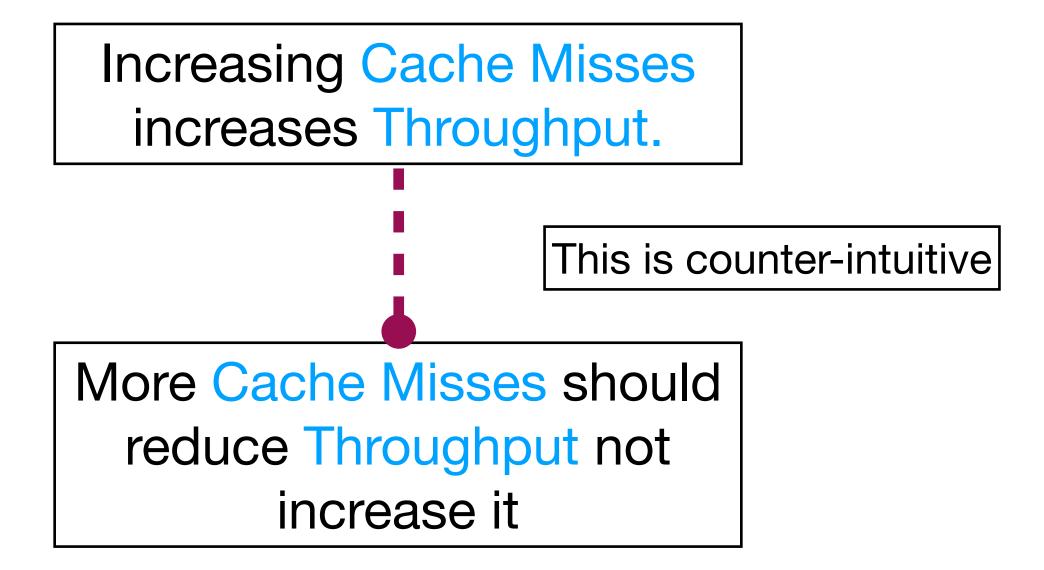
- Blackbox performance models could produce incorrect explanations and unreliable/unstable predictions across environments and in the presence of measurement noise.
- Whitebox performance models do not scale well to real-world systems (with many configuration options and large code bases.

Incorrect explanation



Incorrect explanation

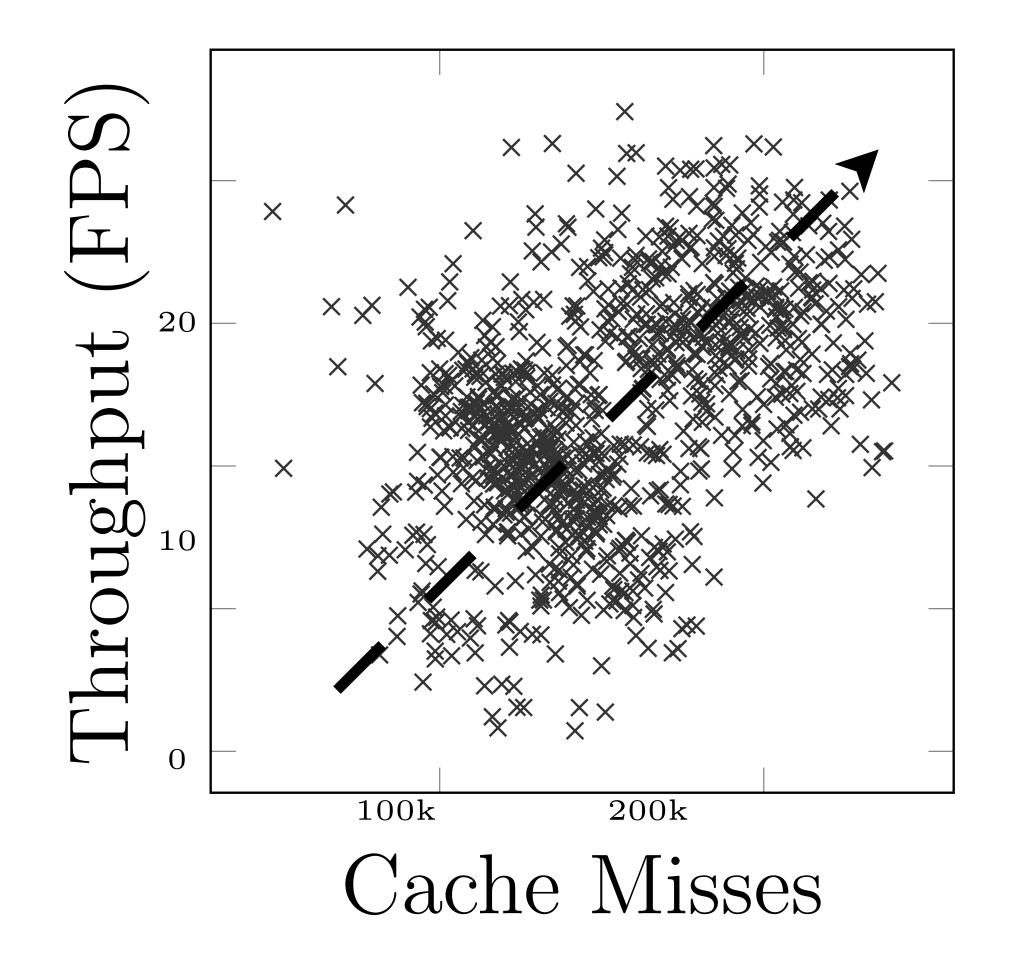


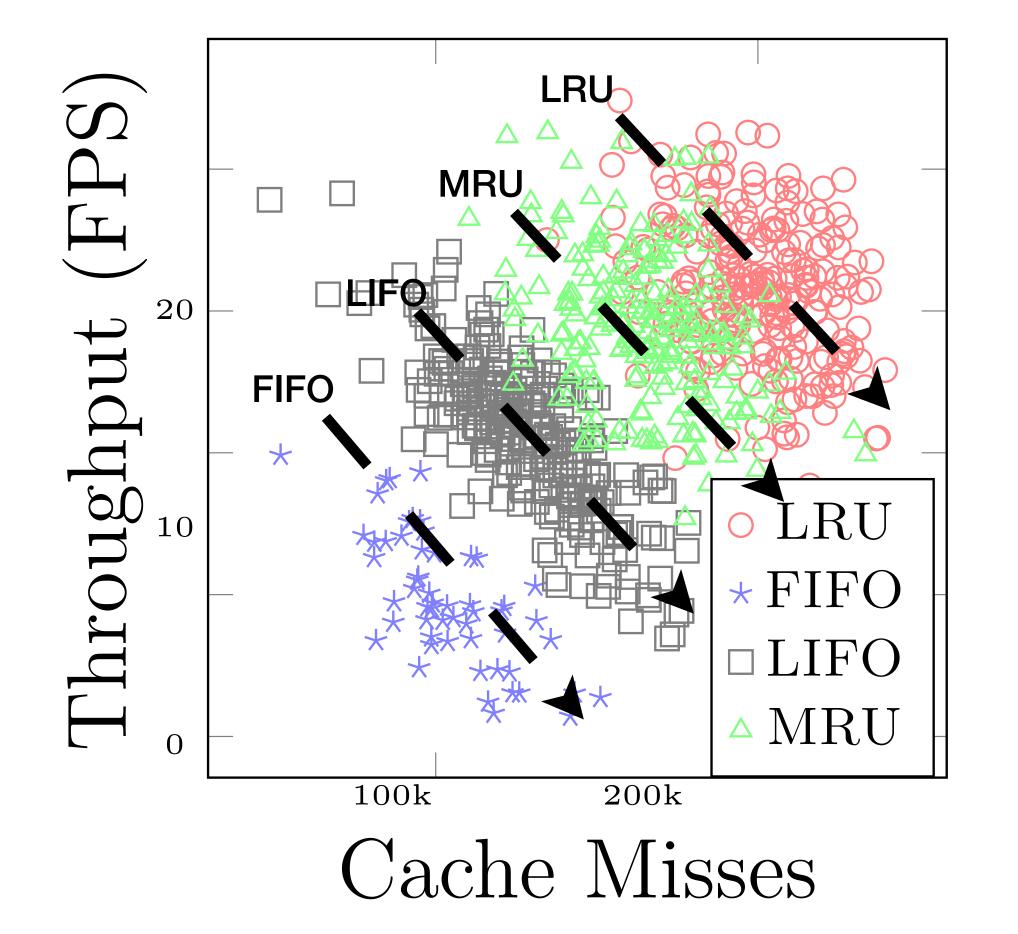




Any statistical models built on this data will be incorrect.

Incorrect explanation





Segregating data on Cache Policy indicates that within each group Increase of Cache Misses result in a decrease in Throughput.

Unstable predictions

Performance influence model in TX2:

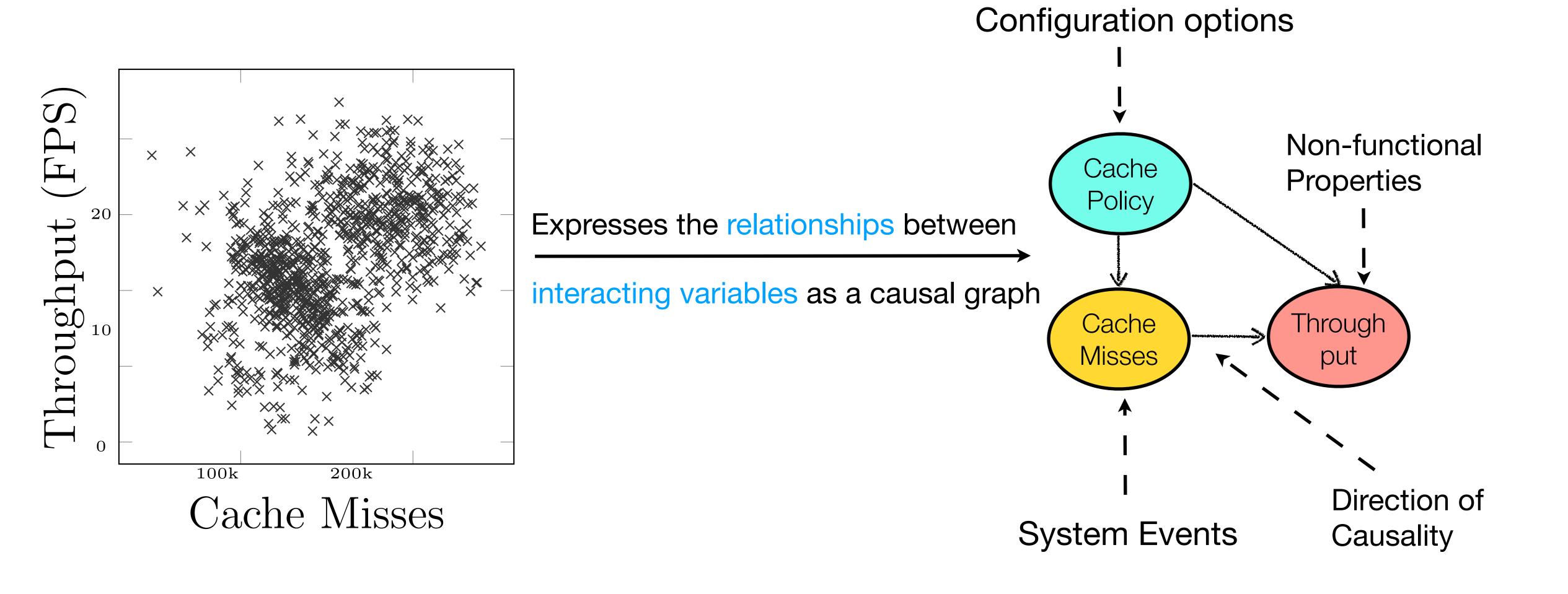
$$Throughput = 2 \times Bitrate + 1.9 \times BatchSize + 1.8 \times BufferSize + 0.5 \times EnablePadding + 5.9 \times Bitrate \times BufferSize + 4.1 \times Bitrate \times BufferSize \times EnablePadding + 5.9 \times Bitrate \times BufferSize \times EnablePadd$$

Performance influence model in Xavier:

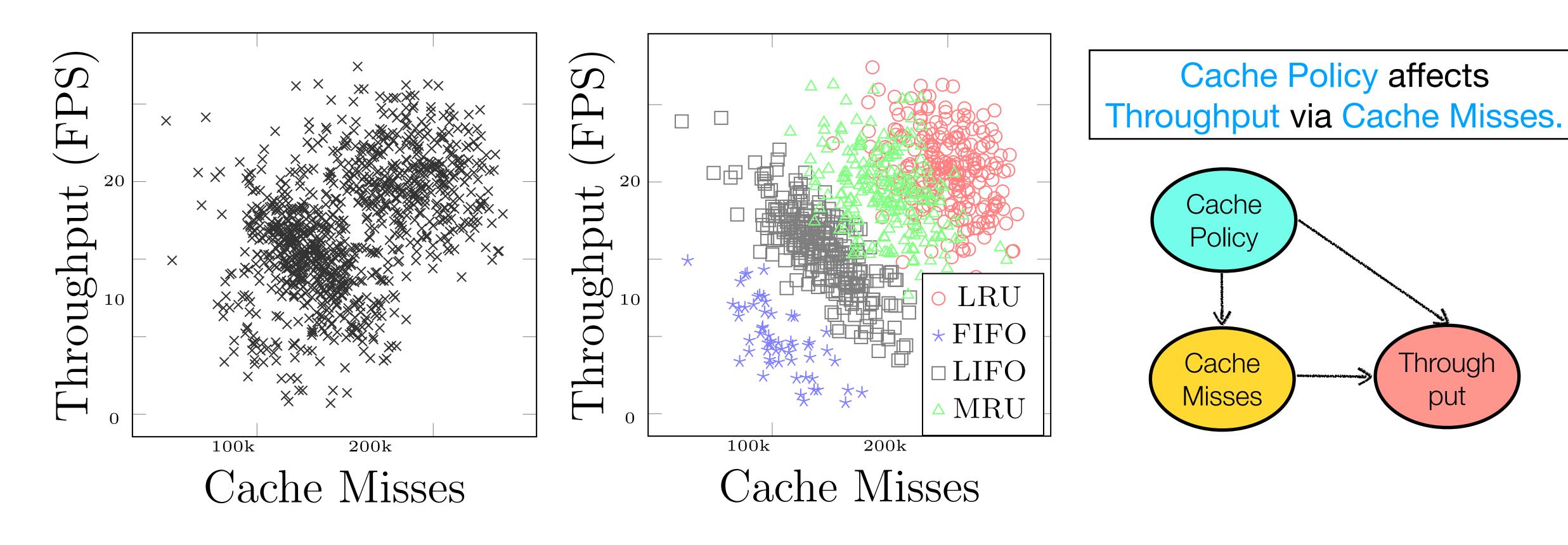
Throughput =
$$5.1 \times Bitrate + 2.5 \times BatchSize + 12.3 \times Bitrate \times BatchSize$$

Performance influence models change significantly across environments, resulting in low accuracy in new environments.

Causal performance modeling



Causal performance models produce correct explanations



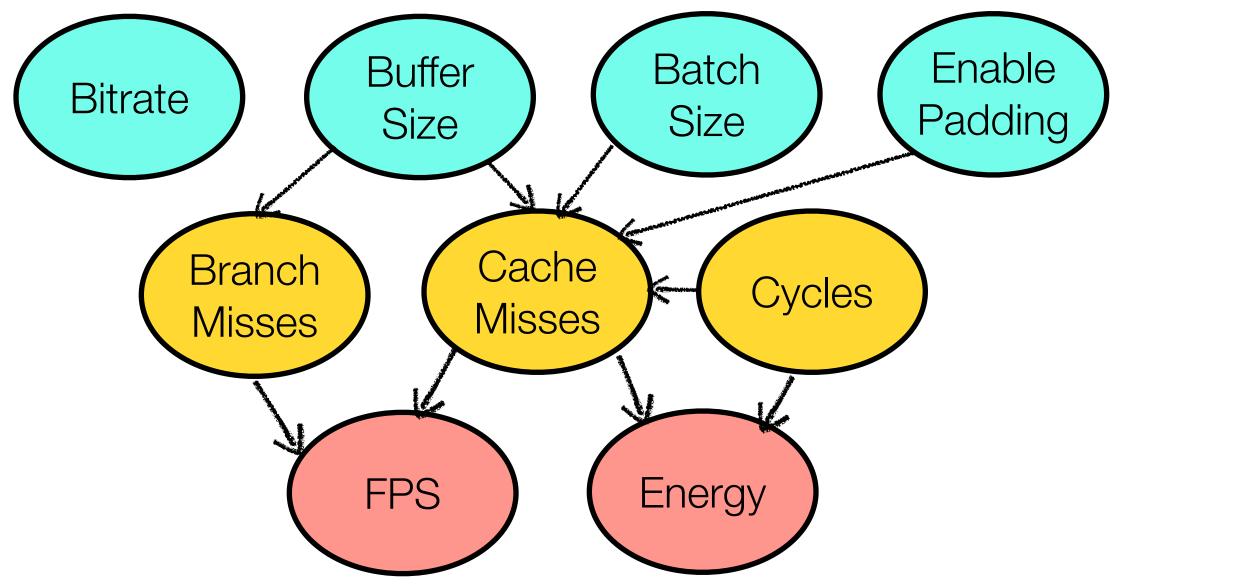


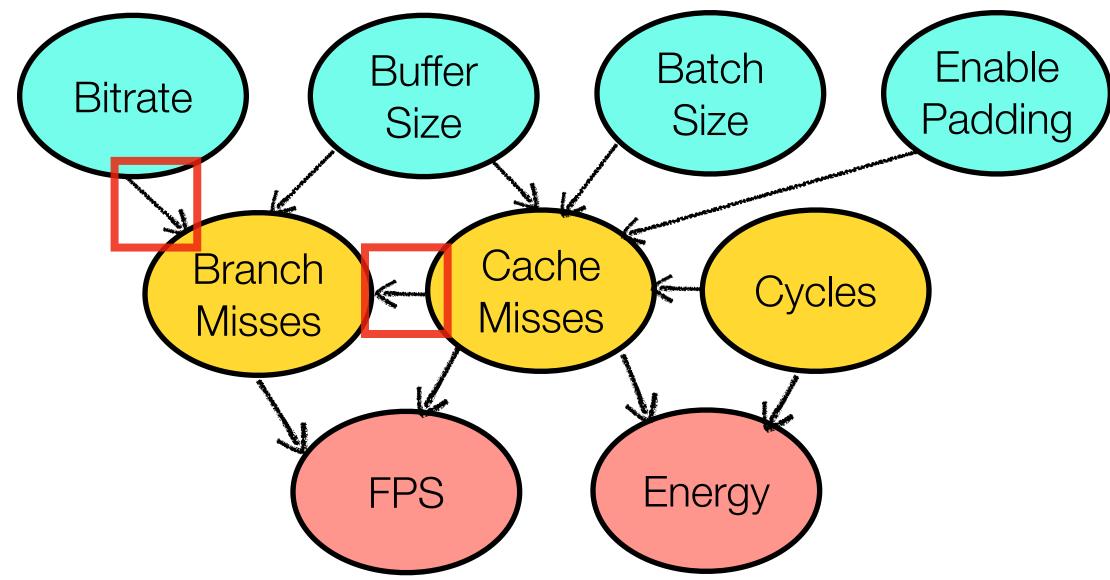
put

Causal performance models are transferable across environments

A partial causal performance model in Jetson TX2

A partial causal performance model in Jetson Xavier

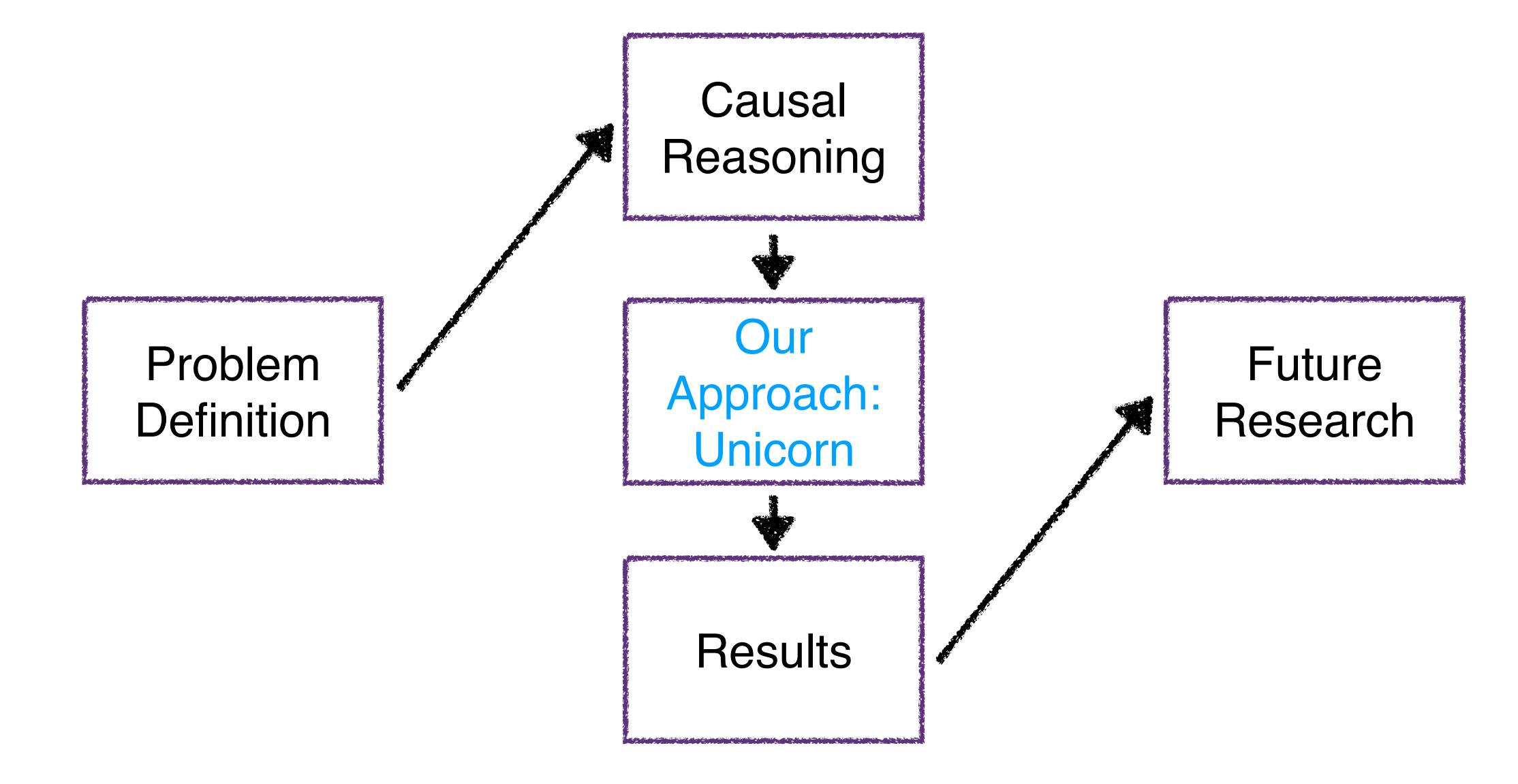


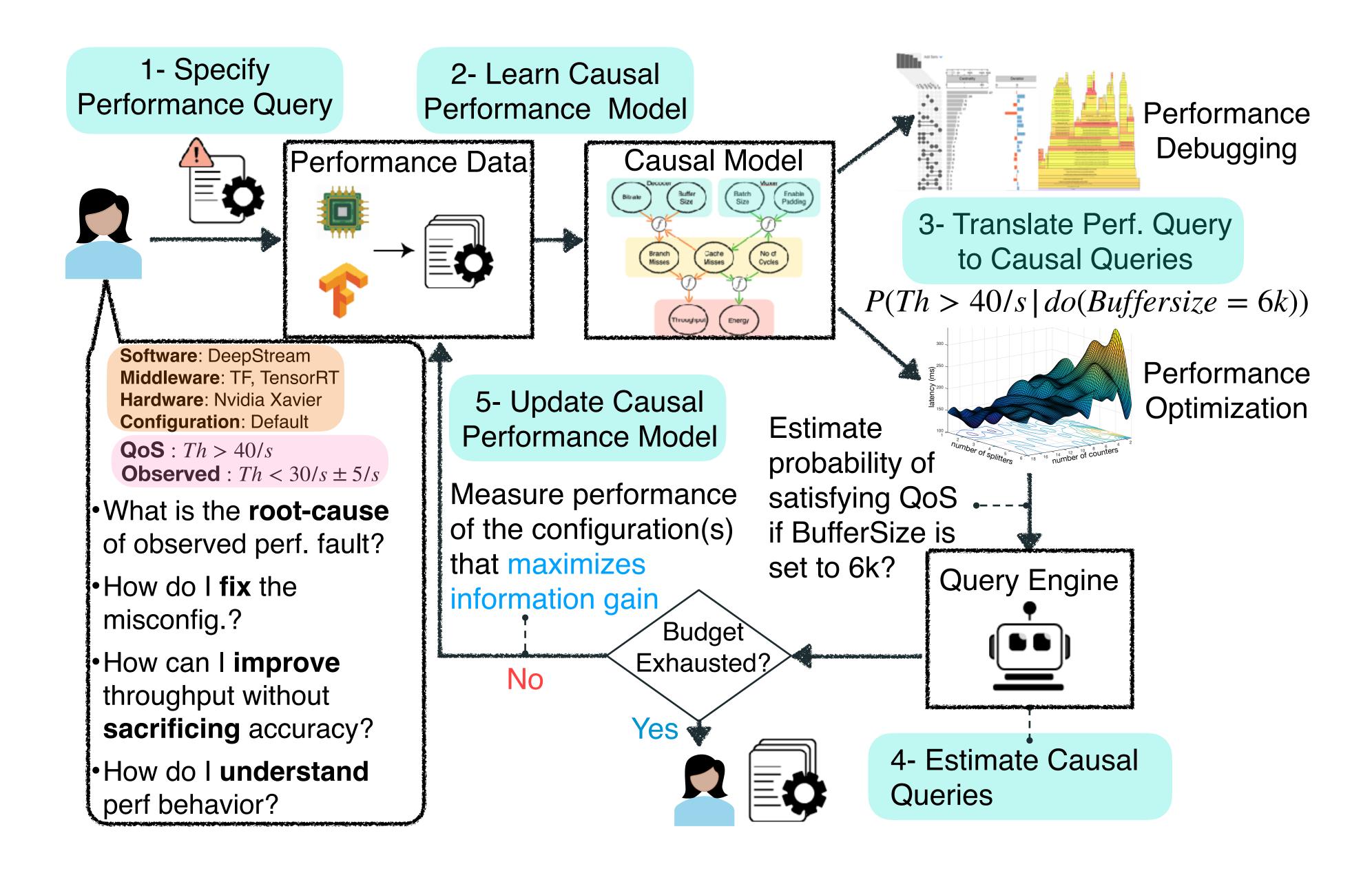


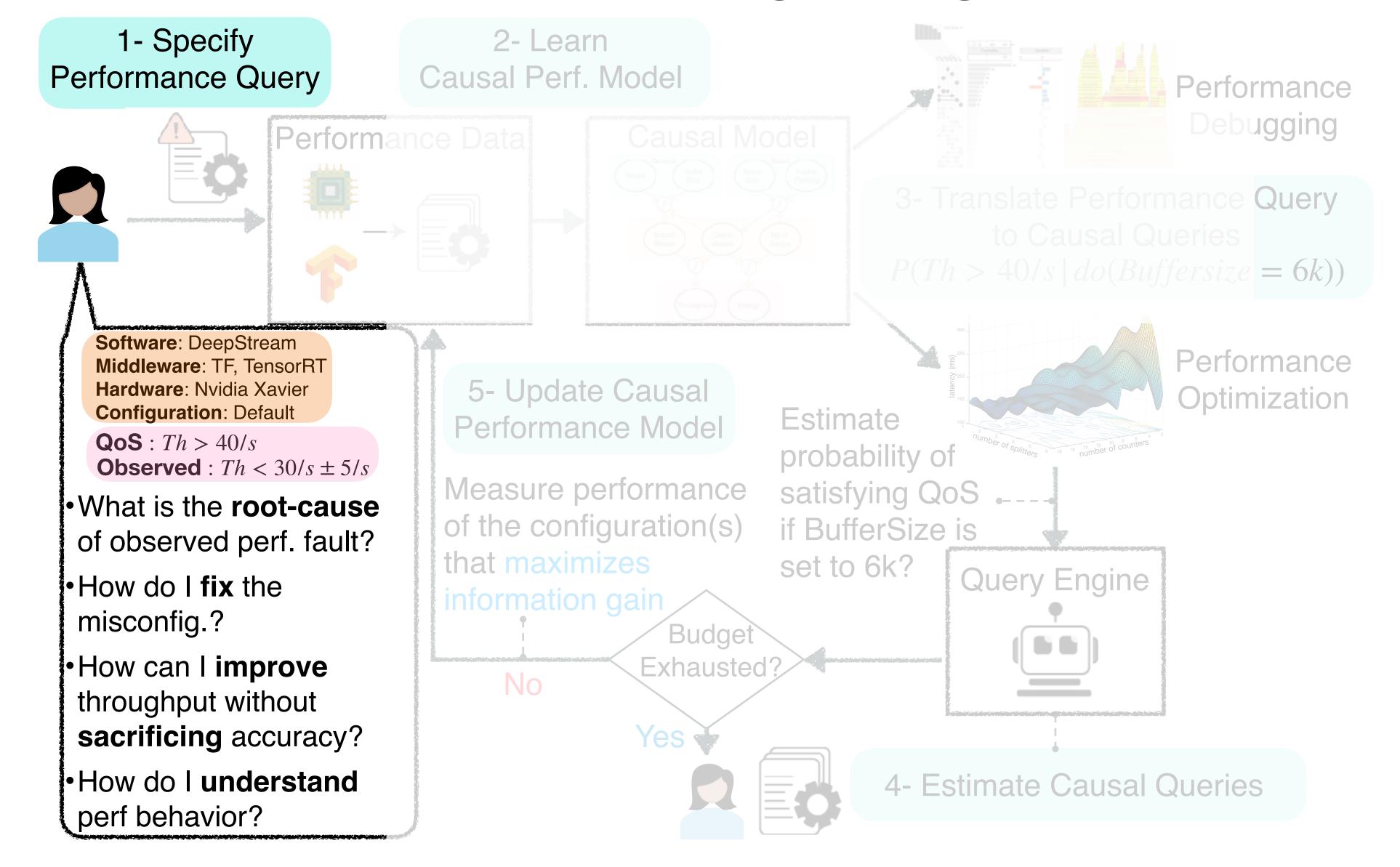


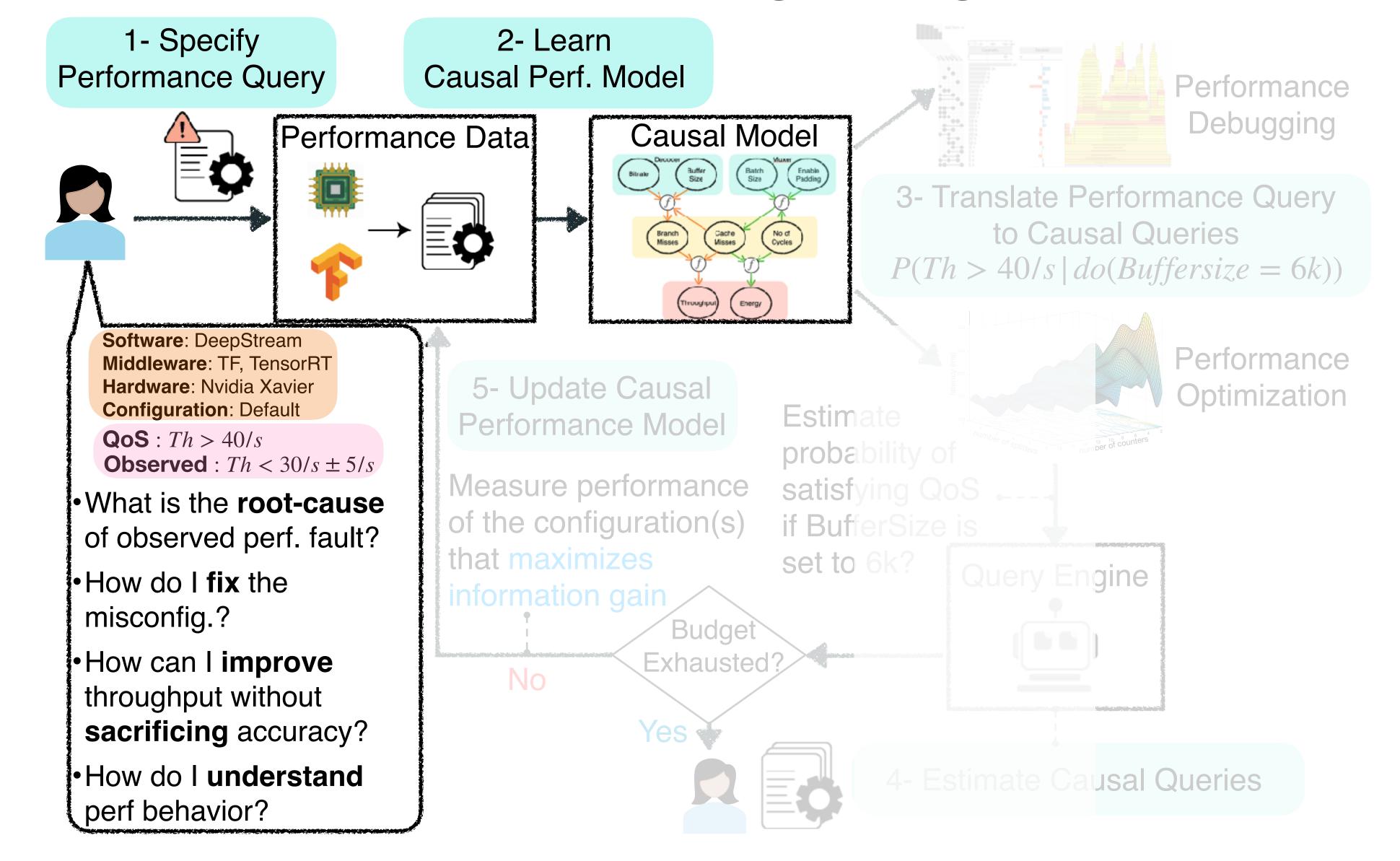
Causal performance models remain relatively stable across environments.

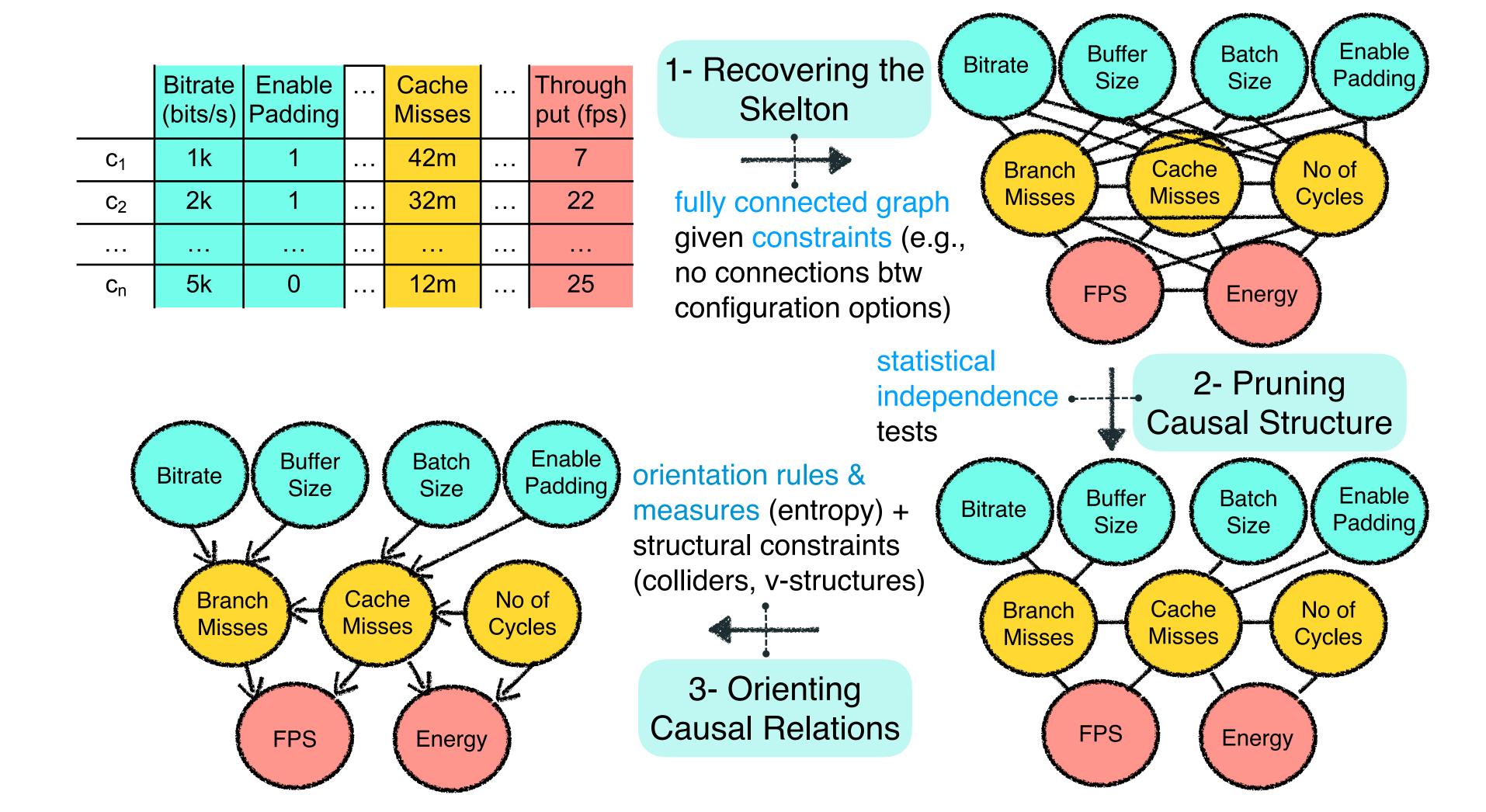
Outline

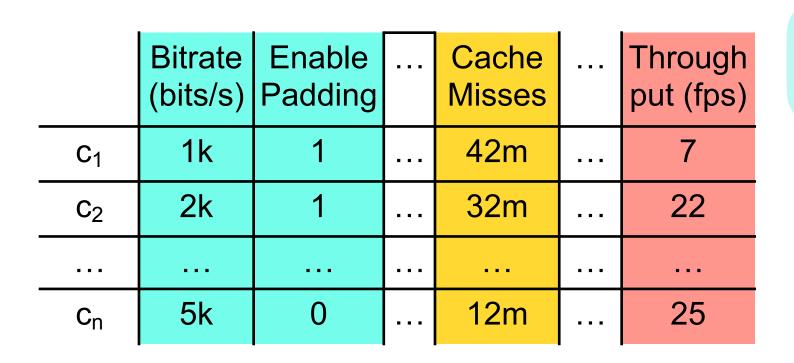


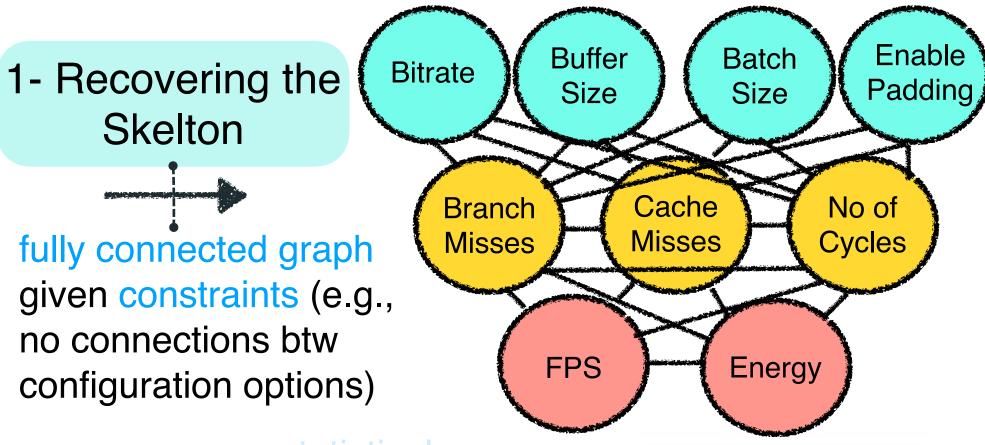


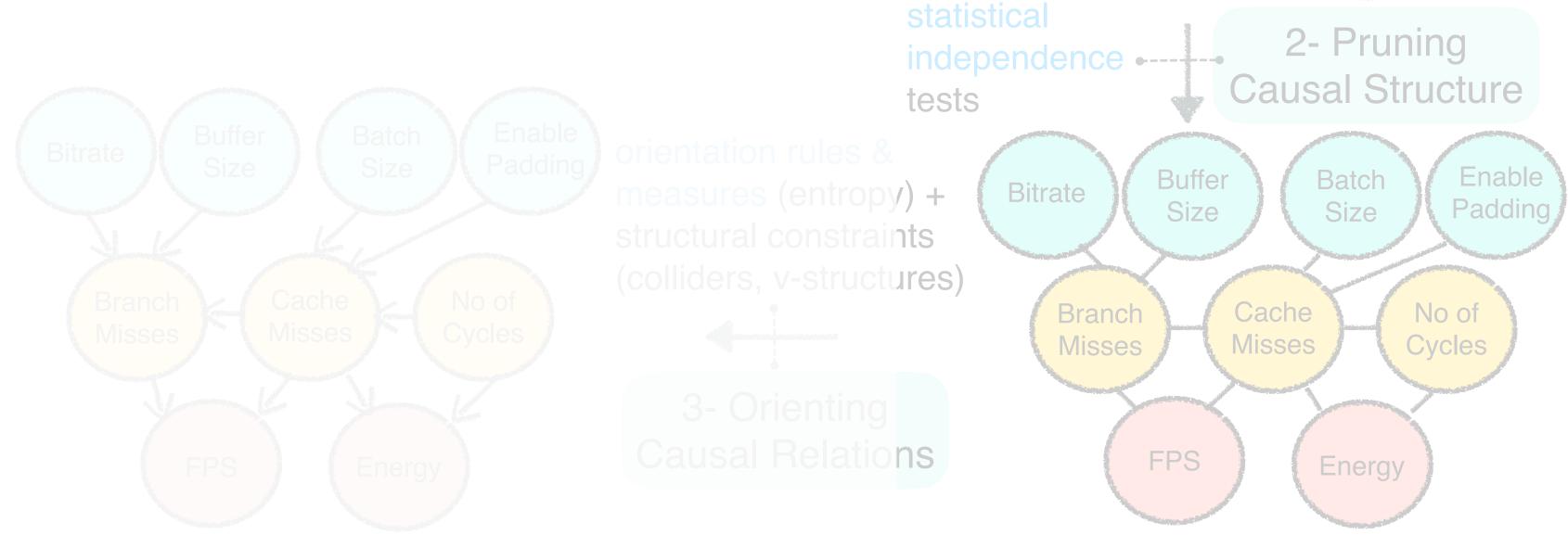


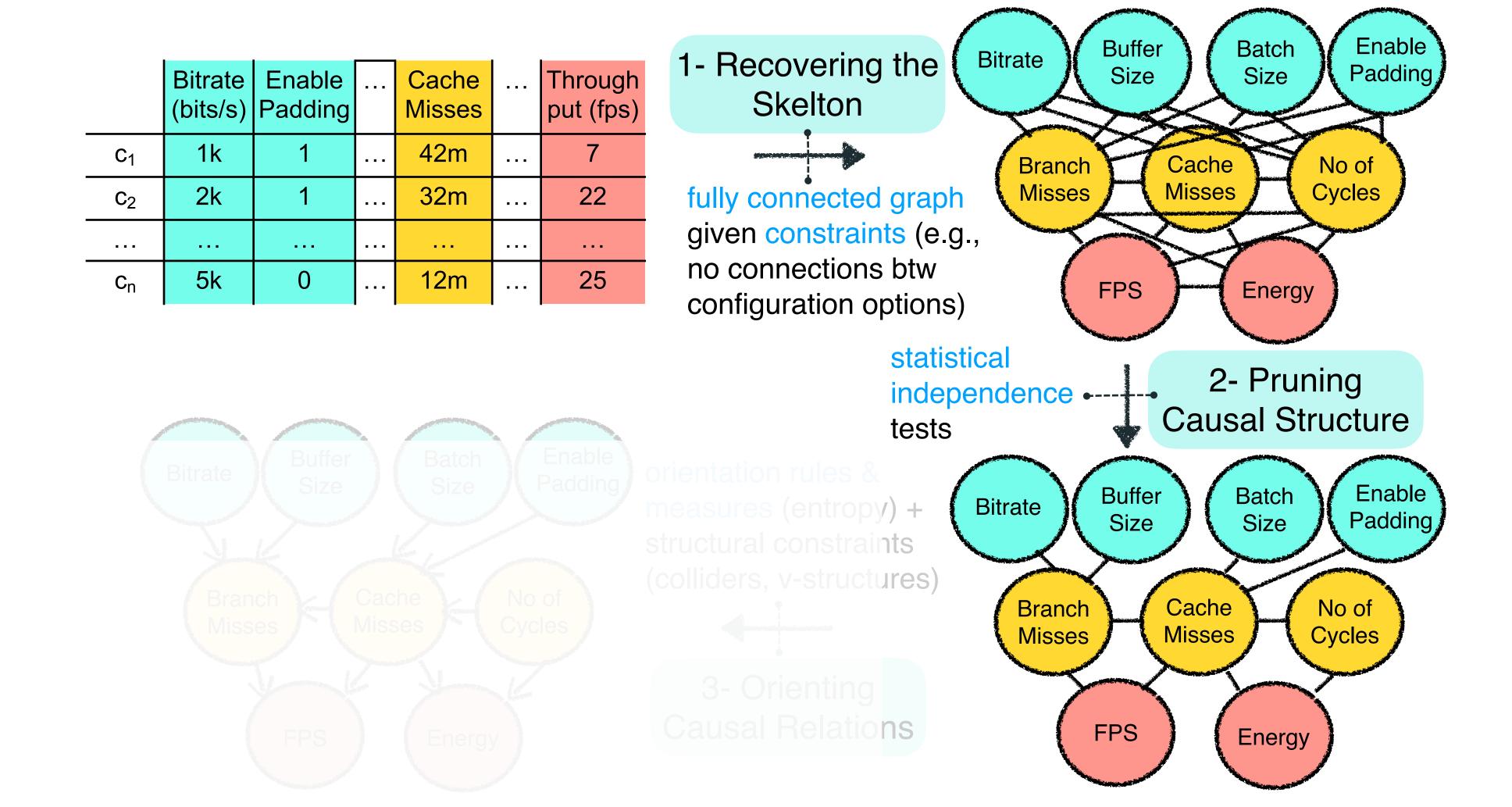


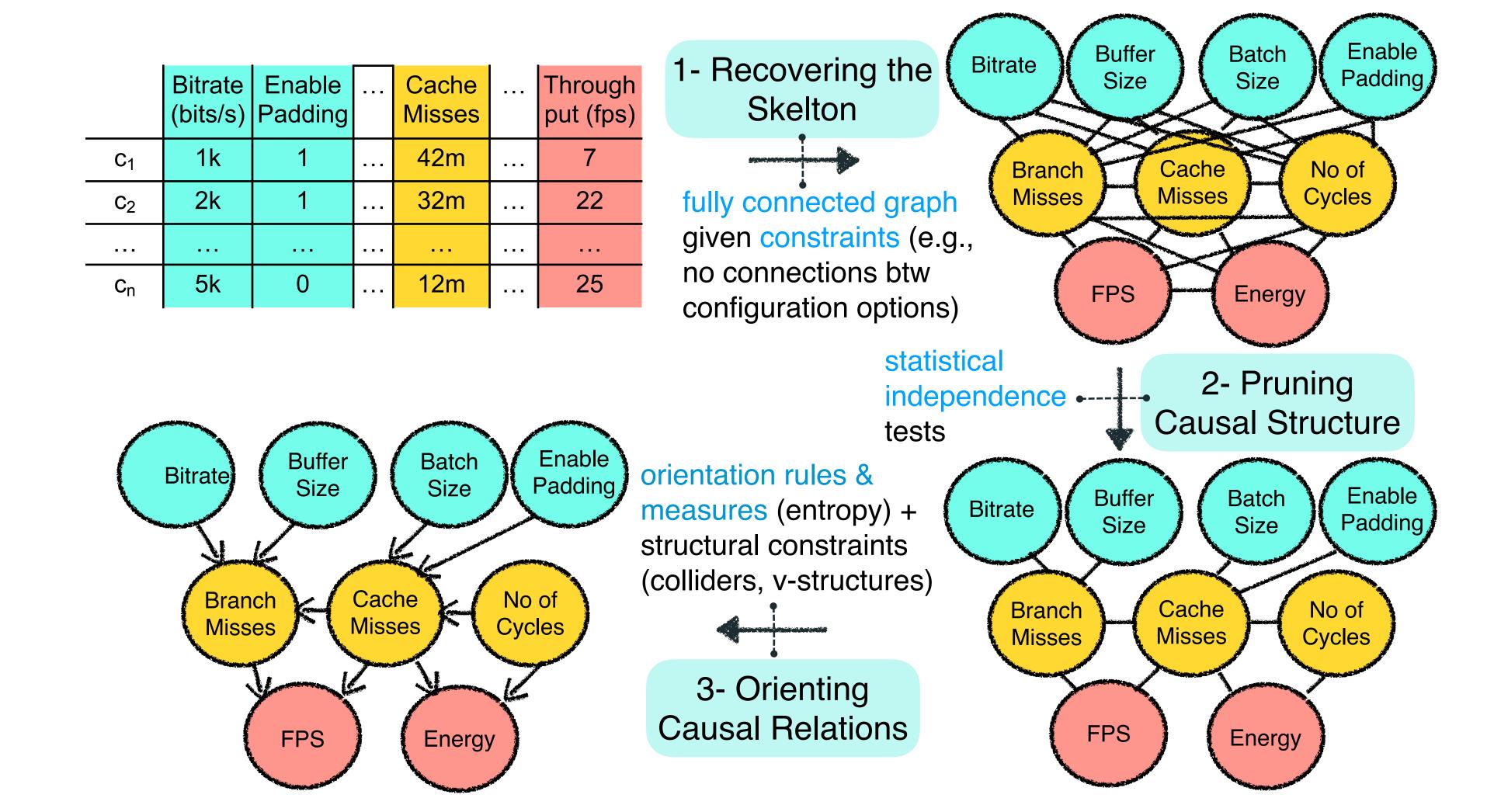


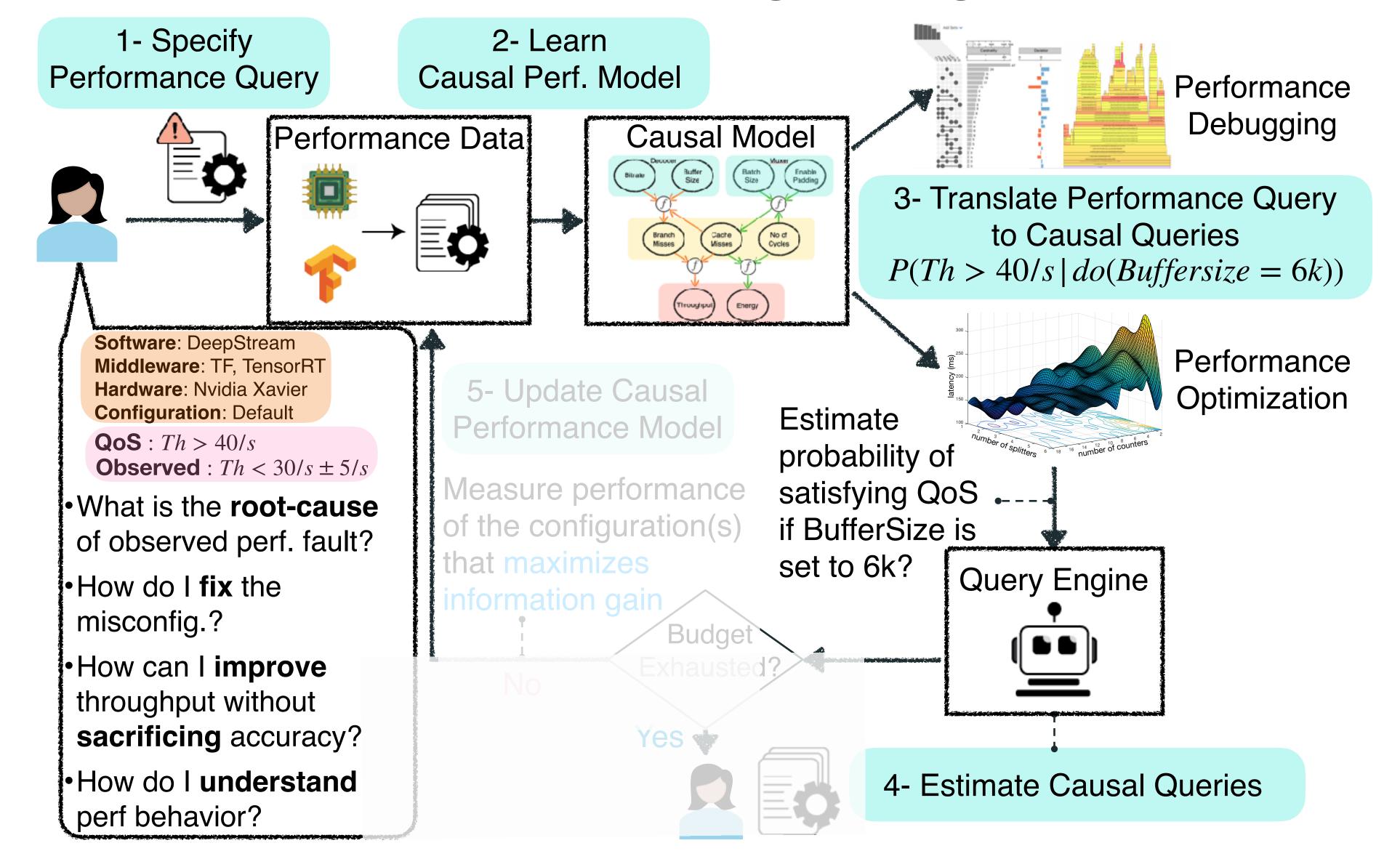












Diagnosing and Fixing the Faults

 Counterfactual inference asks "what if" questions about changes to the misconfigurations

Example



"Given that my current swap memory is 2 Gb, and I have high latency. What is the probability of having low latency if swap memory was increased to 4 Gb?

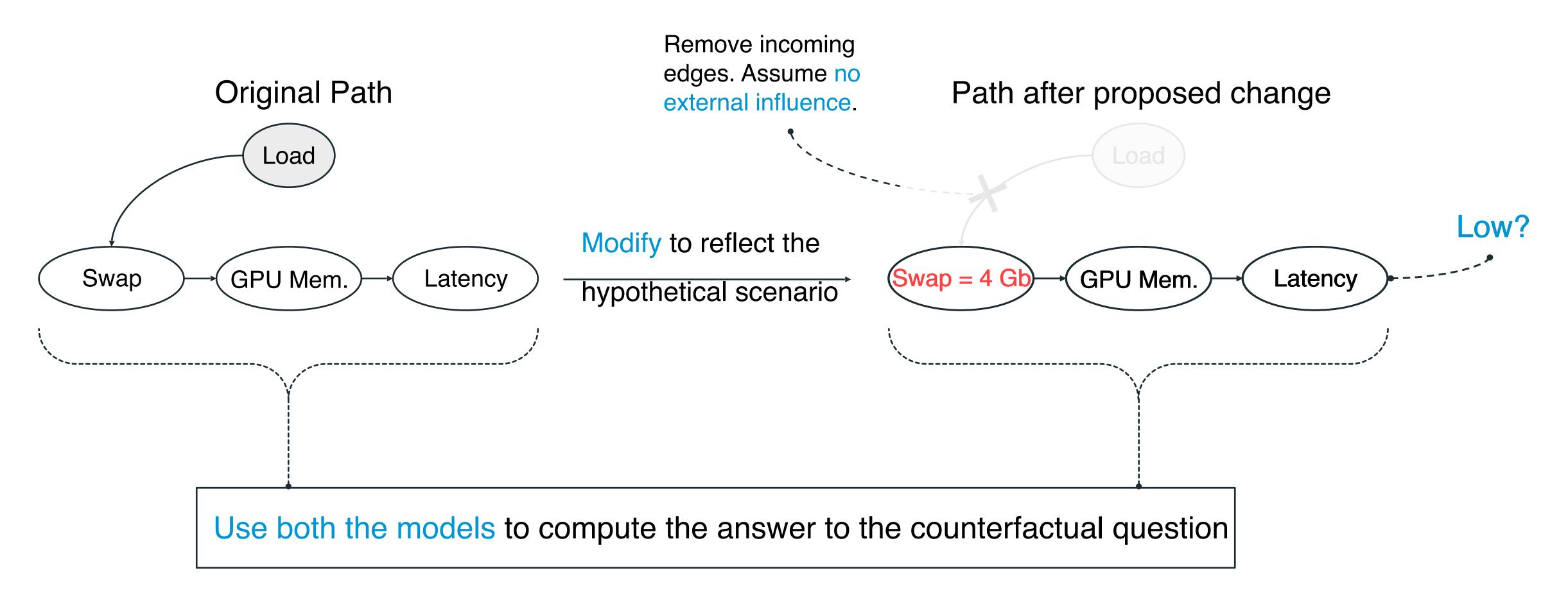
We are interested in the scenario where:

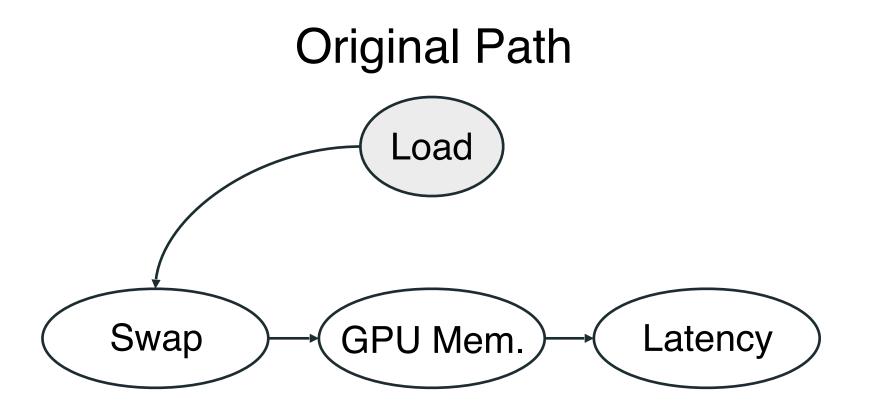
We hypothetically have low latency;

Conditioned on the following events:

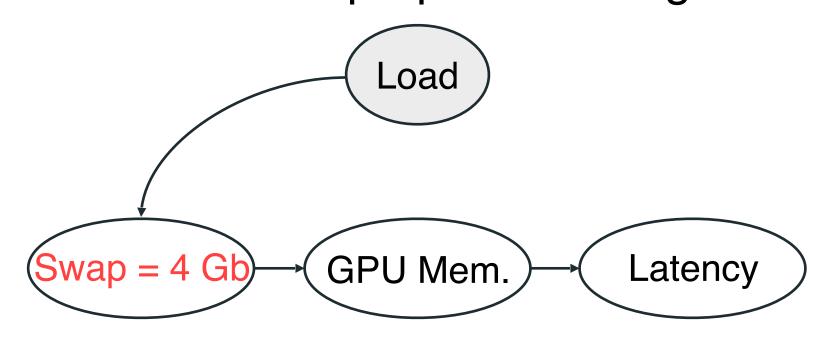
- We hypothetically set the new Swap memory to 4 Gb
- Swap Memory was initially set to 2 Gb
- We observed high latency when Swap was set to 2 Gb
- Everything else remains the same

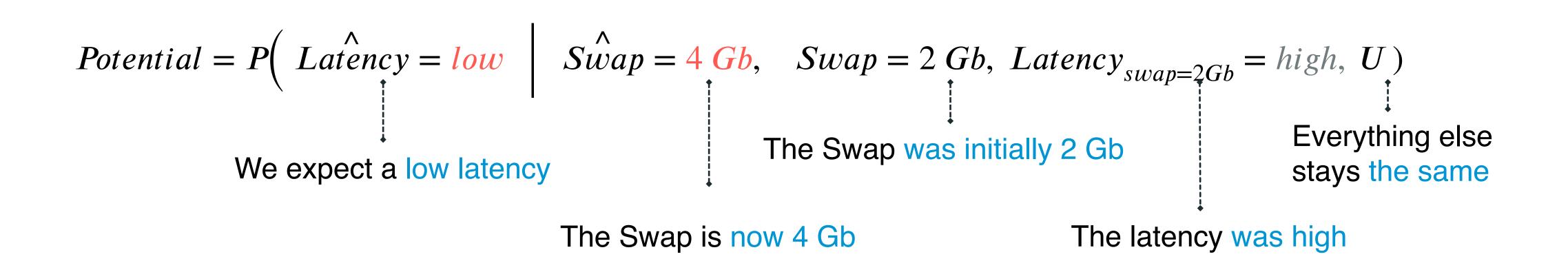
Diagnosing and Fixing the Faults





Path after proposed change





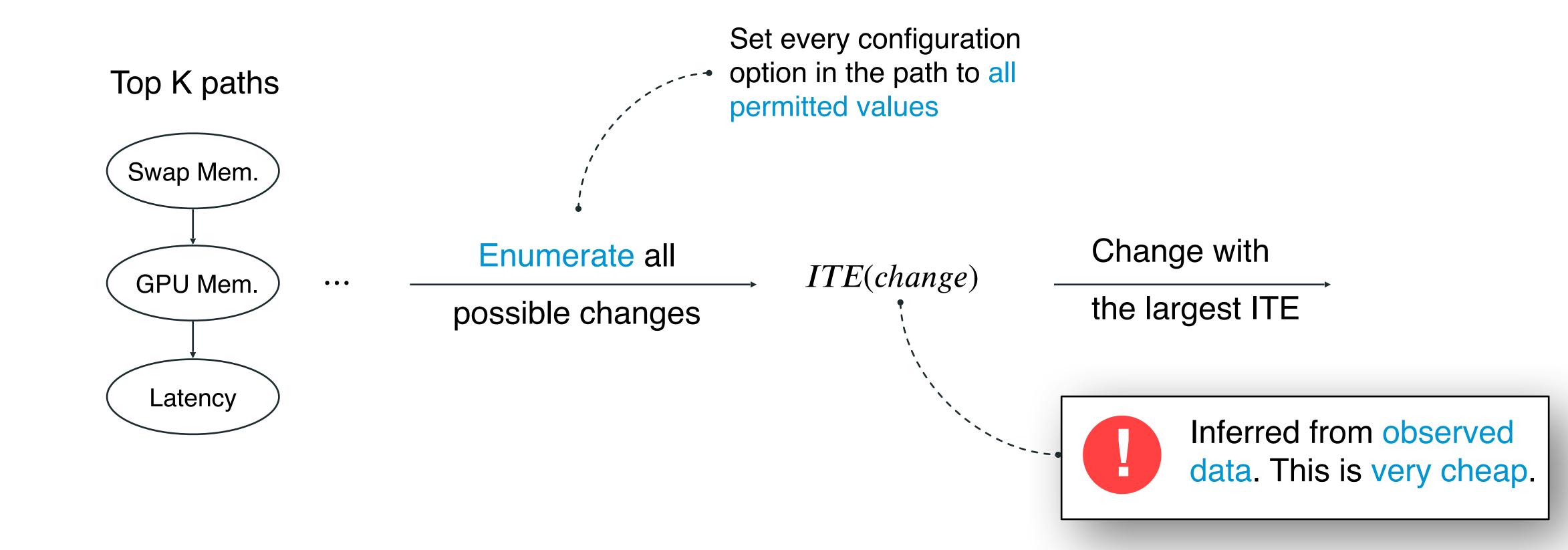
Potential =
$$P(\text{outcome} = \text{good} \mid \text{change, outcome}_{\neg \text{change}} = \text{bad, } \neg \text{change, } U)$$

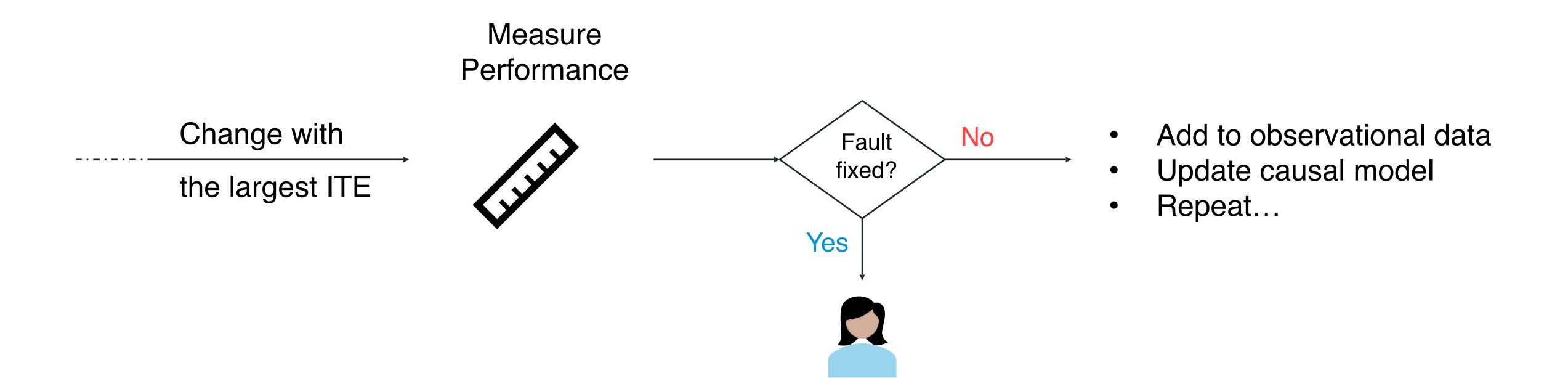
Probability that the outcome is good after a change, conditioned on the past

$$Control = P(out\hat{c}ome = bad | \neg change, U)$$

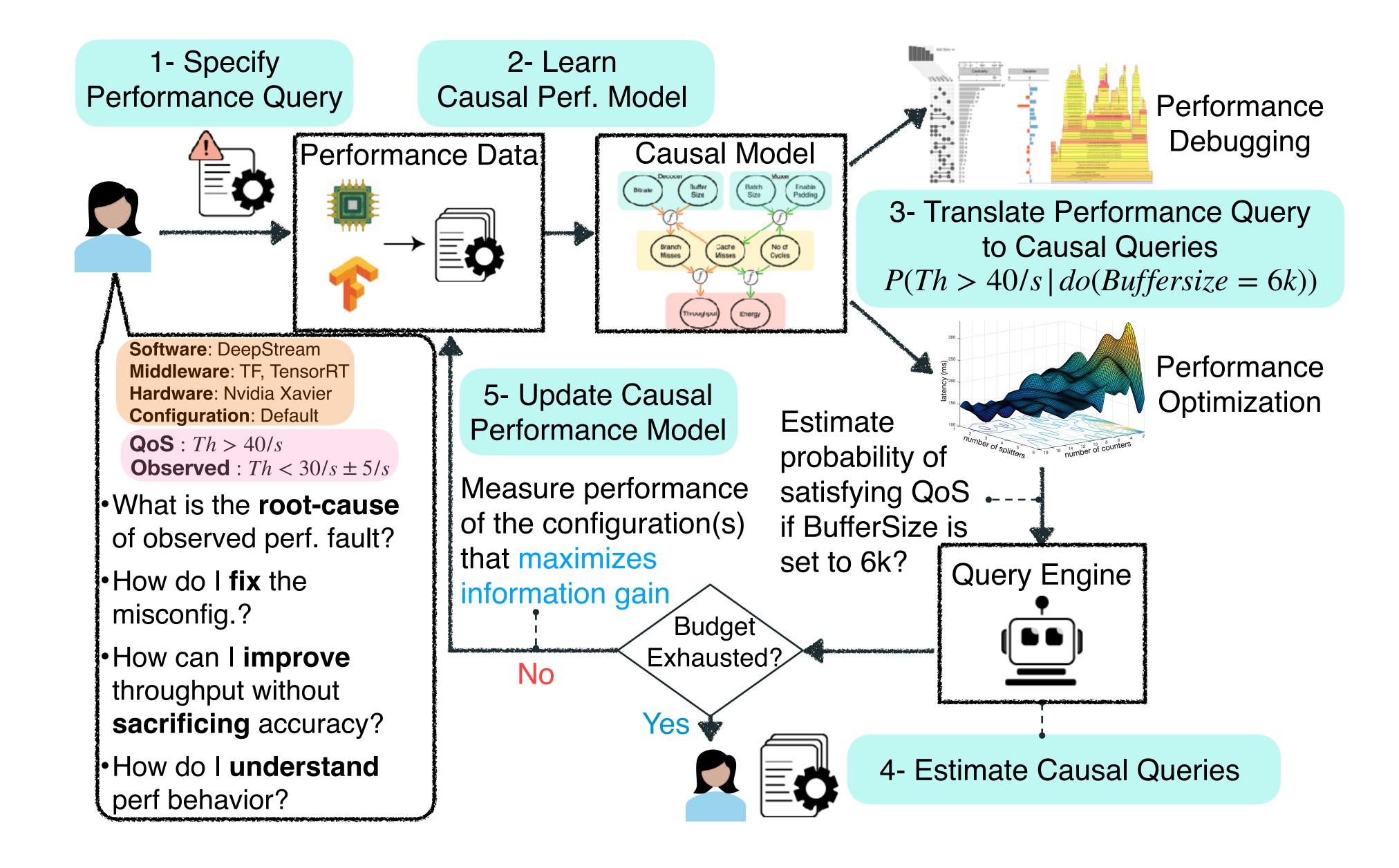
Probability that the outcome was bad before the change

If this difference is large, then our change is useful

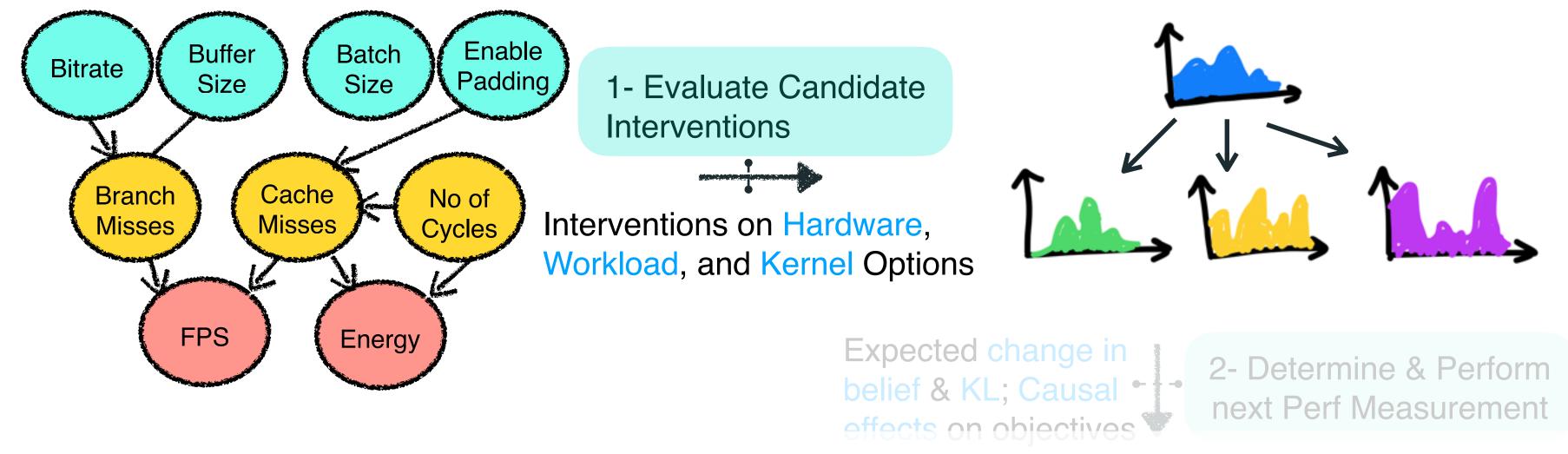


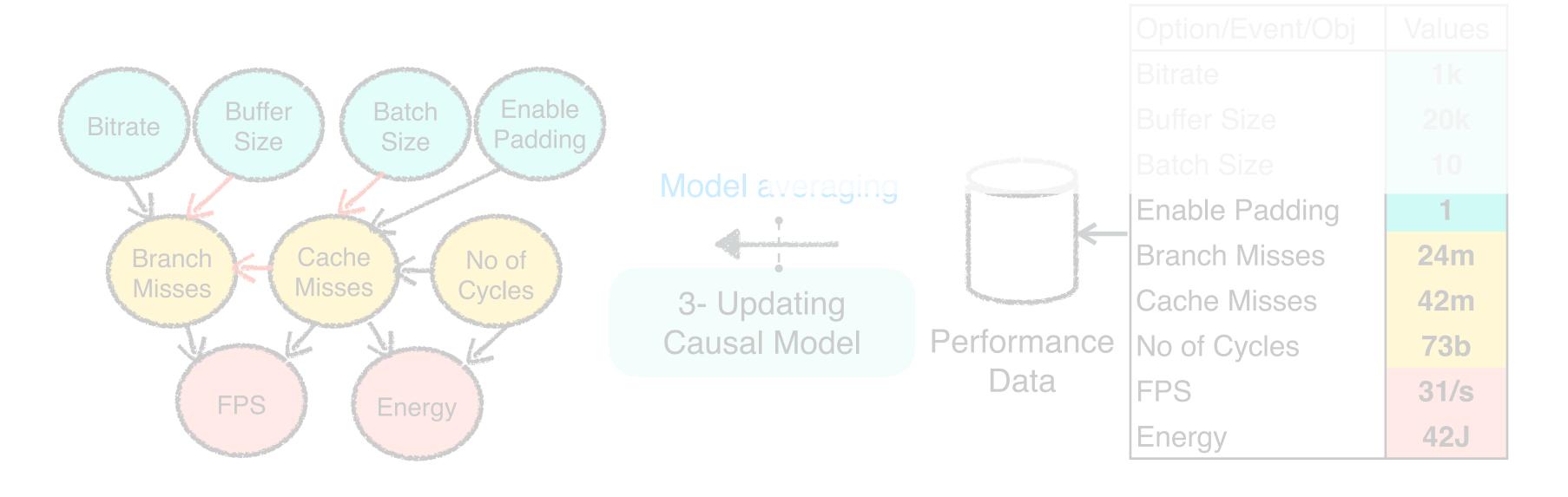


UNICORN: Our Causal Al for Systems Method

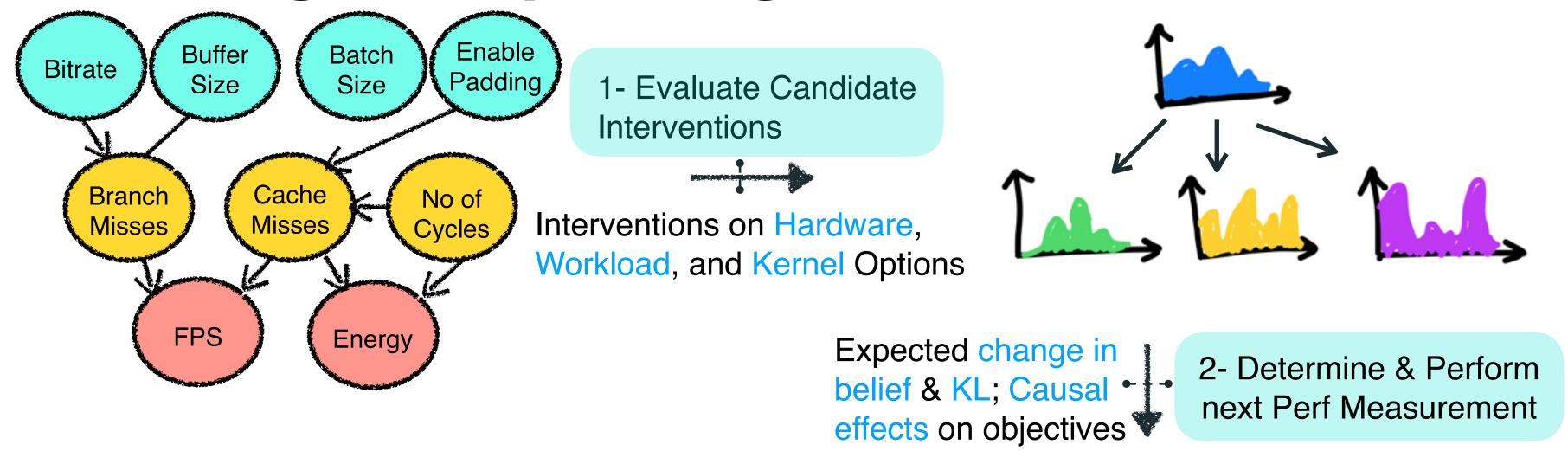


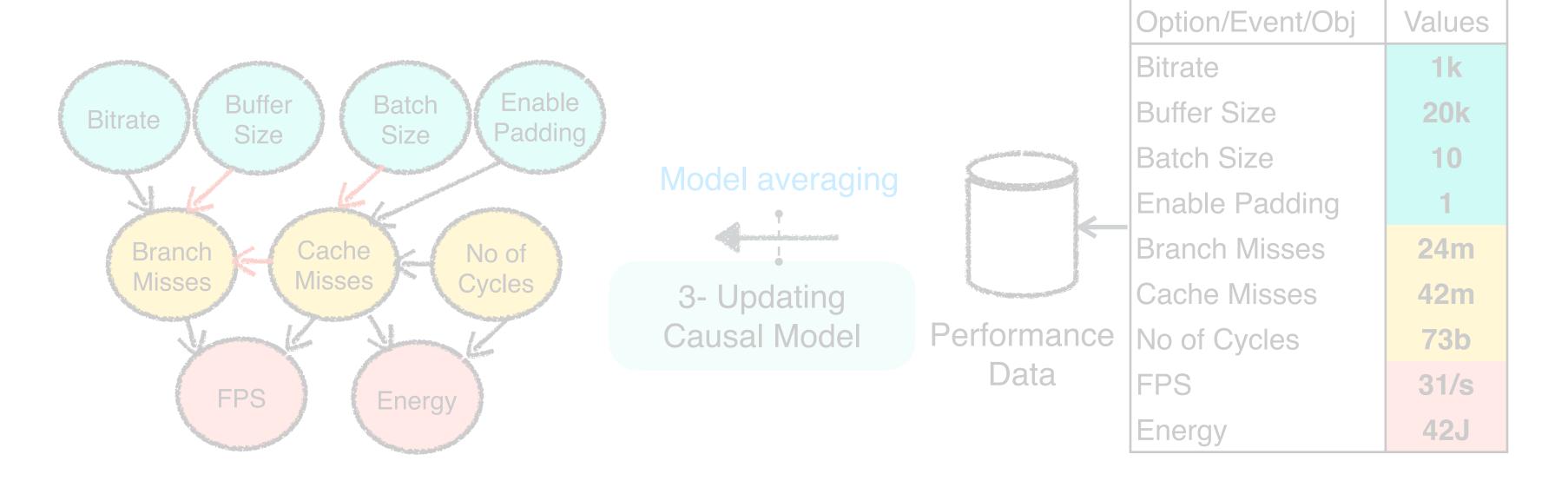
Active Learning for Updating Causal Performance Model



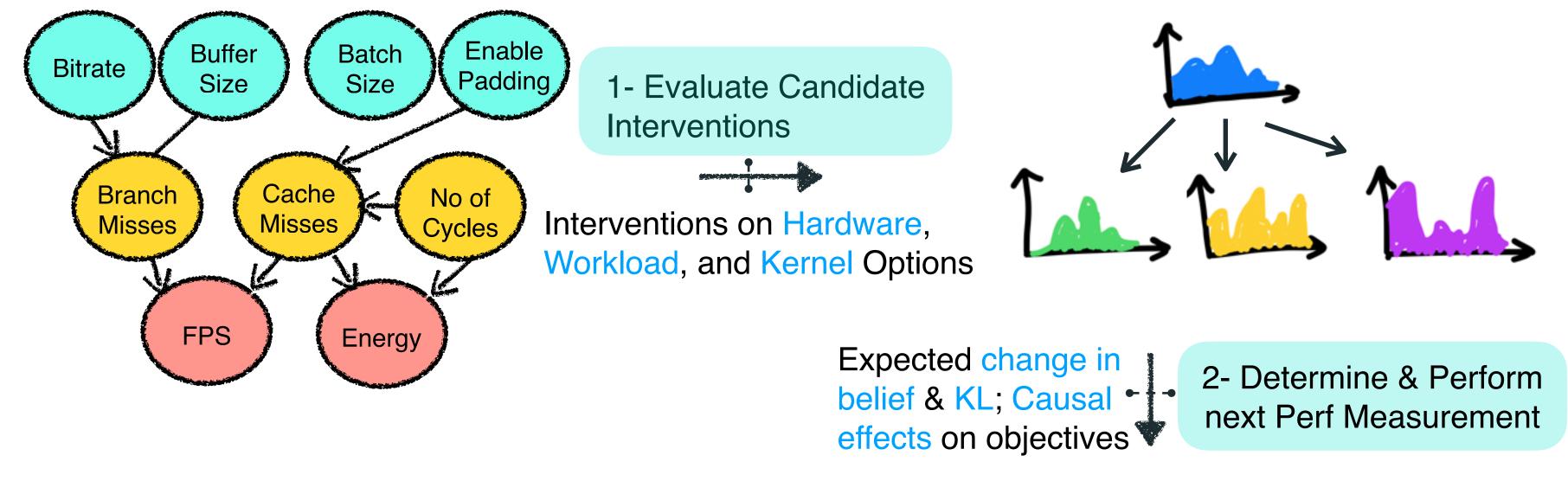


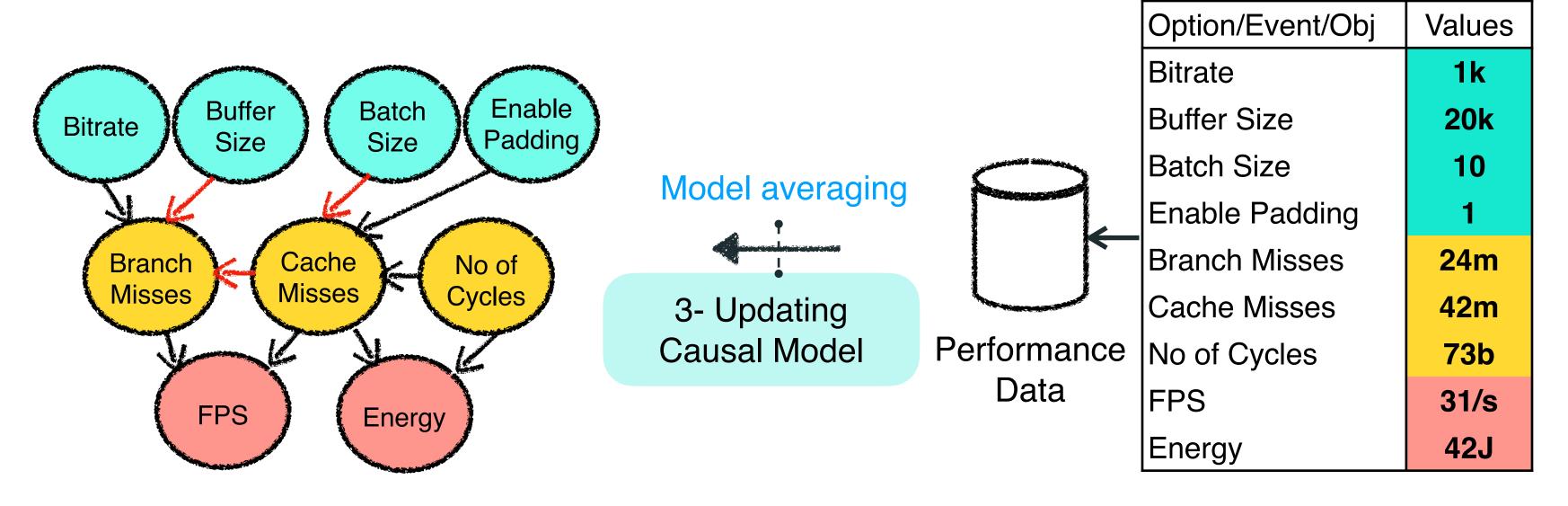
Active Learning for Updating Causal Performance Model



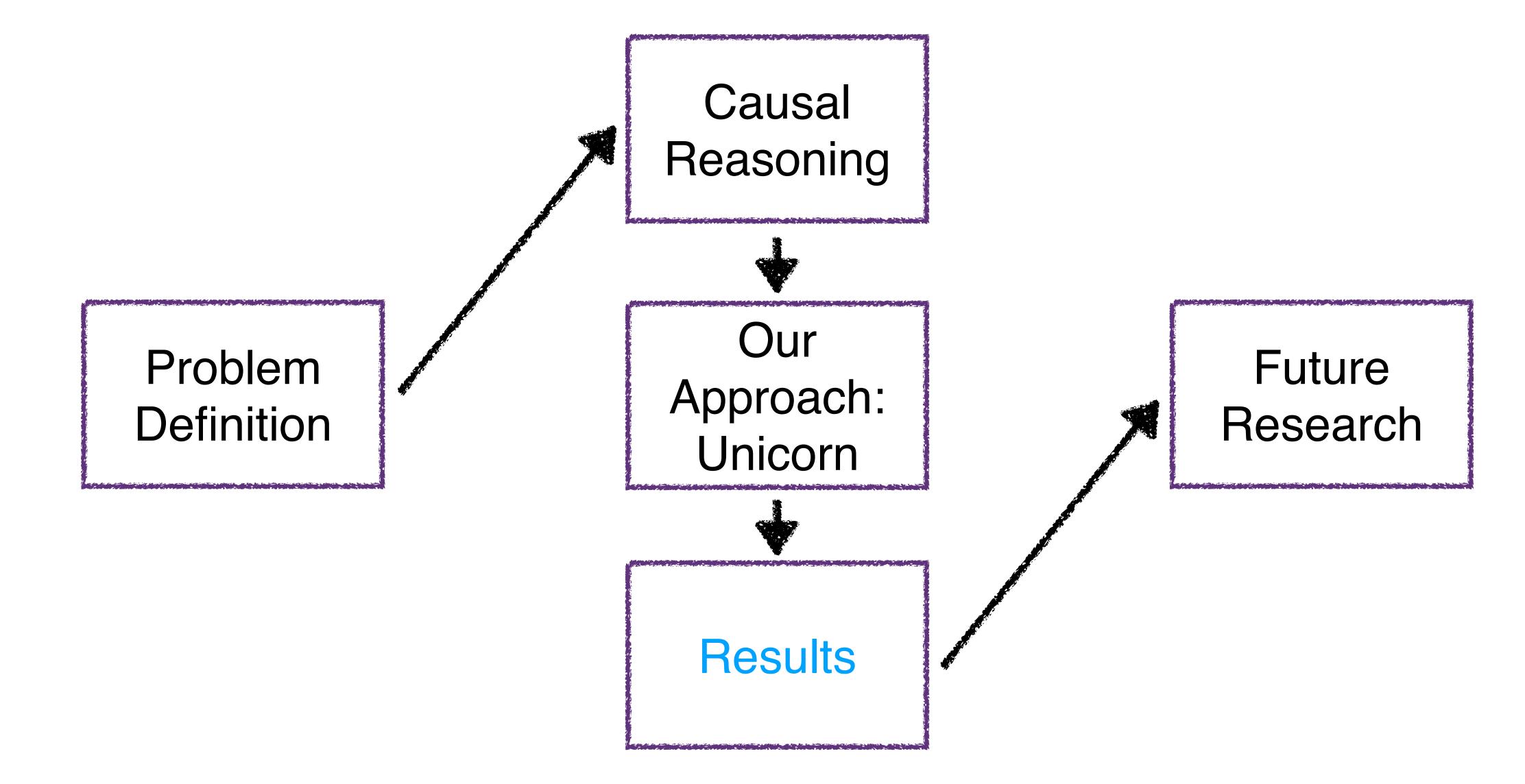


Active Learning for Updating Causal Performance Model





Outline



Results: Case Study



CUDA performance issue on tx2

Home > Autonomous Machines > Jetson & Embedded Systems > Jetson TX2

The user is transferring the code from one hardware to another

Jun '17



william_wu

When we are trying to transplant our CUDA source code from TX1 to TX2, it behaved strange.

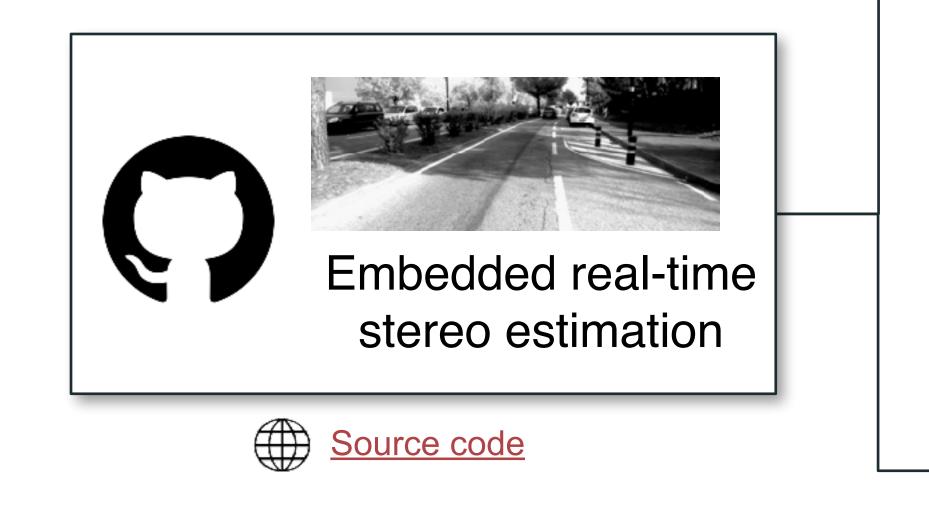
We noticed that TX2 has twice computing-ability as TX1 in GPU, as expectation, we think TX2 will 30% - 40% faster than TX1 at least.

Unfortunately, most of our code base spent twice the time as TX1, in other words, TX2 only has 1/2 speed as TX1, mostly. We believe that TX2's CUDA API runs much slower than TX1 in many cases.

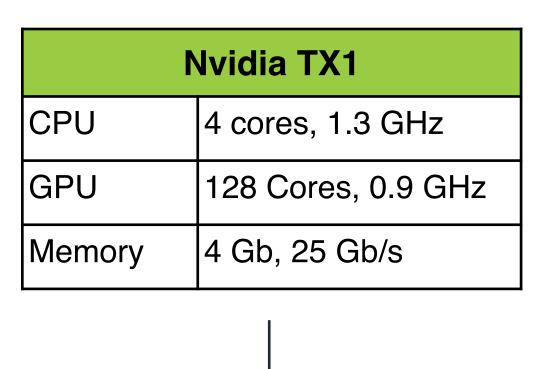
The target hardware is faster than the the source hardware. User expects the code to run at least 30-40% faster.

The code ran 2x slower on the more powerful hardware

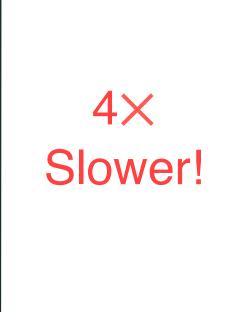
Results: Case Study







More powerful





Nvidia TX2								
CPU	6 cores, 2 GHz							
GPU	256 Cores, 1.3 GHz							
Memory	8 Gb, 58 Gb/s							

17 Fps

Results: Case Study

Configuration	UNICO RN	Decision Tree	Forum
CPU Cores	✓	✓	✓
CPU Freq.	✓	✓	√
EMC Freq.	✓	√	√
GPU Freq.	✓	√	√
Sched. Policy		√	
Sched. Runtime		√	
Sched. Child Proc		√	
Dirty Bg. Ratio		√	
Drop Caches		√	
CUDA_STATIC_RT	√	√	✓
Swap Memory		✓	

	UNICORN	Decision Tree	Forum
Throughput (on TX2)	26 FPS	20 FPS	23 FPS
Throughput Gain (over TX1)	53 %	21 %	39 %
Time to resolve	24 min.	3 ¹ / ₂ Hrs.	2 days

• The user expected 30-40% gain

Results

- X Finds the root-causes accurately
- X No unnecessary changes
- X Better improvements than forum's recommendation
- X Much faster

Evaluation: Experimental Setup

Hardware

Nvidia TX1								
CPU	4 cores, 1.3 GHz							
GPU	128 Cores, 0.9 GHz							
Memory	4 Gb, 25 GB/s							

Nvidia TX2								
CPU	6 cores, 2 GHz							
GPU	256 Cores, 1.3 GHz							
Memory	8 Gb, 58 GB/s							

Nvidia Xavier								
CPU	8 cores, 2.26 GHz							
GPU	512 cores, 1.3 GHz							
Memory	32 Gb, 137 GB/s							

Configuration Space

X 30 Configurations

- 10 software
- 10 OS/Kernel
- 10 hardware
- X 17 System Events

Systems

Xception

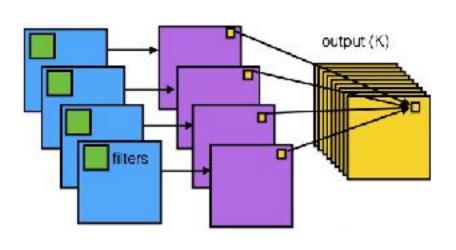
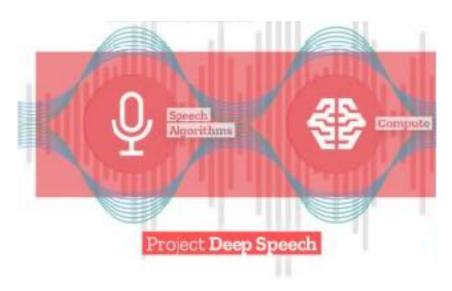


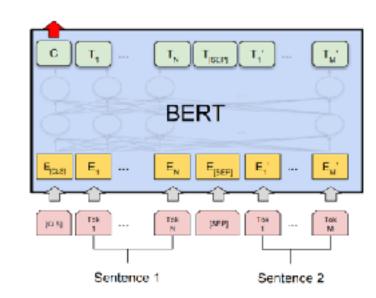
Image recognition (50,000 test images)

DeepSpeech



Voice recognition (5 sec. audio clip)

BERT



Sentiment Analysis (10000 IMDb reviews)

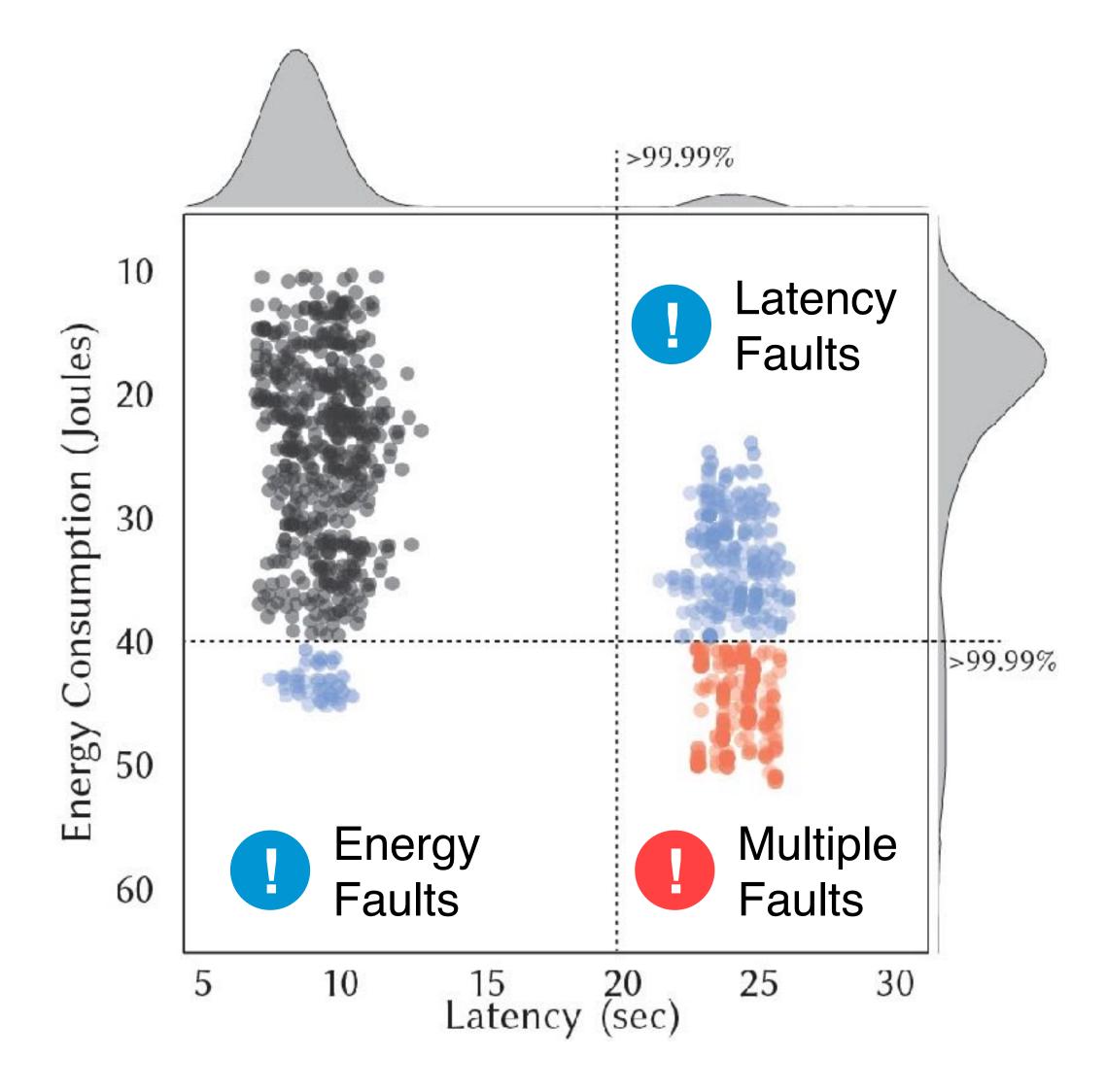
x264



Video Encoder (11 Mb, 1080p video)

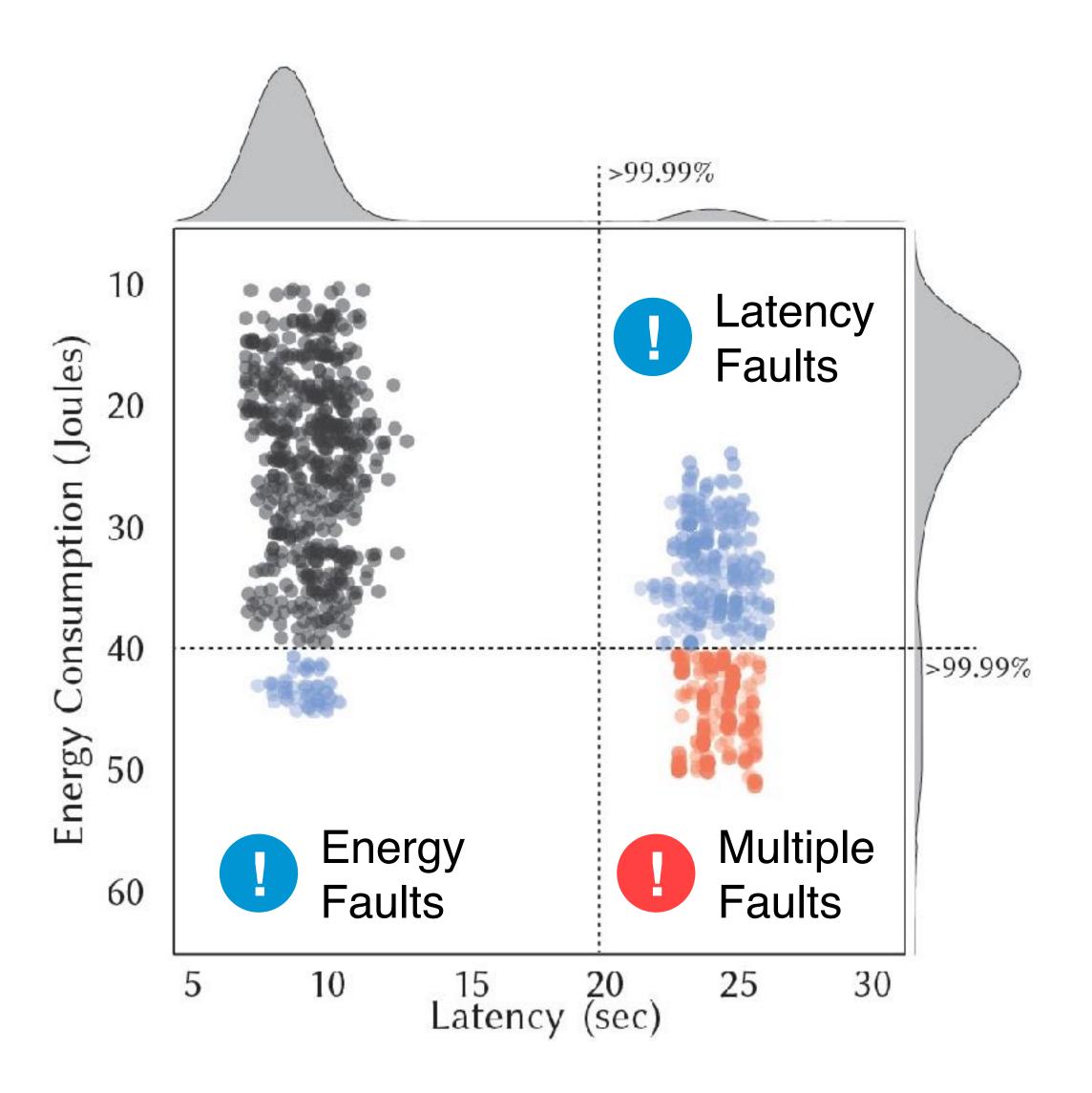
Evaluation: Data Collection

- For each software/hardware combination create a benchmark dataset
 - Exhaustively set each of configuration option to all permitted values.
 - For continuous options (e.g., GPU memory Mem.), sample 10 equally spaced values between [min, max]
- Measure the latency, energy consumption, and heat dissipation
 - Repeat 5x and average



Evaluation: Ground Truth

- For each performance fault:
 - Manually investigate the root-cause
 - "Fix" the misconfigurations
- A "fix" implies the configuration no longer has tail performance
 - User defined benchmark (i.e., 10th percentile)
 - Or some QoS/SLA benchmark
- Record the configurations that were changed



Experimental Setup: Baselines

Debugging

BugDoc: A System for Debugging Computational Pipelines

Raoni Lourenço New York University raoni@nyu.edu

Juliana Freire New York University juliana.freire@nyu.edu Dennis Shasha New York University shasha@courant.nyu.edu

Statistical Debugging for Real-World Performance Problems

Linhai Song Shan Lu*
University of Wisconsin–Madison
{songlh, shanlu}@cs.wisc.edu

Optimization

Sequential Model-Based Optimization for General Algorithm Configuration (extended version)

Frank Hutter, Holger H. Hoos and Kevin Leyton-Brown

University of British Columbia, 2366 Main Mall, Vancouver BC, V6T 1Z4, Canada {hutter, hoos, kevinlb}@cs.ubc.ca

EnCore: Exploiting System Environment and Correlation Information for Misconfiguration Detection

†University of California San Diego §IBM Watson Research Center {jiz013, tixu, yyzhou}@cs.ucsd.edu {Irengan, cxzhang, niyuge, vbala}@us.ibm.com

Iterative Delta Debugging

Cyrille Artho

Research Center for Information Security (RCIS), AIST, Tokyo, Japan

Predictive Entropy Search for Multi-objective Bayesian Optimization

Daniel Hernández-Lobato

DANIEL.HERNANDEZ@UAM.ES

Universidad Autónoma de Madrid, Francisco Tomás y Valiente 11, 28049, Madrid, Spain.

José Miguel Hernández-Lobato

JMHL@SEAS.HARVARD.EDU

AS793@CAM.AC.UK

Harvard University, 33 Oxford street, Cambridge, MA 02138, USA.

Amar Shah

Cambridge University, Trumpington Street, Cambridge CB2 1PZ, United Kingdom.

Ryan P. Adams

RPA@SEAS.HARVARD.EDU

Harvard University and Twitter, 33 Oxford street Cambridge, MA 02138, USA.

Results: Efficiency (Debugging; Single objective)

				Accuracy					Precision				Recall				Gain				Time [†]			
			Unicorn	CBI	DD	ENCORE	ВисДос	Unicorn	CBI	DD	ENCORE	ВисДос	Unicorn	CBI	DD	ENCORE	ВисДос	Unicorn	CBI	DD	ENCORE	ВисДос	Unicorn	Others
		DEEPSTREAM	87	61	62	65	81	83	66	59	60	71	80	61	65	60	70	88	66	67	68	79	0.8	4
	>	XCEPTION	86	53	42	62	65	86	67	61	63	67	83	64	68	69	62	82	48	42	57	59	0.6	4
TX2	atenc	BERT	81	56	5 9	60	57	76	57	55	61	73	71	74	68	67	65	74	54	59	62	58	0.4	4
Τ	ate	DEEPSPEECH	81	61	5 9	60	72	76	58	69	61	71	81	73	61	63	69	76	59	53	55	66	0.7	4
	1	x264	83	5 9	63	62	62	82	69	58	65	66	78	64	67	63	72	85	69	72	68	71	1.4	4
		DeepStream	91	81	79	77	87	81	61	62	64	73	85	63	61	62	75	86	68	62	61	78	0.7	4
~	Α	XCEPTION	84	66	63	63	81	78	56	5 8	66	65	80	69	55	63	68	83	59	50	51	62	0.4	4
/IE	rg	BERT	66	59	53	63	72	70	62	64	64	65	79	61	54	63	66	62	49	36	49	53	0.5	4
XAVIER	Ene	DEEPSPEECH	73	68	63	7 2	71	75	55	59	54	68	78	53	52	59	71	78	64	48	65	63	1.2	4
	I	x264	77	71	70	74	74	83	63	53	61	66	78	67	53	54	72	87	73	71	76	76	0.3	4

Find root causes / more accurately than ML-based methods

Better gain
Up to 20x
faster

Results: Efficiency (Debugging; Multi-objective)

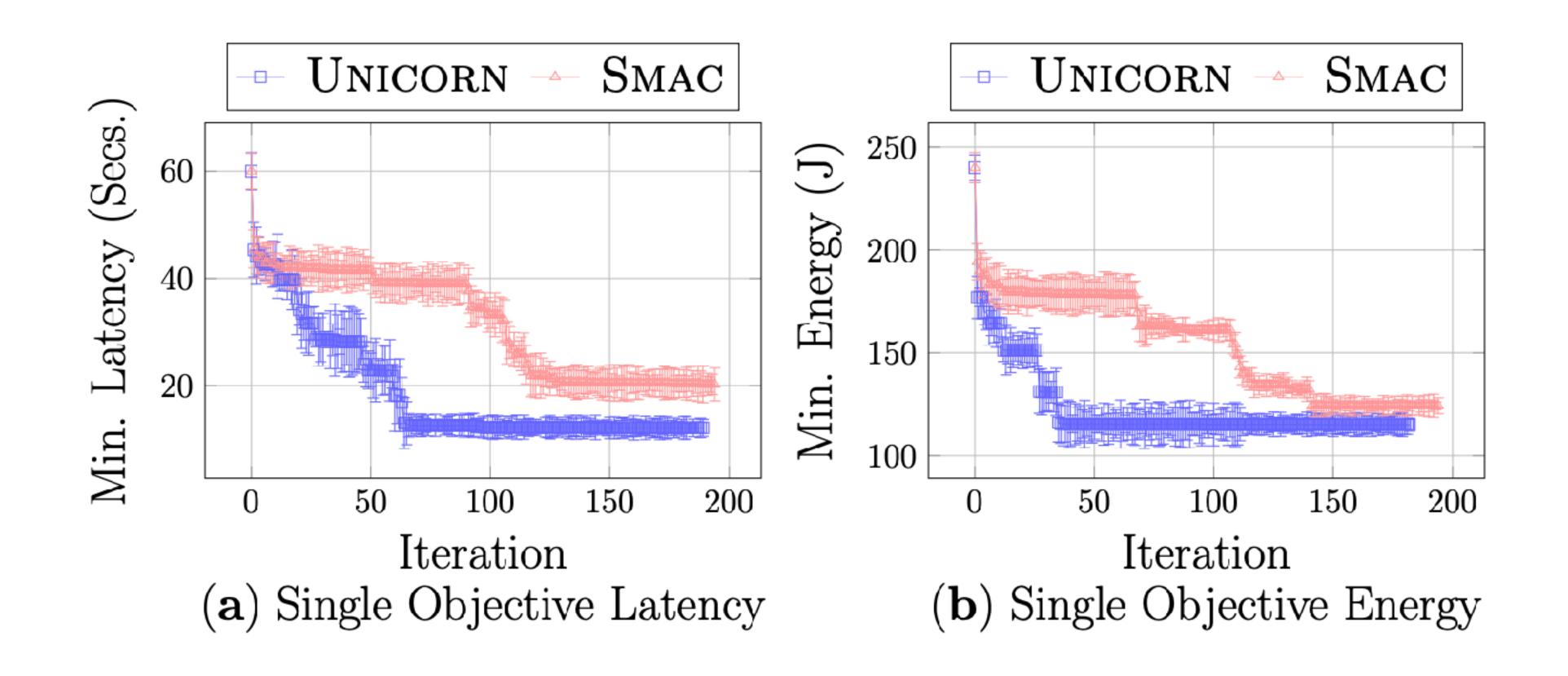
			Accuracy			Precision			Recall			Gain (Latency)			C	Gain (Energy)				ie [†]			
		UNICORN	CBI	ENCORE	ВисДос	Unicorn	CBI	ENCORE	ВисДос	Unicorn	CBI	ENCORE	ВивДос	UNICORN	CBI	ENCORE	ВисДос	Unicorn	CBI	ENCORE	Видрос	Unicorn	Others
+ >	XCEPTION	89	76	81	79	77	53	54	62	81	59	59	62	84	53	61	65	75	38	46	44	0.9	4
rgy	BERT	71	72	73	71	77	42	56	63	79	5 9	62	65	84	53	59	61	67	41	27	4 8	0.5	4
ner ,ate	DEEPSPEECH	86	69	71	72	80	44	53	62	81	51	59	64	88	55	55	62	77	43	43	41	1.1	4
E I	x264	85	73	83	81	83	50	54	67	80	63	62	61	75	62	64	66	76	64	66	64	1	4

[†] Wallclock time in hours

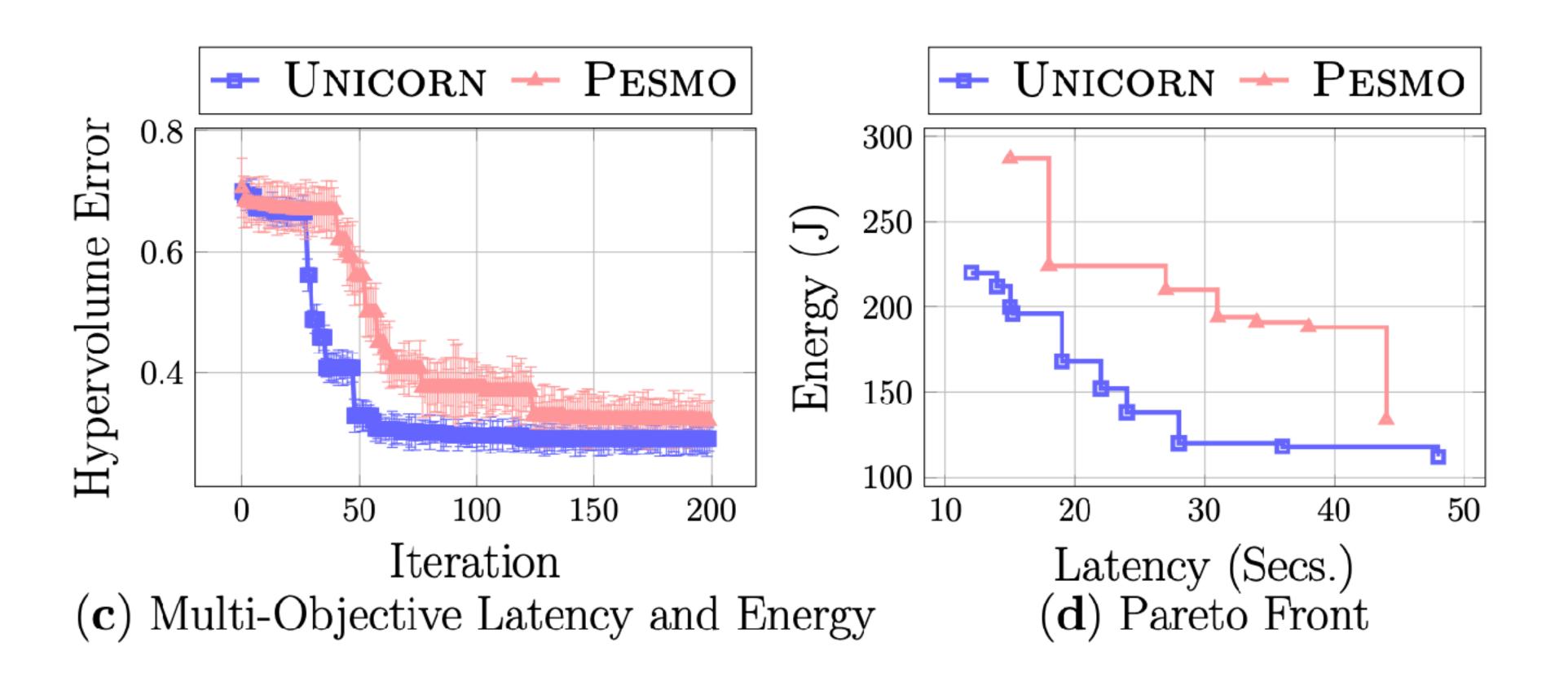
Multiple Faults in Latency & Energy usage

Better gain across both objectives

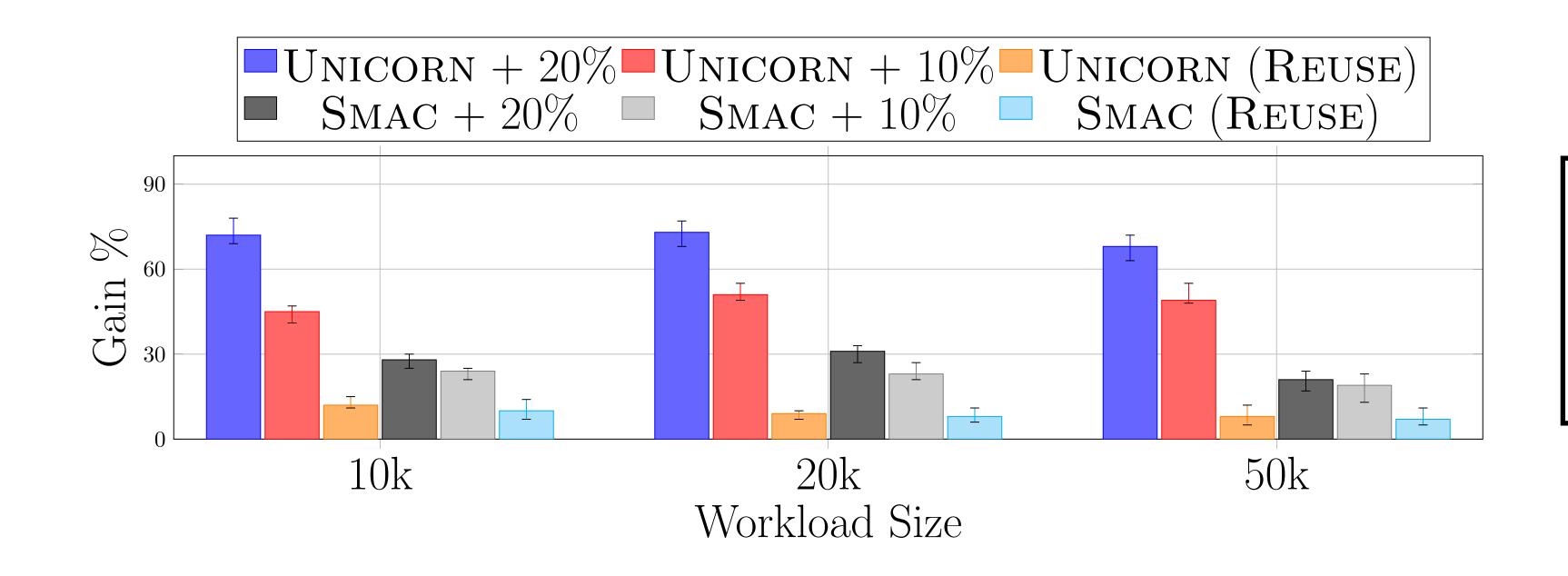
Results: Efficiency (Optimization; Single objective)



Results: Efficiency (Optimization; Multi-objective)

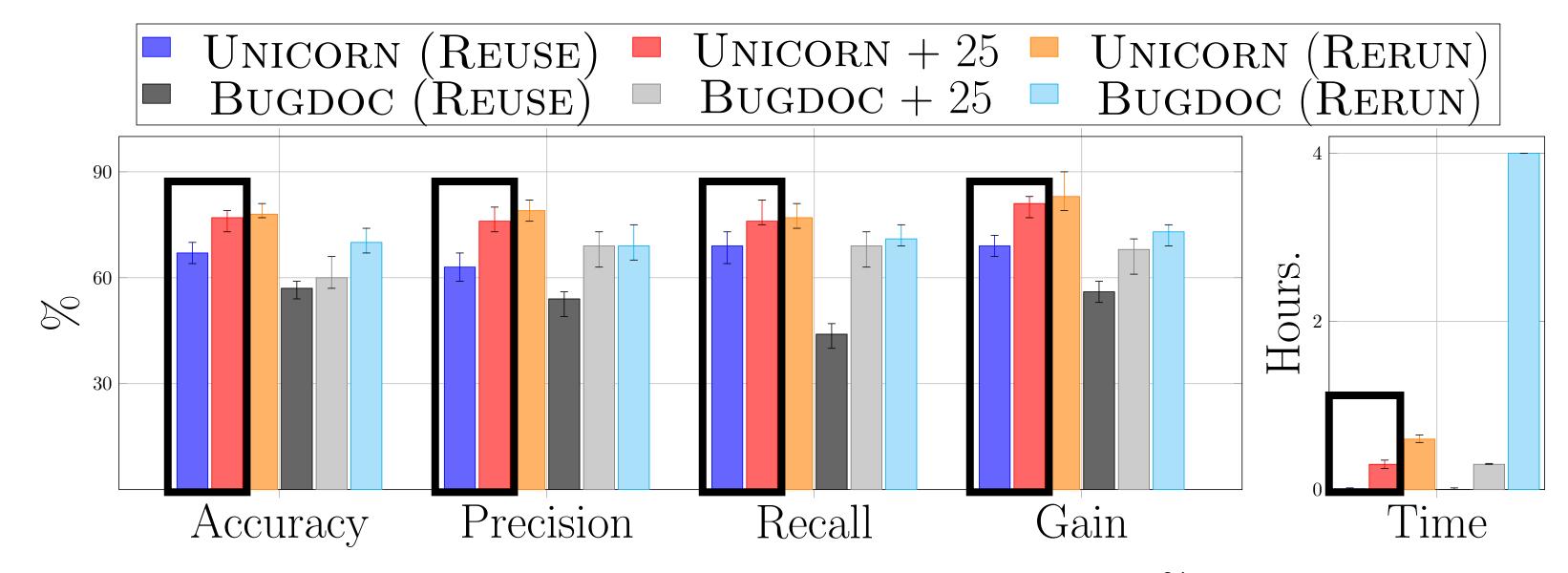


Results: Transferability



UNICORN finds configuration with higher gain when workload changes.

Results: Transferability



UNICORN quickly fixes the bug and achieves higher gain, accuracy, precision and recall when hardware changes

Results: Scalability

							Time	e/Fault	t (in sec.)
System	Configs	Events	Paths	Queries	Degree	Gain (%)	Discovery	Query Eval	Total
SQLite	34	19	32	191	3.6	93	9	14	291
	242	19	111	2234	1.9	94	57	129	1345
	242	288	441	22372	1.6	92	111	854	5312
DEEPSTREAM	53	19	43	497	3.1	86	16	32	1509
	53	288	219	5008	2.3	85	97	168	3113

Discovery time, query evaluation time and total time do not increase exponentially as the number of configuration options and systems events are increased

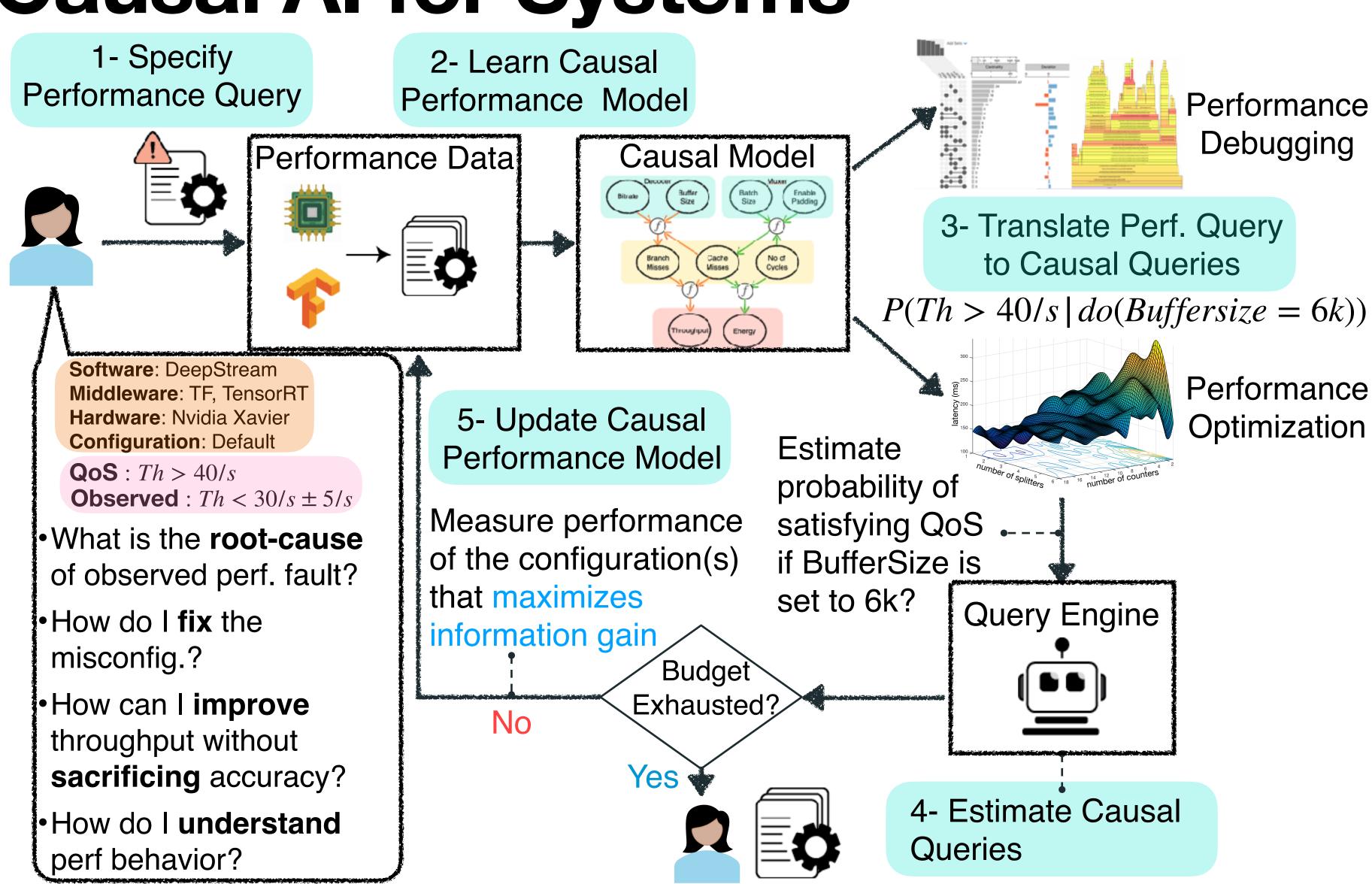
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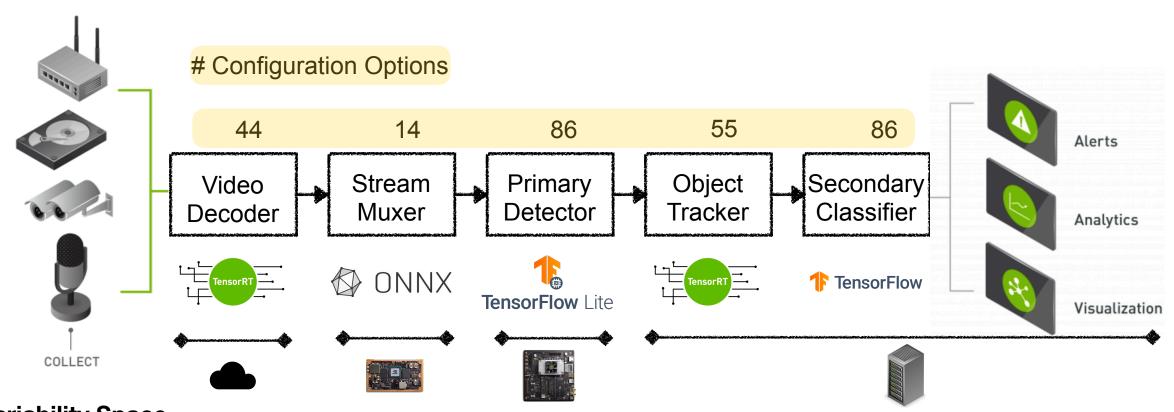
Causal graphs are sparse

Summary: Causal Al for Systems

- 1. Learning a causal performance model for different downstream systems tasks.
- 2. The learned causal model is **transferable** across different environments.
- 3. The causal reasoning approach is **scalable** to largescale systems.



The variability space of today's systems is exponentially increasing Systems are heterogeneous, multiscale, multi-modal, and multi-stream



Variability Space = Algorithm Selection + Configuration Space + System Architecture + **Deployment Environment**

Evaluation: Experimental Setup

Hardware

Nvidia TX1								
CPU	4 cores, 1.3 GHz							
GPU	128 Cores, 0.9 GHz							
Memory	4 Gb, 25 GB/s							

	Nvidia TX2
CPU	6 cores, 2 GHz
GPU	256 Cores, 1.3 GHz
Memory	8 Gb, 58 GB/s

Nvidia Xavier	
CPU	8 cores, 2.26 GHz
GPU	512 cores, 1.3 GHz
Memory	32 Gb, 137 GB/s

Configuration Space

X	30 Configurations	
	 10 software 	
	 10 OS/Kernel 	
	 10 hardware 	
X	17 System Events	

Systems

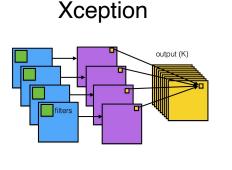
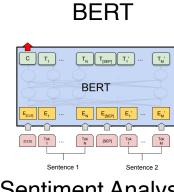


Image recognition (50,000 test images)

DeepSpeech

Voice recognition (5 sec. audio clip)

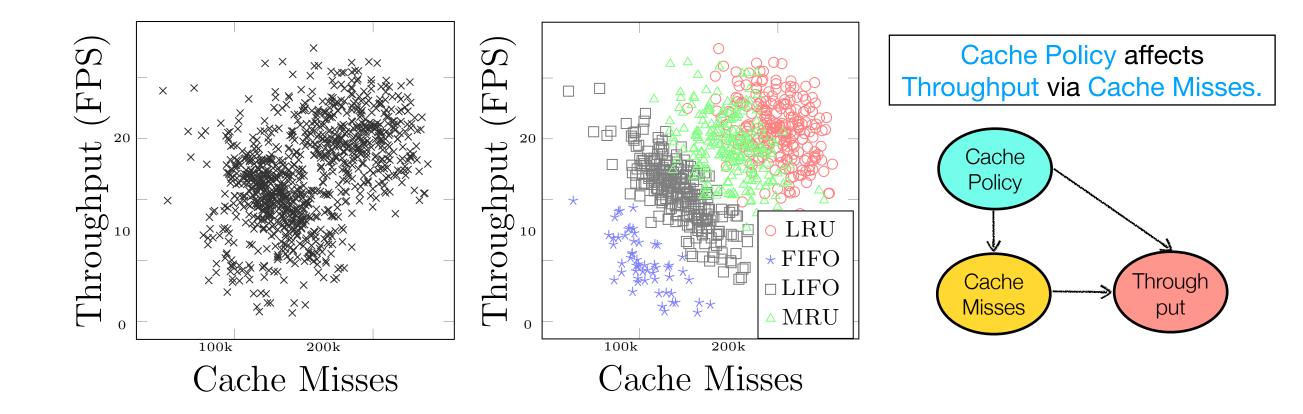


Sentiment Analysis (10000 IMDb reviews)



Video Encoder (11 Mb, 1080p video)

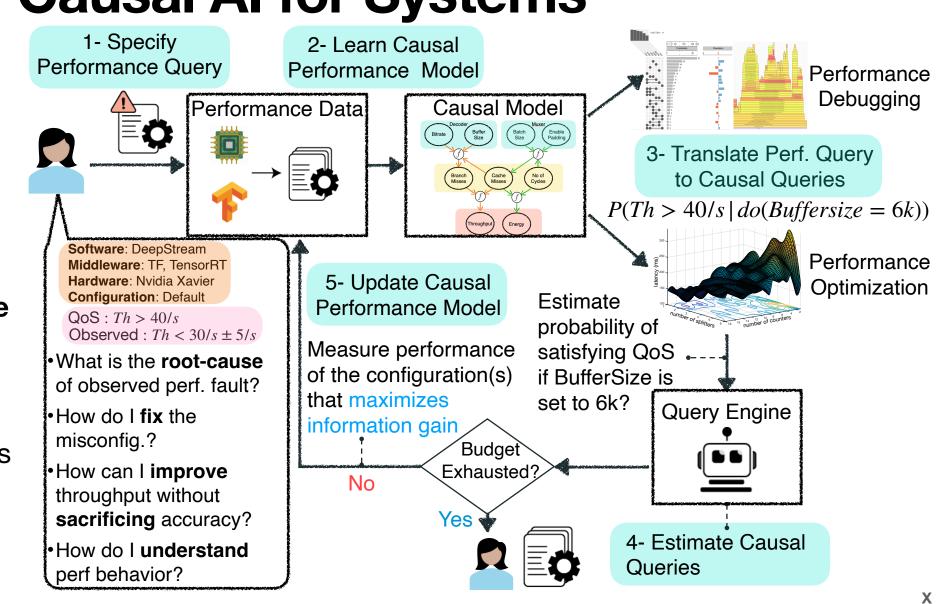
Causal performance models produce correct explanations





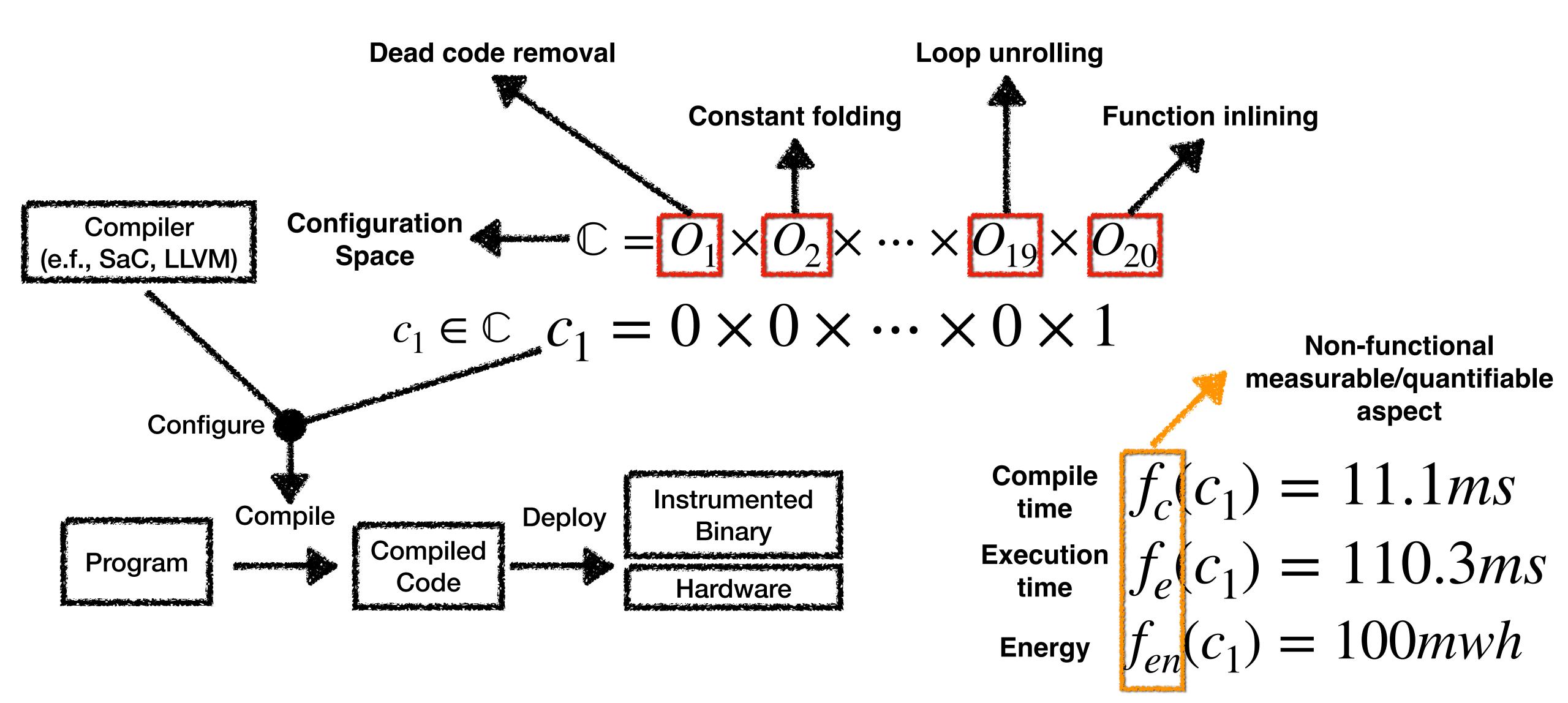
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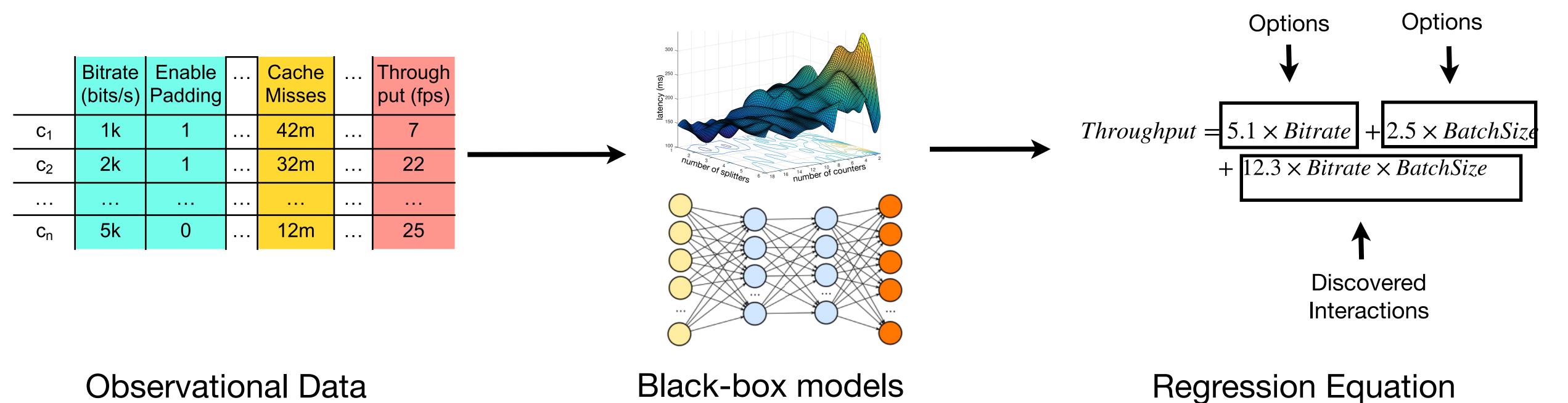


How to resolve these issues faster?

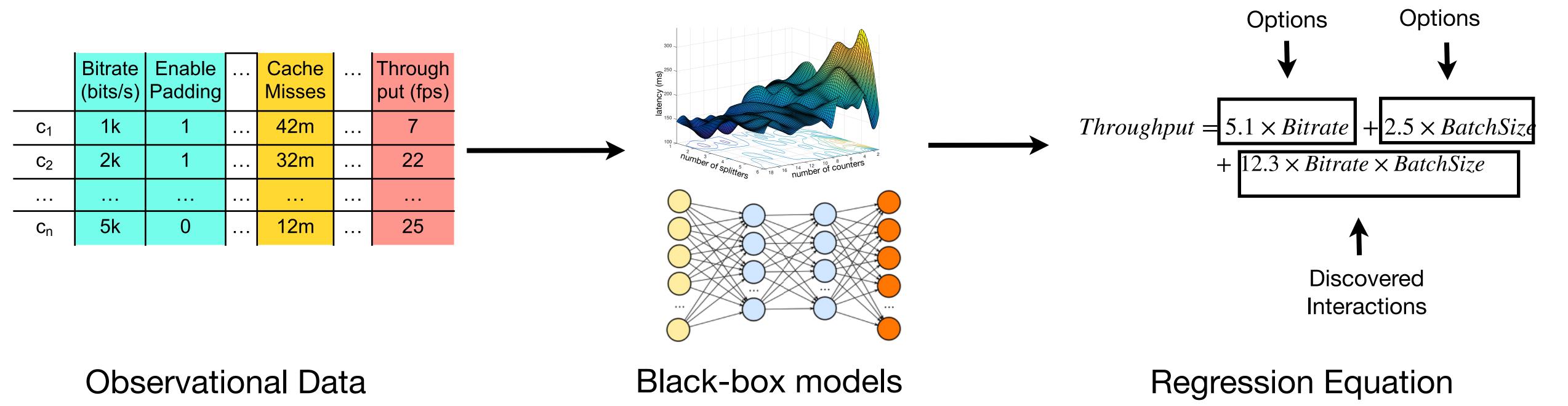
Performance measurement



Performance Influence Models



Performance Influence Models

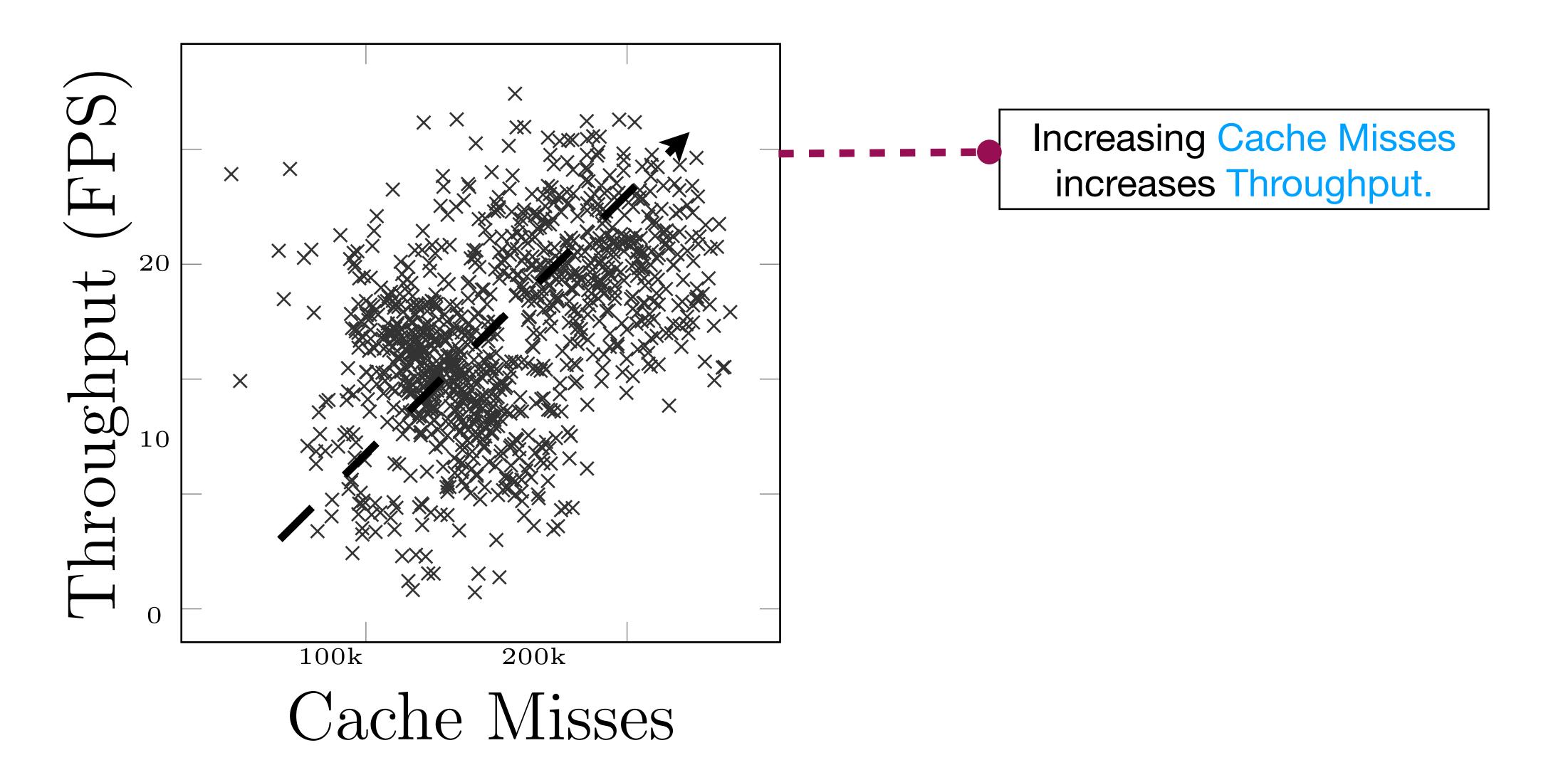


These methods rely on statistical correlations to extract meaningful information required for performance tasks.

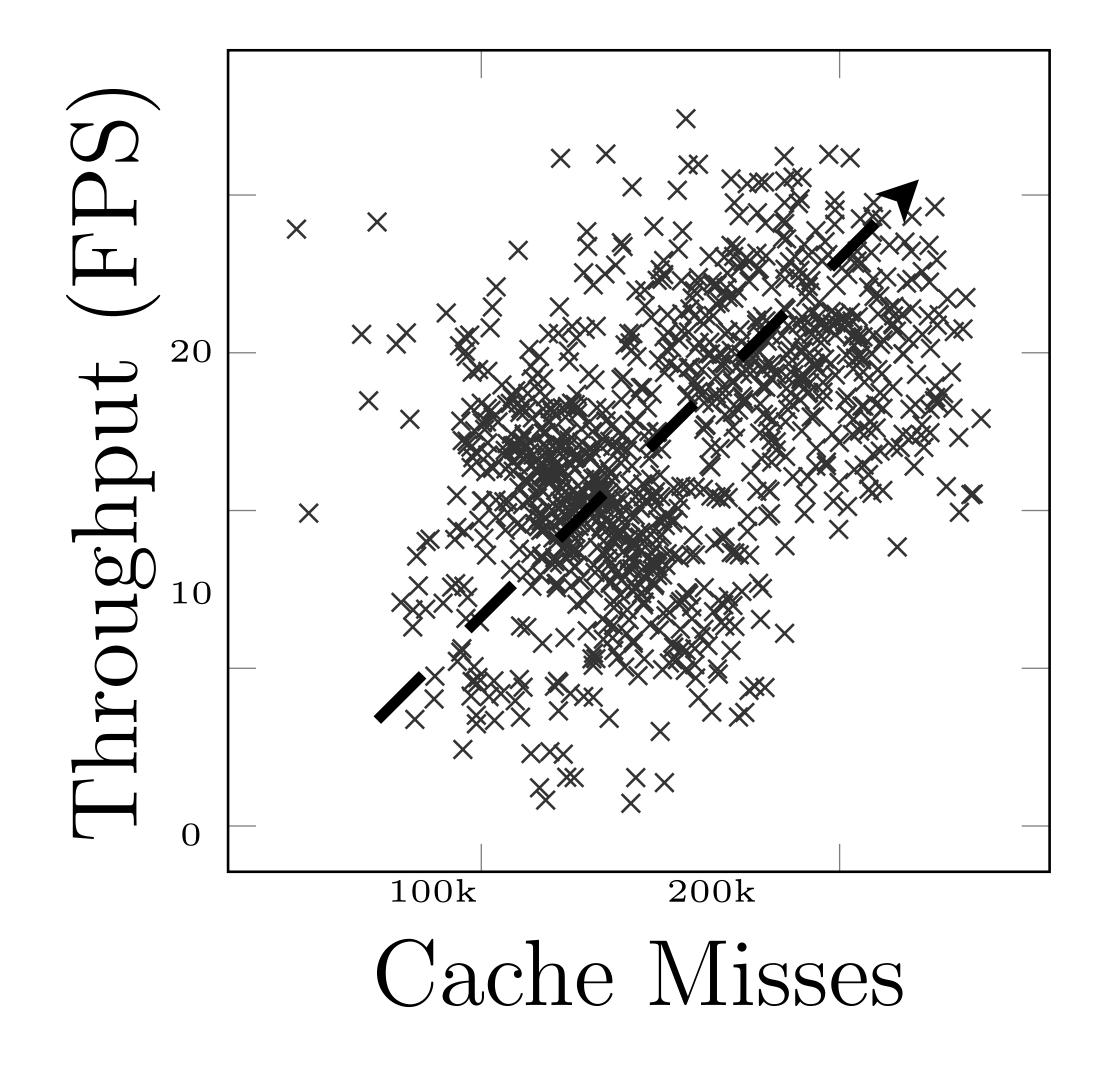
Performance Influence Models suffer from several shortcomings

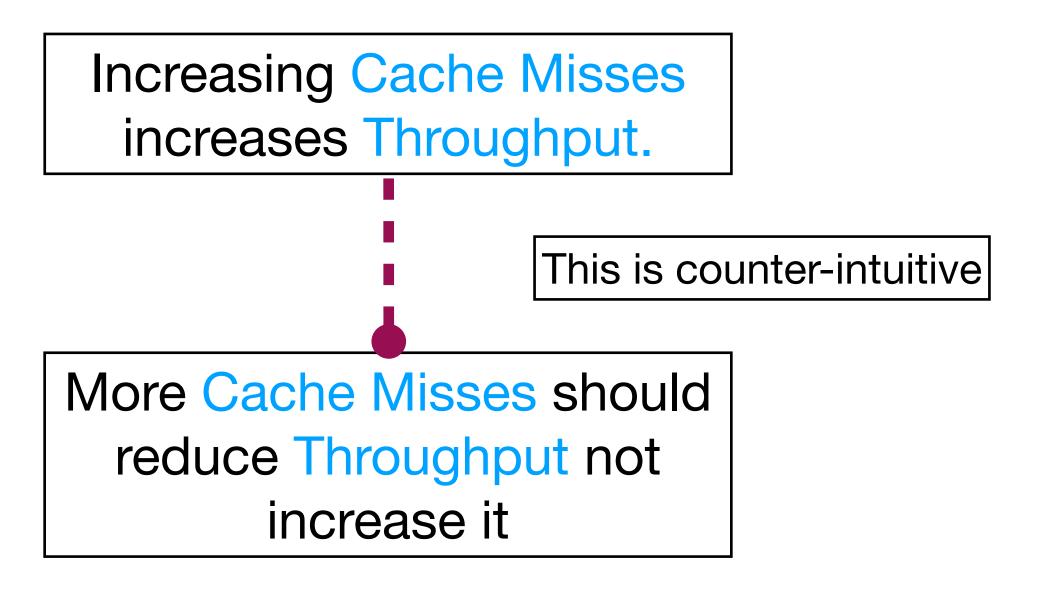
- Performance influence models could produce incorrect explanations
- Performance influence models could produce unreliable predictions.
- Performance influence models could produce unstable predictions across environments and in the presence of measurement noise.

Performance Influence Models Issue: Incorrect Explanation



Performance Influence Models Issue: Incorrect Explanation

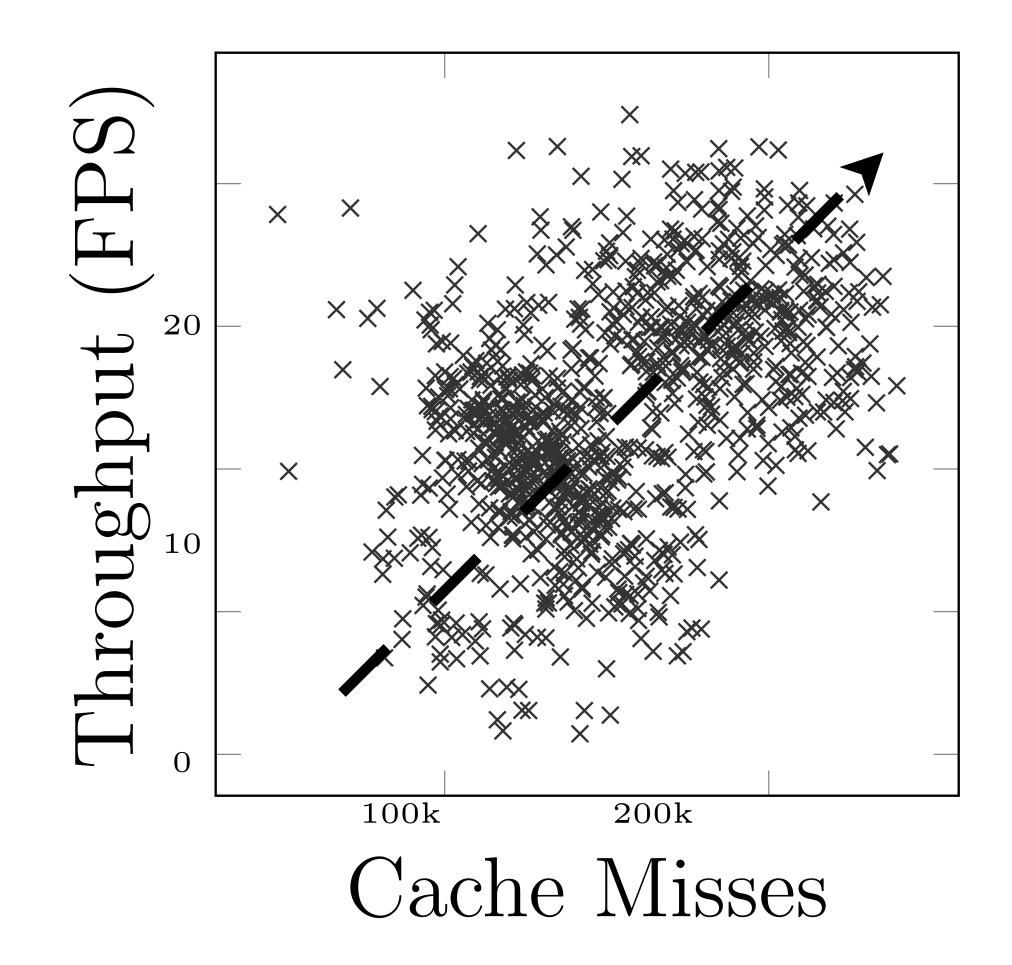


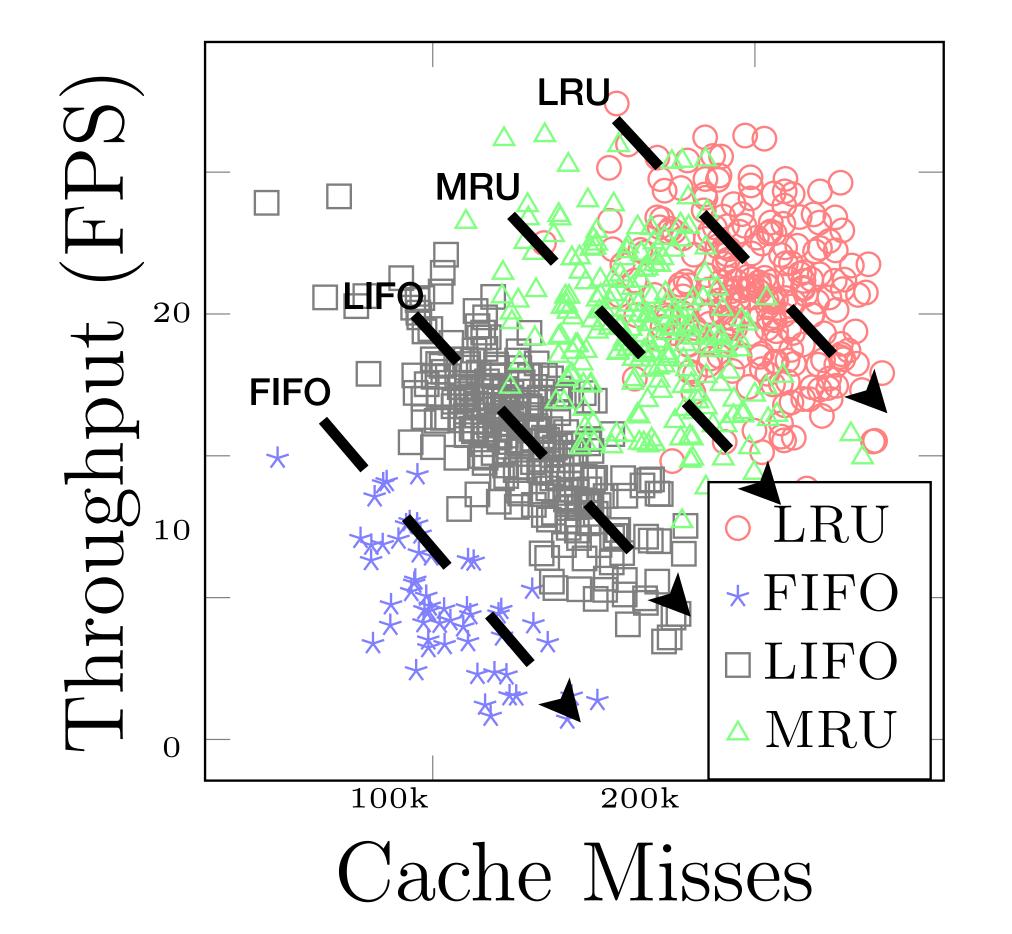




Any ML/statistical models built on this data will be incorrect.

Performance Influence Models Issue: Incorrect Explanation





Segregating data on Cache Policy indicates that within each group Increase of Cache Misses result in a decrease in Throughput.

Performance Influence Models Issue: Unstable Predictors

Performance influence model in TX2.

$$Throughput = 2 \times Bitrate + 1.9 \times BatchSize + 1.8 \times BufferSize + 0.5 \times EnablePadding + 5.9 \times Bitrate \times BufferSize + 0.2 \times Bitrate \times EnablePadding + 4.1 \times Bitrate \times BufferSize \times EnablePadding$$

Performance influence model in Xavier.

Throughput =
$$5.1 \times Bitrate + 2.5 \times BatchSize + 12.3 \times Bitrate \times BatchSize$$

Performance Influence Models change significantly in new environments resulting in less accuracy.

Performance Influence Models Issue: Unstable Predictors

Performance influence model in TX2.

$$Throughput = 2 \times Bitrate + 1.9 \times BatchSize + 1.8 \times BufferSize + 0.5 \times EnablePadding + 5.9 \times Bitrate \times BufferSize + 6.2 \times Bitrate \times EnablePadding + 4.1 \times Bitrate \times BufferSize \times EnablePadding$$

Performance influence model in Xavier.

Throughput =
$$5.1 \times Bitrate$$
 + $2.5 \times BatchSize$ + $12.3 \times Bitrate \times BatchSize$

Performance influence are cannot be reliably used across environments.

Performance Influence Models Issue: Non-generalizability

Performance influence model in TX2

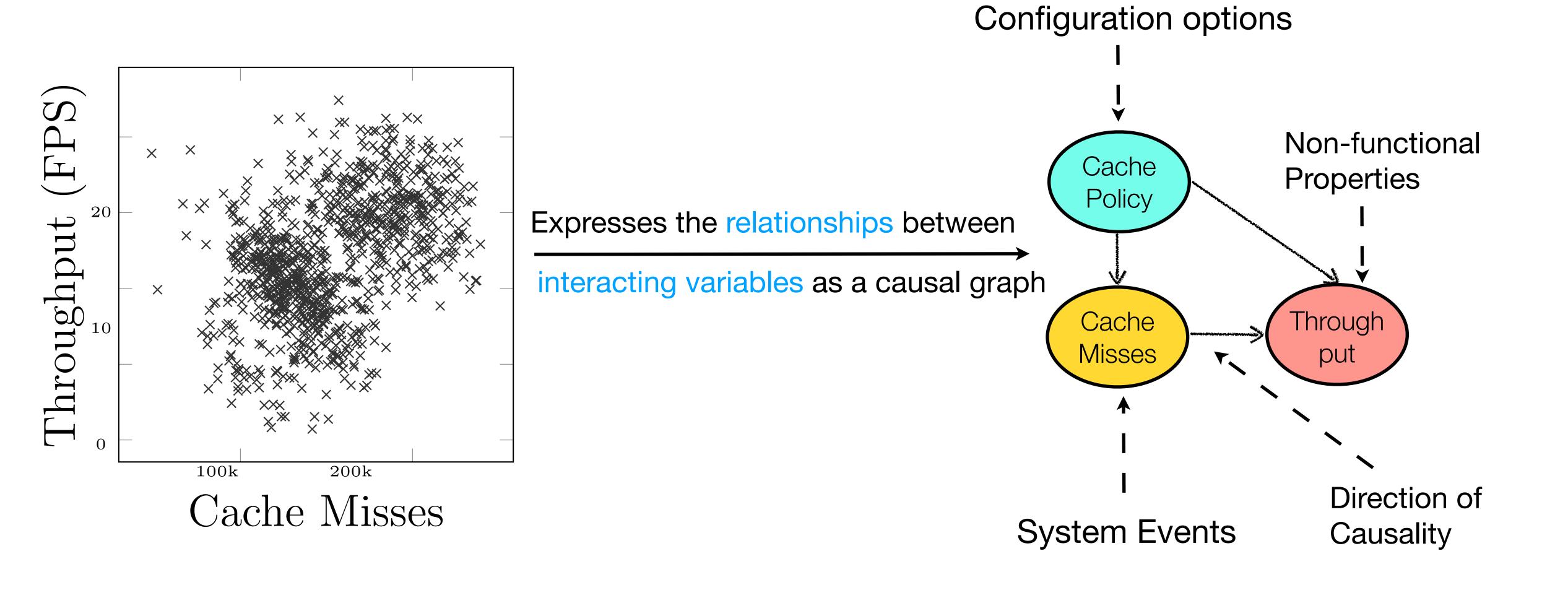
 $Throughput = 2 \times Bitrate + 1.9 \times BatchSize + 1.8 \times BufferSize + 0.5 \times EnablePadding + 5.9 \times Bitrate \times BufferSize + 6.2 \times Bitrate \times EnablePadding + 4.1 \times Bitrate \times BufferSize \times EnablePadding$

Performance influence model in Xavier.

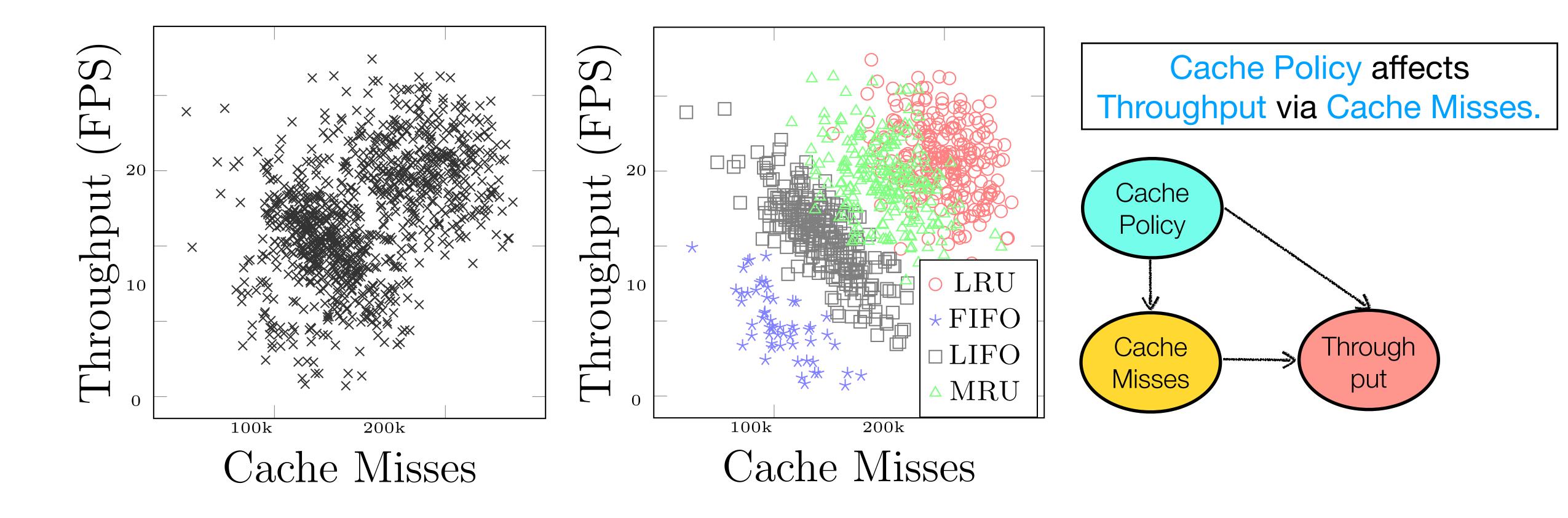
Throughput = $5.1 \times Bitrate + 2.5 \times BatchSize + 12.3 \times Bitrate \times BatchSize$

Performance influence models do not generalize well across deployment environments.

Causal Performance Model



Why Causal Inference? - Produces Correct Explanations

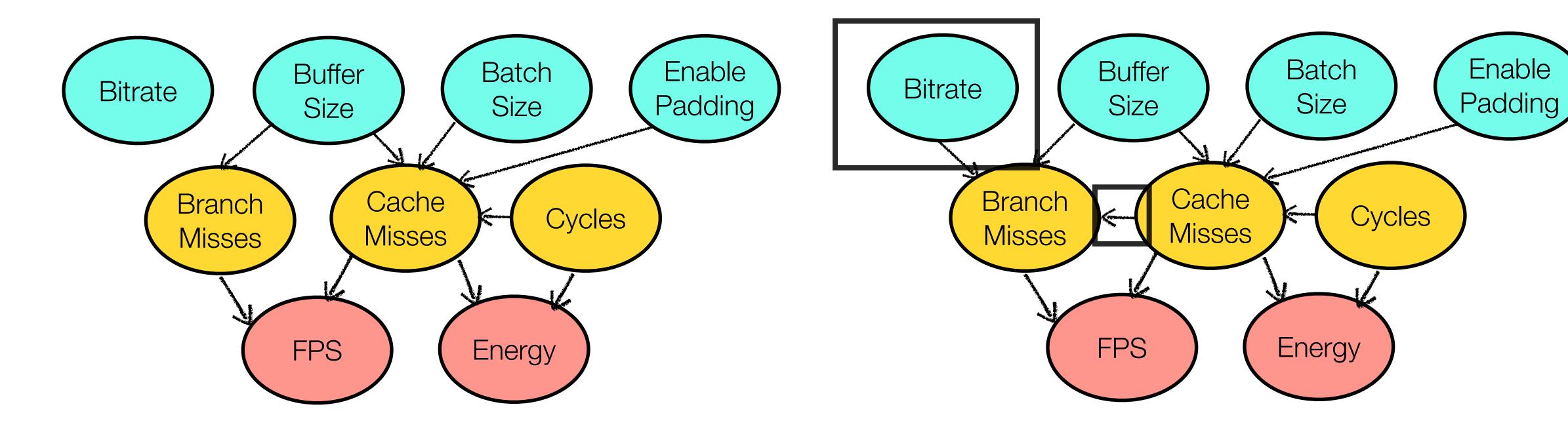


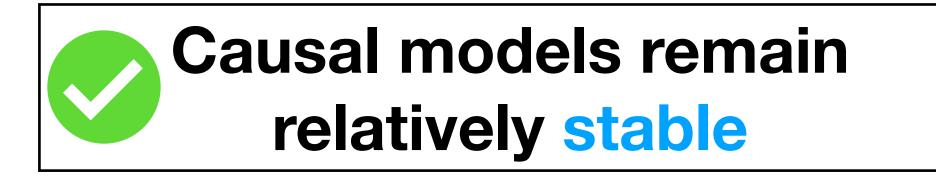


Why Causal Inference? - Minimal Structure Change

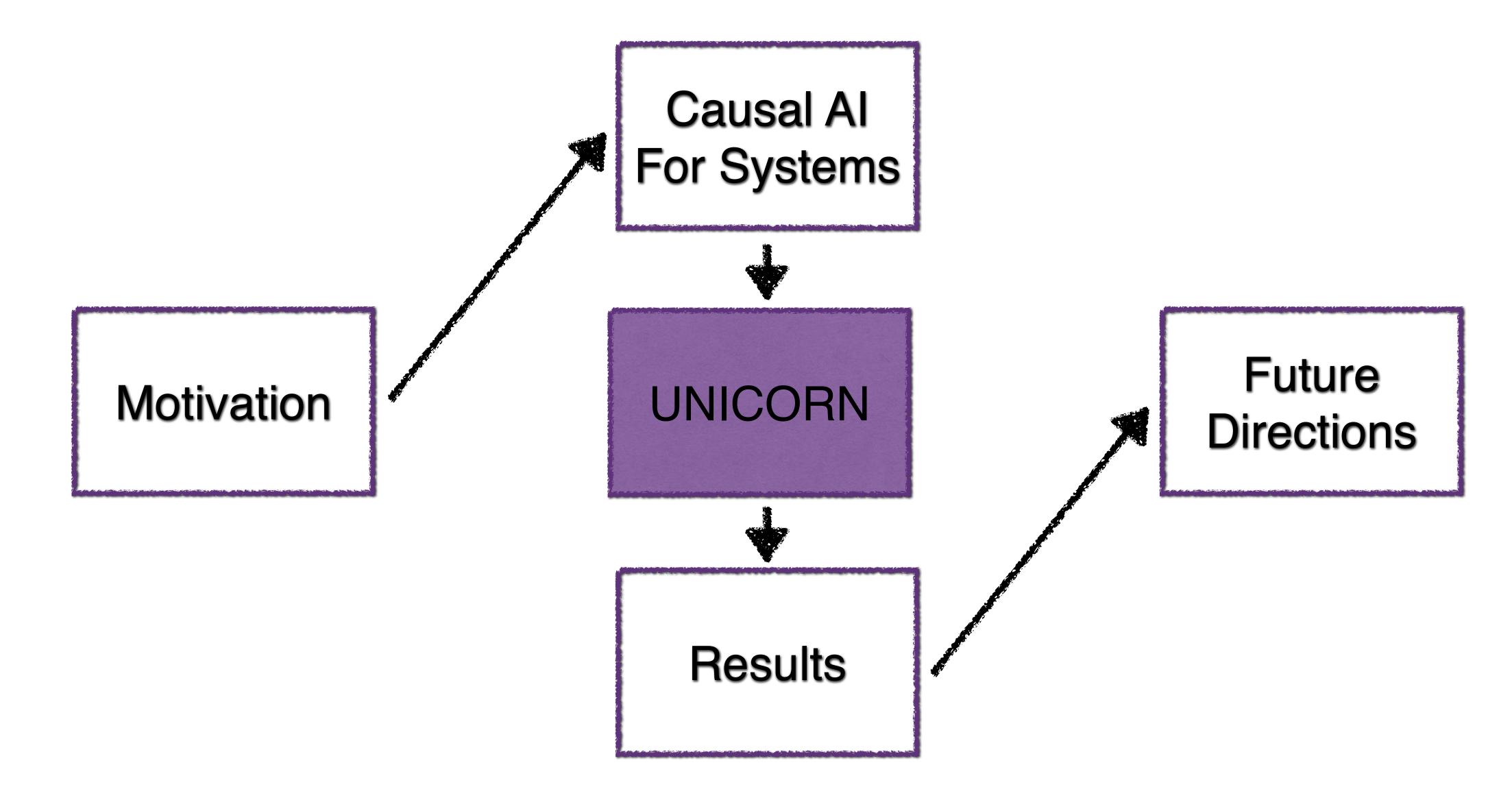
A partial causal performance model in Jetson TX2

A partial causal performance model in Jetson Xavier



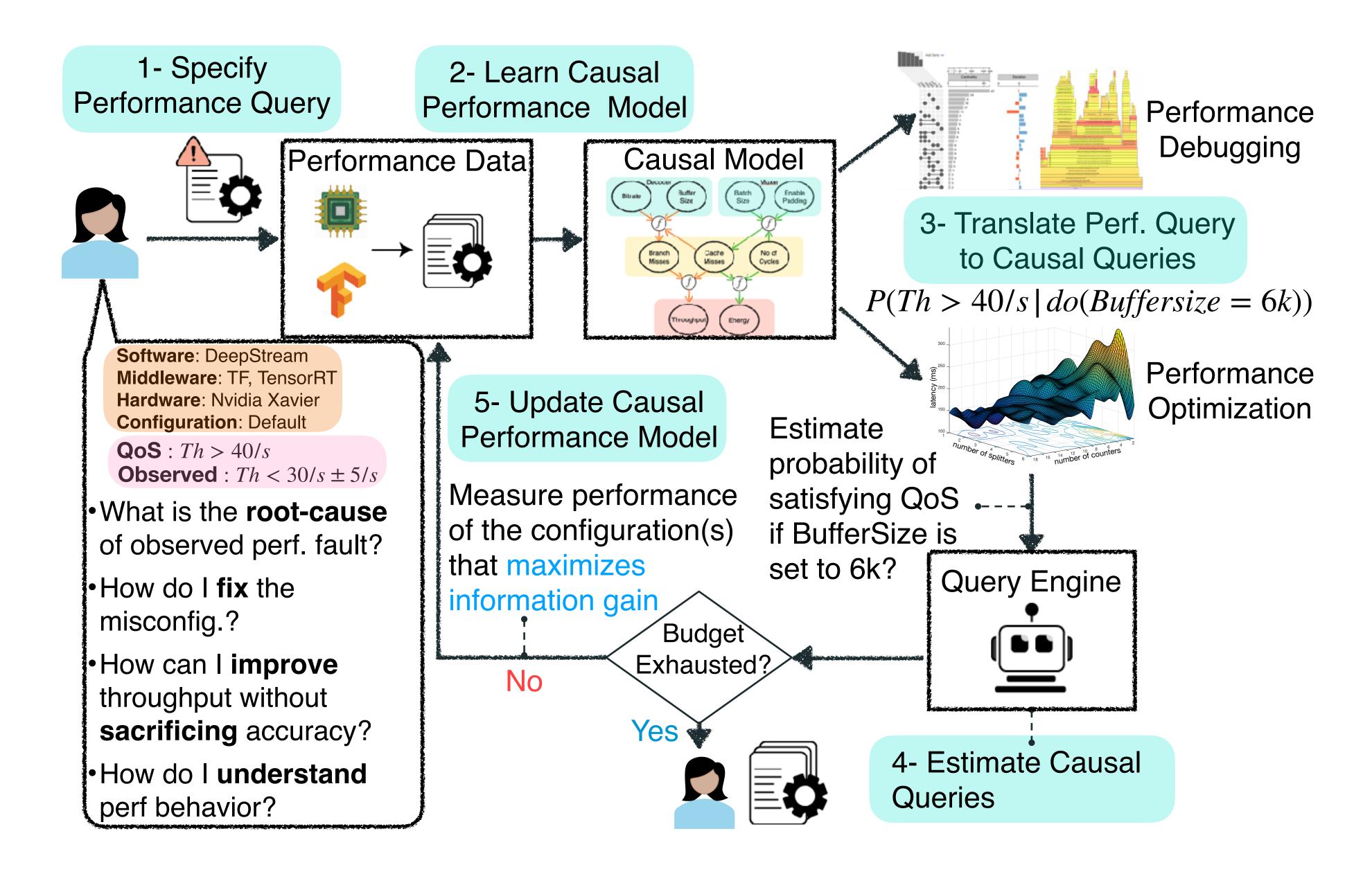


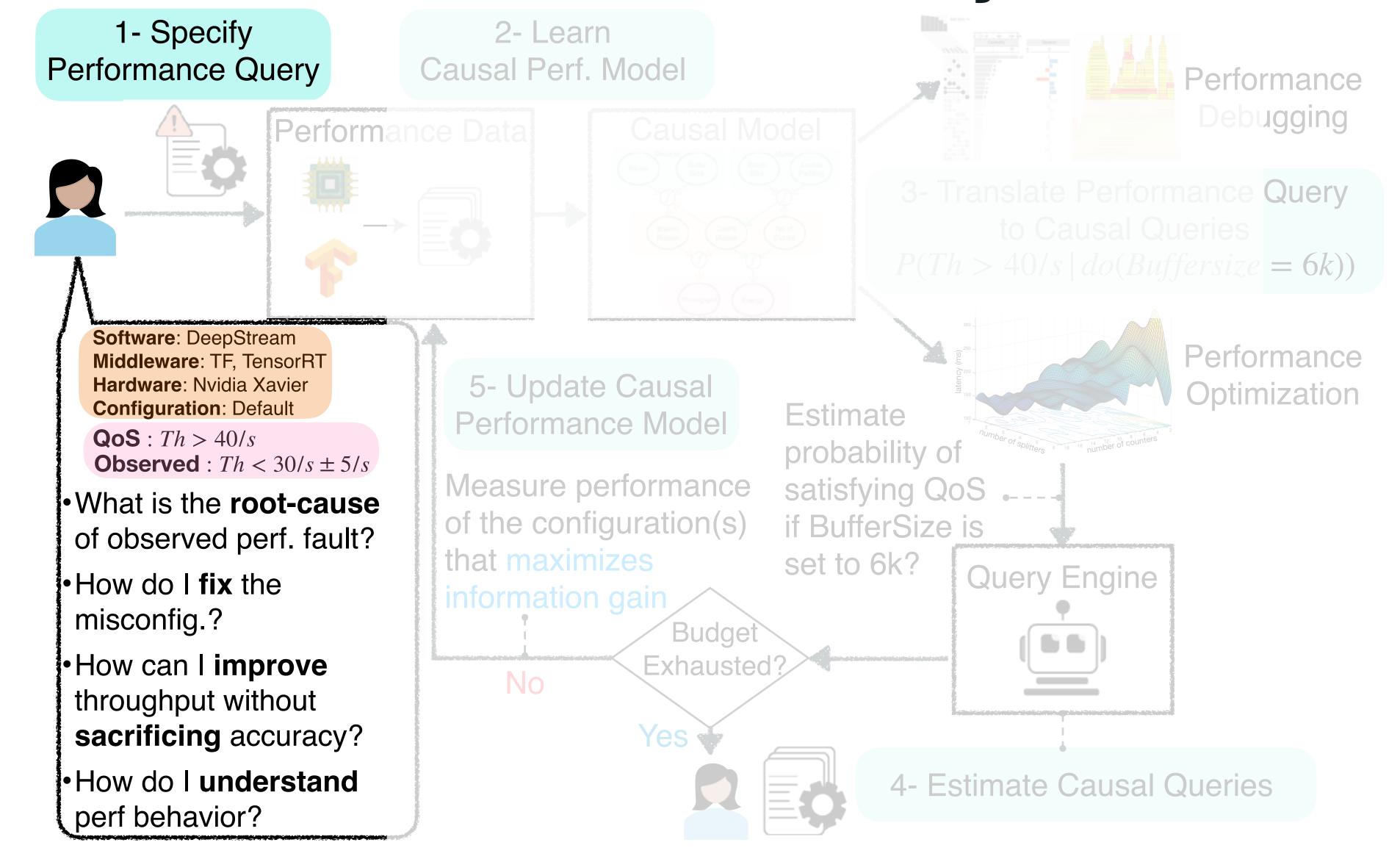
Outline

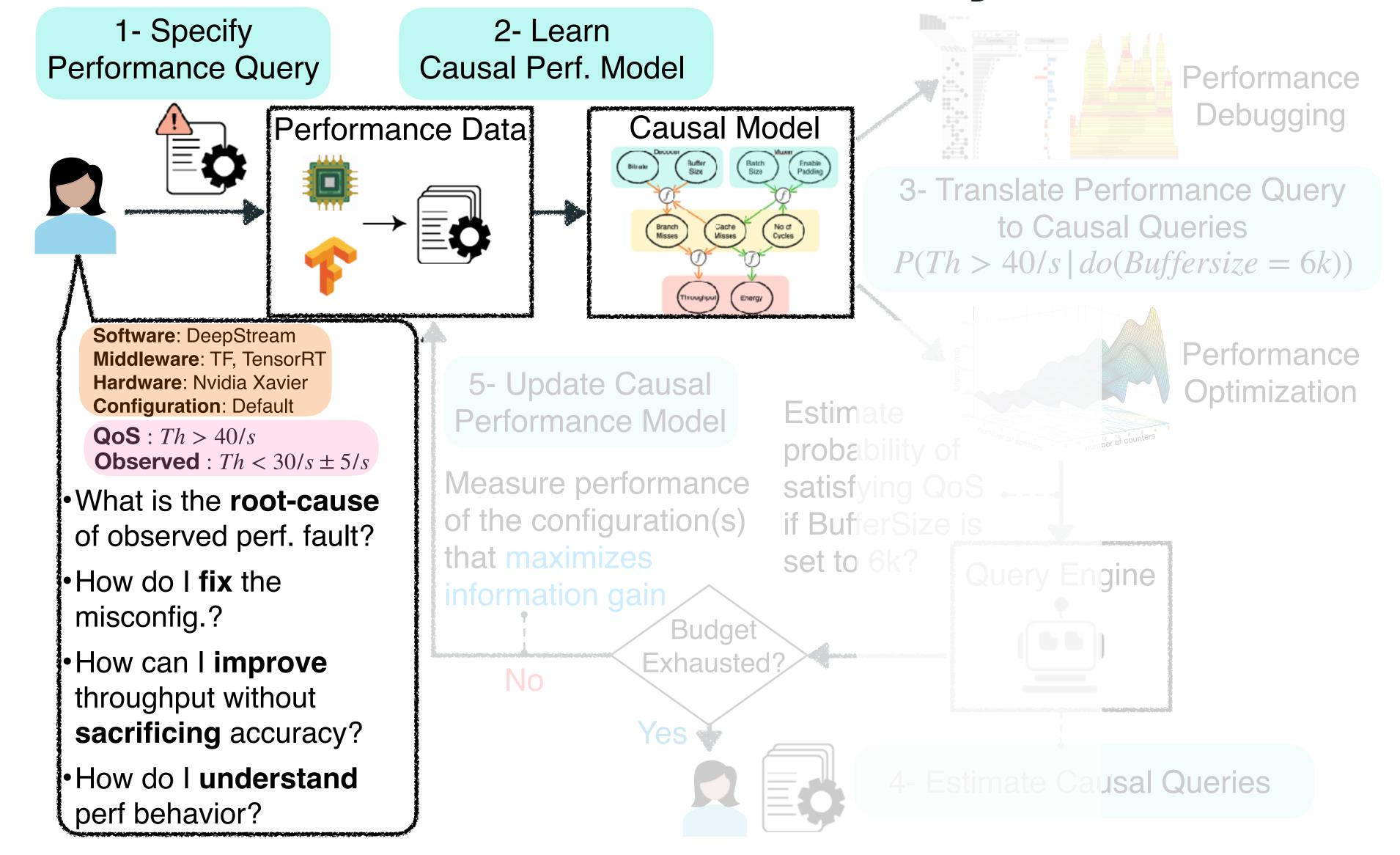


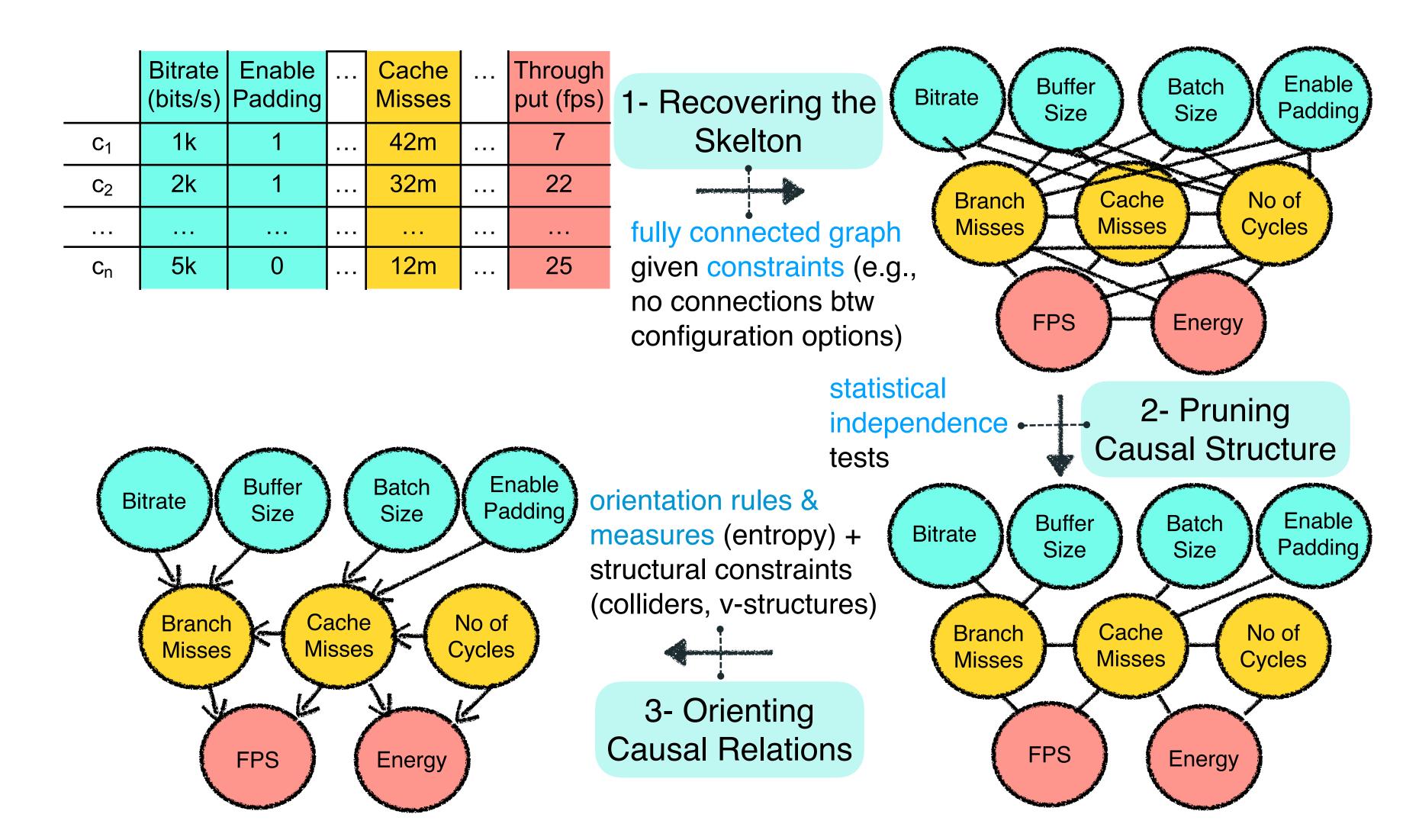
- Build a Causal Performance
 Model that capture the interactions
 options in the variability space
 using the observation performance
 data.
- Iterative causal performance model evaluation and model update
- Perform downstream performance tasks such as performance debugging & optimization using
 Causal Reasoning



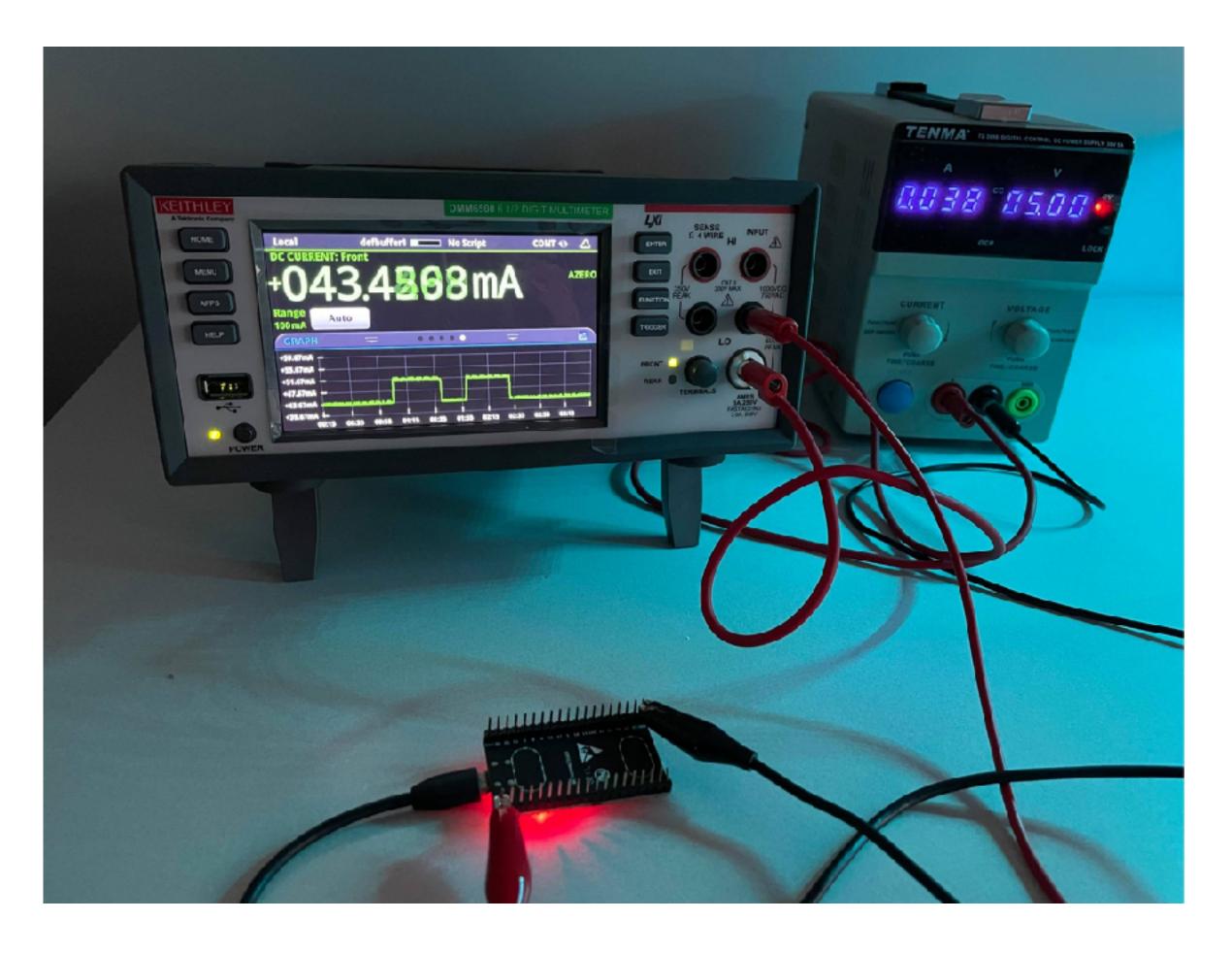




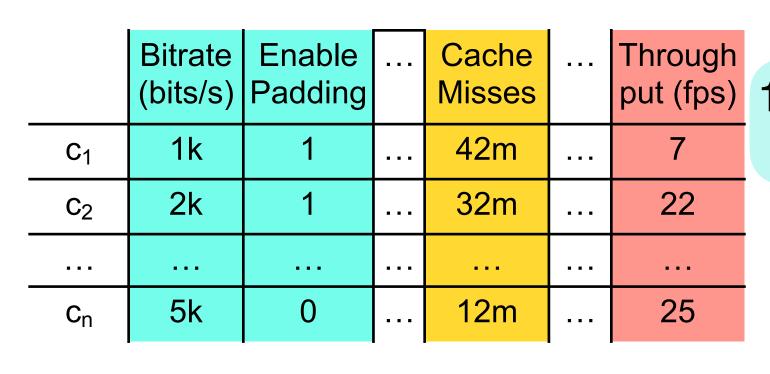


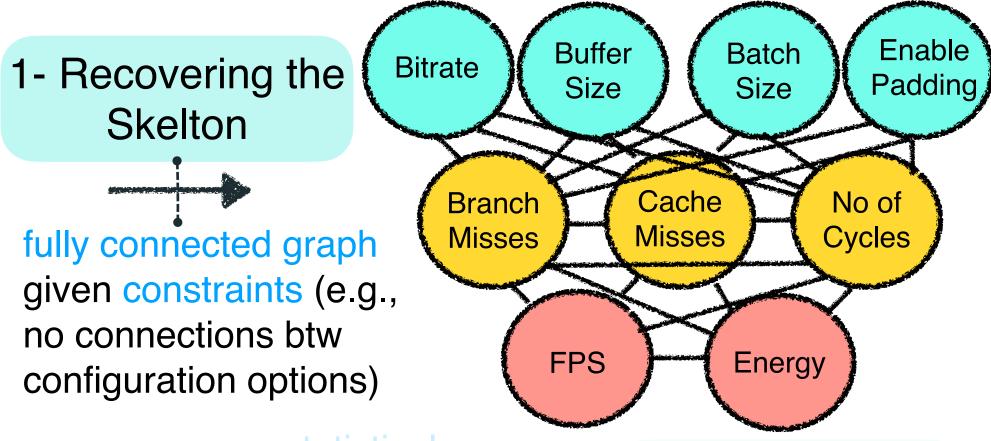


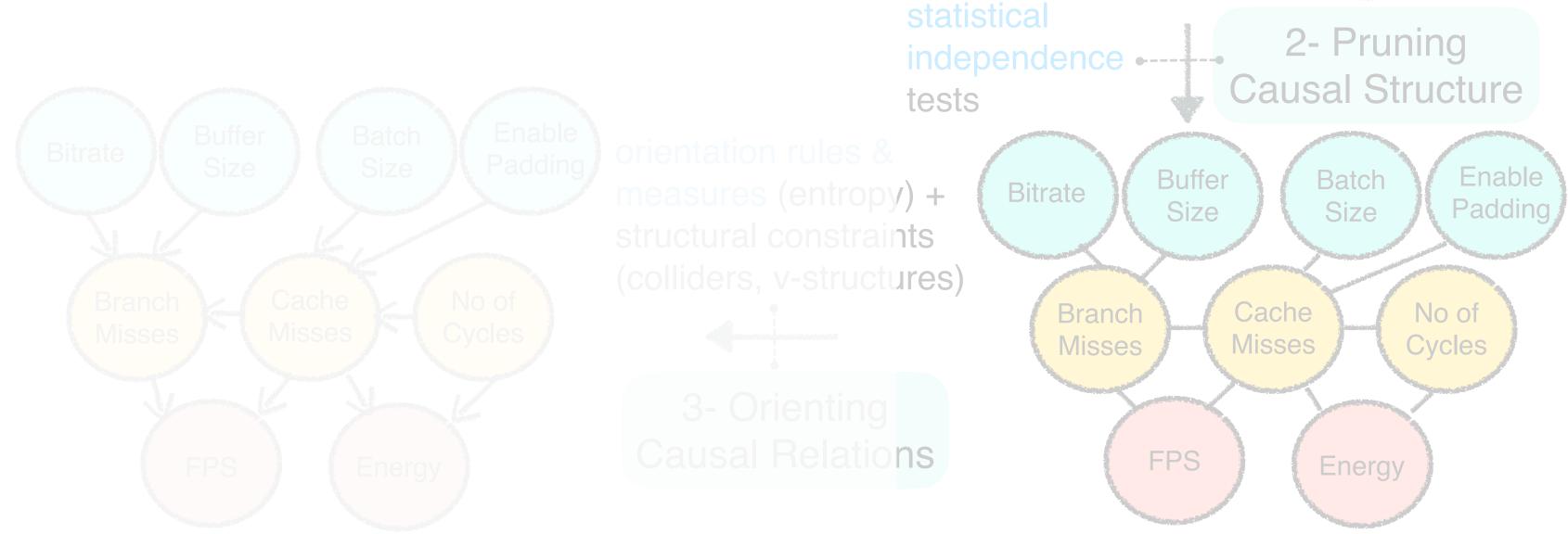
Our setup for performance measurements

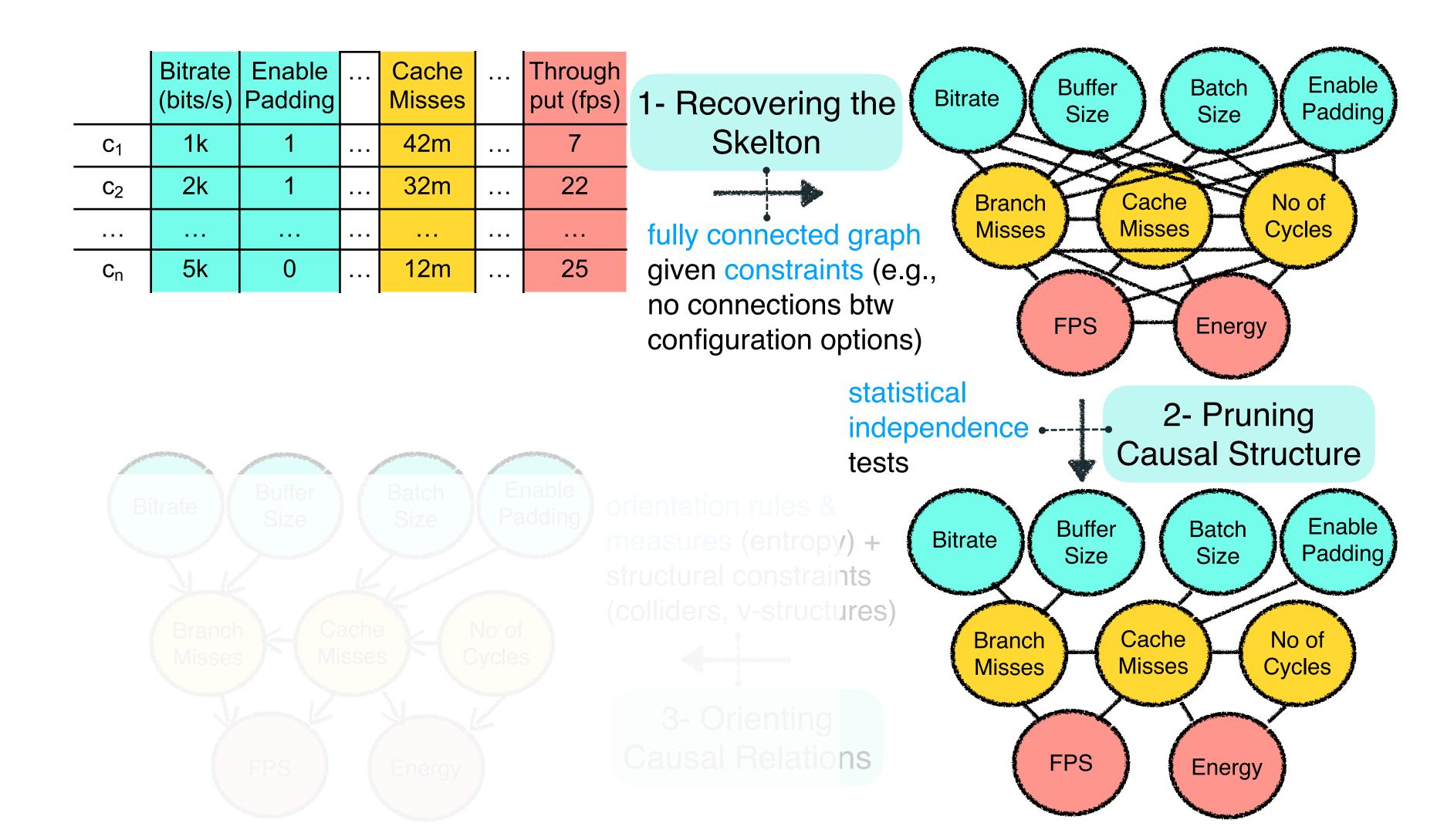


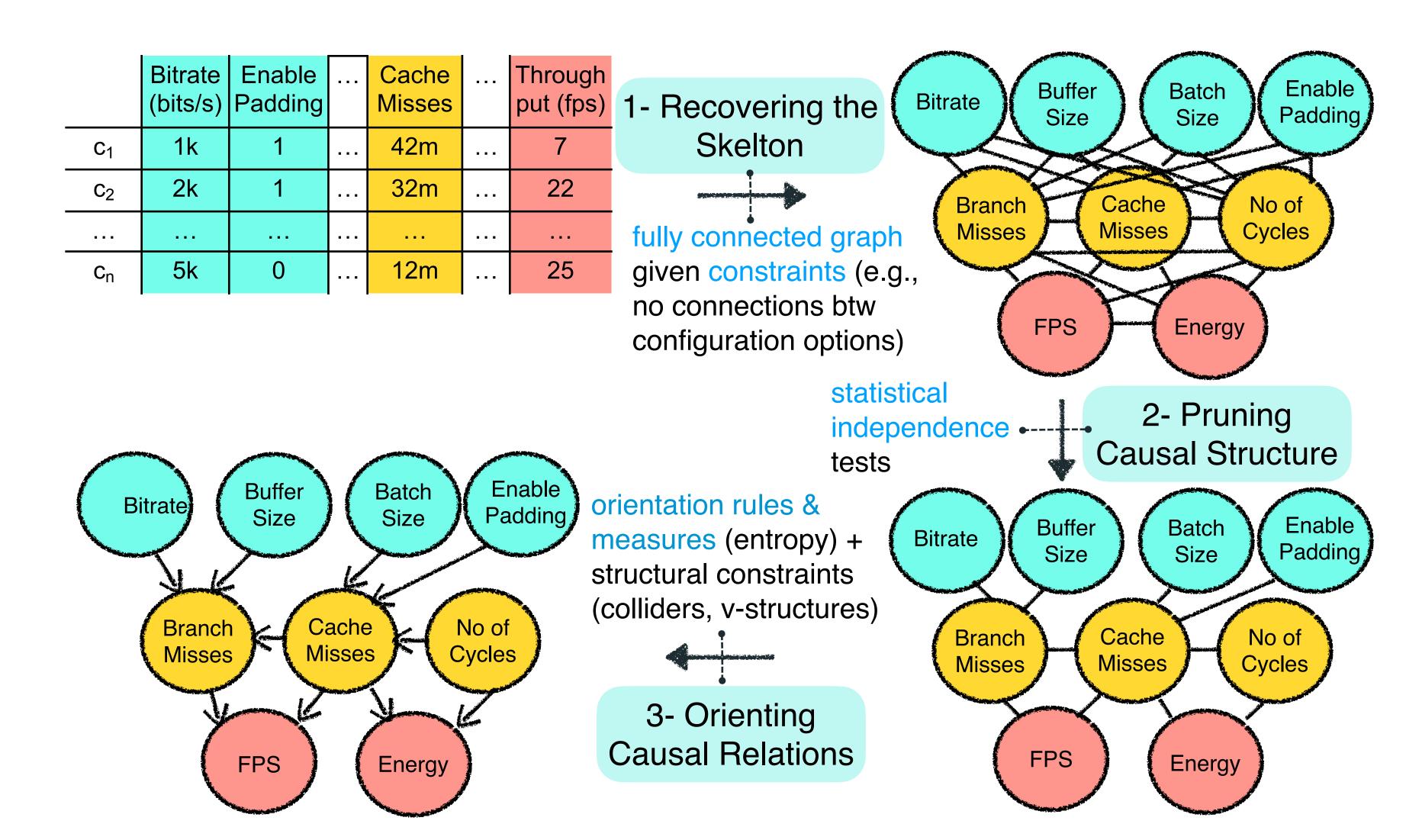






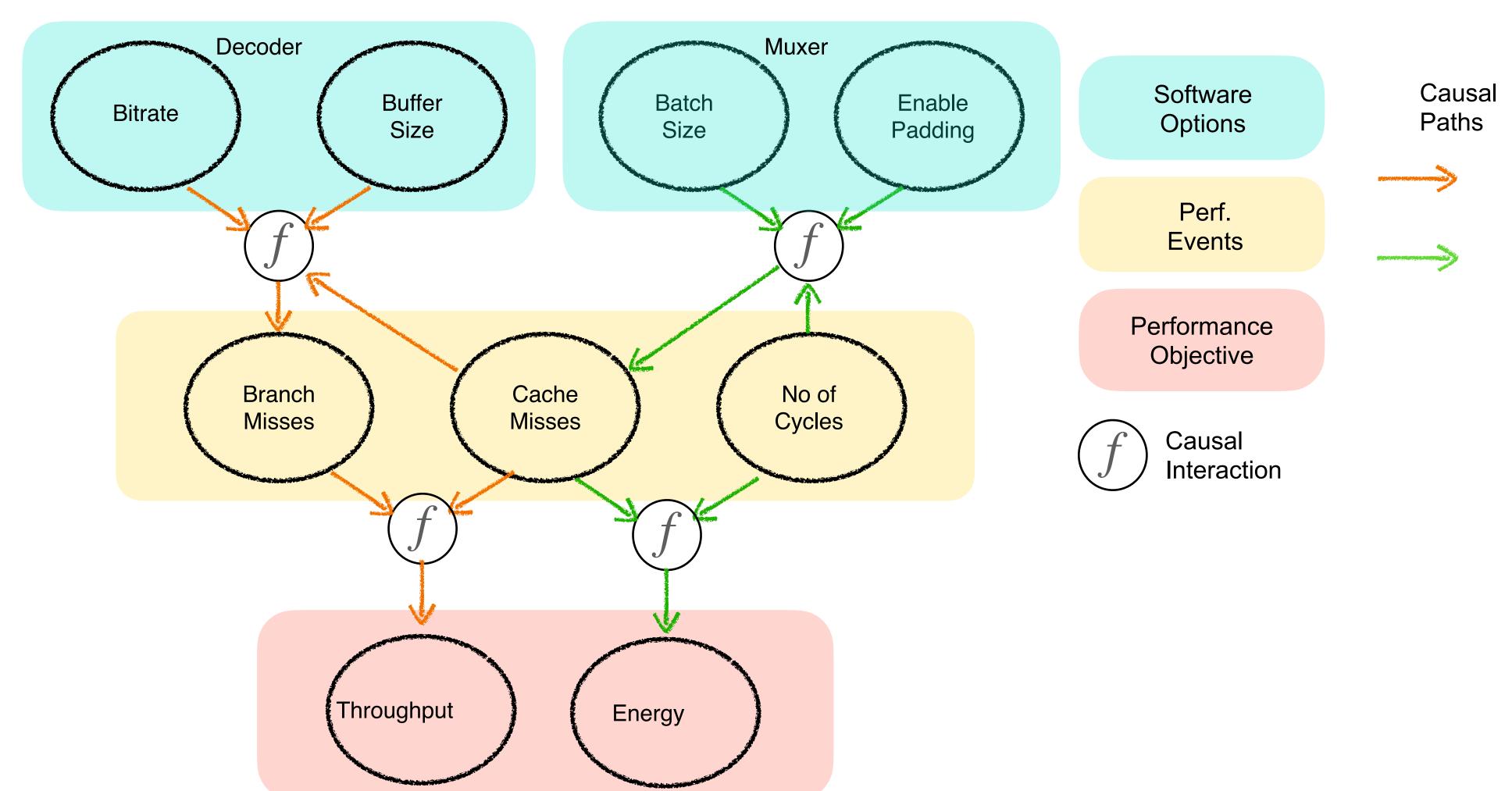


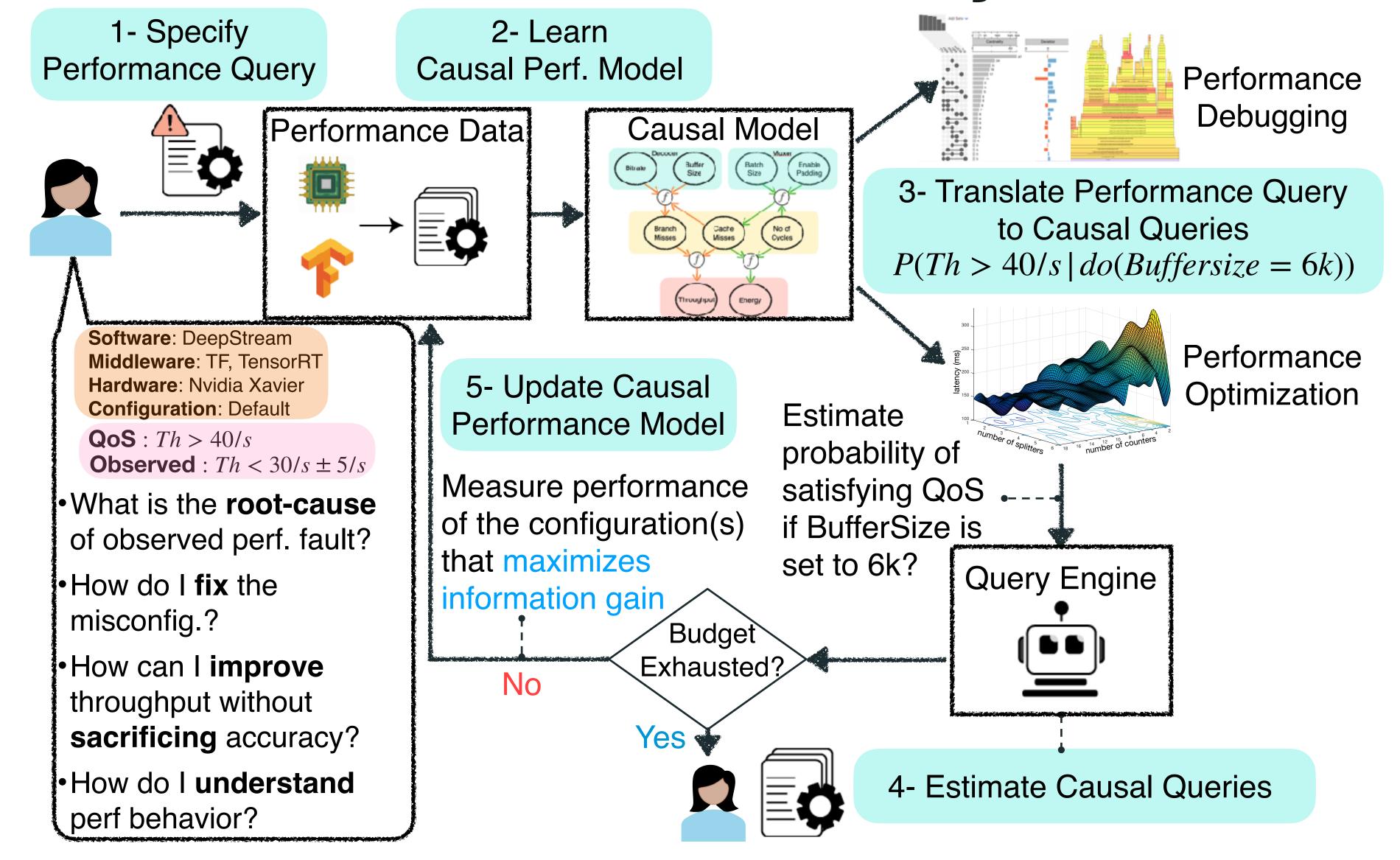




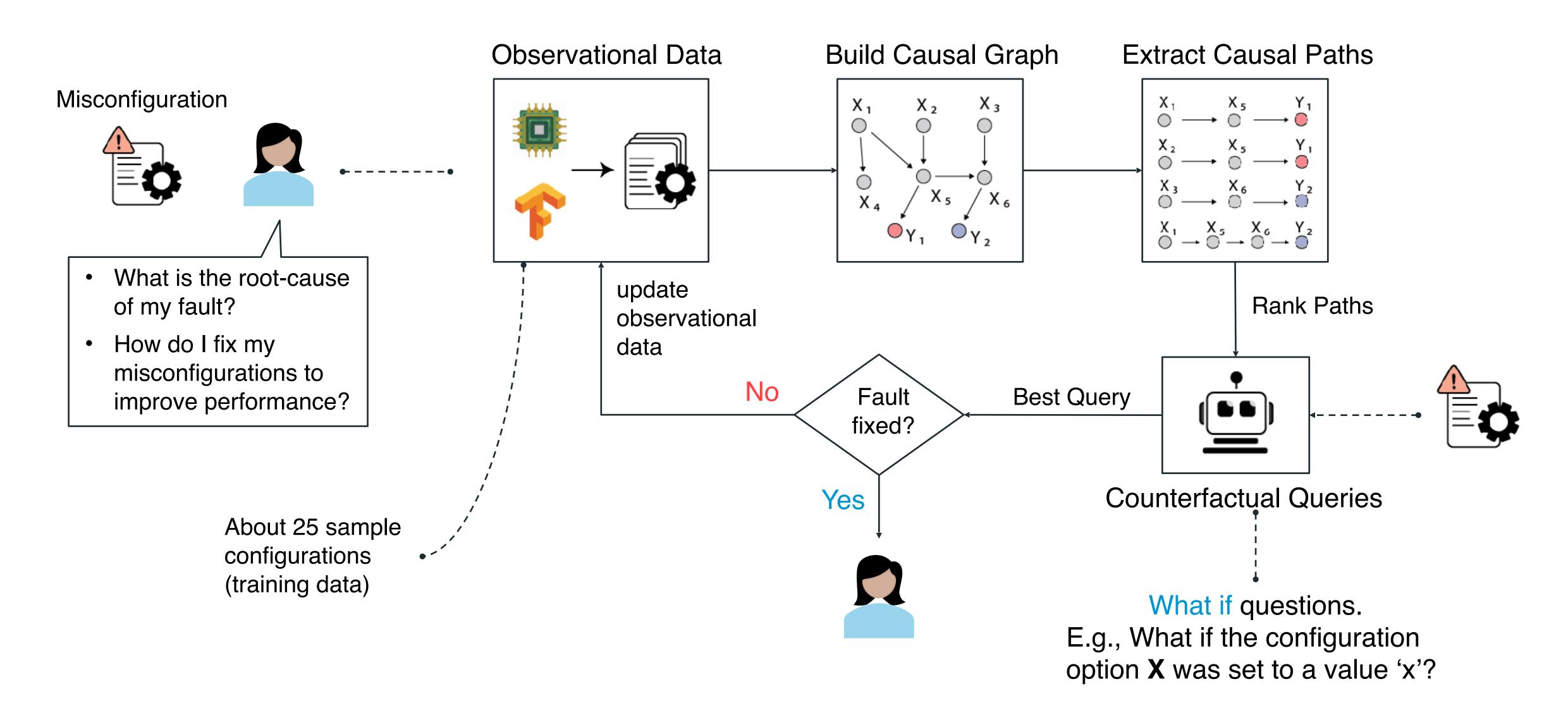
Causal Performance Model

 $Branchmisses = 2 \times Bitrate + 8.1 \times Buffersize + 4.1 \times Bitrate \times Buffersize \times Cachemisses$





Causal Debugging



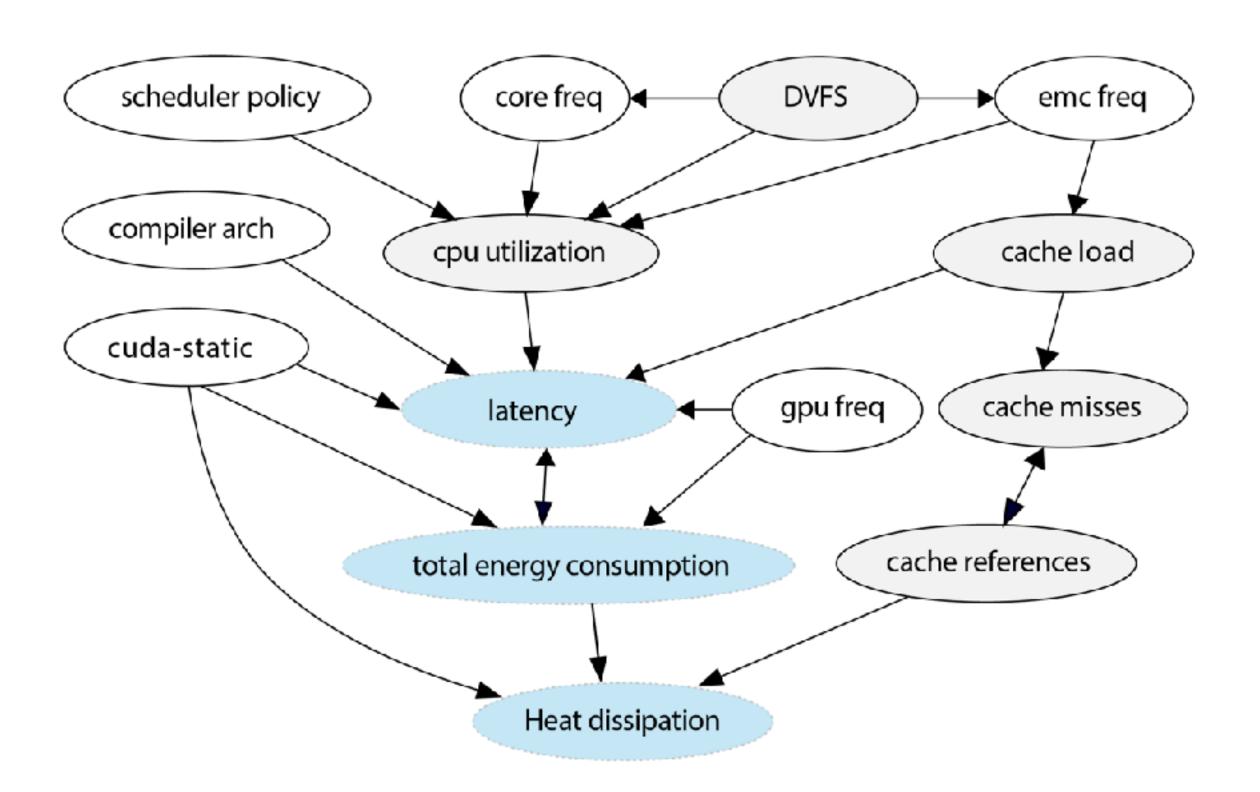
Extracting Causal Paths from the Causal Model

Problem

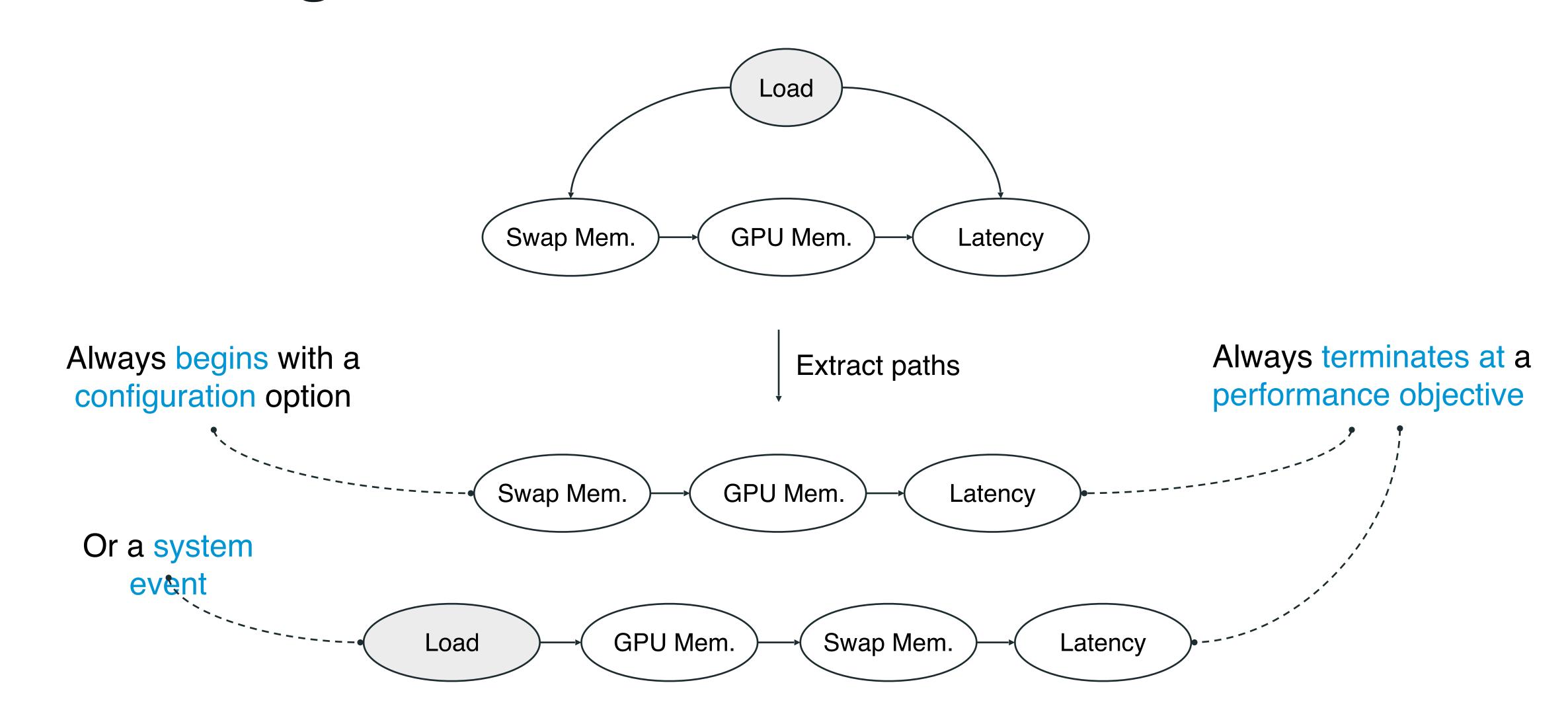
- X In real world cases, this causal graph can be very complex
- X It may be intractable to reason over the entire graph directly

Solution

- ✓ Extract paths from the causal graph
- ✓ Rank them based on their Average Causal Effect on latency, etc.
- ✓ Reason over the top K paths

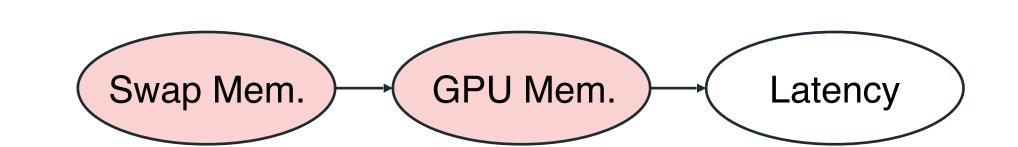


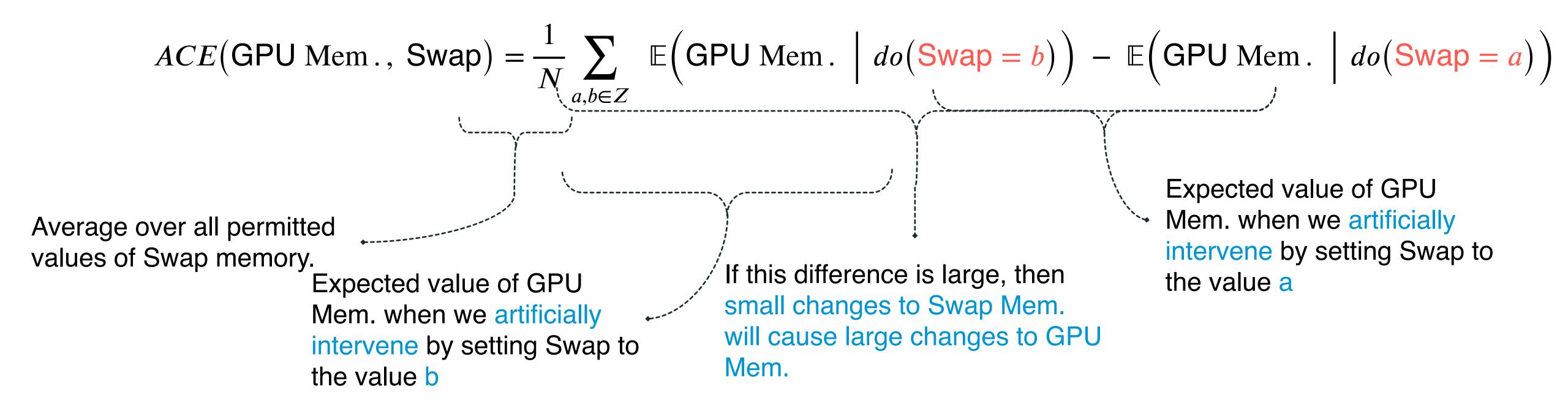
Extracting Causal Paths from the Causal Model



Ranking Causal Paths from the Causal Model

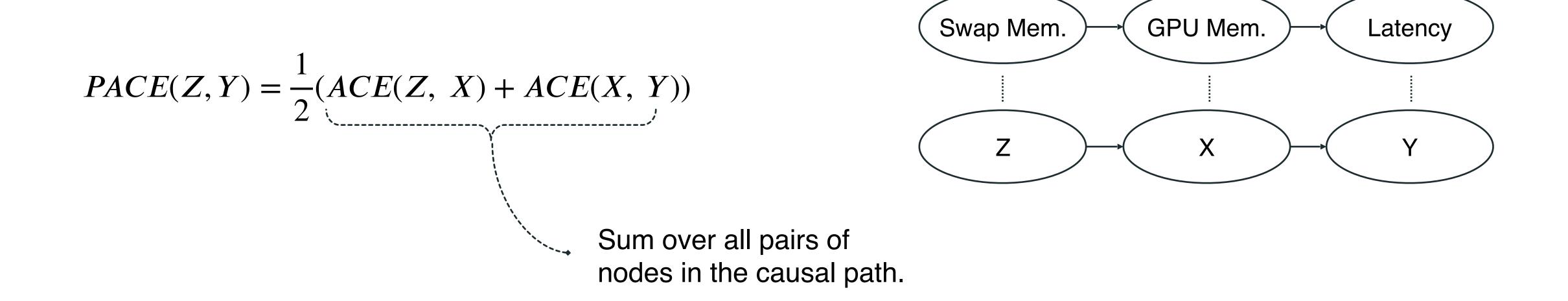
- They may be too many causal paths
- We need to select the most useful ones
- Compute the Average Causal Effect (ACE) of each pair of neighbors in a path



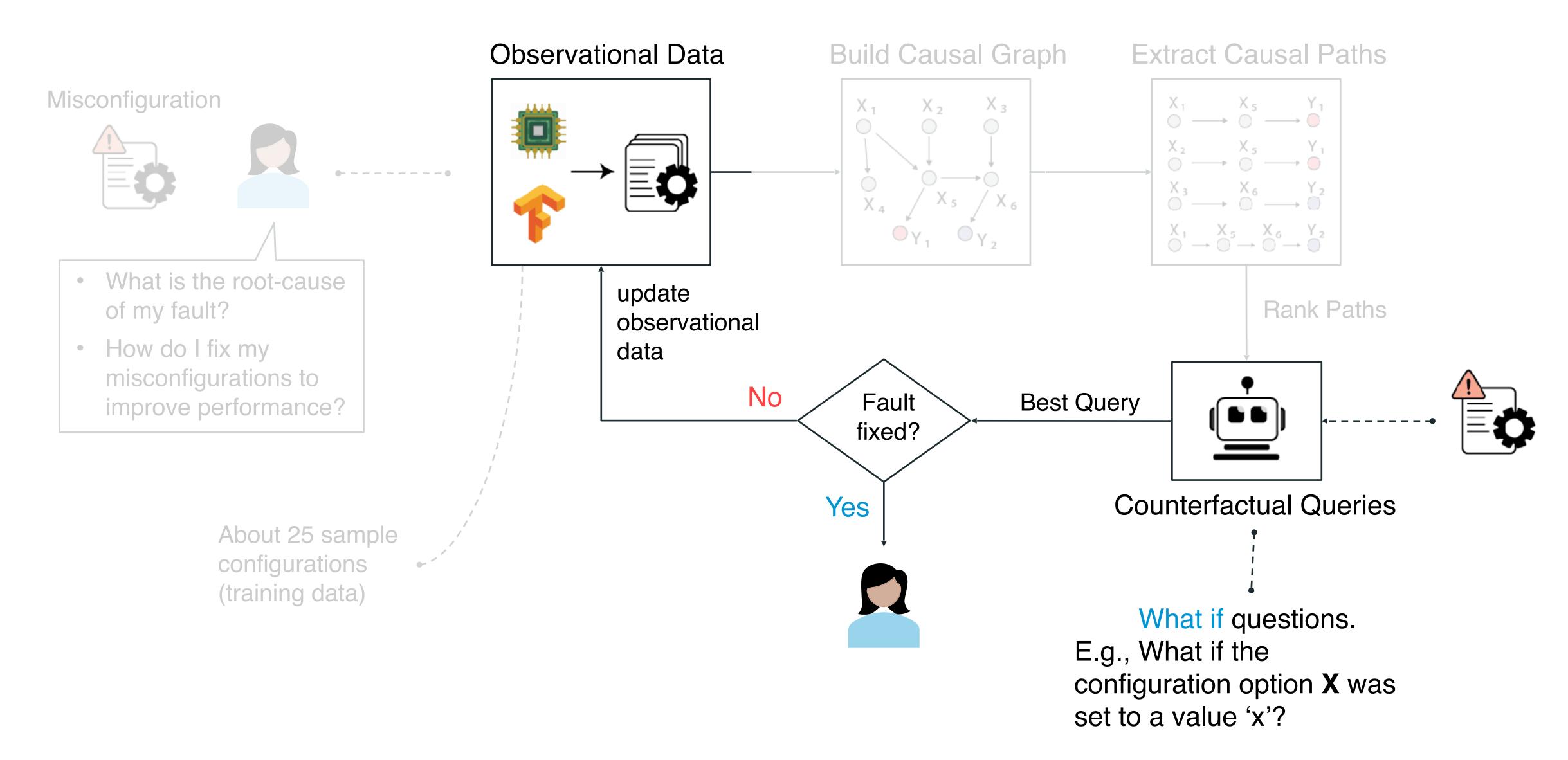


Ranking Causal Paths from the Causal Model

Average the ACE of all pairs of adjacent nodes in the path



- Rank paths from highest path ACE (PACE) score to the lowest
- Use the top K paths for subsequent analysis



 Counterfactual inference asks "what if" questions about changes to the misconfigurations

Example



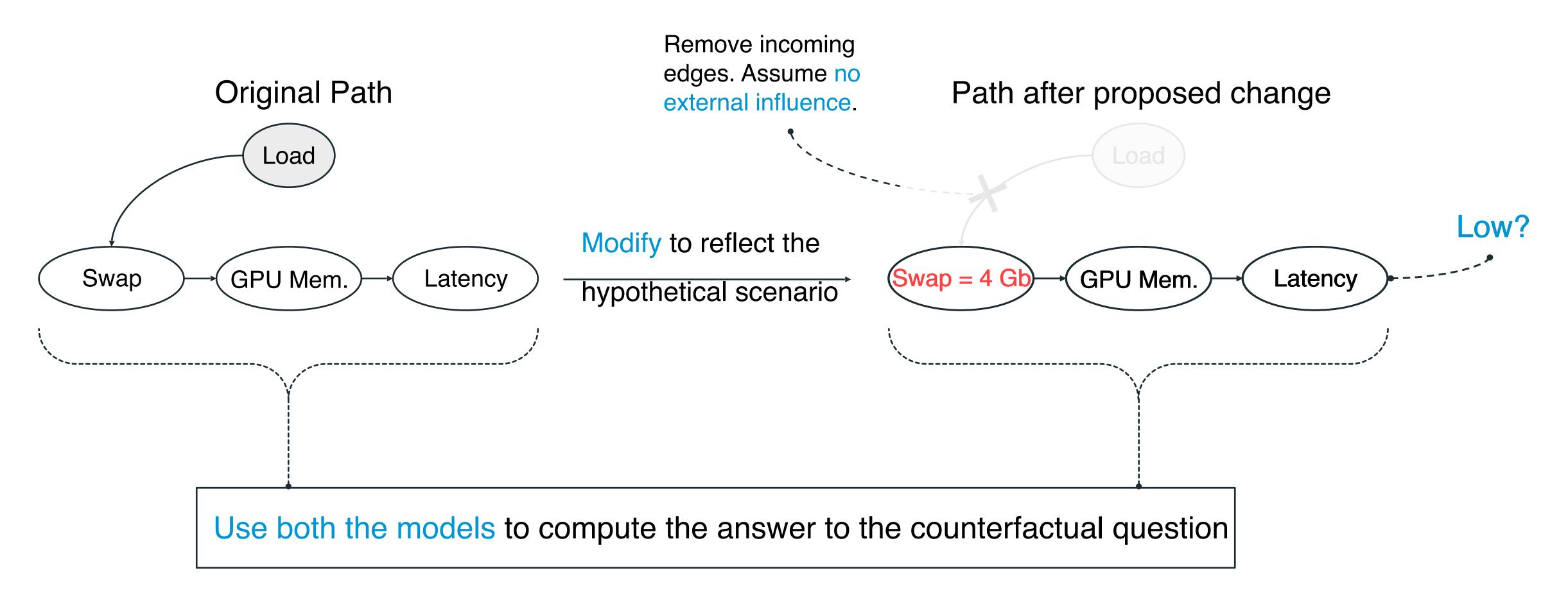
"Given that my current swap memory is 2 Gb, and I have high latency. What is the probability of having low latency if swap memory was increased to 4 Gb?

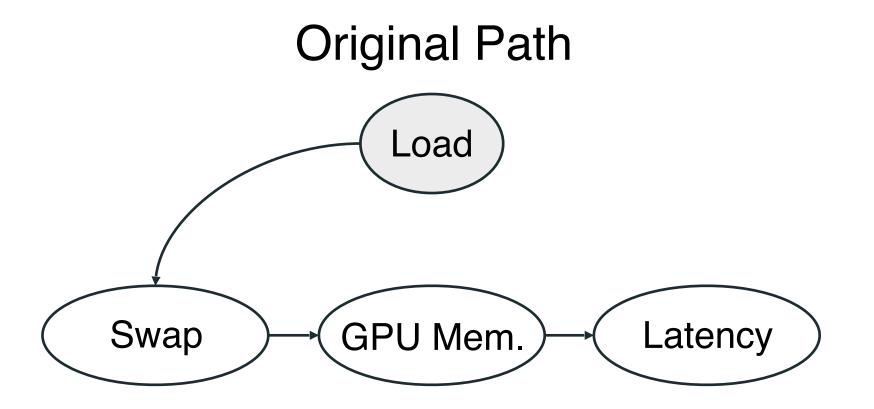
We are interested in the scenario where:

We hypothetically have low latency;

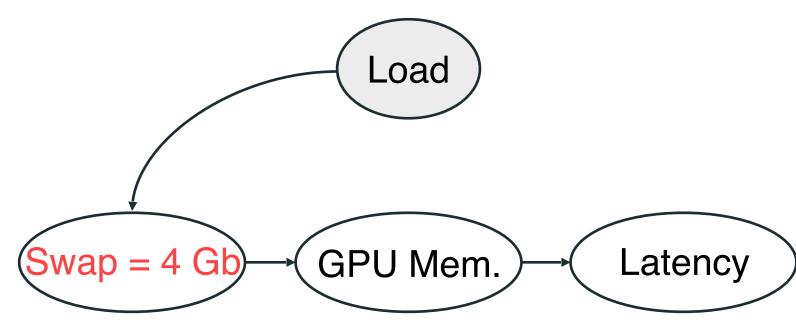
Conditioned on the following events:

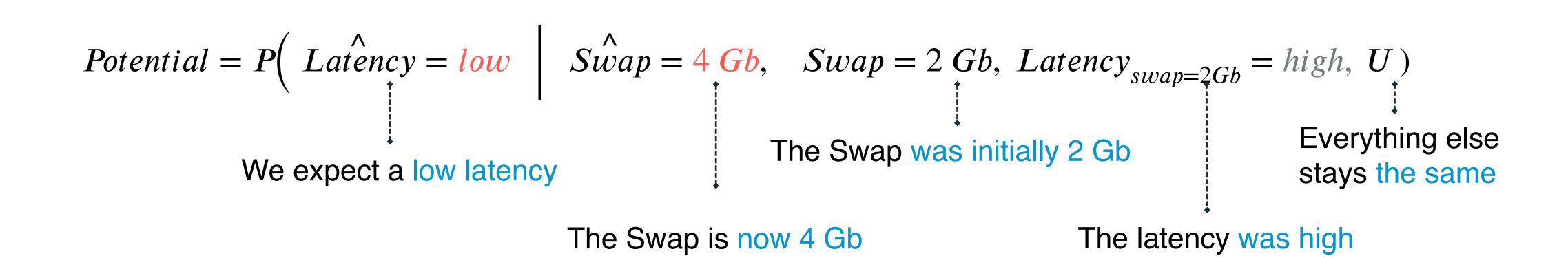
- We hypothetically set the new Swap memory to 4 Gb
- Swap Memory was initially set to 2 Gb
- We observed high latency when Swap was set to 2 Gb
- Everything else remains the same











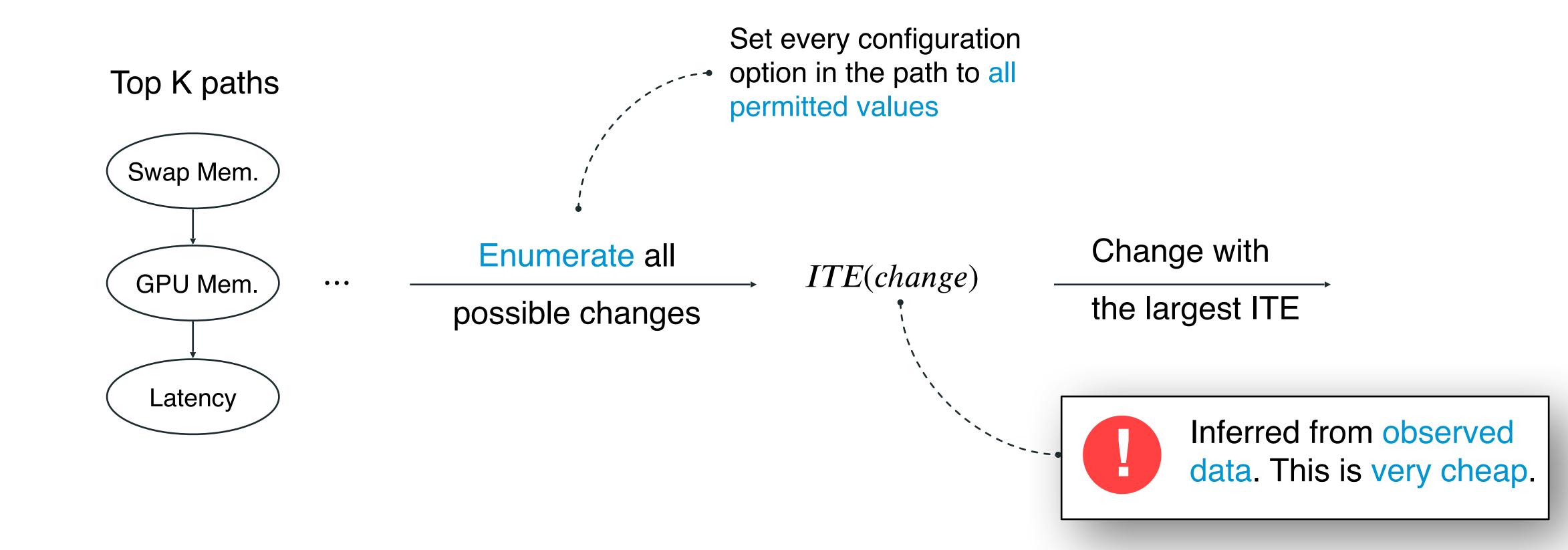
Potential =
$$P(\text{outcome} = \text{good} \mid \text{change}, \text{outcome}_{\neg \text{change}} = \text{bad}, \neg \text{change}, U)$$

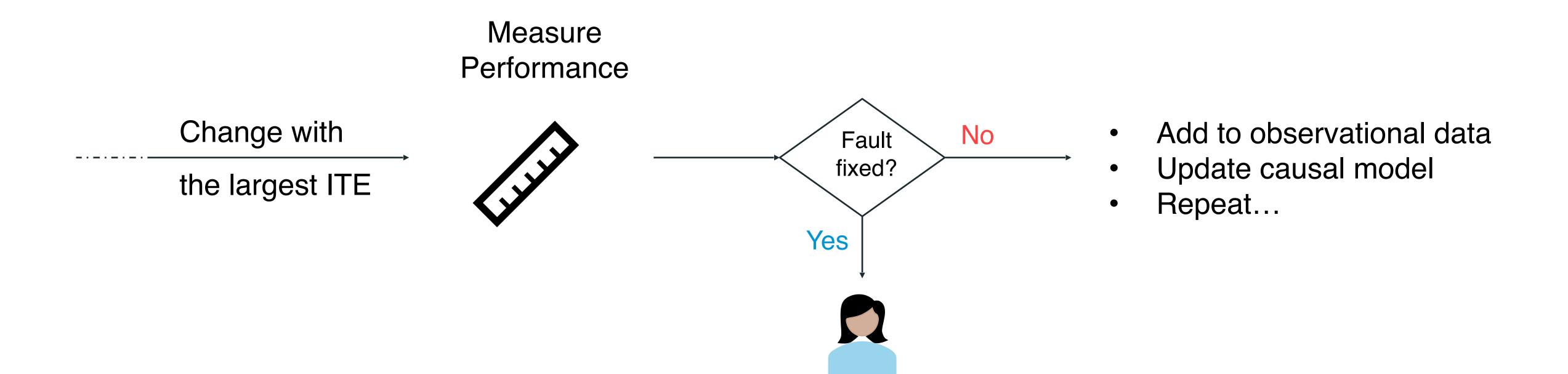
Probability that the outcome is good after a change, conditioned on the past

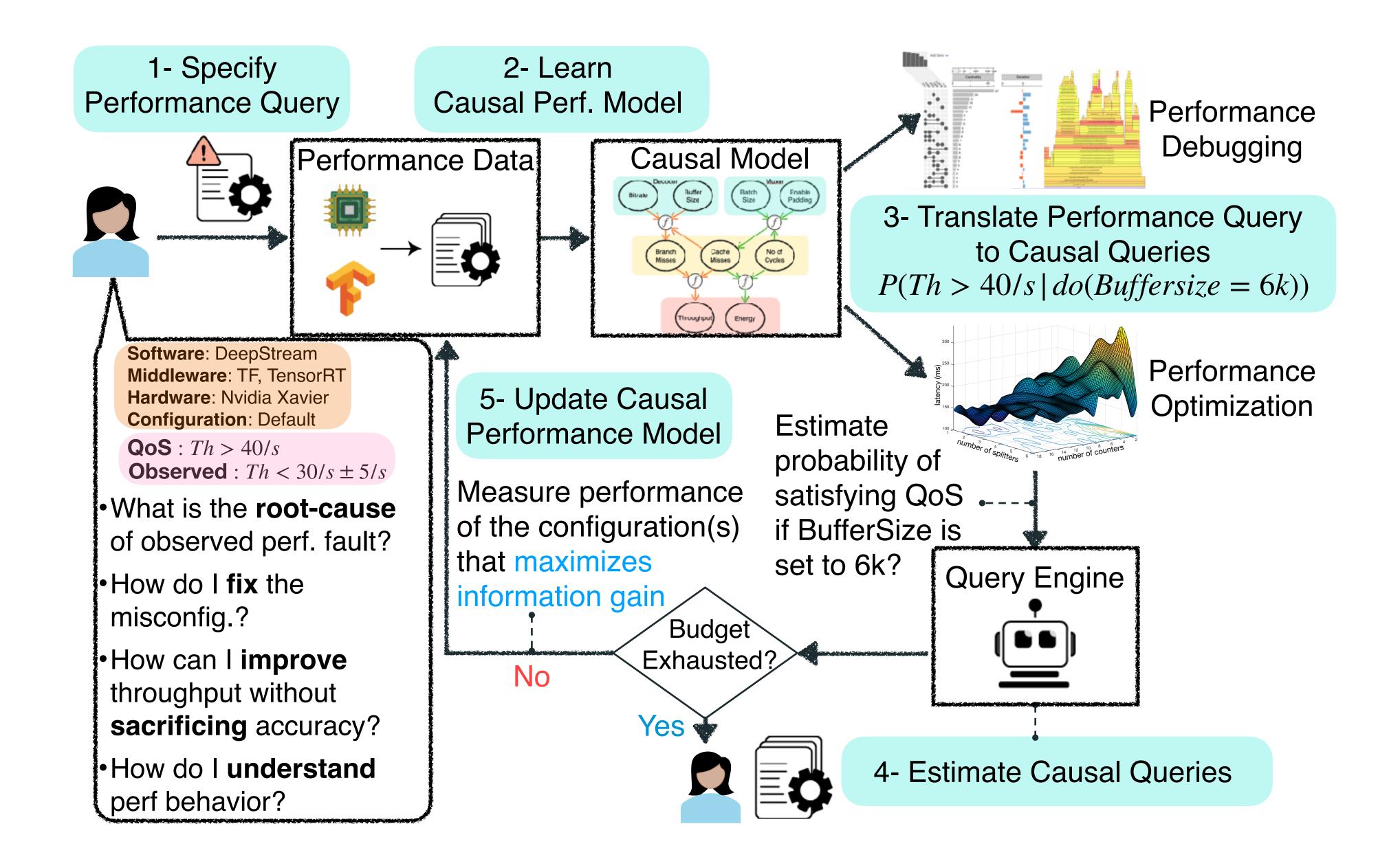
$$Control = P(out\hat{c}ome = bad | \neg change, U)$$

Probability that the outcome was bad before the change

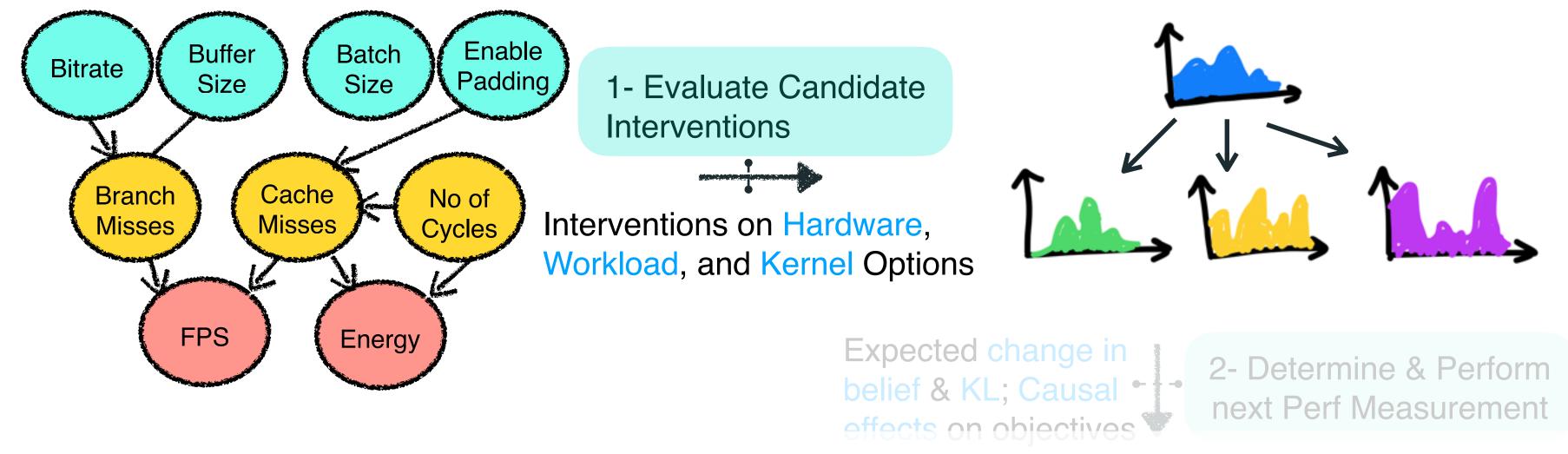
If this difference is large, then our change is useful

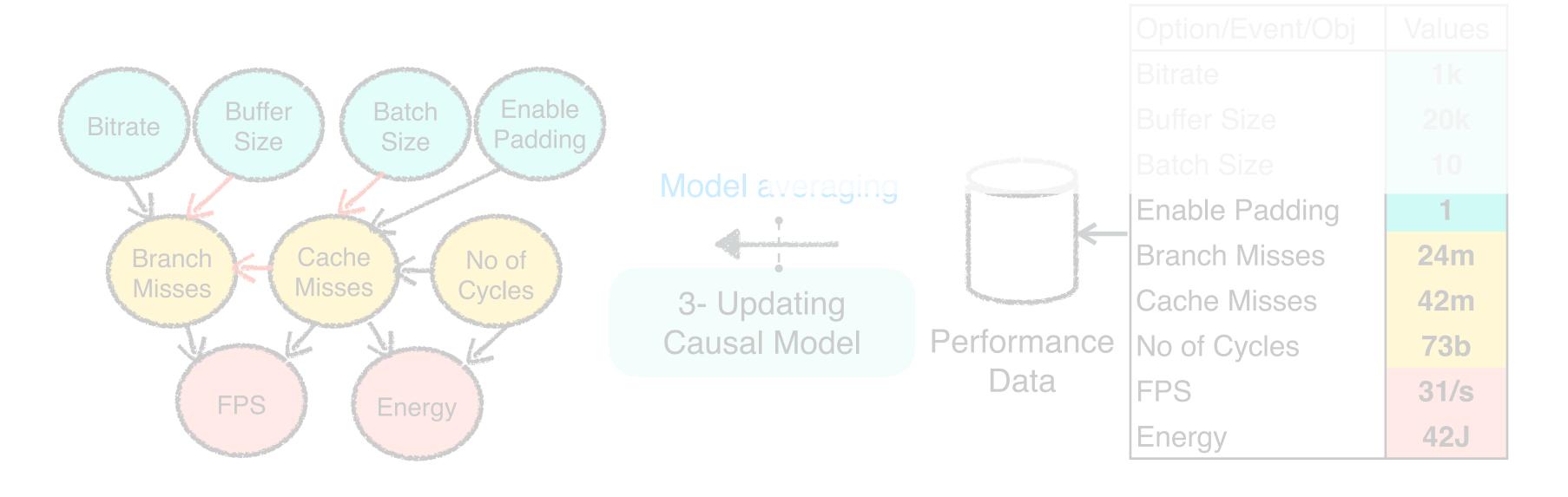




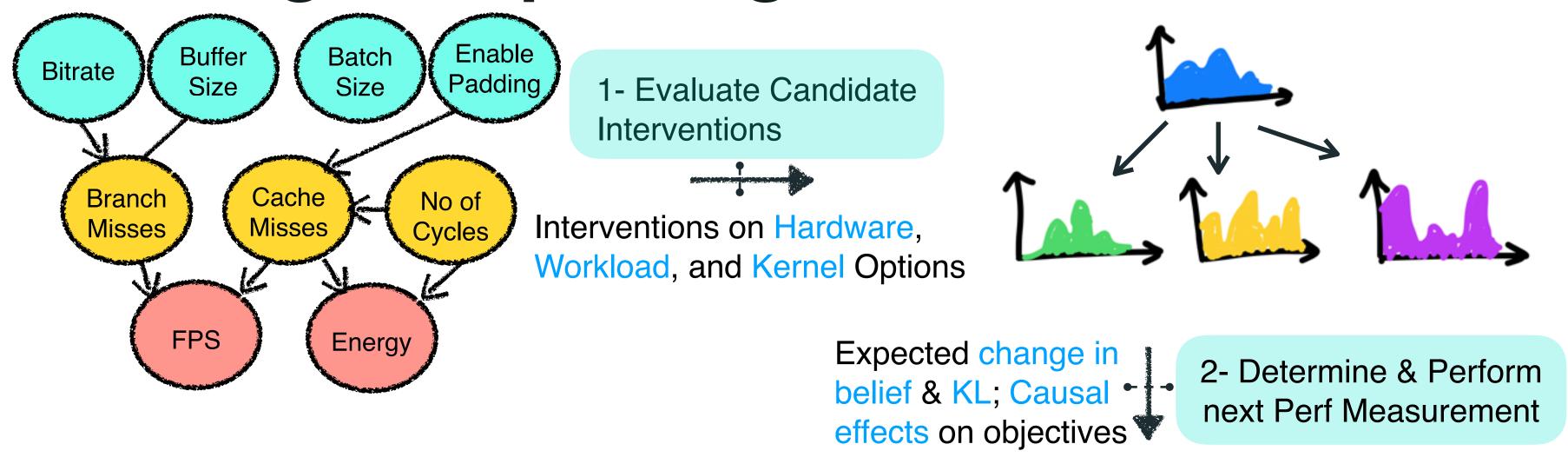


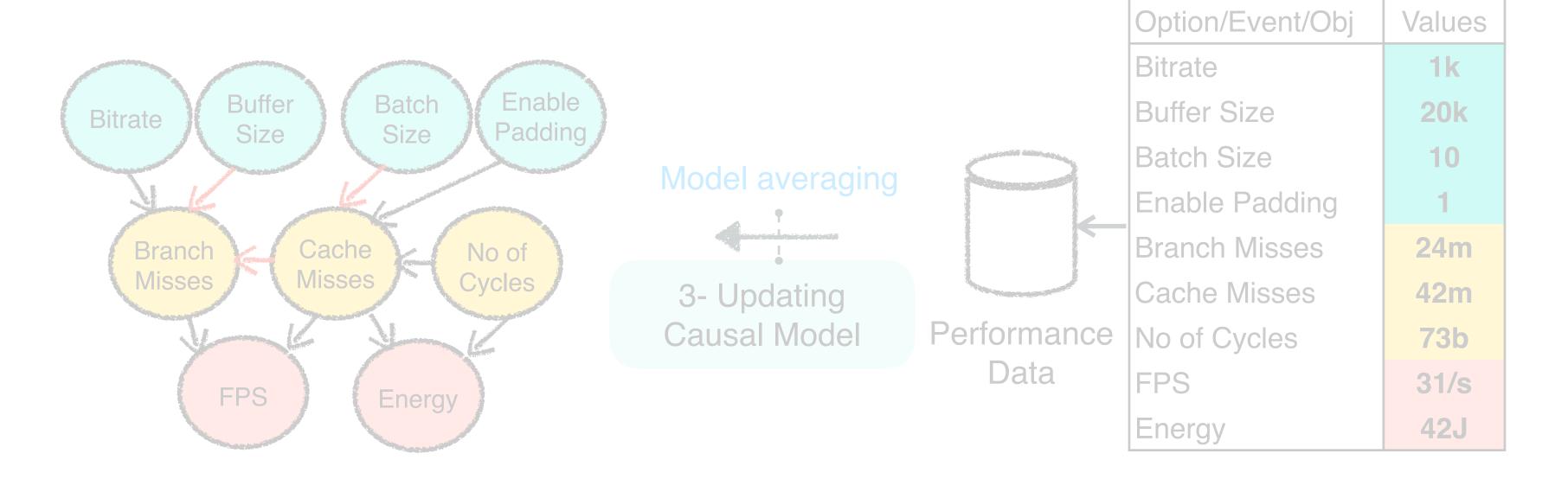
Active Learning for Updating Causal Performance Model



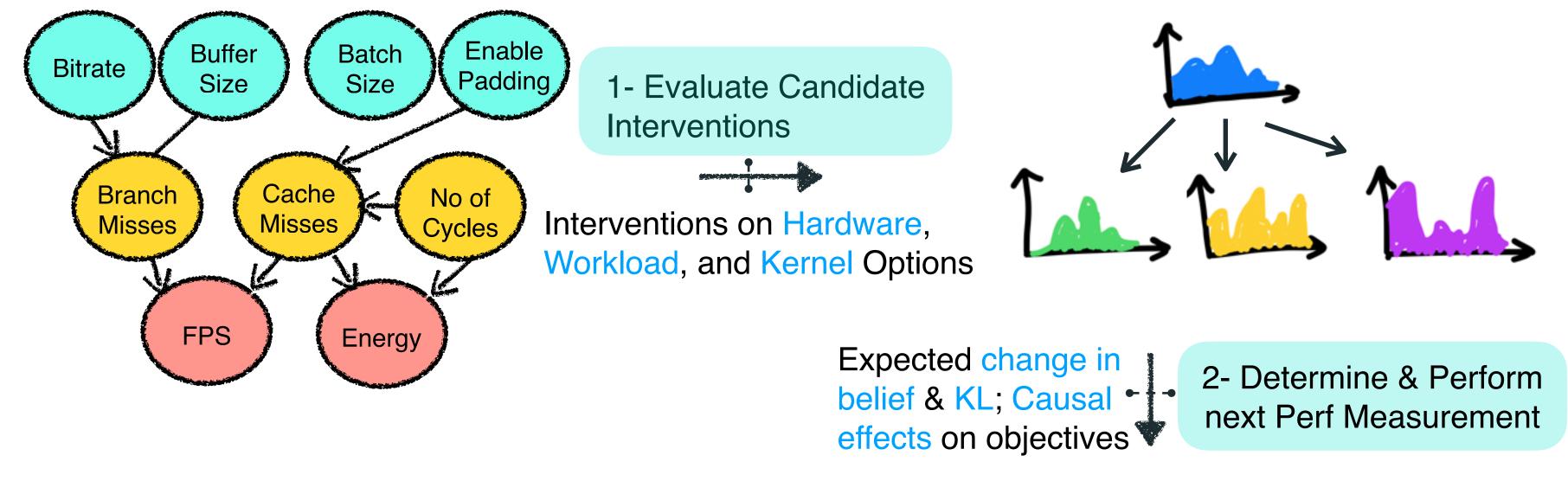


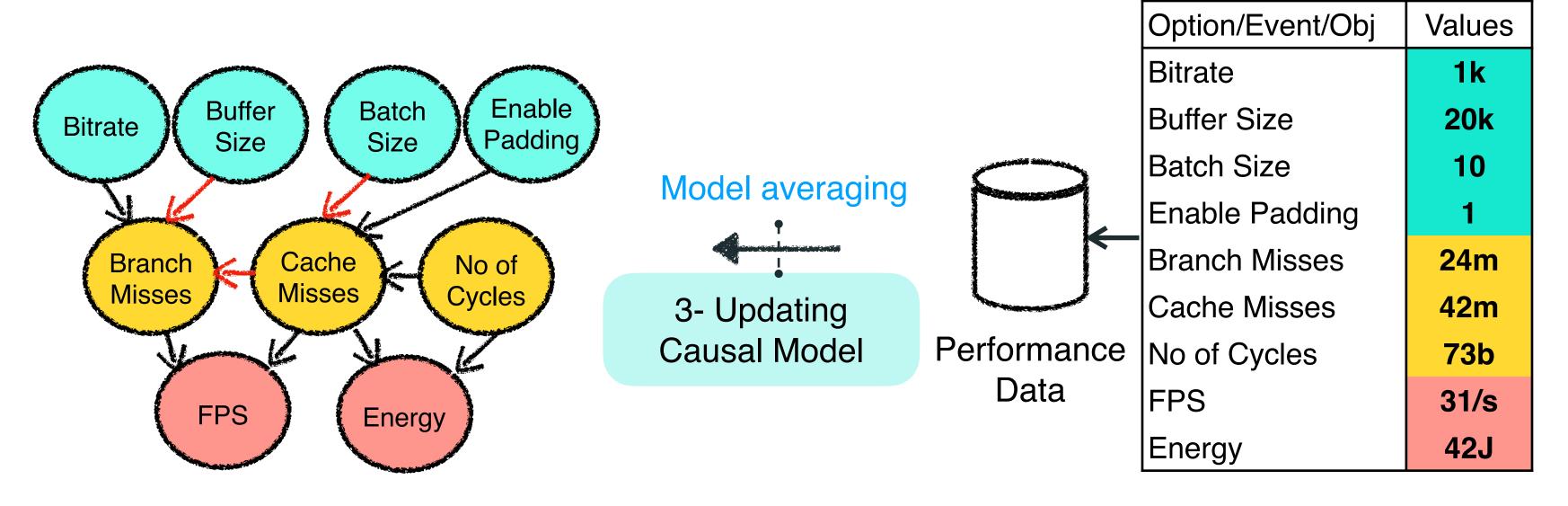
Active Learning for Updating Causal Performance Model





Active Learning for Updating Causal Performance Model





Benefits of Causal Reasoning for System Performance Analysis



There are two fundamental benefits that we get by our "Causal Al for Systems" methodology

- 1. We learn **one central (causal) performance model** from the data across **different performance tasks**:
 - Performance understanding
 - Performance optimization
 - Performance debugging and repair
 - Performance **prediction** for different environments (e.g., canary-> production)
- 2. The causal model is transferable across environments.
 - We observed Sparse Mechanism Shift in systems too!
 - Alternative non-causal models (e.g., regression-based models for performance tasks) are not transferable as they rely on i.i.d. setting.



Unicorn: Reasoning about Configurable System Performance through the Lens of Causality

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Abstract

Modern computer systems are highly configurable, with the total variability space sometimes larger than the number of atoms in the universe. Understanding and reasoning about the performance behavior of highly configurable systems, over a vast and variable space, is challenging. State-of-theart methods for performance modeling and analyses rely on predictive machine learning models, therefore, they become (i) unreliable in unseen environments (e.g., different hardware,

